

Detecting 11K Classes: Large Scale Object Detection without Fine-Grained Bounding Boxes

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Abstract

Recent advances in deep learning greatly boost the performance of object detection. State-of-the-art methods such as Faster-RCNN, FPN and R-FCN have achieved high accuracy in challenging benchmark datasets. However, these methods require fully annotated object bounding boxes for training, which are incredibly hard to scale up due to the high annotation cost. Weakly-supervised methods, on the other hand, only require image-level labels for training, but the performance is far below their fully-supervised counterparts. In this paper, we propose a semi-supervised large scale fine-grained detection method, which only needs bounding box annotations of a smaller number of coarse-grained classes and image-level labels of large scale fine-grained classes, and can detect all classes at nearly fully-supervised accuracy. We achieve this by utilizing the correlations between coarse-grained and fine-grained classes with shared backbone, soft-attention based proposal re-ranking, and a dual-level memory module. Experiment results show that our methods can achieve close accuracy on object detection to state-of-the-art fully-supervised methods on two large scale datasets, ImageNet and OpenImages, with only a small fraction of fully annotated classes.

1. Introduction

Object detection has been in the center stage of computer vision research, and the recent development of deep learning has vastly improved its performance. State-of-the-art algorithms, such as R-FCN [5], FPN [16] and Mask-RCNN [12] have achieved high accuracy on challenging benchmark datasets. However, these methods rely on accurate and complete annotations of object bounding boxes, which are expensive and time consuming to collect.

Exhaustively annotating bounding boxes for a large scale dataset with fine-grained level labels is extremely laborious (here “large scale” not only means large numbers of instances N , but also large numbers of categories C). Due to the multi-label nature of the detection problem, the annotation cost is $O(NC)$. Even with state-of-the-art annotating

methods [21, 22], it is still much more costly than annotating image level labels. Existing object detection datasets are either fully annotated but in small scale, such as PASCAL VOC [8] and MS COCO [17], or large scale but with only parts of categories having bounding box annotations, such as ImageNet [7] and OpenImages [14]. ImageNet has 11K categories that are considered to be trainable (i.e., more than 500 training images), with in total 12M training images. However, only 3K categories and less than 1M training images have bounding boxes annotations [27] (if we count all the ILSVRC-Detection annotations, the number is close to 1.5M). Similarly, OpenImages has more than 8K trainable categories but only 601 categories have bounding box annotations [14]. Even for those categories with bounding box annotations, missing annotations are common [37].

Recent studies propose large scale algorithms to facilitate the detection task on the scale of ImageNet and OpenImages *detection set*, such as R-FCN 3000 [27] and SNIPER with soft sampling [37, 28]. However, these methods still require full bounding boxes annotations. Fully-supervised detectors not only fail to utilize the full capacity of the training data (by ignoring data without bounding box annotations), but also limit the detector’s capability to recognize more fine-grained categories. We believe a better way to train large scale detector is through semi-supervised learning by utilizing both coarse-grained detection data and fine-grained classification data. There are several benefits in such a method: first, comparing to fully-supervised detectors, the semi-supervised detector only needs a relatively small number of coarse-grained classes to be fully annotated with bounding boxes. Intuitively, if we have fully annotated “dogs” with bounding boxes, we do not need bounding boxes for all the species of dogs. This can greatly reduce the annotation costs and make better use of existing data. Second, comparing to weakly-supervised detectors, we still exploit the coarse-grained detection data and train a stronger detector. State-of-the-art weakly-supervised methods are still 30 points below fully-supervised methods [10, 40, 33] in mAP. Our semi-supervised method demonstrates that we can achieve comparable performance

to fully-supervised methods.

The key to solve the problem lies in the correlations between coarse-grained and fine-grained classes. Thus we try to answer the following two questions: 1) How to build proper correlations between fully-supervised coarse-grained data (i.e., with bounding box annotations) and weakly-supervised fine-grained data (i.e., with only image level annotations); 2) How to effectively utilize these correlations to transfer accurate object appearances learned from fully-supervised to weakly-supervised data, and how to learn a better detector from the rich variances of more fine-grained weakly-supervised data.

In this work, we propose a novel large scale semi-supervised object detection solution. Compared to existing works [24, 27], our solution is able to handle both semantic and visual correlations between fully-supervised and weakly-supervised data. More importantly, beyond shared feature learning layers, we explicitly exploit these correlations to transfer knowledge between these two data worlds. The design not only helps extend the capability of the detector to fine-grained classes, but also improve the detector’s performance on coarse-grained classes with the help of rich diversity in fine-grained data. Specifically, we propose a two-stream network with a backbone based on R-FCN. One stream focuses on fully-supervised detection and the other stream solves the weakly-supervised detection with fine-grained data. Two streams share feature learning layers. Our main technical contributions include:

- the augmentation of fully-supervised detection stream with the fine-grained weakly-annotated data. With the shared backbone and multi-task training, we make use of more diverse fine-grained images in weak annotations to boost the detector’s performance
- the soft-attention based proposal re-ranking for weakly-supervised detection stream. We utilize the correlations between coarse- and fine-grained labels to bring attentions to proposals that are more likely to contain related objects from fully-supervised stream to the weakly-supervised stream
- the dual-level memory module with the foreground attention pooling. We augment the network with an external memory module. Similar to clustering loss, this module can transfer knowledge from supervised to unsupervised data and further regularize the training process.

Results on two large scale datasets - OpenImages and ImageNet demonstrate that our method, without the need of bounding boxes annotations, can still achieve high detection accuracy on fine-grained classes, while also boosting the detection performance on coarse-grained classes in some cases. Furthermore, our designed framework is end-to-end trainable and almost as efficient as a standard detection network. The proposed components are well general-

ized and can be easily transferred to any two-stage (RPN based) detectors. The success of our method also provides meaningful insights for practical data collection for object detection: to build a large scale object detector that is capable of detecting tens of thousands of classes (e.g. the 11K classes in ImageNet dataset), what we only need is to collect bounding boxes for a small set of coarse-grained classes and image labels for all fine-grained classes, which can significantly reduce the annotation cost.

2. Related Work

Fully-Supervised Object Detection: Fully-supervised detection can be divided into two categories: 1) One-stage methods, such as YOLO series [23, 24, 25] and SSD [18]. These methods do not require regional proposals and perform detection in a single shot. 2) Two-stage methods, such as Fast R-CNN series [11, 26], R-FCN [5], FPN [16] and Mask-RCNN [12]. These methods build on the same idea that a detector should first generate regional proposals, which are likely to contain objects, then further classify the proposals into background and specific object classes. One-stage methods in general are faster in training and inference, but with lower detection accuracy, compared to two-stage methods. Our proposed framework is built on top of one of the state-of-the-art method, R-FCN with Deformable Convolutional Network [5, 6]. However, it can be easily adopted to any other two-stage detectors.

Weakly-Supervised Object Detection: Weakly-supervised object detection is often formulated as the key instance detection on multi-instance learning, where we view each object proposal as an instance and each image as a bag. The problem is to find out instances that contain objects, given only bag-level supervision. Most weakly-supervised detection methods have two stages: they first utilize Selective Search [36] or Edge Boxes [41] as proposals, and then use a CNN to solve the multi-instance learning problem. There are two main directions to further improve the performance of weakly supervised detection: improving the proposal quality and the aggregation-selection process of proposals. WSDDN [2] is one of the well-known work for weakly-supervised object detection with deep learning. The key idea is to have an additional ranking softmax for proposals to smartly aggregate and select proposal scores. OICR [30] improves WSDDN by incorporating multiple refinement streams with pseudo ground-truth. [34] exploits web images to enhance training data. [31] ditches hand-crafted object proposals in favor of a weakly-supervised version of Regional Proposal Network (RPN). Recently, [10] also proposes to use extra attention map to improve the proposal selection process. In this work, we show that bounding box information of correlated coarse-grained detection classes can drastically improve the weakly-supervised fine-grained stream in both directions.

Semi-Supervised Object Detection: There are only a few research works in the semi-supervised detection field. [32] proposes a LSDA-based method that can handle disjoint set semi-supervised detection. [35] proposes a semiMIL method on disjoint set semi-supervised detection, which achieves better performance than [32]. However, they are not end-to-end trainable and cannot be easily extended to state-of-the-art detection frameworks. NoteRCNN [9] proposes a mining and training scheme for semi-supervised detection, but it needs seed boxes for all categories. YOLO 9000 [24] can also be viewed as a semi-supervised detection framework, but it is no more than a naive combination of detection and classification stream and only relies on the implicit shared feature learning from the network.

To the best of our knowledge, our method is the first end-to-end semi-supervised detection framework that explicitly exploit semantic/visual correlations between coarse-grained detection and fine-grained classification data. Experimental results on ImageNet and OpenImages datasets demonstrate that our solution is effective, and more applicable for real world large scale detection problems.

3. Technical Approach

In this section, we introduce how we solve the problem of semi-supervised fine-grained detection. We first formulate the problem in Section 3.1, then we introduce how we encode visual and semantic correlations in Section 3.2. Our overall architecture is outlined in Section 3.3. The key components are: a fully-supervised detection stream, a weakly-supervised stream with soft-attention based proposal re-ranking, and a dual-level memory module with foreground attention pooling, which are explained in detail in Section 3.3.1, Section 3.3.2 and Section 3.3.3, respectively.

3.1. Problem Formulation

Let \mathcal{X} be the whole dataset consisting of a subset \mathcal{X}_f of \mathcal{C}_f classes with full bounding box annotations (f denotes for fully-annotated), and a subset \mathcal{X}_w of \mathcal{C}_w classes with only image-level annotations (w denotes for weakly-annotated). Let $|\mathcal{C}_f| = C_f$ and $|\mathcal{C}_w| = C_w$. Our goal is to train a detector that is able to accurately detect all $\mathcal{C} = \mathcal{C}_f \cup \mathcal{C}_w$ classes. Our methods target to handle the challenging scenario, where the fully-annotated and weakly-annotated classes are disjoint (i.e., $\mathcal{C}_f \cap \mathcal{C}_w = \emptyset$), and there are much more image level annotations than bounding box annotations (i.e., $C_w \gg C_f$). This scenario includes the most prominent large-scale image datasets, namely ImageNet and OpenImages.

We assume that there exists semantic or/and visual correlations between fully-annotated set \mathcal{C}_f and weakly-annotated set \mathcal{C}_w . We also assume that \mathcal{C}_f contains all

coarse-grained level labels and \mathcal{C}_w contains all *fine-grained* level labels to reflect real world scenarios. For example, for semantic correlation, we could have “dog” as a coarse-grained label with bounding boxes, and “labrador”, “chihuahua”, etc as fine-grained labels without bounding box annotations. Or for visual-semantic correlation, we could have “dog” as a coarse-grained label, and “wolf”, “coyote”, or even “stuffed dog” as fine-grained labels. Our method aims to utilize these correlations to provide accurate bounding boxes predictions for fine-grained classes and improve the training accuracy on coarse-grained classes with related fine-grained data.

3.2. Encoding Correlations between Coarse-Grained and Fine-Grained Classes

We believe the key of a successful semi-supervised detector is to build and utilize correlations between coarse-grained and fine-grained classes. These correlations are bridges that allow us to transfer knowledge between two worlds. Specifically, we consider two kinds of correlations: semantic and visual correlations.

3.2.1 Semantic Correlations

Semantic correlations are extracted from human knowledge and languages on how objects/concepts are structured and related. These correlations are often represented as a directed graph or tree, such as WordNet [20] and Visual Genome [15]. The benefits of such semantic correlations are: 1) They encode strong prior knowledge on how we view the world. 2) They are readily available from various sources. For example, ImageNet is built on WordNet, and OpenImages is built on Google Knowledge Graph.

Encoding semantic correlations are straightforward as these correlations are already represented by a directed graph. For a coarse-grained detection class c_i^f , if we consider its hyponyms as $\mathcal{H}(c_i^f)$, the encoding function can be written as a one-hot vector:

$$\mathcal{M}(c_i^f) = [e_1^w, \dots, e_{C_w}^w], \text{ where } \begin{cases} e_j^w = 1, & \text{if } c_j^w \in \mathcal{H}(c_i^f) \\ 0, & \text{otherwise.} \end{cases} \quad (1)$$

Here c_j^w is an arbitrary fine-grained classification class. The reverse encoding from fine-grained to coarse-grained is just a similar function with hypernyms. We use these mapping functions in subsequent experiments.

There are drawbacks on semantic correlations. First, adding new nodes to the existing graph requires a lot of expert efforts and is prone to errors. Second, semantic correlations are not always transferable to visual similarities, and vice versa. For example, “hyena” biologically is closer to “feline”, but visually more similar to “canine”; “basketball” is visually similar to “orange”, but semantically they

are far away. Therefore, we introduce visual correlations in the next section.

3.2.2 Visual Correlations

Visual correlations describe the visual similarities among objects/concepts. These correlations align better with training objectives, and are more flexible and easier to maintain. To encode visual correlations, we consider two scenarios, directly using detection classes as “super-classes” or building “super-classes” by clustering.

If we have relatively small number of coarse-grained classes, we could treat each of them as a “super-class” and build a two-level encoding. We obtain the i -th object-class representation, x_i , by taking the average of features $x_{i,m}$ (extracted from the final layer of a deep neural network, such as ResNet-101, for sampled images m belonging to the i -th class). After acquiring the representation for each class, we can then encode the correlations between coarse-grained and fine-grained classes through either hard-assignment or soft-assignment.

Let’s denote $d_i^j = \|x_i^f - x_j^w\|_2$ as the Euclidean distance between two representations x_i^f from coarse-grained set and x_j^w from fine-grained set, the hard-assignment encoding function is similar to Eq. 1:

$$\mathcal{M}(c_i^f) = [e_1^w, \dots, e_{C_w}^w], \text{ where } \begin{cases} e_j^w = 1, & \text{if } d_i^j < \theta_i \\ 0, & \text{otherwise.} \end{cases} \quad (2)$$

Here θ_i is the class-specific threshold.

For soft-assignment, which is similar to weighted K-means clustering, we can assign a fine-grained class to multiple/all coarse-grained classes using a softmax function:

$$\mathcal{M}(c_i^f) = [e_1^w, \dots, e_{C_w}^w], \text{ where } e_j^w = \frac{e^{-\beta d_i^j}}{\sum_k e^{-\beta d_k^j}}, \quad (3)$$

where β is the temperature parameter that control the distribution of softmax function.

If we have a large number of coarse-grained classes, to reduce computational cost as well as facilitate more effective visual encoding, we can build a set of super-classes \mathcal{C}_s by (weighted, if we use soft assignment encoding) K-mean clustering on the representations of object classes from the coarse-grained set \mathcal{C}_f . We then have two encoding functions for $\mathcal{C}_s \rightarrow \mathcal{C}_f$ and $\mathcal{C}_s \rightarrow \mathcal{C}_w$ in the same spirit of Eq. 2 and Eq. 3.

3.3. Architecture

To utilize the fully-supervised (coarse-grained) and weakly-supervised (fine-grained) data and their encoded correlations, we build three key components in our framework: 1) a fully-supervised detection stream for coarse-grained classes, 2) a weakly-supervised classification

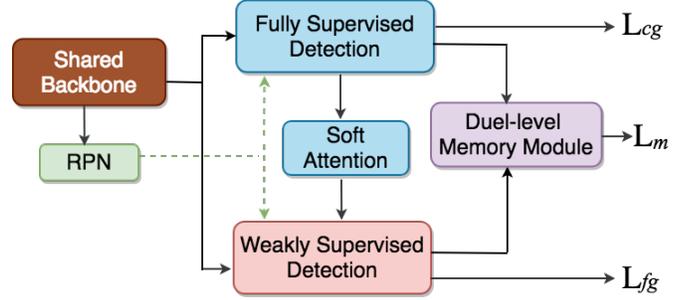


Figure 1: The overview of the designed architecture. The architecture can be split into three streams: 1) a *fully-supervised detection stream*, 2) a *weakly-supervised classification stream*, and 3) the *Correlation components including the soft-attention based proposal re-ranking and a dual-level memory module*. All three streams share common modules such as base CNN layers for feature learning and regional proposal network (RPN). During training, the detection data are used to train the RPN and R-FCN alike coarse-grained detection stream, while the fine-grained data are used to train the fine-grained classification stream. The correlation components are designed to transfer knowledge between coarse-grain and fine-grain.

stream for fine-grained classes, and 3) correlation components to transfer knowledge between coarse-grained and fine-grained data, including shared backbone, soft-attention based proposal re-ranking, and the dual-level memory module. Details of these components are explained in the following sections.

3.3.1 Fully-Supervised Detection Stream

This stream is built on Deformable R-FCN [5]. First, a Regional Proposal Network (RPN) is used for generating proposals and is only trained with detection data to avoid label noises from weakly supervised data. Then, on the shared backbone, we apply position sensitive filters to pool features from each proposal. Since we have C_f classes and $P \times P$ filters per class, there are $(C_f + 1) \times P \times P$ filters. After performing position-sensitive RoI pooling, we apply two fully connected layers to obtain final classification scores and regress bounding box results for each proposal. A cross-entropy loss and a bounding box regression loss are used for classification and regression learning, respectively:

$$\mathcal{L}_{cg} = 0.5 * \mathcal{L}_{cg}^{reg} + \mathcal{L}_{cg}^{cls}, \quad (4)$$

where we use 0.5 as the trade-off parameter [28].

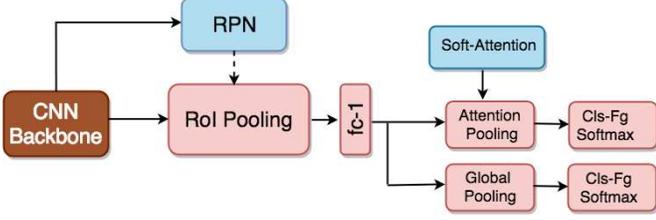


Figure 2: The overview of weakly-supervised stream.

3.3.2 Weakly-Supervised Detection Stream with Soft-Attention Proposal Re-ranking

Weakly-supervised detection can be viewed as a special kind of multi-instance multi-label learning with key instance detection. Each image can be a bag in multi-instance learning and each proposal from the image is an instance in the bag. Since we just have the image(bag)-level labels, the key for solving this problem is how to aggregate proposal-level scores into image-level scores and how we select proposals that are most likely to contain target objects. In the context of deep learning and back-propagation, these two problems are closely tied together.

A classical way to aggregate proposal scores is to use max or average pooling [38, 39]. This works well for getting good image-level predictions, but not for detecting proposals with the highest Intersection over Union (IoU) to ground truth bounding boxes. The most likely reason is that modern CNNs tend to focus on the most discriminative part of objects rather than the whole object [40]. For example, networks trained on ImageNet differentiate “person” from other objects by only using the head/face part rather than the whole body. Therefore, state-of-the-art weakly-supervised object detection methods [2, 34, 33, 10] employ some forms of regularization on the activation maps or the proposals selection to solve the problem.

Fortunately, since we have the fully-supervised detection stream, for each proposal, we actually know the presence or absence of closely related coarse-grained objects for a fine-grained object. Continuing with our “dog” example, considering if we are training the model for “chihuahua”, a proposal with high score on “dog” from the fully-supervised detection stream is much more likely to contain “chihuahua” than a proposal with low score on “dog”. This knowledge from the detection data is one good attention mechanism for weakly-supervised detection.

We design our weakly-supervised branch based on this idea. Similar to the fully-supervised stream, we use the shared RPN to generate proposals, and a RoI pooling layer to exact features for each proposal from shared layers. We select RoI pooling instead of PSRoI pooling to reduce the computation overhead, as PSRoI pooling requires $P \times P$ times more filters than RoI pooling, and there are a large number of classes in our case. After we generate pooled

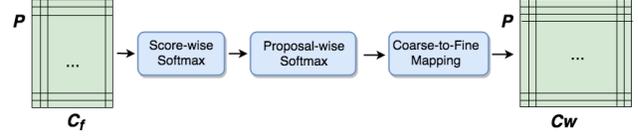


Figure 3: Soft-attention based proposal re-ranking.

features, we obtain proposal-level scores through a fully connected layer. These scores are then sent to two different pooling branches as shown in Figure 2. The first branch is the global pooling: we use max, average or weighted average pooling to aggregate image-level scores, and normalized softmax loss to learn. This branch is designed for smoothing the training process and generating good image-level performance. The second branch is the attention pooling, which transfers knowledge from fully-supervised stream and helps create accurate proposals. Similar to soft-attention mechanism in neural machine translation [1], we use proposal scores from fully-supervised detection stream as an attention map and apply this map to the weakly-supervised detection scores to obtain final proposal scores. This score is then aggregated by average pooling.

As shown in Figure 3, to obtain the attention map for ranking, we need to re-scale and normalize the coarse-grained detection scores, and then map the scores to fine-grained labels using previously discussed mapping functions, i.e., Eq. (1), (2), (3). Assuming we have a score map $\mathcal{S}^f \in \mathbb{R}^{(C_f+1) \times P}$, where $C_f + 1$ is the number of coarse-grained detection classes plus background, and P is the number of proposals. If background class is at index $C_f + 1$, to constrain that each proposal on the map to one unique class, we use a softmax operation defined as:

$$\hat{\mathcal{S}}^f(p, c) = \frac{e^{\mathcal{S}^f(p, c)}}{\sum_{j=1}^{C_f} e^{\mathcal{S}^f(p, j)}}, \forall c \in [1, \dots, C_f], \quad (5)$$

where $\mathcal{S}^f(p, c)$ is the score for proposal p at class c . After obtaining $\hat{\mathcal{S}}^f$, similar to the ranking term in WSDDN [2], we normalize the score map in the direction of proposals to obtain the coarse-grained attention map

$$\mathcal{A}^f(p, c) = \frac{e^{\hat{\mathcal{S}}^f(p, c)}}{\sum_{j=1}^P e^{\hat{\mathcal{S}}^f(j, c)}}, \forall p \in [1, \dots, P], \quad (6)$$

However, since we need to apply the attention map to fine-grained proposals, we utilize the encoding function described in Section 3.2 as a coarse-to-fine mapping function to map the coarse-grained attention map to fine-grained. We obtain the fine-grained attention map $\mathcal{W}^w(p)$ at proposal p as

$$\mathcal{A}^w(p) = \sum_{j=1}^{C_f} \mathcal{A}^f(p, j) * \mathcal{M}(j), \quad (7)$$

where $\mathcal{M}(j)$ is the soft-assignment or one-hot hard-assignment encoding on class j , with dimension C_w . This attention map is then applied to the weakly-supervised score map $\mathcal{S}^w \in \mathbb{R}^{C_w \times P}$ by element-wise product.

The final loss function of the weakly-supervised fine-grained detection branch is:

$$\mathcal{L}_{fg} = \mathcal{L}^{cls}(\text{pool}(\mathcal{S}^w), y) + \lambda \mathcal{L}^{cls}(\text{pool}(\mathcal{S}^w \odot \mathcal{A}^w), y), \quad (8)$$

where y is a multi-label image level label and λ is the trade-off parameter which is set to be 0.1 for all of our experiments. We use Top-5 average pooling for the first term and sum pooling for the second term. Detailed experiments on design choices can be found in our supplemental file.

3.3.3 Dual-Level Memory Module

Neural networks with memory are recently introduced to enable more powerful learning and reasoning ability for addressing several challenging tasks, such as question answering[19], one-shot learning[13] and semi-supervised classification [4]. Augmenting a network with an external memory component acts a similar role as the clustering loss in standard semi-supervised learning, but with dynamically updating feature representations and probabilistic predictions memorization.

Inspired by these works, we propose to add a memory module to our framework to take advantage of the memorable information generated in model learning and to further regularize the learning. Unlike [4], our semi-supervised detection task is a two-level semi-supervised problem. For the detection stream, we do not have bounding box annotations for fine-grained classification data, and for the classification stream, we do not have fine-grained labels for the detection data. Therefore, we need two levels of memory: the coarse-grained proposal-level memory, and the fine-grained image-level memory. Hence, we propose a Dual-Level Memory module with Foreground Attention pooling (DLM-FA).

For the coarse-grained level memory, we have proposal(box)-level labels for coarse-grained detection images, but we are lacking proposal-level coarse-grained labels for fine-grained images. If we view each proposal as one training instance, we are facing a straightforward semi-supervised learning problem and we can directly use the same memory structure as in [4]. The loss function is:

$$\mathcal{L}_m^w = H(\hat{\mathbf{p}}) + D_{KL}(\mathbf{p}||\hat{\mathbf{p}}), \quad (9)$$

where $H(\cdot)$ is the entropy and $D_{KL}(\cdot)$ is the Kullback-Leibler (KL) divergence. $\hat{\mathbf{p}}$ is the memory prediction and \mathbf{p} is the network prediction for each proposal p .

For the fine-grained level memory, we have image-level labels for fine-grained classification images, but we are lacking fine-grained labels for coarse-grained images. However, compared with standard semi-supervised setting,

we are dealing with multi-instance semi-supervised scenario. Therefore, we need to aggregate proposal-level features and predictions to image-level in order to facilitate memory update and prediction. We use Foreground Attention (FA) pooling to filter out noisy proposals. In FA pooling, we only pool features and predictions from proposals with high responses of positive image-level, and aggregate these features and predictions by sum pooling to represent their corresponding images. Specifically, if image I has m proposals $p_{i=1}^m$, and their corresponding features and scores are $\{p_i^f\}_{i=1}^m$ and $\{p_i^s\}_{i=1}^m$, the image-level feature I_c^f for a specific class c is then defined by:

$$I_c^f = \sum_i (p_i^f), \text{ if } \text{argmax}(p_i^s) = c, \quad (10)$$

The image-level predictions I_c^s is pooled in a similar way. After we have the image-level features and scores to update memory modules, we utilize

$$\mathcal{L}_m^f = H(\hat{I}) + D_{KL}(I||\hat{I}), \quad (11)$$

as the loss function for fine-grained level memory. The whole memory loss is then:

$$\mathcal{L}_m = \mathcal{L}_m^w + \mathcal{L}_m^f \quad (12)$$

Details of the memory module can be found in the supplementary file.

4. Experiments

In this section, we first introduce our implementation details. Then we discuss the experimental results and compare them with other baseline methods. We test our method on two most challenging large scale datasets – OpenImages [14] and ImageNet [7].

4.1. Implementation Details and Baselines

Our implementation is based on SNIPER [28]. In particular, we use mixed precision training for larger batch size and faster training speed. ResNet-101 with fp16 weights is used as the shared backbone. We use fp32 weights for the fully connected and convolutional layers of all heads. We train the model on 8 V-100 GPUs with a batch size of 128 (i.e. 16 per GPU). A balance sampling scheme is used for detection and classification data, i.e., we sample the same number of classification and detection data for each batch. The initial learning rate is set to be 0.015 for all experiments. We train all models for 9 epochs and the learning rate is dropped by 0.1 for every 3 epochs. Image horizontal flipping is used for data augmentation. We only use one scale, namely 512×512 for both training and testing. During inference, we run soft NMS [3] on the model outputs with the standard deviation parameter of 0.55 in the Gaussian weighting function.

We compare our method with state-of-the-art fully-supervised detection methods trained on the same data. All results are reported in mean average precision (mAP) with intersection-over-union (IoU) threshold at 0.5. Specifically, our method is compared to: 1) **SNIPER-CG-Fully**: SNIPER trained on coarse-grained data with fully annotated bounding boxes. 2) **SNIPER-FG-Fully**, i.e., SNIPER trained on fine-grained data with fully annotated bounding boxes. 3) **SNIPER-FG-Weakly**: SNIPER with fixed backbone and RPN trained from coarse-grained detection data and fine-tune on fine-grained data with only image-level labels. This is one of the strongest weakly baselines in our test. 4) **SNIPER-All**: SNIPER trained on coarse- and fine-grained data with all bound box and label annotations. We have also compared our methods with semi-supervised detection methods presented in [29, 32, 35], in a same-granularity random-split setting, and achieved favorable results. As this is not the focus of our paper and space limitations, the results are shown in supplemental file.

4.2. OpenImages Results

Class	# classes	# training	# test
Coarse-grained	34	786K	22K
Fine-grained	462	567K	8.8K

Table 1: Statistics for OpenImages dataset.

OpenImagesV4 dataset contains bounding box annotations for 601 classes with a semantic tree based on Google Knowledge Graph. We use all the 462 leaf nodes in the semantic tree as fine-grained classes. These fine-grained classes have 72 direct parent-nodes that can be used as coarse-grained classes. However, since these 72 classes also have hierarchy, for simplicity, we merged the lower level classes into their highest level parent classes. We end up with 34 coarse-grained classes. As discussed in the previous section, we only use bounding box annotations of the coarse-grained classes, and image-level labels for fine-grained classes in training. We use semantic correlations for OpenImages experiment. We evaluate our model on the OpenImages validation dataset for object detection. The validation dataset contains bounding box annotations for all coarse-grained and fine-grained labels. Table 1 shows the statistics for the coarse-grained and fine-grained data in training and validation datasets of OpenImages.

Results of different models are summarized in Table 2. We can see that naive combination of the fully-supervised and weakly-supervised stream without soft-attention and memory can already perform well on both tasks, especially on coarse-grained detection. The naive baseline already outperforms SNIPER-CG-Fully by around 7 points. This implies that the shared backbone benefits a lot from the rich variety of the *closely related* fine-grained images, as well as the multi-task training. However, since we only

Method	Training Data/Label	mAP-CG	mAP-FG
SNIPER [28]	CG-Fully	45.7	-
SNIPER [28]	FG-Fully	-	59.1
SNIPER [28]	All	28.7	54.0
SNIPER-Weakly	FG-Weakly	-	20.2
Naive	CG-Fully+FG-Weakly	52.5	34.0
+Soft-Attention	CG-Fully+FG-Weakly	52.9	49.2
+CG-Memory	CG-Fully+FG-Weakly	52.2	49.6
+DLM-FA	CG-Fully+FG-Weakly	53.5	51.9

Table 2: Test results for different models on OpenImages dataset where we evaluated coarse-grained (CG) and fine-grained (FG) classes separately.

use the simple proposal aggregation method (top-5 pooling), we can see that the fine-grained detection results, though reasonable, are far lower than SNIPER-FG-Fully and SNIPER-All. Despite of this, we can still see that naive weakly-supervised stream still outperforms the pure weakly-supervised method on the same RPN, which further validates the benefits of joint training and shared backbone.

If we add soft-attention based proposal re-ranking during training and inference, the *mAP* on fine-grained class increases by over 15 points. It is clear shown that, bringing the knowledge learned from the detector in can significantly help the weakly-supervised stream. For the memory module, if we just add a single-level coarse-grained memory module similar to [4], we do not see any improvement. However, with the help of Dual-Level Memory module, we can further minimize the gap between our fine-grained stream and the fully-supervised one.

Although it shows that our best model is still 7 points lower than the best fully-supervised model on fine-grained classes, we should mention that, our model actually performs similarly with SNIPER-FG-Fully in terms of $mAP_{0.5:0.95}$, both at around 36. This demonstrates that though we do not have bounding boxes on fine-grained classes, we can still learn to predict as accurately as fully-supervised methods.

4.3. ImageNet Results

Class	# classes	# training	# test
Coarse-grained	200	400K	22K
Fine-grained-3K	2937	870K	46K
Fine-grained-11K	11021	1.7M	-

Table 3: Statistics for ImageNet dataset.

We then run experiments on ImageNet dataset. As shown in Table 3, we use the ILSVRC 2014 Detection set with 200 classes as the coarse-grained set. Two fine-grained sets are tested. One is the 3K set with bounding box annotations, similar to what is used in [27]. For this set, we split 5% of the training data to the validation set to test the performance of our fine-grained stream. The other set contains 11K classes with each class having over 500 training images. There are in total 13M images in this set. In



Figure 4: Qualitative Results. The first row shows the fine-grained detection results from our best OpenImages model (last row of Table 2). The second row shows fine-grained detection results from our ImageNet model on 11K fine-grained classes.

Method	Training Data/Label	mAP-CG	mAP-FG
SNIPER [28]	CG-Fully	54.0	-
SNIPER [28]	3k-FG-Fully	-	41.6
YOLO-9000* [24]	COCO+9k-FG-Weakly	19.9	-
R-FCN-3000* [27]	3k-FG-Fully	34.9	-
Ours-3K	CG-Fully+3k-FG-Weakly	50.7	35.1
Ours-11K	CG-Fully+11k-FG-Weakly	49.1	-

Table 4: Test results for different models on ImageNet dataset where we evaluated coarse-grained (CG) and fine-grained (FG) classes separately. Please note that YOLO-9000 and R-FCN-3000 results are not directly comparable. Based on [27], SNIPER-3k-FG-Fully should be the performance upper bound of R-FCN-3000 on FG.

our experiment, we randomly sample 1/8 images from all classes for training and testing. Such a subset could have been general enough and is a good representative of the full set. We build visual correlations between the fine-grained and coarse-grained classes using the soft assignment introduced before.

From the results summarized in Table 4, we can see that unlike results from OpenImages dataset, our coarse-grained detection result is slightly worse than SNIPER-CG-Fully, by margins of 3.3 and 4.9, respectively. This could be explained by the correlations of coarse-grained and fine-grained data. For OpenImages, the coarse-grained and fine-grained sets are much closely correlated as they are hand-picked to form a compact semantic tree, while for ImageNet, the fine-grained sets are arbitrary picked by the availability of bounding box annotations and the number of training images. The ImageNet dataset could contain much more diverse classes in terms of semantic and visual correlations between the coarse-grained set. Therefore, we do not observe improvement on the coarse-grained performance.

Similar to OpenImages, though our best model is 6 points worse than the best supervised model on fine-grained classes in $mAP_{0.5}$, our model actually performs better than SNIPER-FG-Fully in terms of $mAP_{0.5:0.95}$, with our model

at 25 and SNIPER-FG-Fully at 22. This again demonstrates that we can learn to predict as accurately as fully-supervised methods on large scale datasets.

We also present the detection results of YOLO-9000 and R-FCN-3000 on the CG validation set in Table 4. Note that these methods are not trained on the same data as our method, thus the results cannot be directly compared. However, what we would like to present here is that we are able to train a large-scale detector that is capable of detecting up to 11k classes while still outperforming YOLO-9000 and R-FCN-3000 by a large margin on coarse-grained classes.

Since there is no bounding box annotations for the 11K classes in ImageNet, we demonstrate the qualitative results in Figure 4. Overall, our methods performs reasonably well. For example, our model is able to detect fine-grained animal species and human activities. More qualitative results and failure cases can be found in the supplemental file.

5. Conclusion

In this paper, we have proposed a semi-supervised based method to solve large-scale fine-grained object detection problem. Our method can achieve comparable results to state-of-the-art fully-supervised detectors, by utilizing data from only a small number of fully-annotated coarse-grained classes and large scale weakly-annotated fine-grained classes. Our work not only establishes a new way of learning large scale detectors, but also provides insights for large scale data collection and annotation.

There are a few future directions to explore. Currently we just use a simple two-level tree structure, and have not explored correlations within the coarse-grained or fine-grained set. Apparently, 11k fine-grained classes should not be treated as flat or uncorrelated. A better way is to utilize the hierarchical structures within the fine-grained classes. We can also explore systemic ways of searching for good fine-grained classes that can be well detected, while also helpful for improving the coarse-grained detection.

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