

UniVTG: Towards Unified Video-Language Temporal Grounding

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Abstract

Video Temporal Grounding (VTG), which aims to ground target clips from videos (such as consecutive intervals or disjoint shots) according to custom language queries (e.g., sentences or words), is key for video browsing on social media. Most methods in this direction develop task-specific models that are trained with type-specific labels, such as moment retrieval (time interval) and highlight detection (worthiness curve), which limits their abilities to generalize to various VTG tasks and labels. In this paper, we propose to *Unify the diverse VTG labels and tasks*, dubbed UniVTG, along three directions: Firstly, we revisit a wide range of VTG labels and tasks and define a unified formulation. Based on this, we develop data annotation schemes to create scalable pseudo supervision. Secondly, we develop an effective and flexible grounding model capable of addressing each task and making full use of each label. Lastly, thanks to the unified framework, we are able to unlock temporal grounding pretraining from large-scale diverse labels and develop stronger grounding abilities e.g., zero-shot grounding. Extensive experiments on three tasks (moment retrieval, highlight detection and video summarization) across seven datasets (QVHighlights, Charades-STA, TACoS, Ego4D, YouTube Highlights, TV-Sum, and QFVS) demonstrate the effectiveness and flexibility of our proposed framework. The codes are available at <https://github.com/showlab/UniVTG>.

1. Introduction

With the increasing interest in sharing daily lives, video has emerged as the most informative yet diverse visual form on social media. These videos are collected in a variety of settings, including untrimmed instructional videos [28], and well-edited vlogs [18]. With massive scales and diverse video forms, automatically identifying relevant moments based on user queries has become a critical capability in the industry for efficient video browsing.

This significant demand has given rise to a number of video understanding tasks, including moment retrieval [66, 63, 30], highlight detection [52, 16, 56], and video summarization [14, 45, 42]. As depicted in Fig. 1, mo-

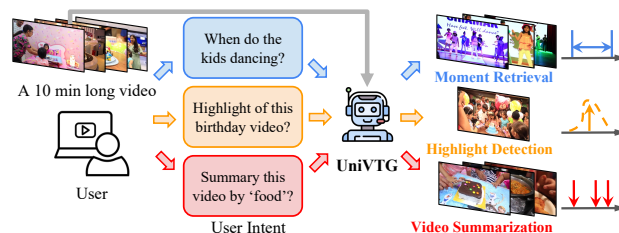


Figure 1: Given a video and a specific user query, UniVTG serves as a general video browsing helper that assists users by returning different scale target clips to support various VTG tasks.

ment retrieval tends to localize consecutive temporal windows (interval-level) by giving natural sentences; highlight detection aims to pick out the key segment with highest worthiness (curve-level) that best reflects the video gist; video summarization collects a set of disjoint shots (point-level) to summarize the video, with general or user-specific queries. Despite task-specific datasets [10, 5, 46, 45] and models [66, 63, 56] have been developed, these tasks are typically studied separately. In general, these tasks share a common objective of grounding various scale clips based on customized user queries, which we refer to as Video Temporal Grounding (VTG).

Though these tasks are closely related, their relationship has not been explicitly studied until recently. [20] introduces the first unified benchmark QVHighlights for moment retrieval and highlight detection, and presents the first model Moment-DETR for jointly learning. On this basis, UMT [26] expands audio inputs, and QD-DETR [29] develops negative-pairs and saliency tokens. Nevertheless, these studies solely focus on designing models that intersect two subtasks and learn grounding capabilities rely on specific labels. This means that they lack the ability to generalize the VTG across diverse temporal labels, such as unique point-level narrations in Ego4D [13]. Furthermore, we have witnessed promising progress in Vision-Language Pretraining (VLP). One notable work is GLIP [23, 64], which develops a unified model via joint utilizing large-scale diverse image annotations such as image captions and bounding boxes for spatial grounding. However, we do not observe similar progress in video-language pretraining. Most works in this area are designed for video-level tasks such as video-text retrieval [54, 47] rather than temporal grounding. This

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is largely due to the manual cost of fine-grained temporal annotations is expensive, making it challenging to obtain open-source, scalable yet diverse annotations to support grounding pretraining along the temporal axis in videos.

Therefore, we see a clear motivation to pursue a Unified VTG framework and propose our UniVTG, which aims to unify diversity in VTG along three directions: **(i) From the label and task aspect**, we first define a formulation for VTG where each video is decomposed as a clip sequence that each clip is assigned three basic query-conditional elements. Such a formulation enables us to unify various VTG labels and tasks under the same framework. Moreover, to address the limitation of temporal labels, we propose a data annotation scheme based on CLIP [36] to produce scalable fine-grained pseudo labels. **(ii) From the model aspect**, we develop a flexible yet effective grounding model that inherits the principles of our formulation. Our model devises single-stream and dual-stream pathways for modality fusion and modality alignment respectively, and is equipped with three heads to decode three key elements. This favorable design is capable of addressing each task and utilizing each label. **(iii) Lastly**, thanks to the unified framework and the availability of pseudo labels, we can perform **large-scale temporal grounding pretraining** across various labels to enhance our grounding abilities. This empowers us to address various VTG downstream tasks across multiple domains, including zero-shot inference.

To validate the effectiveness of our proposed framework, we conduct experiments not only on joint moment retrieval and highlight detection benchmark (QVHighlights [20]), but also on three individual tasks for moment retrieval (Ego4D [13], Charades-STA [10], TACoS [38]), highlight detection (YouTube Highlights [46], TVSum [45]) and video summarization (QFVS [42]). Our UniVTG, one unified model with 4.2M samples for temporal grounding pretraining, has achieved remarkable results, outperforming state-of-the-art methods that are specifically tailored for each task. Overall, our contributions are four folds:

- To the best of our knowledge, our UniVTG is the first video temporal grounding pretraining that across varied domains and tasks, including moment retrieval, highlight detection and video summarization.
- We introduce a unified VTG framework that can fully leverage rich supervision from open-source, scalable yet diverse temporal annotations, such as point-level, interval-level, and curve-level labels.
- To address the limitations of pretraining corpus, we develop an efficient annotation method that uses CLIP as a teacher to produce scalable pseudo temporal labels.
- We demonstrate the effectiveness and flexibility of the proposed framework across four settings and seven datasets. Detailed ablation studies validate the superiority of the proposed components.

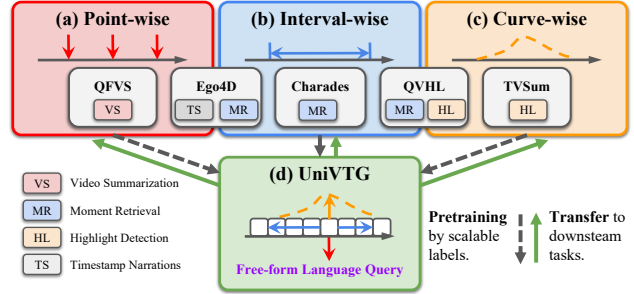


Figure 2: Diverse VTG labels can be divided into three types, each mainly associated with specific benchmarks: **(a) point-level labels** for video summarization [42] and timestamp narrations [13]; **(b) interval-level labels** for moment retrieval [13, 10, 20]; **(c) curve-level labels** for highlight detection [45, 20]. **(d) UniVTG** unifies diverse labels and tasks within one framework, enabling large-scale pretraining with diverse labels (dotted gray line) that can be transferred to various downstream tasks (solid green line).

2. Related Work

2.1. Video Temporal Grounding

We review three VTG tasks: moment retrieval, highlight detection, and video summarization, and compare them as different variations of a common problem.

Moment Retrieval aims to localize target moments *i.e.*, one [10] or many [20] continuous intervals within a video by a language query, as shown in Fig. 2 (b). Previous methods fall into two categories: proposal-based and proposal-free. The proposal-based methods [2, 10, 66] employ a two-stage process of scanning the entire video to generate candidate proposals, which are then ranked based on their matching to the text query. In contrast, the proposal-free methods [7, 61, 11, 63, 30] learn to regress the start and end boundaries directly without requiring proposal candidates. Our UniVTG borrows from proposal-free approaches but extends it by incorporating diverse temporal labels and tasks with a concise design.

Highlight Detection aims to assign a worthiness score to each video segment *e.g.*, Fig. 2 (c), and then return the top highest scoring segment as the highlight. Previous highlight detection datasets [40, 46, 45] tend to be domain-specific and query-agnostic, in which many efforts [15, 52, 16, 56, 3] treat this task as a visual or visual-audio scoring problem. Nevertheless, video highlights typically have a theme, which is often reflected in the video titles [45] or topics [46] *e.g.*, “surfing”. Recently, [20] proposes a joint moment retrieval and highlight detection benchmark QVHighlights that enables users to produce various highlights for one video conditional on different text queries.

Video Summarization aims to summarize the whole video by a set of shots to provide a quick overview *e.g.*, Fig. 2 (a), which contains two forms: Generic video summarization [14, 45, 27, 17] that captures the important scene using visual clues merely, while Query-focused video summariza-

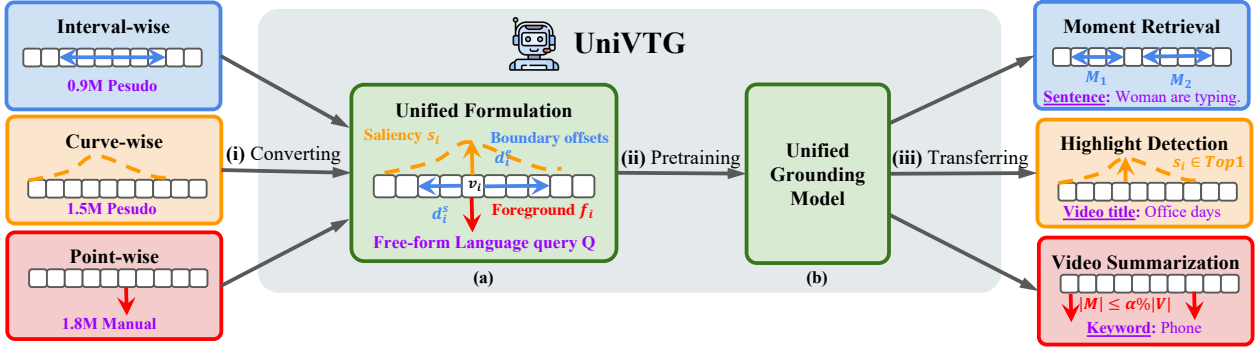


Figure 3: **Illustration of UniVTG pipeline.** (i) Given any kind of labels, such as interval label, we first convert it into our (a) **unified formulation** (§ 3.1) by deriving other two labels (point and curve labels). (ii) Once we have collect a large-scale diverse labels (§ 3.2), we leverage them to pretrain a **unified grounding model** (§ 4). (iii) Next, the unified model is transferred to various VTG downstream tasks *e.g.*, highlight detection.

tion [42, 32, 49] that allows users to customize the summary by specifying text keywords (*e.g.*, tree and cars). The latter is closer to practical usage hence we focus on it. Recently, IntentVizor [49] proposes an interactive approach allowing users to adjust their intents to obtain a superior summary.

In general, each of the three tasks represents a specific form of VTG that grounds different scales of clips from videos (*e.g.*, a consecutive clip set, a single clip or a disjoint clip set) by offering customized text queries (*e.g.*, sentences, titles or keywords). However, previous methods address some subtasks solely. Based on this insight, our goal is to develop a unified framework to handle all of them.

2.2. Vision-Language Pretraining

The emergence of large-scale vision-language datasets, such as [43, 41, 28, 4], has paved the way for the development of VLP [36, 22, 19, 34, 21] to enhance video-text representation for various vision-language tasks [60, 54, 53]. The representative CLIP [36] has shown that *image-level* visual representations can be effectively learned using large-scale noisy image-text pairs. Furthermore, GLIP [23, 64] makes an effort along the spatial axis, which leverages various image annotations, such as image labels, captions, and bounding boxes, to develop strong *region-level* understanding capacity for spatial grounding tasks. However, due to the expensive manual cost of fine-grained *temporal-level* annotations *i.e.*, temporal bounding box, this grounding pretraining has not been extended to the temporal axis in videos, limiting its progress to match the spatial counterparts. To address this limitation, we explore alternative approaches that leverage accessible timestamp narrations [13] and derive pseudo supervision as the pretraining corpus.

On the other hand, there are several efforts have been made to perform temporal-friendly video pretraining [1, 55, 6, 62] to pursue a better video representation for grounding tasks. But the resulting pretraining model still requires an additional grounding model such as 2D-TAN [66] to perform video grounding. In contrast, powered by our unified framework and scalable pseudo annotations, we can directly

conduct VLP with grounding as a pretraining task. This way eliminates the need for additional grounding models and enables zero-shot grounding capacity.

3. Towards Unified VTG: Tasks and Labels

The UniVTG pipeline is displayed in Fig. 3. In this section, we start by introducing the unified formulation.

3.1. Unified Formulation

Given a video V and a language query Q , we first divide V into a sequence of L_v fixed-length clips $\{v_1, \dots, v_{L_v}\}$, where each clip v_i is of length l and has a centered timestamp t_i . The free-form text query Q has L_q tokens, denoted as $Q = \{q_1, \dots, q_{L_q}\}$. We then define three elements for each clip $v_i = (f_i, d_i, s_i)$, described as follows:

- **Foreground indicator** $f_i \in \{0, 1\}$: a binary value indicating whether the i -th clip v_i belongs to the foreground or not. If clip v_i is the foreground of Q , then $f_i = 1$, otherwise $f_i = 0$.
- **Boundary offsets** $d_i = [d_i^s, d_i^e] \in \mathbb{R}^2$: the temporal distance that converts the clip timestamp t_i to its interval boundaries. Here, d_i is valid when $f_i = 1$. The d_i^s is the distance between the starting of the interval and t_i , whereas d_i^e is the distance between the ending and t_i . Thus, the whole temporal interval b_i of v_i can be represented as $b_i = [t_i - d_i^s, t_i + d_i^e]$
- **Saliency score** $s_i \in [0, 1]$: a continuous score determining the relevance between the visual content of clip v_i and the query Q . If the clip and query are highly correlated, $s_i = 1$; If they are totally irrelevant, then $s_i = 0$. Notably, it is reasonable to assume that $s_i > 0$ if a clip is in the foreground of Q , otherwise $s_i = 0$.

In Fig.3 (a), we draw a schematic diagram to represent these three elements of clip v_i in our definition.

3.2. Revisiting Various VTG Tasks and Labels

Treating clips as the atom composition of a video, we define the VTG problem as collecting a target clip set $M =$

$\{v_i \in V|Q\}$ from V , conditional on language query Q . We next illustrate how to extend this definition to various tasks and labels. Especially, for each label, we answer:

1. How to collect scalable label corpus for pretraining?
2. When using the unified formulation, how can we obtain unknown elements based on the available one?

3.2.1 Moment Retrieval and Interval-wise Label.

Moment retrieval aims to localize one [10] or many [20] intervals in a video corresponding to a sentence Q . As shown in Fig. 3 (Right blue), moment retrieval aims to select m consecutive clip sets $M = M_1 \cup \dots \cup M_m$, where $m \geq 1$, and M_j is the j -th target moment. M can be simplified as the boundary set of foreground clips $\{b_i | f_i = 1\}$.

The temporal interval with specific target boundaries is a common label for moment retrieval. However, annotating intervals requires manually reviewing the full video, which is expensive. A solution is ASR [28, 57] that provide start and end timestamps, but ASR is often too noisy and poorly aligned with the visual content, making it suboptimal. Here, we sought an alternative solution. We found that visual captions [43, 4] tend to be descriptive, making them well-suited as grounding queries, thus if we can know how these videos are cut from the raw source, we can use this information to create pseudo intervals. We find that VideoCC [31] is a viable option for this purpose. It is worth noting that VideoCC is initially developed for video-level pretraining (e.g., power video-text retrieval), and we are the pioneer to investigate its potential in temporal grounding pretraining.

Once we obtain intervals, we convert interval labels into the proposed formulation by defining $f_i = 0$ and $s_i = 0$ for clips that are not in target interval, and we assign $f_i = 1$ and assume $s_i > 0$ for clips that belongs to the target interval.

3.2.2 Highlight Detection and Curve-wise Label.

Highlight detection aims to assign an importance score to each video clip (making its annotations like a curve), then return the few highest-scoring clips as the highlight, where queries may [20] or may not [46, 45] be provided as input. For video highlighting datasets without language queries, we can use *video titles* [45] or *video domain name* [46] as Q because they are highly related to the topic of the video. Then, this task is equivalent to picking clips with the top highest saliency scores i.e. $M = \{v_i | s_i \in \text{top-}K\}$.

Due to the interestingness contain subjectivity, the same video usually needs to be labeled by several people to eliminate bias. This makes curve labels the most expensive yet informative temporal annotations. Therefore, we are motivated to find an efficient way of producing scalable curve labels. Intuitively, interestingness reflects how each clip is relevant to the video gist. As depicted in Fig. 4 (a), we first define a concept bank using an open-world detection class list [41]. Next, we use CLIP as a teacher to get the clip-level cosine similarities between each concept. Then, we

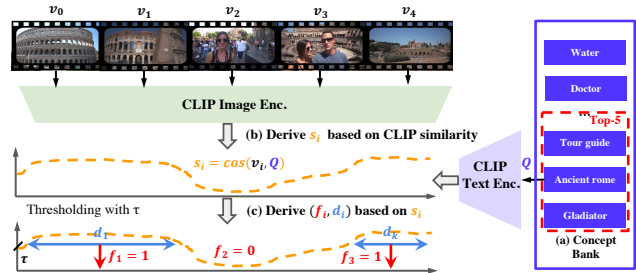


Figure 4: **Process of using CLIP to produce temporal labels.** (a) We first use a concept bank to cover diverse open-world concepts. (b) Next, we use CLIP as teacher to calculate the clip-level scores between each concept to get top-5 concepts as video gist, and treat their clip scores as saliency s_i . (c) Based on s_i , we further derive the interval and point labels via thresholding.

select top-5 concepts as the video gist, and save their CLIP similarities as pseudo curve labels, i.e., Fig. 4 (b).

As shown in Fig. 4 (c), after obtaining curve labels, we assign $f_i = 1$ for clips with s_i greater than a threshold τ , otherwise $f_i = 0$. The τ is estimated based on the similarity of each video, refer to Supp. for details. The offsets d_i are defined as the distance between the foreground clip and its nearest neighboring clips where $f_i = 0$.

3.2.3 Video Summarization and Point-wise Label.

Query-focused video summarization [42] aims to summarize the entire video with a set of shots to provide a quick overview, with user-specific concepts (for example, trees and cars). The generated summary should be succinct and representative of the entire video around the given query. We define this task by regarding *keywords* as Q , and select a set of clips $M = \{v_i | f_i = 1\}$, where the size of M is required to not exceed $\alpha\%$ of the original video length $|M| \leq \alpha\%|V|$ e.g., $\alpha = 2\%$.

The annotations in QFVS [42] are point labels that indicate whether each shot belongs to the concept or not. The cost of point labels is much cheaper than that of interval and curve labels since people only need to glance at a specific time. The recently Ego4D [13] dataset uses this point labeling to annotate massive-scale data by assigning a narration to an exact timestamp, such as “I am opening the washing-machine” at $t_i = 2.30$ sec. Due to the favorable scale, it is natural to adapt them for large-scale pretraining. Recently, there have been attempts to improve video-text representation using point-wise annotations to improve the video-text representation [24, 67, 35] and augment NLQ [13] baselines [37]. Despite this, these methods mainly focus on transferring within the same domain.

For point labels, we derive $s_i > 0$ if clip $f_i = 1$, otherwise $s_i = 0$. During pretraining, we estimate its temporal label b_i based on the average distance between consecutive narrations within the video [24, 37, 35].

4. Towards Unified VTG: Model

We here introduce our unified model which seamlessly inherits our proposed unified formulation.

4.1. Overview

As shown in Fig. 5, our model mainly comprises a frozen video encoder, a frozen text encoder, and a multi-modal encoder. The video and text encoders are kept consistent with Moment-DETR [18], which employs the concatenation of CLIP [36] (ViT-B/32) and SlowFast [9] (R-50) features as video representation, and use the CLIP text encoder [36] to extract token level features. Our multi-modal encoder contains k self-attention blocks that followed by three specific heads to decode the prediction.

Given an input video V with L_v clips and a language query Q with L_q tokens, we first apply the video encoder and the text encoder to encode the video and text respectively, then project them to the same dimension D by two Feed-Forward Networks (FFN), and thus obtain video features $\mathbf{V} = \{\mathbf{v}_i\}_{i=1}^{L_v} \in \mathbb{R}^{L_v \times D}$ and text features $\mathbf{Q} = \{\mathbf{q}_j\}_{j=1}^{L_q} \in \mathbb{R}^{L_q \times D}$. Next, we design two pathways for cross-modal alignment and cross-modal interaction.

(i) For cross-modal alignment, we first adopt an attentive pooling operator to aggregate the query tokens $\mathbf{Q} \in \mathbb{R}^{L_q \times D}$ into a sentence representation $\mathbf{S} \in \mathbb{R}^{1 \times D}$. Especially,

$$\mathbf{S} = \mathbf{A}\mathbf{Q}, \quad (1)$$

where the weight $\mathbf{A} = \text{Softmax}(\mathbf{W}\mathbf{Q}) \in \mathbb{R}^{1 \times L_q}$ and $\mathbf{W}^{1 \times L_q}$ is a learnable embedding. Then \mathbf{V} and \mathbf{S} are sent to perform contrastive learning (described in § 4.2).

(ii) For cross-modal interaction, learnable position embeddings \mathbf{E}^{pos} and modality-type embeddings \mathbf{E}^{type} are added to each modality to retain both positional and modal-ity information:

$$\begin{aligned} \tilde{\mathbf{V}} &= \mathbf{V} + \mathbf{E}_V^{pos} + \mathbf{E}_V^{type}, \\ \tilde{\mathbf{Q}} &= \mathbf{Q} + \mathbf{E}_T^{pos} + \mathbf{E}_T^{type}. \end{aligned} \quad (2)$$

Next, the text and video tokens are concatenated and get a joint input $\mathbf{Z}^0 = [\tilde{\mathbf{V}}; \tilde{\mathbf{Q}}] \in \mathbb{R}^{L \times D}$, where $L = L_v + L_q$. Further, \mathbf{Z}^0 is fed into the multi-modal encoder, which contains k transformer layers with each layer consisting of a Multi-headed Self-Attention and FFN blocks.

$$\mathbf{Z}^d = \text{MLP}(\text{MSA}(\mathbf{Z}^{d-1})), \quad d \in \{1 \dots k\}. \quad (3)$$

We take the video tokens $\tilde{\mathbf{V}}^k \in \mathbb{R}^{L_v \times D}$ from the multi-modal encoder E_m as output $\mathbf{Z}^k = [\tilde{\mathbf{V}}^k; \tilde{\mathbf{Q}}^k] \in \mathbb{R}$, and feed \mathbf{Z}^k into the following heads for prediction.

4.2. Pretraining Objectives

To match the previous unified formulation *i.e.*, (f_i, d_i, s_i) , we devise three different heads to decode each element respectively, each one calling a capability.

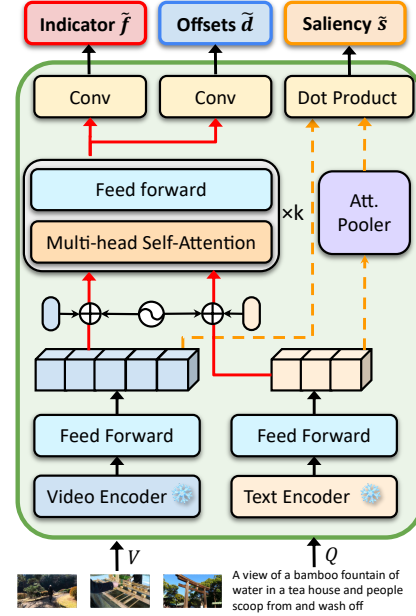


Figure 5: **Unified grounding model** contains a video encoder, a text encoder, and a multi-modal encoder followed by three output heads, corresponding to three key elements $(\tilde{f}_i, \tilde{d}_i, \tilde{s}_i)$. Besides, our model has two pathways: one for cross-modal interaction (solid red line) and the other for cross-modal alignment (broken orange line).

Foreground head for Matching. Taking the output $\tilde{\mathbf{V}}^k \in \mathbb{R}^{L_v \times D}$ from the multi-modal encoder, this head applies three 1×3 Conv layers, each with D filters and followed by a ReLU activation. Finally, sigmoid activations are attached to output the prediction \tilde{f}_i per clip. We use the binary cross-entropy loss as a training objective.

$$\mathcal{L}_f = -\lambda_f \left(f_i \log \tilde{f}_i + (1 - f_i) \log (1 - \tilde{f}_i) \right). \quad (4)$$

Boundary head for Localization. The design of this head is similar to the foreground head except for the last layer, which has 2 outputs channel for the left and right offsets. Taking the $\tilde{\mathbf{V}}^k \in \mathbb{R}^{L_v \times D}$, this head outputs offsets $\{\tilde{d}_i\}_i^{L_v}$ per clip. Then, we devise the predicted boundary \tilde{b}_i and use the combination of smooth $L1$ loss [12] and generalized IoU loss [39] as our training objectives.

$$\mathcal{L}_b = \mathbb{1}_{f_i=1} \left[\lambda_{L1} \mathcal{L}_{\text{SmoothL1}}(\tilde{d}_i, d_i) + \lambda_{\text{IoU}} \mathcal{L}_{\text{IoU}}(\tilde{b}_i, b_i) \right]. \quad (5)$$

Notably, this regression objective is only devised for foreground clips *i.e.*, $f_i = 1$.

Saliency head for Contrasting. Since we define saliency as the relevance between visual context and text query, it is natural to interpret this score as a similar measurement between video and text modalities. Taking the video tokens $\mathbf{V} = \{\mathbf{v}_i\}_{i=1}^{L_v} \in \mathbb{R}^{L_v \times D}$ and sentence representation $\mathbf{S} \in \mathbb{R}^{1 \times D}$, we define the predicted saliency score \tilde{s}_i between

clip v_i and text query Q as their cosine similarities:

$$\tilde{s}_i = \cos(\mathbf{v}_i, \mathbf{S}) := \frac{\mathbf{v}_i^T \mathbf{S}}{\|\mathbf{v}_i\|_2 \|\mathbf{S}\|_2}, \quad (6)$$

where $\|\cdot\|_2$ represents the L_2 -norm of a vector.

For each video \mathbf{V} , we randomly sample a foreground clip \mathbf{v}_p with $f_p = 1$ and $s_p > 0$ as a positive sample; we treat other clips in the same video \mathbf{v}_j with saliency s_j less than s_p as negative samples, *i.e.*, $\Omega = \{j | s_j < s_p, 1 \leq j \leq L_v\}$, and perform **intra-video** contrastive learning:

$$\mathcal{L}_s^{\text{intra}} = -\log \frac{\exp(\tilde{s}_p/\tau)}{\exp(\tilde{s}_p/\tau) + \sum_{j \in \Omega} \exp(\tilde{s}_j/\tau)}, \quad (7)$$

where τ is a temperature parameter and set as 0.07.

Besides, we regard sentences from other samples within batches $k \in B$ as negative samples, and develop the **inter-video** contrastive learning for cross-sample supervision:

$$\mathcal{L}_s^{\text{inter}} = -\log \frac{\exp(\tilde{s}_p/\tau)}{\sum_{k \in B} \exp(\tilde{s}_p^k/\tau)}, \quad (8)$$

where B is the training batch size and $\tilde{s}_p^k = \cos(\mathbf{v}_i, \mathbf{S}_k)$.

Our saliency score head training loss is the combination of inter- and intra-video contrastive learning:

$$\mathcal{L}_s = \lambda_{\text{inter}} \mathcal{L}_s^{\text{inter}} + \lambda_{\text{intra}} \mathcal{L}_s^{\text{intra}}. \quad (9)$$

To this end, our total training objective is the combination of each head loss overall clips in the training set.

$$\mathcal{L} = \frac{1}{N} \sum_{i=1}^N (\mathcal{L}_f + \mathcal{L}_b + \mathcal{L}_s), \quad (10)$$

where N is the clip number of the training set.

4.3. Inference

During inference, given a video V and a language query Q , we first feed forward the model to obtain $\{f_i, \tilde{b}_i, \tilde{s}_i\}_{i=1}^{L_v}$ for each clip v_i from three heads. Next, we describe how we carry out output for individual VTG tasks respectively.

Moment Retrieval. We rank clips predicted boundaries $\{\tilde{b}_i\}_{i=1}^{L_v}$ based on their $\{f_i\}_{i=1}^{L_v}$ probabilities. Since the predicted L_v boundaries are dense, we adopt a 1-d Non-Max Suppression (NMS) with a threshold 0.7 to remove highly overlapping boundary boxes, yielding a final prediction.

Highlight Detection. For each clip, to fully utilize the foreground and saliency terms, we rank all clips based on their $\{\tilde{f}_i + \tilde{s}_i\}_{i=1}^{L_v}$ scores, and then return the few top clip (*e.g.*, Top-1) as predictions.

Video Summarization. Using the same preprocessing settings [42, 51], the videos are first divided as multiple segments via KTS algorithm [33]. Then the clip scores from each segment are computed, and these scores are integrated. We rank all clips based on their foreground $\{\tilde{f}_i\}_{i=1}^{L_v}$ and return the Top-2% clips as a video summary.

Dataset	Task	Pseudo?	Label	# Samples	Domain
Ego4D [13]	PT	✗	Point	1.8M	Egocentric
VideoCC [31]	PT	✓	Interval	0.9M	Web
CLIP teacher	PT	✓	Curve	1.5M	Open
QVHighlights [18]	MR + HL	✗	Interval + Curve	10.3K	VLog, News
NLQ [13]	MR	✗	Interval	15.1K	Egocentric
Charades-STA [10]	MR	✗	Interval	16.1K	Indoor
TACoS [38]	MR	✗	Interval	18.2K	Kitchens
YoutubeHL [46]	HL	✗	Curve	600	Web
TVSum [45]	HL	✗	Curve	50	Web
QFVS [42]	VS	✗	Point	4	Egocentric

Table 1: **Dataset statistics.** The **upper side** datasets are used for pretraining (PT) which cover three label types, two of which are pseudo. The **lower side** datasets are used for downstream tasks (MR: Moment Retrieval, HL: Highlight Detection, VS: Video Summarization).

5. Experiments

In this section, we conduct experiments on various benchmarks to evaluate our approach. Mainly, we design the experiments to study the following questions:

Q1: How much improvement could be made by UniVTG grounding pretraining?

Q2: What are the effects of using different pretraining corpus from various labels?

Q3: Is it necessary to use the proposed unified formulation and unified model?

More ablation studies can be found in Supplementary.

5.1. Datasets and Settings

We have summarized the dataset information in Tab. 1. For pretraining, we gather 1.8M point labels from Ego4D and 0.9M interval labels from VideoCC [31]. For curve labels, we apply CLIP teacher method (Fig. 4) to Ego4D and VideoCC datasets to get 1.5M pseudo labels. Therefore, a total of 4.2M temporal annotations are used for grounding pretraining. For downstream tasks, we assess our methods on four VTG tasks across seven datasets, spanning (i) Jointly moment retrieval and highlight detection; (ii) Moment Retrieval; (iii) Highlight Detection; (iv) Video Summarization. Additional details are listed in Supp.

Evaluation Metrics. For QVHighlights, we follow official [20], Recall@1 with IoU thresholds 0.5 and 0.7, mean average precision (mAP) with IoU thresholds 0.5 and 0.75, and the average mAP over a series of IoU thresholds [0.5:0.05:0.95] are used for moment retrieval. For highlight detection, mAP and HIT@1 are used, a clip is treated as a true positive if it has the saliency score of Very Good. For Charades-STA, NLQ, TACoS, Recall@1 with IoU thresholds 0.3, 0.5 and 0.7, and mIoU are used. For YouTube Highlights and TVSum, we follow [26] and use mAP and Top-5 mAP, respectively. For QFVS, we follow [49] that reports F1-score per video as well as an average.

Implementation Details. We set $k = 4$ multi-modal transformer encoder layers, with $d = 1024$ hidden size and 8 attention heads. The drop path rates are 0.1 for trans-

Method	Moment Retrieval					HD	
	R1		mAP			\geq Very Good	
	@0.5	@0.7	@0.5	@0.75	Avg.	mAP	HIT@1
BeautyThumb [44]	–	–	–	–	–	14.36	20.88
DVSE [25]	–	–	–	–	–	18.75	21.79
MCN [2]	11.41	2.72	24.94	8.22	10.67	–	–
CAL [8]	25.49	11.54	23.40	7.65	9.89	–	–
CLIP [36]	16.88	5.19	18.11	7.0	7.67	31.30	61.04
XML [20]	41.83	30.35	44.63	31.73	32.14	34.49	55.25
XML+ [18]	46.69	33.46	47.89	34.67	34.90	35.38	55.06
MDETR [18]	52.89	33.02	54.82	29.40	30.73	35.69	55.60
MDETR w/ PT	59.78	40.33	60.51	35.36	36.14	37.43	60.17
UMT†[26]	56.23	41.18	53.83	37.01	36.12	38.18	59.99
UMT† w/ PT	60.83	43.26	57.33	39.12	38.08	39.12	62.39
UniVTG	58.86	40.86	57.60	35.59	35.47	38.20	60.96
UniVTG w/ PT	65.43	50.06	64.06	45.02	43.63	40.54	66.28
UniVTG ZS	25.16	8.95	27.42	7.64	10.87	35.96	53.50

Table 2: **Jointly Moment Retrieval and Highlight Detection results on QVHighlights test split¹**. †: introduce audio modality. w/ PT: fine-tuning after pre-training; ZS: zero-shot inference.

former layers and 0.5 for input FFN projectors. During the pretraining stage, our experiments are carried out on 8 A100 GPUs. When it comes to downstream tasks, we use one GPU. For moment retrieval, all baselines and UniVTG use the same video and text features. For highlight detection and video summarization, we report results following [26] and [49]. See Supp. for more details.

5.2. Comparison with State-of-the-arts (Q1)

5.2.1 Joint Moment Retrieval and Highlight Detection

As illustrated in Tab. 2, we first evaluate our UniVTG on QVHighlights test split: (i) Without pretraining, UniVTG has shown comparable performance to two joint optimization counterparts Moment-DETR [18] and UMT [26], demonstrating its superior model design for joint task optimization. (ii) With large-scale pretraining, UniVTG exhibits a significant improvement on all metrics, such as +8.16 Avg. mAP and +5.32 HIT@1. As a result, UniVTG surpasses all baselines by a large margin. Notably, UMT introduces audio modality and ASR pretraining [26],

¹Codalab QVHighlights Evaluation

Method	NLQ [13]				Charades-STA [10]				TACoS [38]			
	R@0.3	R@0.5	R@0.7	mIoU	R@0.3	R@0.5	R@0.7	mIoU	R@0.3	R@0.5	R@0.7	mIoU
2D TAN [66]	4.33	1.83	0.60	3.39	58.76	46.02	27.50	41.25	40.01	27.99	12.92	27.22
VSLNet [63]	4.54	2.40	1.01	3.54	60.30	42.69	24.14	41.58	35.54	23.54	13.15	24.99
MDETR [18]	4.34	1.81	0.65	3.53	65.83	52.07	30.59	45.54	37.97	24.67	11.97	25.49
UniVTG	7.28	3.95	1.32	4.91	70.81	58.01	35.65	50.10	51.44	34.97	17.35	33.60
UniVTG w/ PT	11.74	7.54	3.25	7.88	72.63	60.19	38.55	52.17	56.11	43.44	24.27	38.63
UniVTG ZS	6.48	3.48	1.16	4.63	44.09	25.22	10.03	27.12	5.17	1.27	0.27	4.40

Table 3: **Moment Retrieval results on NLQ, Charades-STA, and TACoS benchmarks.** All baselines use the same video features (CLIP ViT-B/32 and SlowFast R-50) and text features (CLIP text enc.). w/ PT means fine-tuning after pre-training; ZS means zero-shot inference.

but it is still worse than us by Avg. mAP of 5.55 and HIT@1 of 3.89. (iii) Due to the large-scale pretraining, UniVTG can perform zero-shot grounding and outperforms several supervised baselines without any training samples.

5.2.2 Moment Retrieval

In Tab. 3, we compare the results of our method and the mainstream moment retrieval methods on three widely used benchmarks. (i) Similar to the observation made by QVHighlights, without pretraining, we find that UniVTG is still superior to other compared methods. This demonstrates once more the effectiveness of our concise architecture. (ii) Large-scale grounding pretraining has resulted in significant improvements, leading to a considerable increase in the mIoU *i.e.*, +2.97 in NLQ, +2.07 in Charades-STA, and +5.03 in TACoS. (iii) Notably, in NLQ, our zero-shot result has outperformed all the baselines methods due to the close pretraining domain. However, it is worth mentioning that the zero-shot performance on TACoS is inferior. This could be because the videos have scenes that are very similar to each other, with only small spatial variations, making it difficult to effectively apply zero-shot methods.

5.2.3 Highlight Detection

In Tab. 4 and Tab. 5, we conduct highlight detection experiments on YouTube Highlights and TVSum respectively, where the baselines with † (rows 6-9) are incorporate with audio features. We observe that (i) grounding pretraining brings improvement on UniVTG and surpasses all baselines in Avg. mAP. (ii) In TVSum, gain discrepancy among domains may stem from its small scale (50 samples) and scoring subjectivity. In contrast, the larger YouTube dataset (600 videos) yields more consistent pretraining gains. (iii) Moreover, in zero-shot setting, UniVTG beats several video-only baselines such as [46, 48].

5.2.4 Video Summarization

In Tab. 6, we present the QFVS benchmark results. Our pre-trained UniVTG achieves a 0.8% higher Avg. F1-score than IntentVizor [49], where the latter is an interactive method and being tailored for the video summarization task. This result demonstrates the generalization of our method on video summarization task.

Method	Dog	Gym	Par.	Ska.	Ski.	Sur.	Avg.
RRAE [58]	49.0	35.0	50.0	25.0	22.0	49.0	38.3
GIFs [15]	30.8	33.5	54.0	55.4	32.8	54.1	46.4
LSVM [46]	60.0	41.0	61.0	62.0	36.0	61.0	53.6
LIM-S [52]	57.9	41.7	67.0	57.8	48.6	65.1	56.4
SL-Module [56]	70.8	53.2	77.2	72.5	66.1	76.2	69.3
MINI-Net† [16]	58.2	61.7	70.2	72.2	58.7	65.1	64.4
TCG† [59]	55.4	62.7	70.9	69.1	60.1	59.8	63.0
Joint-VA† [3]	64.5	71.9	80.8	62.0	73.2	78.3	71.8
UMT† [26]	65.9	75.2	81.6	71.8	72.3	82.7	74.9
UniVTG	71.8	76.5	73.9	73.3	73.2	82.2	75.2
UniVTG w/ PT	74.3	79.0	74.4	84.9	75.1	83.9	78.6
UniVTG ZS	36.8	62.8	65.9	39.2	64.5	54.0	53.9

Table 4: **Highlight Detection results of mAP on YouTube HL.** † denotes using audio modality.

Method	V1	V2	V3	V4	Avg.
QC-DPP [42]	48.68	41.66	36.51	29.96	44.19
CHAN [51]	49.14	46.53	58.65	33.42	46.94
QSAN [50]	48.52	46.64	56.93	34.25	46.59
WHM [32]	50.96	48.28	58.41	39.18	49.20
IntentVizor [49]	51.27	53.48	61.58	37.25	50.90
UniVTG	52.54	54.48	56.73	40.37	51.03
UniVTG w/ PT	49.85	56.97	59.35	40.62	51.70

Table 6: **Video Summarization results of F-score on QFVS.**

5.3. Ablation Studies

Effect of different labels for pretraining (Q2). In Tab. 7 top half, we investigate the effect of different labels corpus for pretraining. The results here are before unified formulation *i.e.*, the original label provided by the pretraining set. Our findings (rows 1-4) indicate that (i) incorporating any type of label for pretraining yields considerable performance gains on most benchmarks. (ii) Combining all three types of data (row 5) for pretraining further boost the outcomes, such as +5.2 MR’s mAP and +1.1 HL’s mAP over baseline (row 1) on QVHighlights.

Effect of unified formulation (Q3). In Tab. 7 bottom half, we further study the impacts of unified formulation *i.e.*,

row	Pretraining Corpus			Unified Labels?			QVHighlights		TACoS	YouTube
	Ego4D	VideoCC	CLIP	Point	Interval	Curve	MR	HL	MR	HL
	Point	Interval	Curve				mAP	mAP	mIoU	mAP
1							36.13	38.83	33.60	75.15
2	✓			✓			39.89	39.48	35.33	75.32
3		✓			✓		39.81	39.75	35.11	74.76
4			✓			✓	39.16	39.80	35.68	75.44
5	✓	✓	✓	✓	✓	✓	41.37	39.97	35.87	75.66
6	✓			✓	✓	✓	41.53	39.66	36.52	75.27
7		✓		✓	✓	✓	40.96	40.10	36.78	76.10
8			✓	✓	✓	✓	42.19	40.43	35.85	77.48
9	✓	✓	✓	✓	✓	✓	45.99	41.25	38.63	78.56

Table 7: **Ablation studies on pretraining corpus.** ✓ denotes the elements derived by us, which are not provided in vanilla training corpus: Ego4D, VideoCC, and CLIP teacher.

Method	VT	VU	GA	MS	PK	PR	FM	BK	BT	DS	Avg.
sLSTM [65]	41.1	46.2	46.3	47.7	44.8	46.1	45.2	40.6	47.1	45.5	45.1
SG [27]	42.3	47.2	47.5	48.9	45.6	47.3	46.4	41.7	48.3	46.6	46.2
LIM-S [52]	55.9	42.9	61.2	54.0	60.4	47.5	43.2	66.3	69.1	62.6	56.3
Trailer [48]	61.3	54.6	65.7	60.8	59.1	70.1	58.2	64.7	65.6	68.1	62.8
SL-Module [56]	86.5	68.7	74.9	86.2	79.0	63.2	58.9	72.6	78.9	64.0	73.3
MINI-Net† [16]	80.6	68.3	78.2	81.8	78.1	65.8	57.8	75.0	80.2	65.5	73.2
TCG† [59]	85.0	71.4	81.9	78.6	80.2	75.5	71.6	77.3	78.6	68.1	76.8
Joint-VA† [3]	83.7	57.3	78.5	86.1	80.1	69.2	70.0	73.0	97.4	67.5	76.3
UMT† [26]	87.5	81.5	88.2	78.8	81.5	87.0	76.0	86.9	84.4	79.6	83.1
UniVTG	83.9	85.1	89.0	80.1	84.6	81.4	70.9	91.7	73.5	69.3	81.0
UniVTG w/ PT	92.0	77.8	89.8	83.8	82.2	85.8	74.3	91.8	90.5	77.6	84.6
UniVTG ZS	78.5	67.0	75.3	63.6	67.0	66.8	35.4	85.3	83.1	50.0	67.2

Table 5: **Highlight Detection results of Top-5 mAP on TVSum.** † denotes using audio modality.

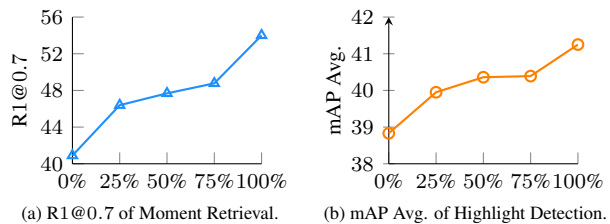


Figure 6: **Effect of pretraining scale on QVHighlights dataset.**

the benefits of deriving unknown elements for pretraining. From rows 2-4 vs rows 6-8, We find that (i) training corpora receive performance gains in most settings, which proves that the label converting methods are crucial for better utilizing temporal labels. (ii) Among all settings, curve labels appear to be the most effective ones, and beat the manual point labels except in a few domains *e.g.*, TACoS. (iii) We get the optimal result (row 9) by using full three converted corpus for pretraining, with 4.62 MR’s mAP and 1.28 HL’s mAP increase over counterparts (row 5) on QVHighlights.

Effect of pretraining scale. In Fig. 6, we explore the effect of utilizing various scales of labels for pretraining. We observe a steady performance improvement on both moment retrieval and highlight detection tasks as the training sample size increases. It also shows that unifying labels to construct a large training corpus can greatly benefit the VTG.

6. Conclusion

This paper introduces UniVTG, a framework that unifies diverse VTG tasks and labels by addressing three key challenges: (i) We define a unified formulation for VTG to convert various labels and tasks under a single framework, and propose a label scaling scheme. (ii) We develop an effective yet flexible model that can handle various VTG tasks and training labels. (iii) Due to the unified framework and availability of scalable labels, it becomes feasible to perform large-scale temporal grounding pretraining over diverse labels. We demonstrate the effectiveness and flexibility of our UniVTG on four settings across seven datasets, spanning joint optimization as well as individual tasks.

7. Acknowledgements

This project is supported by the National Research Foundation, Singapore under its NRFF Award NRF-NRFF13-2021-0008, the DSO National Laboratories, Mike Zheng Shou’s Start-Up Grant from NUS. The computational work for this article was partially performed on resources of the National Super computing Centre, Singapore.

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