# Supplementary Material for Orderless Recurrent Models for Multi-label Classification 

Vacit Oguz Yazici ${ }^{1,2}$, Abel Gonzalez-Garcia ${ }^{1}$, Arnau Ramisa ${ }^{2,3}$, Bartlomiej Twardowski ${ }^{1}$, Joost van de Weijer ${ }^{1}$<br>${ }^{1}$ Computer Vision Center, Universitat Autonoma de Barcelona, Barcelona, Spain<br>${ }^{2}$ Wide-Eyes Technologies, Barcelona, Spain ${ }^{3}$ Universitat de Vic, Barcelona, Spain<br>\{voyazici, agonzalez,bartlomiej.twardowski, joost\}@cvc.uab.es, arnau.ramisa@uvic.cat

## 1. Introduction

This is the supplementary material of the paper Orderless Recurrent Models for Multi-label Classification. We first exhibit some images whose labels are sorted differently by the proposed predicted label alignment (PLA) and frequent-first approach. Then, we show co-occurrence matrices of different super-categories of the MS-COCO dataset computed by the best BCE and LSTM models.

## 2. Qualitative comparison of PLA and other methods

In Figures 1-2, we can see different orders yielded by the PLA and frequent-first approaches. The images are chosen to emphasize the problems with the approaches that use predefined orders. As can be seen in the images, the frequentfirst approach always predicts the labels in the same order. This leads to confusion in case of dominant but less frequent objects or minor but more frequent objects in an image. Then, this confusion leads to duplicate predictions in different time steps.

## 3. Additional co-occurrence matrices of LSTM and BCE models

In Figure 3, the predicted class co-occurence matrices for binary cross entropy (BCE) and predicted label alignment (PLA) models can be seen. The levels of co-occurence in BCE are noticeably higher than those on PLA, as it reuses the same parts of image for different predictions of similar objects (e.g. bike and motorbike). This can be observed especially on the animals, food, vehicle and kitchen super-categories. In the animals super-category the BCE model overshoots co-occurrence of dogs-cats and horsescows, while in the vehicles the confusion is on the buses, trucks and cars. In the kitchen super-category the confusion is the worst since most of the images are images of entire kitchens and the BCE model uses the entire scene for dif-


Figure 1: Comparisons of orders yielded by the PLA and frequent-first approaches (wrong or duplicate predictions are underlined).
ferent predictions. On the other hand, the LSTM model has much lower differences with the ground truth, since the previous predictions are taken into account at every time step.


Figure 2: See caption of Figure 1.


Figure 3: Co-occurence matrices for BCE (left) and PLA (right) models. BCE re-uses evidence to predict different objects, and hence has higher co-occurence levels due to false positives.

