

# Supplementary Material for “Transductive Learning for Zero-Shot Object Detection”

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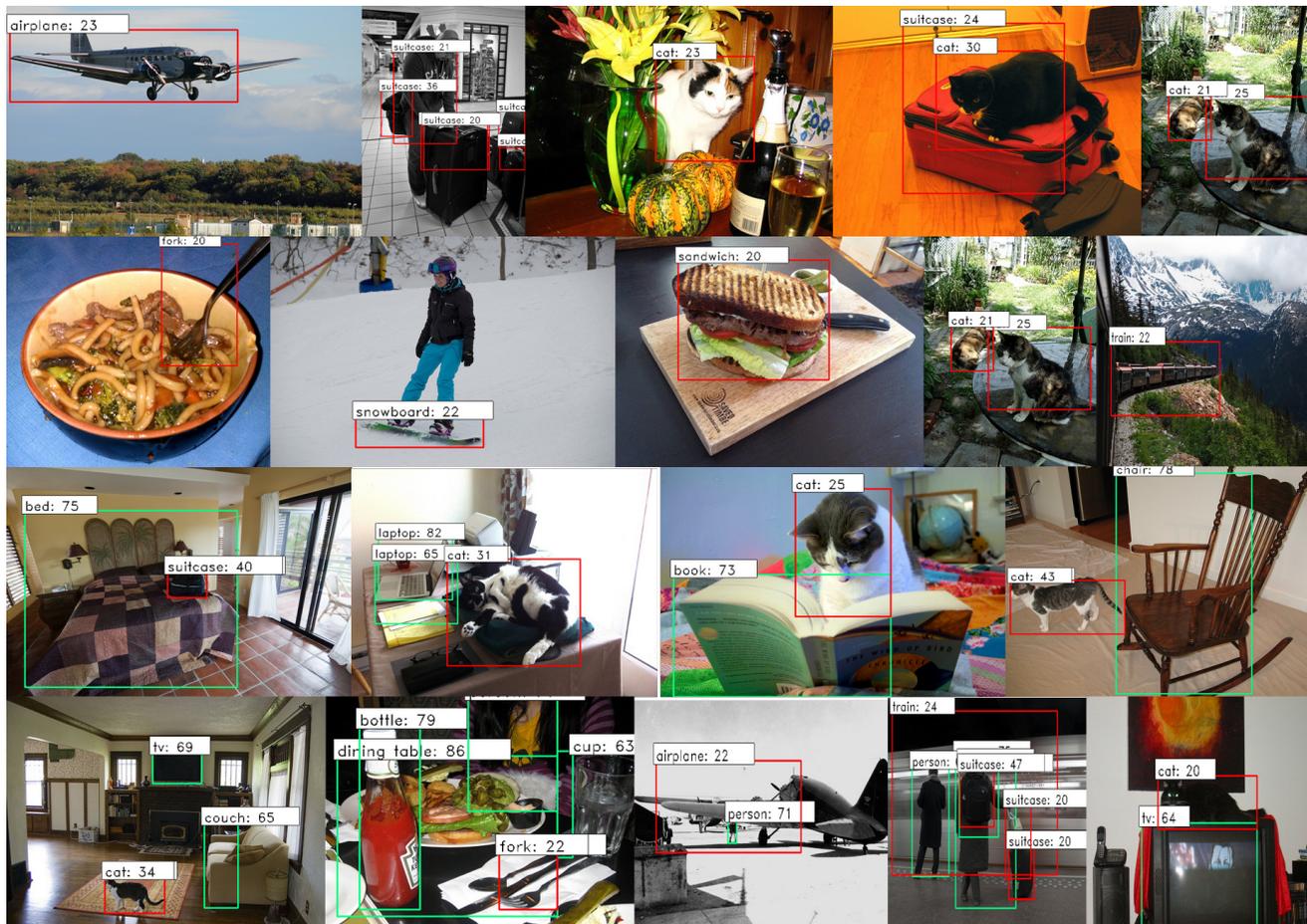


Figure 1: More qualitative results of ZSD (*top two rows*) and GZSD (*bottom two rows*). Red and green bounding boxes represent unseen and seen classes respectively.

## 1. Qualitative Results

In Fig. 1, we show more qualitative results of our approach.

## 2. Validation Experiment

To fix  $\lambda$  and  $t_h$ , we remove the term  $L_d(u)$  and  $L'_d(u)$  from Eq. 3 so that the loss becomes independent of  $\eta$  and  $\beta$ . Now, for different values of  $t_h = \{.2, .3, .4\}$  and

$\lambda = \{.1, .3, .5, .6, .8, 1\}$ , we perform a grid search on traditional detection task. In Table 1(a), we report the results of such validation experiment where  $t_h = .3$  and  $\lambda = .2$  performs the best. The reason  $t_h = .3$  works the best is that the same value was used during fixed pseudo-labeling for the seen classes. The hyper-parameter  $\lambda$  controls the balance between fixed and dynamic pseudo-labeling. When  $\lambda = 1$ , the network is trained with only fixed pseudo-labeling. Thus, traditional detection performs similarly

(38.25, 38.95, 39.48) across different  $t_h$ . Then, keeping all the chosen hyper-parameters fixed, we run another grid search for  $\beta = \{.1, .3, .5, .7, .9, 1\}$  and  $\eta = \{1, 2, 3, 4, 5\}$  on the same traditional detection task.  $\beta$  and  $\eta$  control the object/background imbalance of dynamic pseudo-labeling. Table 1(b) shows that  $\beta = 0.1$  and  $\eta = 1$  are the recommended values from our validation experiments.

(a)  $L_d = L_d(s)$  case: Varying  $\lambda$  and  $t_h$  with  $L_d(u) = L'_d(u) = 0$

$\lambda(\rightarrow)$	.2	.4	.5	.6	.8	1
$t_h=.2$	0.0	0.0	0.0	0.0	38.80	38.25
$t_h=.3$	<b>39.57</b>	37.51	24.91	0.7	37.87	38.95
$t_h=.4$	0.0	0.0	0.0	0.0	0.55	39.48

(b)  $L_d = L_d(s) + L_d(u) + L'_d(u)$  case: Varying  $\beta$  and  $\eta$

$\beta(\rightarrow)$	.1	.3	.5	.7	.9	1
$\eta=1$	<b>43.38</b>	41.06	39.14	40.98	41.73	38.81
$\eta=2$	41.59	39.05	39.40	37.65	41.47	39.98
$\eta=3$	40.66	41.13	41.89	40.47	39.65	39.87
$\eta=4$	40.64	40.48	40.00	40.15	42.42	39.82
$\eta=5$	40.22	36.73	41.73	37.85	32.94	40.94

Table 1: mAP scores of validation experiments. Selected hyper-parameters:  $\lambda = .2$ ,  $t_h = 0.3$ ,  $\beta = .1$  and  $\eta = 1$ .