

NÜWA-LIP: Language-guided Image Inpainting with Defect-free VQGAN

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This supplemental material mainly contains:

- Discussion with Partial Convolution in Section I
- Details of DF-VQGAN and MP-S2S in Section II
- Details of proposed datasets in Section III
- User Study in Section IV
- More comparisons with other models in Section V
- More comparisons of DF-VQGAN in Section VI
- More comparisons with VQGAN in Section VII
- More inpainting results in Section VIII
- Analyses of failure case in Section IX
- Broader impact and limitations in Section X

I. Difference with Partial Convolution

We note that Liu *et al.* [6] propose a partial convolutional layer (PConv) where the convolution operation is masked and renormalized to be conditioned on only non-defective pixels for image inpainting task. It is defined as:

$$PConv(x) = \begin{cases} \mathbf{W}^T(\mathbf{x} \odot \mathbf{m}) \frac{\text{sum}(\mathbf{1})}{\text{sum}(\mathbf{m})} + b, & \text{if } \text{sum}(\mathbf{m}) > 0 \\ 0, & \text{otherwise} \end{cases}, \quad (1)$$

where x is the defective image and m is the mask matrix.

In contrast, we simplify the formulation of our defect-free operation in DF-VQGAN by removing the symmetrical connection, and the defect-free operations on convolution, normalization, and attention layers are defined as:

$$\begin{aligned} \text{Conv}'(y) &= \text{Conv}^{\text{DF}}(x) \odot (1 - m) + \text{Conv}(y) \odot m, \\ \text{Norm}'(y) &= \text{Norm}^{\text{DF}}(x) \odot (1 - m) + \text{Norm}(y) \odot m, \\ \text{Attn}'(y) &= \text{Attn}^{\text{DF}}(x) \odot (1 - m) + \text{Attn}(y) \odot m, \end{aligned} \quad (2)$$

where y represents the ground-truth image and $x = y \odot m$. Conv^{DF} , Norm^{DF} , and Attn^{DF} are the defect-free operations, which are defined as:



Figure A. **Comparison with PConv and DF-VQGAN.** We incorporate the PConv operation into VQGAN and compare the result of oracle inpainting with our DF-VQGAN. We can observe that result of PConv easily generate distorted structures in defective regions.

$$\begin{aligned} \text{Conv}^{\text{DF}}(x) &= \mathbf{W}_c^T(x \odot m) + b, \\ \text{Conv}(y) &= \mathbf{W}_c^T(y) + b, \\ \text{Norm}^{\text{DF}}(x) &= \frac{x - \frac{N}{N_m} \mathbf{E}[x]}{\sqrt{\frac{N-1}{N_m-1} \text{Var}[x']} + \epsilon}, \\ \text{Norm}(y) &= \frac{y - \mathbf{E}[y]}{\sqrt{\text{Var}[y]} + \epsilon}, \\ \text{Attn}^{\text{DF}}(x) &= \text{Softmax}(x^T \mathbf{W}_a x) \odot m \odot x, \\ \text{Attn}(y) &= \text{Softmax}(y^T \mathbf{W}_a y) \odot y, \end{aligned} \quad (3)$$

where N and N_m are the numbers of all pixels and defective pixels in x , respectively. x' is the revised x with the defective region fulfilling with $\frac{N}{N_m} \mathbf{E}[x]$. $\mathbf{E}[\cdot]$ and $\text{Var}[\cdot]$ denote expectation and variance, respectively. \mathbf{W}_c (\mathbf{W}_a) is shared parameters between Conv^{DF} and Conv (Attn^{DF} and Attn).

Comparing Eqn. (1) with Eqns. (2-3), our DF-VQGAN has two differences with PConv: (1) DF-VQGAN is a VAE model, which is trained by reconstructing a full image \hat{y} from a full image y . For adopting VAE in the inpainting task, we need to introduce mask m carefully without destroying the schema of VAE. However, PConv is not a VAE model, and it takes the defective image x as input to predict a inpainted result \hat{y} . (2) Instead of performing on the convolution layer only, our DF-VQGAN focuses on three operations, which may easily lead to receptive spreading. This allows our DF-VQGAN effectively learn the valid features from defective input and reconstruct results with high fidelity. To validate the effectiveness of DF-VQGAN, we add the PConv

operation to VQGAN and train it with the same setting as DF-VQGAN. We also provide quantitative and qualitative comparison with PConv in Fig. A and Tab. C. We can see that PConv tends to generate modified hue and distorted structures while our DF-VQGAN can generate results with better quality, indicating the effectiveness of our defect-free operation.

II. Details of DF-VQGAN and MP-S2S

DF-VQGAN. It adopts the settings of the vanilla VQGAN [4]. The vocab size is set to 8,192, and the learning rate is 5×10^{-6} . The batch size and the dim of the latent token is set to 200 and 256, respectively. The input resolution is 256×256 and DF-VQGAN encodes the input to 32×32 tokens. We pretrain the DF-VQGAN with ImageNet [3].

MP-S2S. The layer number in encoder E^l , E^h and E^t is set to 12, respectively. The layer number in the autoregressive decoder is 24. All Transformers have 20 heads and the hidden size is 1024. We set the learning rate to 5×10^{-4} , and the batch size to 320. The text encoder E^t and tokenizer is initialized with the text encoder and tokenizer from pre-trained CLIP [8]. The E^l and E^h are trained from scratch. We use Conceptual Captions [10] as the pre-training corpus.

III. Details of Proposed Datasets

We follow [5] and select the test sets of MSCOCO and Flickr to build our MaskCOCO and MaskFlickr. As for MaskVG, we randomly select 10,000 samples from the VG dataset. For each image-text pair, the original image and corresponding caption are considered ground-truth images and text descriptions. Each image will be cropped and resized to the resolution of 256×256 . The defective image is generated by masking with either one bounding box of the object or a random irregular region. The details of the proposed three datasets are listed in Tab. A. We will release them under a Creative Commons Attribution 4.0 License.

Table A. Details of the evaluation datasets.

DATASET	IMAGE-TEXT PAIRS	MASK RATIO
MASKCOCO	5000	31.5%
MASKFLICKR	1000	48.3%
MASKVG	10000	14.6%

IV. User Study

To further evaluate the quality of our NÜWA-LIP and baselines, we conduct a user study from real human perception. We randomly select 500 samples from the MaskCOCO dataset and compare with NÜWA-LIP, NÜWA, and GLIDE

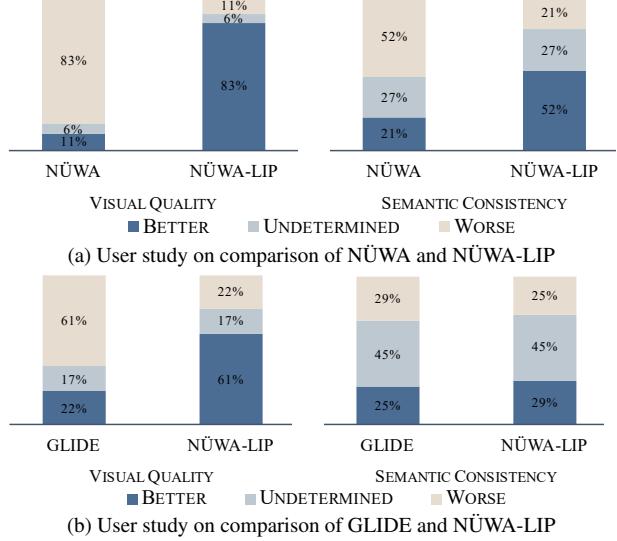


Figure B. User study of NÜWA-LIP and baselines.

on two aspects, *i.e.*, visual quality and semantic consistency. The visual quality focuses on evaluating the structures whether they are photo-realistic or contain distorted details. The semantic consistency assesses whether the inpainted results have semantically consistent content with the language guidance. Volunteers with a computer vision background are required to give a choice about which one has better quality. From Fig. B, we can observe that compared with these competing methods (*i.e.*, NÜWA and GLIDE), our NÜWA-LIP has obvious better performance in both visual quality and semantic consistency, which indicates that our NÜWA-LIP can generate more photo-realistic and consistent results.

V. Comparisons with Other Models

To explore the effectiveness of NÜWA-LIP, we conduct additional experiments with other inpainting models. Specifically, we compare NÜWA-LIP with TDANET [13], a popular non-pre-trained language-guided inpainting model, and MASKGIT [2] and LAMA [11], which are class-conditional and unconditional inpainting models pre-trained on large-scale data, respectively. For MASKGIT, we use CLIP to classify the class of the ground-truth image as the input. As shown in Tab. B, NÜWA-LIP outperforms all these models, showing its effectiveness and the essentials of the language.

Discussion with Stable Diffusion STABLE DIFFUSION is an effective model for visual synthesis tasks. Fig. C shows the difference between STABLE DIFFUSION and most prior image inpainting works [2, 11, 13]. In general image inpainting settings, the input image for the inpainting model is defective or damaged. However, the input image of STABLE DIFFUSION should be normal images without defective

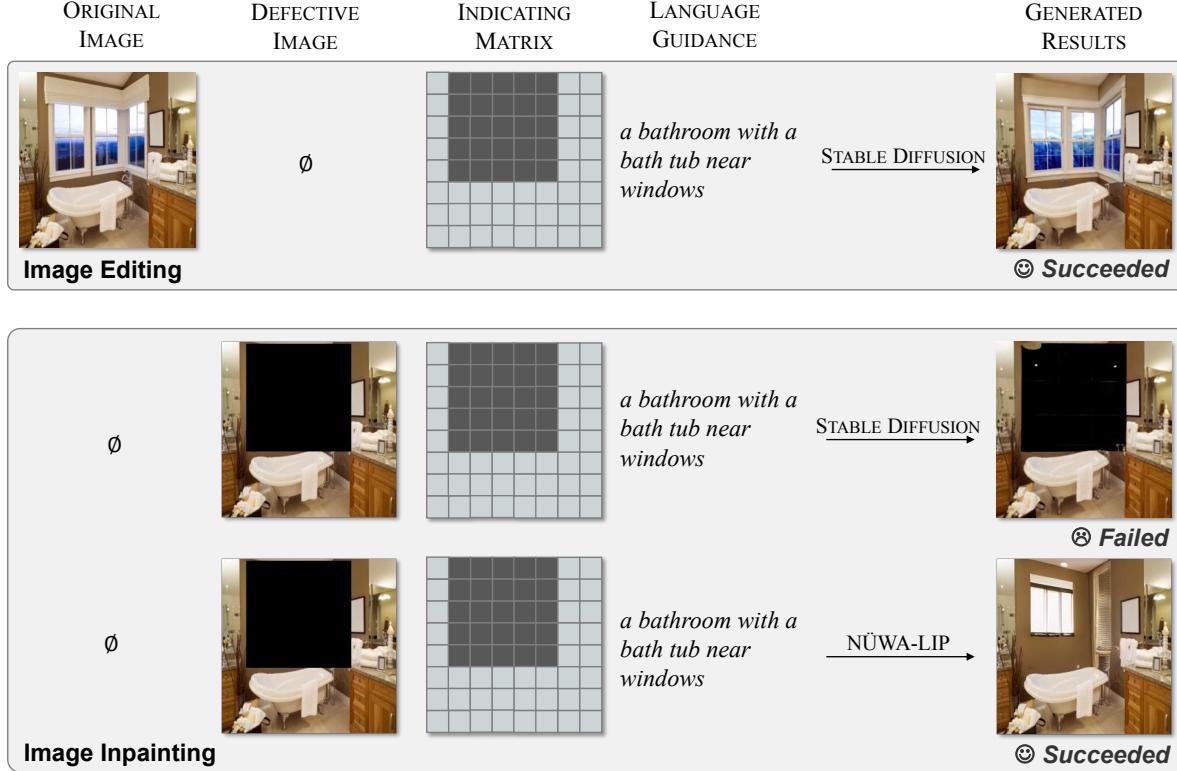


Figure C. **Comparison of STABLE DIFFUSION and NÜWA-LIP pipelines.** Different from most prior works, the input image of STABLE DIFFUSION needs to be well-formed, which is called image editing in most related works.

Table B. **Comparsion with different models on MaskCOCO.**
† denotes trained or finetuned on COCO.

MODEL	FID [†]	CLIP SCORE [†]
STABLE DIFFUSION [9] (IMAGE EDITING)	10.9	30.38
TDANET [†] [13]	27.2	27.90
LAMA [11]	17.3	24.38
MASKGIT [2]	15.5	27.20
NÜWA-LIP (W/O PRETRAIN) [†]	11.0	28.74
NÜWA-LIP	12.0	29.34
NÜWA-LIP (FINETUNE) [†]	10.5	29.65

or damaged regions, which is called image editing in most related works [2, 7, 12]. From Fig. C, we can find that STABLE DIFFUSION is hard to directly handle these types of defective images. For a fair comparison, the input image of STABLE DIFFUSION is set to the ground-truth without corrupted regions, while ours and other baselines take the occluded image as input for the general inpainting task. Here we use their official implementation from DIFFUSERS¹ and

checkpoints² on this type of defective input. Besides, STABLE DIFFUSION is trained on the LAION-5B dataset, which is $1000 \times$ larger than ours. From Tab. B we can observe that our method still obtains comparable performance.

VI. More Comparisons of DF-VQGAN

Table C. **More quantitative comparisons of DF-VQGAN on ImageNet.** DF-VQGAN outperforms VQGAN or VQGAN-P on both image reconstruction (IMG.REC) and oracle inpainting (ORC.INP).

MODEL	RESOLUTION	TOKEN LENGTH	VOCAB SIZE	IMG.REC	ORC.INP
VQGAN	$256^2 \rightarrow 16^2$	256	12288	6.03	7.15
VQGAN-P	$256^2 \rightarrow 16^2$	256	12288	6.03	3.77
PARTIAL CONV.	$256^2 \rightarrow 16^2$	256	12288	6.83	7.14
TS-VQGAN	$256^2 \rightarrow 16^2$	256	12288	5.89	6.47
DF-VQGAN/s	$256^2 \rightarrow 16^2$	256	12288	5.14	5.44
DF-VQGAN	$256^2 \rightarrow 16^2$	256	12288	5.16	2.95

To validate whether *relative estimation* can avoid receptive spreading of defective regions, we compare VQGAN with DF-VQGAN/s, which is DF-VQGAN without *symmetrical connection*. In the upper part of Tab. C, we can find that we significantly reduce the FID score from 7.15

¹<https://github.com/huggingface/diffusers>

²We use the best SD-V1-4 checkpoint.

to 5.44 in the oracle inpainting task. Besides, the gain in image reconstruction can be ascribed to the usage of *relative estimation* in improving the robustness of the model.

We further validate whether *symmetrical connection* can protect the information of non-defective regions. We compare DF-VQGAN with VQGAN-P, which directly copies and pastes the non-defective region of the image into the generated results. In the bottom part of Tab. C, we can find that we achieve a better FID score (*i.e.*, 2.95 v.s. 3.77) in oracle inpainting task, which indicates that our symmetrical connection can make a significantly better transition between the non-defective region and inpainted part. Meanwhile, we obtain a comparable FID score of 5.16 in the image reconstruction task. The comparison with DF-VQGAN/s shows the benefits of combining *relative estimation* and *symmetrical connection* in image inpainting task.

Finally, we conduct the comparison with TS-VQGAN [1], which is used in conditional image synthesis to encode an image without defective regions. The goal of TS-VQGAN is to avoid information leaking, which means results are more similar to reference images rather than the target condition. Different from TS-VQGAN, DF-VQGAN works in the image inpainting scenario, in which defective regions and non-defective regions exist at the same time in an image. From Tab. C, we can observe that our approach still outperforms TS-VQGAN with a large margin in oracle inpainting.

VII. More Comparisons with VQGAN

We provide more visual results in Fig. D to compare our DF-VQGAN with vanilla VQGAN and analyze their performance on both defective and non-defective regions. We can find that our DF-VQGAN can well capture the semantic details and generate consistent structures in defective regions. More importantly, our DF-VQGAN can well keep the non-defective content unchanged.

VIII. More Inpainting Results

We provide more inpainting results to show the effectiveness of NÜWA-LIP in Fig F. We can observe that NÜWA-LIP can leverage the text guidance well and generate results with higher fidelity and better consistency.

IX. Failure Case

Although NÜWA-LIP shows effectiveness in most cases, we find that it may fail in some cases like Fig. E, which shows fine-tuning will cause failure in inpainting some rare objects. In most cases, fine-tuning brings impressive improvement in the quality of the inpainted images but may fail in some objects which occurs very little in the fine-tuning dataset. We will balance the distribution of each object and augment these with fewer samples.

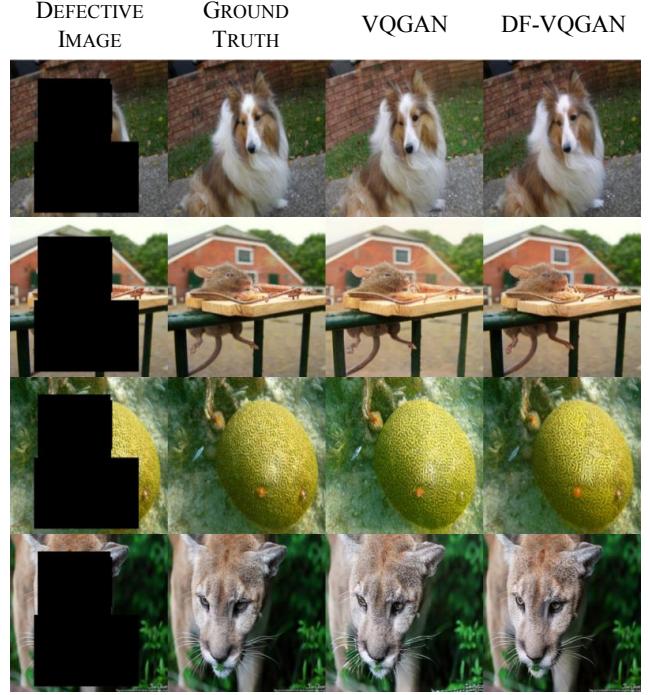


Figure D. **More illustration on oracle inpainting.** DF-VQGAN shows better ability in generating consistent details in defective regions and keeping non-defective regions unchanged.



Figure E. **Failure case of NÜWA-LIP.** The failure case may be caused by the rare objects in the fine-tuning dataset.

X. Broader Impact and Limitations

NÜWA-LIP, which is an effective model for language-guided image inpainting, can provide the potential for users to edit and manipulate an image, which may lead to destructive behaviors, *e.g.*, fake images may be abused in some cases like news reporting. We will explore a more trustworthy model to prevent such abuse cases. Besides, as a common issue of autoregressive models, handling an extremely large image would have a much higher computational cost, and may be easy for users to retrain this model.



A kitchen with a bright window and house plants.



A herd of cattle sitting in front of a church with a steeple.



A person with an orange blanket covering them, sleeping on a wooden park bench.



A yellow and blue train is next to an overhang.



A light house on the grass land. A light house near the sea. A light house in the sea.



A woman sitting on the grass. A kid looking for something. A little bonfire.



A stack of books. A white bird. A toy car. A stone block.



A man sleeping with his cat next to him.



Man on a contraption, surrounded by a bicycle.



A cat eating a bird it has caught.



A fork rests on a plate next to a piece of cake.



A man in the black suit. A man in the black sports wear. A man in the blue suit.



A motorcycle is parked with the airplane above. A motorcycle is parked under the sunshine. A motorcycle is parked beside snow mountains.



A motorcycle is parked under the sunny day. A motorcycle is parked near forest. A motorcycle is parked at night. A motorcycle is parked in the city center.

Figure F. More inpainting results. NÜWA-LIP can effectively complete the defective image under the guidance of different texts.

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