Grounded Video Description

Luowei Zhou\textsuperscript{1,2}, Yannis Kalantidis\textsuperscript{1}, Xinlei Chen\textsuperscript{1}, Jason J. Corso\textsuperscript{2}, Marcus Rohrbach\textsuperscript{1}
\textsuperscript{1} Facebook AI, \textsuperscript{2} University of Michigan

github.com/facebookresearch/grounded-video-description

Figure 1: Word-level grounded video descriptions generated by our model on two segments from our ActivityNet-Entities dataset. We also provide the descriptions generated by our model without explicit bounding box supervision, [15] and the ground-truth descriptions (GT) for comparison.

1. Introduction

Image and video description models are frequently not well grounded [6] which can increase their bias [4] and lead to hallucination of objects [9], \textit{i.e.} the model mentions objects which are not in the image or video \textit{e.g.} because they might have appeared in similar contexts during training. This makes models less accountable and trustworthy, which is important if we hope such models will eventually assist people in need [1, 11]. Additionally, grounded models can help to explain the model’s decisions to humans and allow humans to diagnose them [7]. While researchers have started to discover and study these problems for image description [6, 4, 9, 7], they are even more pronounced for video description due to the increased difficulty and diversity, both on the visual and the language side.

Fig. 1 illustrates this problem. A video description approach (without grounding supervision) generated the sentence “A man standing in a gym” which correctly mentions “a man” but hallucinates “gym” which is not visible in the video. Although a man is in the video it is not clear if the model looked at the bounding box of the man to say this word [4, 9]. For the sentence “A man […] is playing the piano” in Fig. 2, it is important to understand that which “man” in the image “A man” is referring to, to determine if a model is correctly grounded. Such understanding is crucial for many applications when trying to build accountable systems or when generating the next sentence or responding to a follow up question of a blind person: \textit{e.g.} answering “Is he looking at me?” requires an understanding which of the people in the image the model talked about.

The goal of our research is to build such grounded systems. As one important step in this direction, we collect ActivityNet-Entities (short as ANet-Entities) which grounds or links noun phrases in sentences with bounding boxes in the video frames (see Fig. 2 for an example). It is based on ActivityNet Captions [5], one of the largest benchmarks in video description.

Our new dataset allows us to introduce a novel grounding-based video description model that learns to jointly generate words and refine the grounding of the objects generated in the description. We explore how this explicit supervision can benefit the description generation compared to unsupervised methods that might also utilize region features but do not penalize grounding.

Our contributions are two-fold. First, we collect our large-scale ActivityNet-Entities dataset, which grounds video descriptions to bounding boxes on the level of noun phrases. Our dataset allows both teaching models on explicit object grounding and evaluating the grounding accuracy. Second, we propose a grounded video description framework which is able to learn from the bounding box supervision in ActivityNet-Entities and we demonstrate its superiority over baselines and prior work in generating grounded video descriptions.

2. ActivityNet-Entities Dataset

In order to train and test models capable of explicit grounding-based video description, one requires both language and grounding supervision. Although Flickr30k Entities [8] contains such annotations for images, no large-
When it comes to videos, region-level annotations come with a number of unique challenges. A video contains more information than can fit in a single frame, and video descriptions reflect that. They may reference objects that appear in a disjoint set of frames, as well as multiple persons and motions. To be more precise and produce finer-grained annotations, we annotate noun phrases (NP) rather than simple object labels. Moreover, one would ideally have dense region annotations at every frame, but the annotation cost in this case would be prohibitive for even small datasets. Therefore in practice, video datasets are typically sparsely annotated at the region level [3]. favouring scale over density, we choose to annotate segments as sparsely as possible and annotate every noun phrase only in one frame inside each segment. Dataset stats and comparisons with other related datasets can be found in Tab. 2.

3. Experiments

Details regarding methods and evaluations can be found at [13]. We show in Tab. 1a the results on description quality, object localization accuracy (indicated by Attn., Grd., \( F_{1,attn} \), and \( F_{1,loc} \)) and region classification accuracy (Cls.). All metrics are the higher the better. Our supervised method (GVD), i.e., with box supervision during training, outperforms the unsupervised counterpart in four of the five language metrics and gets significantly boosts in all the localization/classification metrics. We also set the new SotA on Bleu@1, METEOR and SPICE metrics, with relative gains of 2.8%, 3.9% and 6.8%, respectively over the previous best [15]. We observe slightly inferior results on Bleu@4 and CIDEr (-2.8% and -1.4%, respectively) but after examining the generated sentences, we see that prior work [15] generates repeated words way more often. The human evaluation in Tab. 1b further supports our discoveries from the automatic evaluation, that our GVD method generates descriptions with better quality.

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### Table 1: Results on ANet-Entities test set.

<table>
<thead>
<tr>
<th>Method</th>
<th>Bleu@1</th>
<th>Bleu@4</th>
<th>METEOR</th>
<th>CIDEr</th>
<th>SPICE</th>
<th>Attn.</th>
<th>Grd.</th>
<th>( F_{1,attn} )</th>
<th>( F_{1,loc} )</th>
<th>Cls.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Masked Transformer [15]</td>
<td>22.9</td>
<td>2.41</td>
<td>10.6</td>
<td>46.1</td>
<td>13.7</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Bi-LSTM+TempoAttn [15]</td>
<td>22.8</td>
<td>2.17</td>
<td>10.2</td>
<td>42.2</td>
<td>11.8</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Our Unsup. (w/o SelfAttn)</td>
<td>23.1</td>
<td>2.16</td>
<td>10.8</td>
<td>44.9</td>
<td>14.9</td>
<td>16.1</td>
<td>22.3</td>
<td>3.73</td>
<td>11.7</td>
<td>6.41</td>
</tr>
<tr>
<td>Our Sup. Attn.+Cls. (GVD)</td>
<td>23.6</td>
<td>2.35</td>
<td>11.0</td>
<td>45.5</td>
<td>14.7</td>
<td>34.7</td>
<td>43.5</td>
<td>7.59</td>
<td>25.0</td>
<td>14.5</td>
</tr>
</tbody>
</table>

(a) Results on ANet-Entities test set. The top one score for each metric is in bold. (b) Human evaluation of sentence quality. We present results for our supervised approach vs. our unsupervised baseline and vs. Masked Transformer [15].

### Table 2: Comparison of video description datasets with noun phrase or word-level grounding annotations.

<table>
<thead>
<tr>
<th>Dataset</th>
<th>Domain</th>
<th># Vid/Img</th>
<th># Sent</th>
<th># Obj</th>
<th># BBboxes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Flickr30k Entities [5]</td>
<td>Image</td>
<td>32k</td>
<td>160k</td>
<td>480</td>
<td>276k</td>
</tr>
<tr>
<td>MPII-MD [10]</td>
<td>Video</td>
<td>1k</td>
<td>1k</td>
<td>4</td>
<td>26k</td>
</tr>
<tr>
<td>YouCook2 [11]</td>
<td>Video</td>
<td>2k</td>
<td>15k</td>
<td>67</td>
<td>135k</td>
</tr>
<tr>
<td>ActivityNet Humans [12]</td>
<td>Video</td>
<td>5.3k</td>
<td>30k</td>
<td>1</td>
<td>63k</td>
</tr>
<tr>
<td>ActivityNet-Entities (ours)</td>
<td>Video</td>
<td>15k</td>
<td>52k</td>
<td>432</td>
<td>158k</td>
</tr>
</tbody>
</table>

Figure 2: An annotated example from our dataset. The dashed box (“people”) indicates a group of objects.

(a) A man in a striped shirt is playing the piano on the street while people watch him.

(b) A man in a striped shirt is playing the piano on the street while people watch him.
References


