

# HyperShot: Few-Shot Learning by Kernel HyperNetworks – supplementary material

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## A. Additional results

This section provides additional results in the 5-way (1-shot and 5-shot) classification tasks for models using larger backbones, namely ResNet-10 and ResNet-12 [11], as well as an expanded version of Table 1 from the main text, containing more baselines. We provide the results for ResNet-10 on the **CUB** and **mini-ImageNet** datasets in Table 1, for ResNet-12 on **mini-ImageNet** dataset in Table 2 and for Conv4 on the **CUB** and **mini-ImageNet** datasets in Table 3. It should be noted that the results for ResNet-10 on **mini-ImageNet** for all methods were obtained by us using a unified codebase [3, 27]. On the other hand, for benchmarks of ResNet-10 on **CUB** and ResNet-12 on **mini-ImageNet** we report the accuracies of methods other than HyperShot as reported in [27] and [45], respectively.

**ResNet-10 – CUB and mini-ImageNet** In the **CUB** dataset classification tasks (see Table 1), HyperShot is amongst the state-of-the-art models achieving classification accuracy often equal within the variance to the best models. Considering the 5-shot scenario, the highest classification result across the evaluated methods ( $86.38\% \pm 0.15$ ) obtained the GPLDLA model based on the Gaussian Processes framework. However, the HyperShot performance,  $86.28\% \pm 0.29$ , is the second-best but even lies within the variance of the best model. In the 1-shot setting, ProtoNet obtains the highest result ( $73.22\% \pm 0.92$ ), whereas Hyper-

Shot is the third one ( $71.99\% \pm 0.70$ ) but still equal according to the variances.

In the **mini-ImageNet** classification task with the ResNet-10 backbone, HyperShot achieves the second-best accuracy in both 1-shot and 5-shot settings\*. In the 1-shot setting, the DKT model [27] achieved the best result, with HyperShot being a close second, with only 0.04 pp difference. In the 5-shot setting, the baseline++ approach outperforms all others by a large margin [3], whereas HyperShot and ProtoNet [35] achieve similar, second-best results. We observe that apart from HyperShot, which achieves second-best results in both settings, models which perform well in one setting are outperformed by others in the second and vice versa.

**ResNet-12 – mini-ImageNet** In the **mini-ImageNet** classification task with the ResNet-12 backbone (see Table 2), HyperShot ranks relatively low in terms of accuracy (63.30% and 76.21% in the 1-shot and 5-shot settings, respectively), as compared to recently proposed approaches such as RENet [14] and FEAT [45], which outperform it by a large margin. Nevertheless, we note that for the experiments on ResNet-12 we used the same set of hyperparameters as in the ResNet-10 experiments, which may not be an optimal choice for a larger backbone.

\*In the case of the **mini-ImageNet** classification with ResNet10, we benchmarked all of the listed models ourselves. To our best knowledge, previously, there were no reported benchmarks on this dataset with the ResNet-10 backbone.

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It is worth noticing that HyperShot without adaptation steps performances sometimes slightly better than the same with adaptation. We even observe that a few first steps of adaptation procedure result in an unnoticeable increase of accuracy of the basic model. However, the usual 10 steps result in this setting in slightly worse performance, so one should use it cautiously. We decided to report the results after the standard adaptation procedure only.

## B. Training details

In this section, we present in detail the architecture and hyperparameters of HyperShot.

**Architecture overview** From a high-level perspective, the architecture of HyperShot consists of three parts:

- backbone - a convolutional feature extractor.
- neck - a sequence of zero or more fully-connected layers with ReLU nonlinearities in between.
- heads - for each parameter of the target network, a sequence of one or more linear layers, which predicts the values of that parameter. All heads of HyperShot have identical lengths, hidden sizes, and input sizes that depend on the generated parameter's size.

The target network generated by HyperShot re-uses its backbone. We outline this architecture in Figure 1.

**Backbone** For each experiment described in the main body of this work, we follow [27] in using a shallow backbone (feature extractor) for HyperShot as well as referential models. This backbone consists of four convolutional layers, each consisting of a convolution, batch normalization, and ReLU nonlinearity. Apart from the first convolution, which has the number of input size equal to the number of image channels, each convolution has an input and output size of 64. We apply max-pooling between each convolution, which decreases by half the resolution of the processed feature maps. The output of the backbone is flattened so that the further layers can process it.

We perform additional experiments described in Appendix A where instead of the above backbone, we utilize ResNet-10 [11].

**Datasets** For the purpose of making a fair comparison, we follow the procedure presented in, e.g., [27, 3]. In the case of the **CUB** dataset [41], we split the whole amount of 200 classes (11788 images) across train, validation, and test consisting of 100, 50, and 50 classes, respectively [3]. The **mini-ImageNet** dataset [32] is created as the subset of **ImageNet** [34], which consists of 100 different classes represented by 600 images for each one. We followed the

standard procedure and divided the **mini-ImageNet** into 64 classes for the train, 16 for the validation set, and the remaining 20 classes for the test. The well-known **Omniglot** dataset [17] is a collection of characters from 50 different languages. The **Omniglot** contains 1623 white and black characters in total. We utilize the standard procedure to include the examples rotated by  $90^\circ$  and increase the size of the dataset to 6492, from which 4114 were further used in training. Finally, the **EMNIST** dataset [4] collects the characters and digits coming from the English alphabet, which we split into 31 classes for the test and 31 for validation.

**Data augmentation** We apply data augmentation during model training in all experiments, except **Omniglot**  $\rightarrow$  **EMNIST** cross-domain classification. The augmentation pipeline is identical to the one used by [27] and consists of the random crop, horizontal flip, and color jitter steps.

## C. Hyperparameters

Below, we outline the hyperparameters of architecture and training procedures used in each experiment.

We use cosine similarity as a kernel function and averaged support embeddings aggregation in all experiments. HyperShot is trained with the learning rate of 0.001 with the Adam optimizer [16] and no learning rate scheduler. Task-specific adaptation is also performed with the Adam optimizer and the learning rate of 0.0001.

For the natural image tasks (**CUB**, **mini-ImageNet**, **mini-ImageNet**  $\rightarrow$  **CUB** classification), we use a hypernetwork with the neck length of 2, head lengths of 3, and a hidden size of 4096, which produce a target network with a single fully-connected layer. We perform training for 10000 epochs.

For the simpler **Omniglot**  $\rightarrow$  **EMNIST** character classification task, we train a smaller hypernetwork with the neck length of 1, head lengths of 2, and the hidden size of 512, which produces a target network with two fully-connected layers and a hidden size of 128. We train this hypernetwork for a shorter number of epochs, namely 2000.

We summarize all the above hyperparameters in Table 4.

## D. Source code

The source code required for running the experiments is available at <https://github.com/gmum/few-shot-hypernets-public>.

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Table 1. The classification accuracy results for the inference tasks in the **CUB** and **mini-ImageNet** dataset in the 5-way (1-shot and 5-shot) scenarios. We consider models using the ResNet-10 backbone. The highest results are bold and second-highest in italic (the larger, the better).

Method	CUB		mini-ImageNet	
	1-shot	5-shot	1-shot	5-shot
<b>Feature Transfer</b>	63.64 $\pm$ 0.91	81.27 $\pm$ 0.57	–	–
<b>Baseline++</b> [3]	69.55 $\pm$ 0.89	85.17 $\pm$ 0.50	54.35 $\pm$ 0.34	<b>75.26 <math>\pm</math> 0.16</b>
<b>MatchingNet</b> [40]	71.29 $\pm$ 0.87	83.47 $\pm$ 0.58	54.18 $\pm$ 0.09	67.71 $\pm$ 0.20
<b>ProtoNet</b> [35]	<b>73.22 <math>\pm</math> 0.92</b>	85.01 $\pm$ 0.52	53.28 $\pm$ 0.17	73.04 $\pm$ 0.15
<b>MAML</b> [6]	70.32 $\pm$ 0.99	80.93 $\pm$ 0.71	–	–
<b>RelationNet</b> [38]	70.47 $\pm$ 0.99	83.70 $\pm$ 0.55	51.88 $\pm$ 0.45	67.21 $\pm$ 0.16
<b>DKT + CosSim</b> [27]	70.81 $\pm$ 0.52	83.26 $\pm$ 0.50	–	–
<b>DKT + BNCosSim</b> [27]	72.27 $\pm$ 0.30	85.64 $\pm$ 0.29	<b>56.03 <math>\pm</math> 0.50</b>	71.28 $\pm$ 0.12
<b>SimpleShot</b> [42]	53.78 $\pm$ 0.21	71.41 $\pm$ 0.17	–	–
<b>GPLDLA</b> [15]	71.30 $\pm$ 0.16	<b>86.38 <math>\pm</math> 0.15</b>	–	–
<b>HyperShot</b>	71.99 $\pm$ 0.70	86.28 $\pm$ 0.29	55.36 $\pm$ 0.64	73.06 $\pm$ 0.30
<b>HyperShot + adaptation</b>	71.60 $\pm$ 0.59	86.22 $\pm$ 0.30	55.99 $\pm$ 0.63	72.87 $\pm$ 0.33

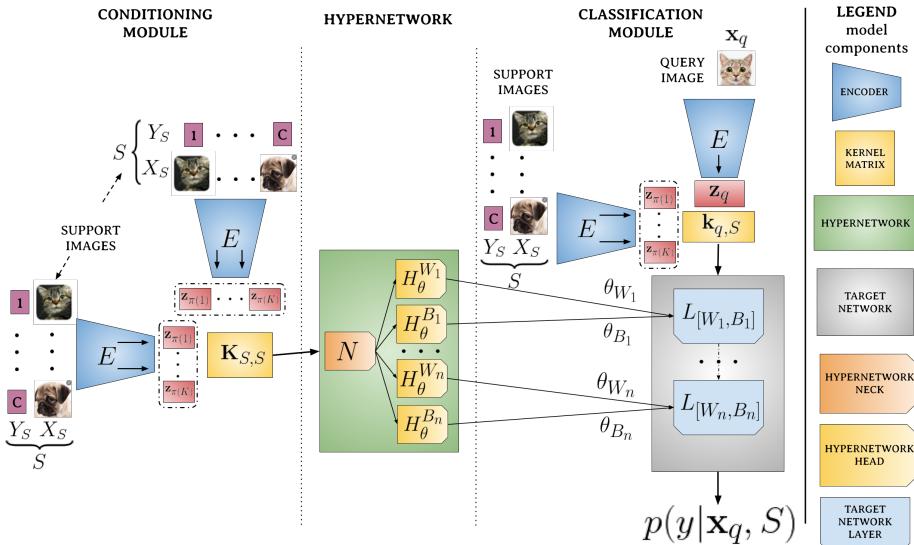


Figure 1. A detailed outline of the architecture of HyperShot, with the denoted flow of parameters generated by the hypernetwork heads.

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Table 2. The classification accuracy results for the inference tasks in the **mini-ImageNet** dataset in the 5-way (1-shot and 5-shot) scenarios. We consider models using the ResNet-12 backbone. The highest results are bold and second-highest in italic (the larger, the better).

Method	1-shot	5-shot
<b>cosine classifier</b> [3]	$55.43 \pm 0.81$	$77.18 \pm 0.61$
<b>TADAM</b> [26]	$58.50 \pm 0.30$	$76.70 \pm 0.30$
<b>Shot-Free</b> [33]	$59.04$	$77.64$
<b>TPN</b> [21]	$59.46$	$75.65$
<b>MTL</b> [37]	$61.20 \pm 1.80$	$75.50 \pm 0.80$
<b>RFS-simple</b> [39]	$62.02 \pm 0.63$	$79.64 \pm 0.44$
<b>ProtoNet</b> [35]	$62.39 \pm 0.21$	$80.53 \pm 0.14$
<b>MetaOptNet</b> [18]	$62.64 \pm 0.82$	$78.63 \pm 0.46$
<b>MatchingNet</b> [40]	$63.08 \pm 0.80$	$75.99 \pm 0.60$
<b>MAML</b> [6]	$63.11 \pm 0.92$	—
<b>PPA</b> [28]	$59.60$	$73.34$
<b>CAN</b> [12]	$63.85 \pm 0.48$	$79.44 \pm 0.34$
<b>NegMargin</b> [20]	$63.85 \pm 0.81$	$81.57 \pm 0.56$
<b>DeepEMD</b> [47]	$65.91 \pm 0.82$	$82.41 \pm 0.56$
<b>FEAT</b> [45]	$66.78 \pm 0.20$	$82.05 \pm 0.14$
<b>RENet</b> [14]	<b><math>67.60 \pm 0.44</math></b>	<b><math>82.58 \pm 0.30</math></b>
<b>HyperShot</b>	$59.12 \pm 0.26$	$76.53 \pm 0.22$
<b>HyperShot + adaptation</b>	$60.30 \pm 0.31$	$76.21 \pm 0.20$

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Table 3. The classification accuracy results for the inference tasks on **CUB** and **mini-ImageNet** datasets in the 1-shot and 5-shot settings. The highest results are in bold and second-highest in italic (the larger, the better). This is an expanded version of Table 1 from the main text.

Method	CUB		mini-ImageNet	
	1-shot	5-shot	1-shot	5-shot
<b>ML-LSTM</b> [32]	–	–	$43.44 \pm 0.77$	$60.60 \pm 0.71$
<b>SNAIL</b> [22]	–	–	$45.10$	$55.20$
<b>LLAMA</b> [10]	–	–	$49.40 \pm 1.83$	
<b>VERSA</b> [9]	–	–	$48.53 \pm 1.84$	$67.37 \pm 0.86$
<b>Amortized VI</b> [9]	–	–	$44.13 \pm 1.78$	$55.68 \pm 0.91$
<b>Meta-Mixture</b> [13]	–	–	$49.60 \pm 1.50$	$64.60 \pm 0.92$
<b>SimpleShot</b> [42]	–	–	$49.69 \pm 0.19$	$66.92 \pm 0.17$
<b>Feature Transfer</b> [49]	$46.19 \pm 0.64$	$68.40 \pm 0.79$	$39.51 \pm 0.23$	$60.51 \pm 0.55$
<b>Baseline++</b> [3]	$61.75 \pm 0.95$	$78.51 \pm 0.59$	$47.15 \pm 0.49$	$66.18 \pm 0.18$
<b>MatchingNet</b> [40]	$60.19 \pm 1.02$	$75.11 \pm 0.35$	$48.25 \pm 0.65$	$62.71 \pm 0.44$
<b>ProtoNet</b> [35]	$52.52 \pm 1.90$	$75.93 \pm 0.46$	$44.19 \pm 1.30$	$64.07 \pm 0.65$
<b>RelationNet</b> [38]	$62.52 \pm 0.34$	$78.22 \pm 0.07$	$48.76 \pm 0.17$	$64.20 \pm 0.28$
<b>DKT + CosSim</b> [27]	$63.37 \pm 0.19$	$77.73 \pm 0.26$	$48.64 \pm 0.45$	$62.85 \pm 0.37$
<b>DKT + BNCosSim</b> [27]	$62.96 \pm 0.62$	$77.76 \pm 0.62$	$49.73 \pm 0.07$	$64.00 \pm 0.09$
<b>VAMPIRE</b> [24]	–	–	$51.54 \pm 0.74$	$64.31 \pm 0.74$
<b>PLATIPUS</b> [7]	–	–	$50.13 \pm 1.86$	–
<b>ABML</b> [31]	$49.57 \pm 0.42$	$68.94 \pm 0.16$	$45.00 \pm 0.60$	–
<b>OVE PG GP + Cosine (ML)</b> [36]	$63.98 \pm 0.43$	$77.44 \pm 0.18$	$50.02 \pm 0.35$	$64.58 \pm 0.31$
<b>OVE PG GP + Cosine (PL)</b> [36]	$60.11 \pm 0.26$	$79.07 \pm 0.05$	$48.00 \pm 0.24$	$67.14 \pm 0.23$
<b>Reptile</b> [25]	–	–	$49.97 \pm 0.32$	$65.99 \pm 0.58$
<b>R2-D2</b> [2]	–	–	$48.70 \pm 0.60$	$65.50 \pm 0.60$
<b>VSM</b> [48]	–	–	$54.73 \pm 1.60$	$68.01 \pm 0.90$
<b>PPA</b> [28]	–	–	$54.53 \pm 0.40$	–
<b>MAML</b> [6]	$56.11 \pm 0.69$	$74.84 \pm 0.62$	$45.39 \pm 0.49$	$61.58 \pm 0.53$
<b>MAML++</b> [1]	–	–	$52.15 \pm 0.26$	$68.32 \pm 0.44$
<b>iMAML-HF</b> [30]	–	–	$49.30 \pm 1.88$	–
<b>SignMAML</b> [5]	–	–	$42.90 \pm 1.50$	$60.70 \pm 0.70$
<b>Bayesian MAML</b> [46]	$55.93 \pm 0.71$		$53.80 \pm 1.46$	$64.23 \pm 0.69$
<b>Unicorn-MAML</b> [43]	–	–	$54.89$	–
<b>Meta-SGD</b> [19]	–	–	$50.47 \pm 1.87$	$64.03 \pm 0.94$
<b>MetaNet</b> [23]	–	–	$49.21 \pm 0.96$	–
<b>PAMELA</b> [29]	–	–	$53.50 \pm 0.89$	$70.51 \pm 0.67$
<b>FEAT</b> [44]	$68.87 \pm 0.22$	$82.90 \pm 0.15$	$55.15 \pm 0.20$	$71.61 \pm 0.16$
<b>DFSVLwF</b> [8]	–	–	$56.20 \pm 0.86$	–
<b>HyperShot</b>	$65.27 \pm 0.24$	$79.80 \pm 0.16$	$52.42 \pm 0.46$	$68.78 \pm 0.29$
<b>HyperShot+ adaptation</b>	$66.13 \pm 0.26$	$80.07 \pm 0.22$	$53.18 \pm 0.45$	$69.62 \pm 0.20$

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Table 4. Hyperparameters

hyperparameter	CUB	mini-ImageNet	mini-ImageNet → CUB	Omniglot → EMNIST
kernel function	cosine similarity	cosine similarity	cosine similarity	cosine similarity
learning rate	0.001	0.001	0.001	0.001
hypernetwork’s head layers no.	3	3	3	2
hypernetwork’s neck layers no.	2	2	2	1
hypernetwork layers’ hidden dim	4096	4096	4096	512
support embeddings aggregation	averaged	averaged	averaged	averaged
taskset size	1	1	1	1
target network layers no.	1	1	1	2
target network activation	ReLU	ReLU	ReLU	ReLU
adaptation epochs (if used)	10	10	10	10
adaptation learning rate	0.0001	0.0001	0.0001	0.0001
optimizer	Adam	Adam	Adam	Adam
epochs no.	10000	10000	10000	2000

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