

## INTRODUCTION

- ▶ We present an algorithm to address both *unsupervised* and *semi-supervised* domain adaptation problems.
- ▶ Our goal is to learn a latent space,  $\mathcal{H} \subset \mathbb{R}^p$  in which domain disparities are minimized.
- ▶ We show such a space can be learned by **1.** matching the statistical properties of the projected domains (e.g., covariance matrices), **2.** adapting the Mahalanobis metric of the latent space to the labeled data.

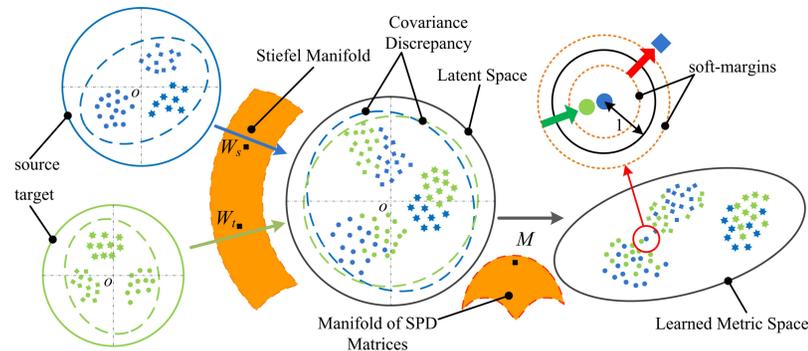


Figure: A diagram of our proposal. The marker shapes represents instance labels and color represents their original domain.

## OUR MODEL

- ▶ To learn  $W_s \in \mathbb{R}^{s \times p}$ ,  $W_t \in \mathbb{R}^{t \times p}$  and  $M \in \mathbb{S}_{++}^p$  we propose to minimize a loss function in the form,

$$\mathcal{L} = \mathcal{L}_d + \lambda \mathcal{L}_u; \quad (1)$$

- $\mathcal{L}_d$ : a discriminative loss defined on labeled similar and dissimilar pairs.
- $\mathcal{L}_u$ : a loss indicating statistical disparity between source and target domains.

### Discriminative Loss ( $\mathcal{L}_d$ )

- Defined on labeled pairs,  $(z_{1,k}, z_{2,k})$ ;  $k = 1, 2, \dots, N_p$  with,  $z_{1,k}, z_{2,k} \in \mathcal{H}$  and a label  $y_k \in \{+1, -1\}$ .
- Pulls similarly labeled pairs (i.e.  $y_k = +1$ ) closer and pushes dissimilarly labeled pairs (i.e.  $y_k = -1$ ) apart.

- ▶ We see improvements when,
  - Using a differentiable approximation to the hinge-loss.
  - Appending with softer margins.

- ▶ Our discriminative loss term takes the form,

$$\mathcal{L}_d = \frac{1}{N_p} \sum_{k=1}^{N_p} \ell_\beta(\mathbf{M}, y_k, z_{1,k} - z_{2,k}, 1 + y_k \epsilon_k) + r(\mathbf{M}) + \frac{1}{N_p} \sqrt{\sum \epsilon_k^2}, \quad (2)$$

with,

$$\ell_\beta(\mathbf{M}, y, \mathbf{x}, u) = \frac{1}{\beta} \log(1 + \exp(\beta y(\mathbf{x}^T \mathbf{M} \mathbf{x} - u))). \quad (3)$$

Here,  $r(\mathbf{M})$  is the regularizer for the metric,  $\mathbf{M}$  and  $\epsilon_k \in \mathbb{R}$ ,  $k = 1, 2, \dots, N_p$  are slack-variables.

### Loss over Domain Statistics ( $\mathcal{L}_u$ )

- First Order Statistics : Use centered data.
- Second Order Statistics : Match source and target covariances.

When  $\Sigma_s \in \mathbb{S}_{++}^s$  and  $\Sigma_t \in \mathbb{S}_{++}^t$  being the covariance matrices of the source and target domains,

$$\mathcal{L}_u = \frac{1}{p} \delta_s(W_s^T \Sigma_s W_s, W_t^T \Sigma_t W_t), \quad (4)$$

with  $\delta_s$  being the Stein divergence,

$$\delta_s(\mathbf{P}, \mathbf{Q}) = \log \det\left(\frac{\mathbf{P} + \mathbf{Q}}{2}\right) - \frac{1}{2} \log \det(\mathbf{P}\mathbf{Q}), \quad (5)$$

for  $\mathbf{P}, \mathbf{Q} \in \mathbb{S}_{++}$ .

## OPTIMIZATION

We optimize the loss function in an **alternating** fashion w.r.t. each model parameter (i.e.  $W_s, W_t, M$  and the slack variables).

### Constraints on the Loss Function

- **Orthogonality on projection matrices**  $W_s$  and  $W_t$  is motivated by the common practice in dimensionality reduction.
- Must follow  $M \in \mathbb{S}_{++}$  for the Metric.

### Using Riemannian Optimization Techniques

- **The Stiefel Manifold**,  $St(p, n)$ : The set of  $(n \times p)$ -dimensional matrices,  $p \leq n$ , with orthonormal columns.
- **The SPD Manifold**,  $\mathbb{S}_{++}^p$ : The set of  $(p \times p)$  dimensional real, Symmetric Positive Definite matrices.

### A Faster Solution with Product Topology

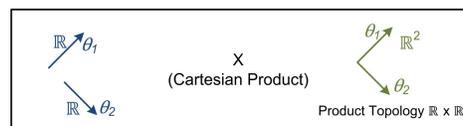


Figure: A demonstration on forming of a product topology.

We form the product topology,

$$\mathcal{M}_{prod.} = St(p, s) \times St(p, t) \times \mathbb{S}_{++}^p \times \mathbb{R}^{N_p}, \quad (6)$$

to avoid alternating optimization on model parameters.

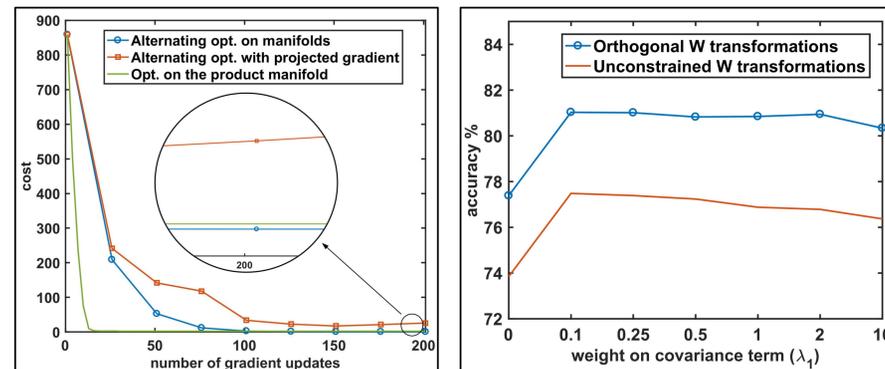


Figure: (Left) Comparison of optimization methods. (Right) Importance of the orthogonality constraint.

## EXPERIMENTAL RESULTS

### Experiments on Office-Caltech10 Dataset.

- Average performances on all 12 transformation sets in Office-Caltech10 dataset.

|                  | SURF        | VGG-FC6     | VGG-FC7     |                  | SURF        | VGG-FC6     | VGG-FC7     |
|------------------|-------------|-------------|-------------|------------------|-------------|-------------|-------------|
| NN-t             | 29.0        | 75.6        | 76.2        | 1-NN-s           | 23.5        | 65.2        | 66.7        |
| SVM-t            | 48.9        | 84.8        | 83.8        | SVM-s            | 38.9        | 70.2        | 70.6        |
| HFA[1]           | 48.1        | 83.7        | 83.0        | GFK[4]           | 42.5        | 76.1        | 73.2        |
| MMDT[2]          | 52.5        | 80.8        | 78.1        | SA[5]            | 44.2        | 75.3        | 73.1        |
| CDLS[3]          | 53.5        | 85.9        | 85.4        | CORAL[6]         | <b>46.7</b> | 78.3        | 76.1        |
| <b>ILS(1-NN)</b> | <b>55.6</b> | <b>88.5</b> | <b>86.4</b> | <b>ILS(1-NN)</b> | 46.0        | <b>80.8</b> | <b>78.8</b> |

Table: Semi-super. DA on Office-Calt.10

Table: Unsuper. DA on Office-Calt.10

- ▶ Performance gain when PCA subspaces are replaced

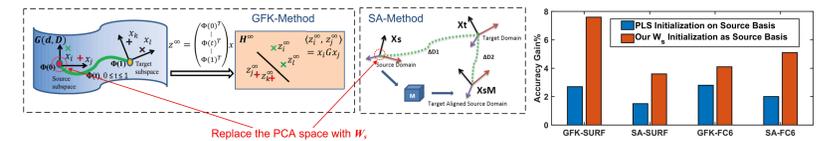
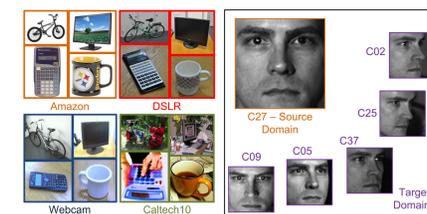


Figure: Performance improvement in GFK[4] and SA[5] methods when their PCA subspaces are replaced with our  $W_s$  matrix.

### Recognizing Faces with Pose Variations.



| Camera Pose      | C09         | C05         | C37         | C25         | C02         |
|------------------|-------------|-------------|-------------|-------------|-------------|
| 1-NN-s           | 92.5        | 55.7        | 28.5        | 14.8        | 11.0        |
| SVM-s            | 87.8        | 65.0        | 35.8        | 15.7        | 16.7        |
| GFK-PLS[4]       | 92.5        | 74.0        | 32.1        | 14.1        | 12.3        |
| SA[5]            | <b>97.9</b> | 85.9        | 47.9        | 16.6        | 13.9        |
| CORAL[6]         | 91.4        | 74.8        | 35.3        | 13.4        | 13.2        |
| <b>ILS(1-NN)</b> | 96.6        | <b>88.3</b> | <b>72.9</b> | <b>28.4</b> | <b>34.8</b> |

Table: (Left) Samples of domain images for Office-Caltech10 and PIE faces. (Right) Performance on face recognition with pose differences on Multiview-PIE dataset.

## FUTURE EXTENSIONS

- ▶ Our solution could be extended to **multiple source domain adaptation**.
- ▶ The latent space is compatible with **Heterogeneous domain adaptation**.
- ▶ **Stochastic optimization** on Riemannian manifolds for **large scale experiments**.

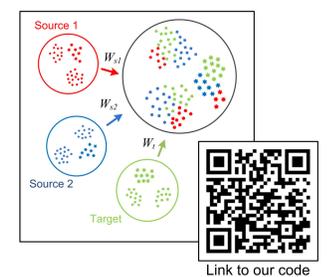


Figure: (Left) Multiple sources extension. (Right) Link to our code.

## References.

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