

Scale-Equivalent Distillation for Semi-Supervised Object Detection

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A. Appendix

A.1. Implementation of SED on DETR.

Our method can be extended to DETR, a single feature map detector based on anchor-free label assignment rule. We match the predictions of input in different views according to Hungarian algorithm, where the pair-wise matching cost is defined as: $L_{\text{match}} = D_{\text{JS}}(p_1, p_2) + \lambda L_{\text{IoU}}(b_1, b_2)$, where $D_{\text{JS}}(p_1, p_2)$ is JS-Divergence between the probability vectors and L_{IoU} is GIoU loss [10]. The python-style pseudo-code of matching algorithm is provided in Alg. 1. The DETR model is trained with AdamW setting the transformer’s learning rate to 10^{-4} , the backbone’s learning rate to 10^{-5} , and weight decay to 10^{-4} . The model is trained with a long schedule for 300 epochs and the learning rate is multiplied by 0.1 at 200 epochs. The other settings are the same as DETR [1].

A.2. Stronger augmentations.

Geometric augmentations are common image data augmentations. Therefore, we further conduct experiments with stronger augmentations: color + geometric augmentations, to demonstrate the extendability of SED. We simply adopt the same geometric transformations in RandAug [3], including *RandRotate*, *RandTranslation* and *RandShear*. We set the rand level to 5 and select only 1 transformation to apply. The results in Tab. 1 show that additional geometric augmentations lead to incremental improvement.

A.3. Implementation and Training Details.

Our implementation is based on MMDetection framework [2]. The default detector is set as Faster-RCNN [9] with FPN [7] and ResNet-50 [5] for a fair comparison with prior works [8, 11–14]. **Code will be released.**

Training Details. The weights of the backbone are first initialized by the corresponding ImageNet-Pretrained model, which is a default setting in existing works [6, 8, 11, 14]. All the models are trained with learning rate starting at 0.01. The learning rate drops by 0.1 at the 120k and 160k iteration for 180k training schedule as default. We set the weight decay to 0.0001, batch size to 16, and the mo-

Algorithm 1 Matching Pseudocode, PyTorch-like

```
1 def hungarian_match(cls_score_1, cls_score_2,
2     bbox_pred_1, bbox_pred_2, cls_weight,
3     iou_weight):
4     # cls_score: [bs, num_query, c]
5     # bbox_pred: [bs, num_query, 4]
6     cls_dist = JSCost(cls_score_1, cls_score_2)
7     iou_dist = IoUCost(bbox_pred_1, bbox_pred_2)
8     cost = cls_dist * cls_weight + iou_dist *
9     iou_weight
10
11    bs = cost.shape[0]
12    col_inds = []
13    for i in range(bs):
14        col_ind = linear_sum_assignment(cost[i])
15        col_inds.append(col_ind)
16
17    return col_inds
```

Method	Data	AP	Augmentation
Supervised	VOC07	74.3	-
STAC [11]	VOC07+12	77.45	C, G
DGML [12]	VOC07+12	78.60	-
UBT [8]	VOC07+12	77.37	C
ISMT [13]	VOC07+12	77.23	C, DropBlock
IT [14]	VOC07+12	78.30	C, Mixup, Mosaic
Ours	VOC07+12	80.60	C
Ours	VOC07+12	81.44	C, G

Table 1. Results on Pascal VOC 2007 test set. AP_{50} is reported. “-” means that the training details are missing in the source paper.

mentum is 0.9 for SGD optimizer. Like [8], we separate 5k/10k/12k/90k iterations from the whole process as the burn-in phase for 5%/10%/35k/100% data protocols. For verifying the effectiveness of our method, we simply set the λ_s and λ_d in Eq. 1 as 0.5 and 1 separately. The EMA update rate starts with 0.99 and steps to 0.9 at the 120k iteration, aligned with the learning rate decay policy.

Data Augmentation. As shown in Tab. 2, the weak data augmentation only contains random resize from (1333, 640) to (1333, 800) and random horizontal flip with a probability of 0.5. The strong data augmentation is composed of random Color Jittering, Grayscale, Gaussian Blur, and Cutout [4], without any geometric augmentation.

Process	Probability	Strong Augmentation		Details
		Parameters		
Color Jittering	0.8	brightness, contrast, saturation = 0.4, 0.4, 0.4		Brightness factor is chosen uniformly from [0.6, 1.4], Contrast factor is chosen uniformly from [0.6, 1.4], Saturation factor is chosen uniformly from [0.6, 1.4]
Grayscale	0.2	None		None
GaussianBlur	0.5	$\sigma \sim U(0.1, 2.0)$		Gaussian filter kernel size is 23
Cutout 1	0.7	scale=(0.05, 0.2), ratio=(0.3, 3.3)		Randomly selects a rectangle region in an image
Cutout 2	0.5	scale=(0.02, 0.2), ratio=(0.1, 6)		Randomly selects a rectangle region in an image
Cutout 3	0.3	scale=(0.02, 0.2), ratio=(0.05, 8)		Randomly selects a rectangle region in an image

Table 2. Details of data augmentations.

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