## **DSConv: Efficient Convolution Operator**

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## 1. Derivation of Equation (2)

The bit-size of the normal convolution is simply the number of floating point numbers in its tensor:

$$s_c = 32 \cdot C_o \cdot C_i \cdot K^2 \tag{1}$$

The bit-size of the *DSConv* is the sum of the VQK and the KDS:

$$s_d = b \cdot C_o \cdot C_i \cdot K^2 + 32 \cdot C_o \cdot \lceil \frac{C_i}{B} \rceil \cdot K^2$$
 (2)

The ratio is:

$$p = \frac{b \cdot C_o \cdot C_i \cdot K^2 + 32 \cdot C_o \cdot \lceil \frac{C_i}{B} \rceil \cdot K^2}{32 \cdot C_o \cdot C_i \cdot K^2}$$
 (3)

$$p = \frac{b}{32} + \frac{\left\lceil \frac{C_i}{B} \right\rceil}{C_i} \tag{4}$$

## 2. Derivation of Equation (9)

The number of operations needed for normal convolution

is: 
$$T_{conv} = C_i \cdot C_o \cdot K^2 \cdot T_{FP} \tag{5}$$

Supposing that the MAX, SHIFT and MASK operations take  $\eta T_{int}$ , where  $\eta$  is the ideality factor. The number of operations needed for *DSConv* is:

$$T_{ds} = C_i \cdot C_o \cdot K^2 \cdot T_{int}(1+\eta) + \lceil \frac{C_i}{B} \rceil \cdot C_o \cdot K^2 \cdot T_{FP}$$
 (6)

So the time taken for the *DSConv* should be less than normal convolution:

$$T_{ds} \le T_{conv} \tag{7}$$

From which we find that:

$$T_{int} \le T_{FP} \frac{C_i - \lceil \frac{C_i}{B} \rceil}{C_i (1+n)} \tag{8}$$

## 3. Additional Results

Table 1 shows additional results of quantizing the more compact networks MobileNetV1, MobileNetV2, ShuffleNetV2, and a more accurate version of GoogleNet. Notice that as expected, more compact networks (particularly

the ones using depth-wise convolution) are prone to higher accuracy loss, as a result of lower redundancy.

Figure 1 shows the distribution of weight values for the VQK, KDS and resulting tensor compared to the original Weights of the first layer of ResNet50.

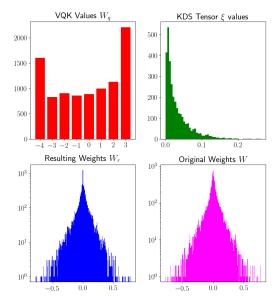


Figure 1. Result of quantizing the first layer of Resnet50 using b=3 and B=128 compared to original weights.