

Target Problems

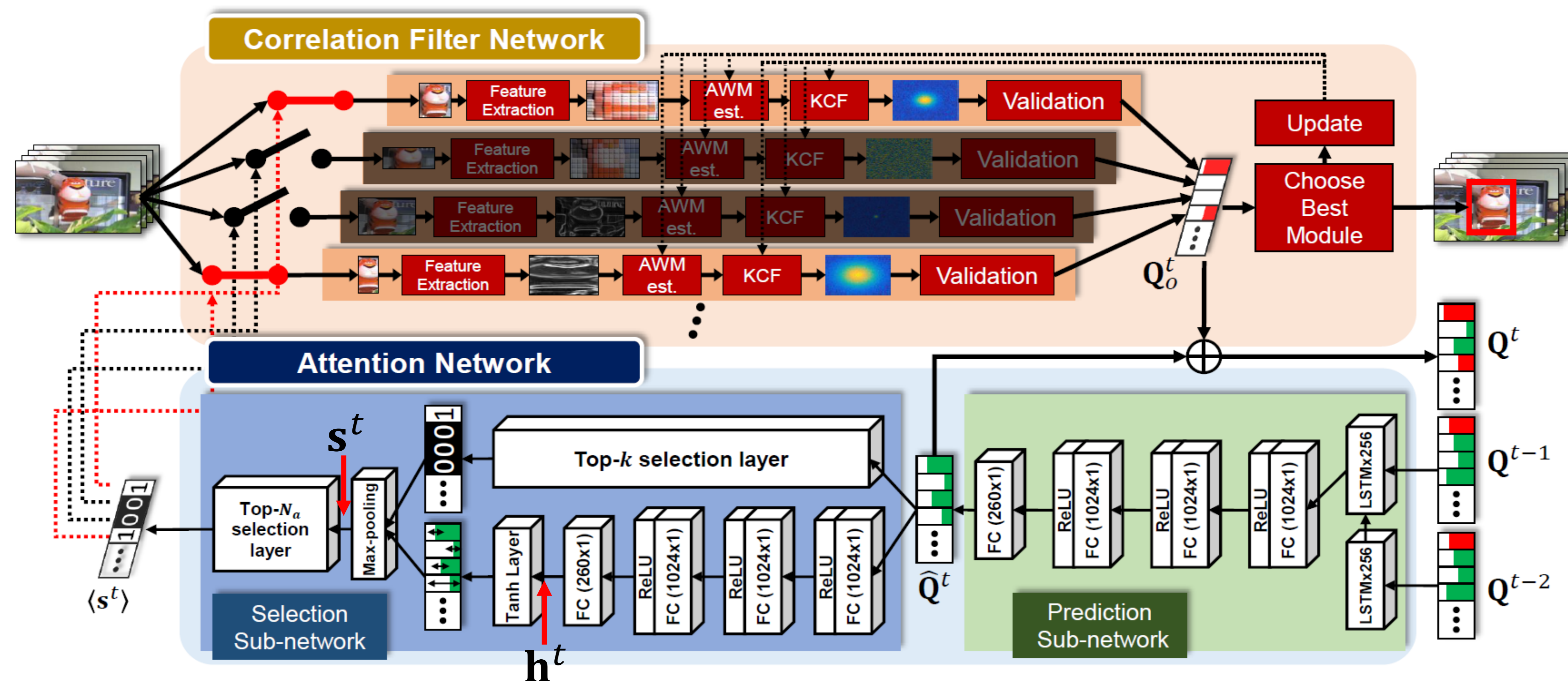
- By using many properties, tracking performance can be improved
- But, needs much time to consider various properties of target

Approach & Contribution

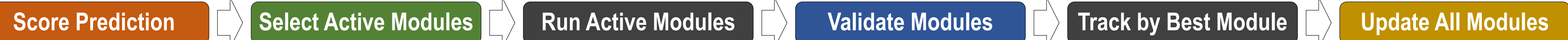


- Attentional Correlation Filter Network**
 - Attention Network
 - >> Predict the module-wise performance
 - >> Select the attentional modules
 - Correlation Filter Network
 - >> A lot of tracking modules with different properties
 - >> Novel properties (flexible aspect ratio, delay etc.)

Overall Framework



Tracking Step



From prev. score vectors, $\{Q^{t-1}, Q^{t-2}, \dots\}$

Prediction sub-network

$$\hat{Q}^t \in \mathbb{R}^{260}$$

predict curr. score vector

Selection sub-network

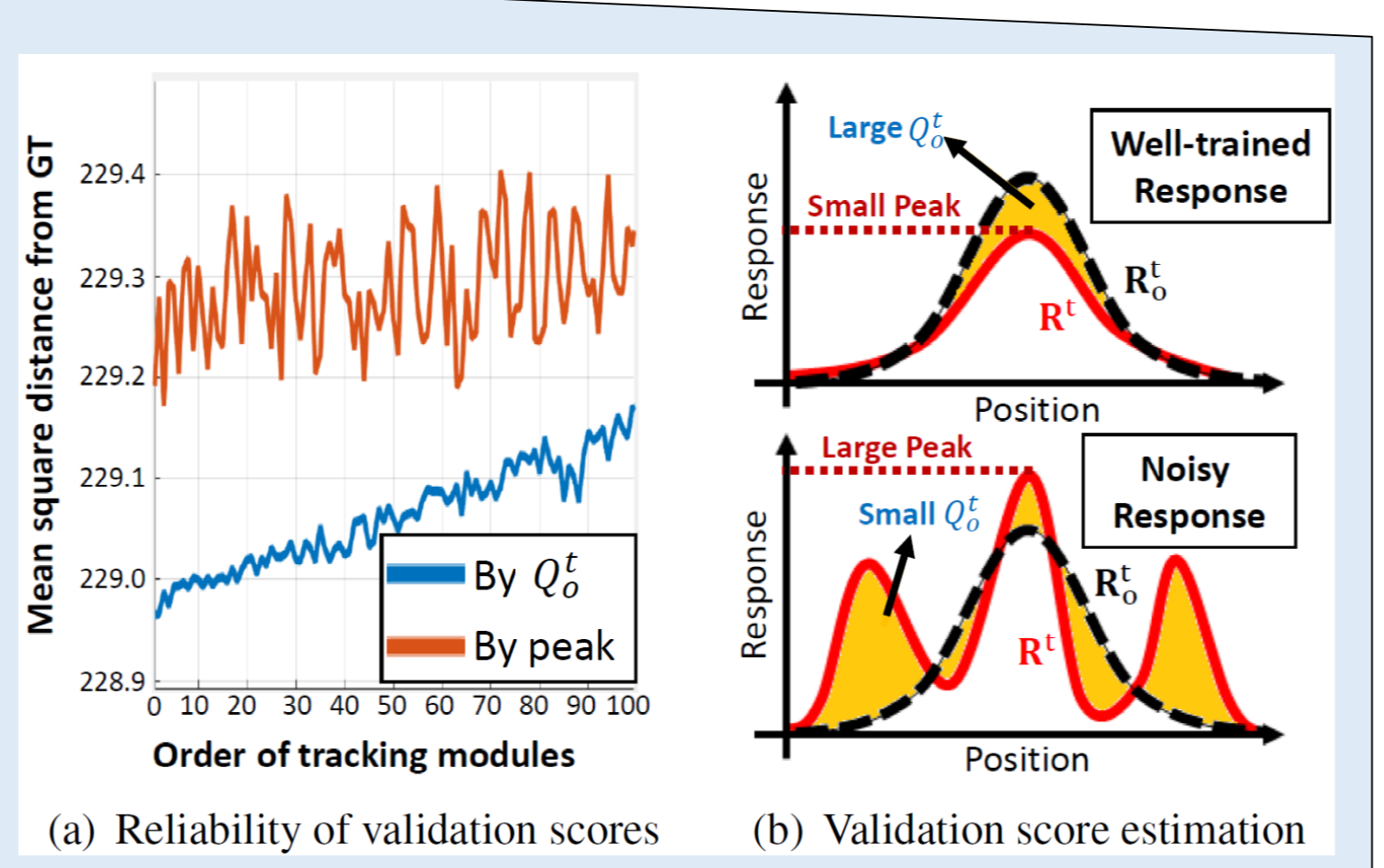
- Two Conditions
 - High predicted validation scores
 - High prediction error on score prediction

- Validation Score for Active Modules**
 - Use Euclidian distance to ideal response

$$Q_o^t = \exp(-\|R^t - R_o^t\|_2)$$

$$R_o^t = \mathcal{G}(p^t, \sigma_G^2)_{W \times H}$$
- Predicted Score for Inactive Modules**

$$Q^t = (1 - \langle s^t \rangle) * \hat{Q}^t + \langle s^t \rangle * Q_o^t$$



- Only a part of modules**
 - Different Feature
 - Different Kernel
- Scale change**
 - Share non-scalable CF
- Delayed update**
 - Reuse previous CFs

Correlation Filter Network

260 Tracking Modules

- Each tracking module is AtCF [1]
- 2 Features (Color intensity, HOG)
- 2 Kernel types (Gaussian, Polynomial)
- 13 Flexible scale changes (-2x, -x, +x, +2x, -2y, -y, +y, +2y, +xy, +2xy, 0)
- 5 Delayed updates (0, -1, -2, -3, -4 frames)

Pre-training of Attention Network

Loss Function

$$E = \sum_{i=1}^N \left\{ \|Q(i) - Q_{GT}(i)\|_2^2 + \lambda \|s(i)\|_0 \right\}$$

$$Q(i) = (1 - \langle s(i) \rangle) * Q(i) + \langle s(i) \rangle * Q_{GT}(i)$$

Relaxation

$$E = \sum_{i=1}^N \left\{ \left\| (1-s(i)) * (\hat{Q}(i) - Q_{GT}(i)) \right\|_2^2 + \lambda \|s(i)\|_0 \right\}$$

$$Q(i) = (1 - s(i)) * \hat{Q}(i) + s(i) * Q_{GT}(i)$$

- Prediction sub-network

$$E = \sum_{i=1}^N \left\{ \left\| \hat{Q}(i) - Q_{GT}(i) \right\|_2^2 \right\}$$
- Selection sub-network

$$E = \sum_{i=1}^N \left\{ \left\| (1-s(i)) * (\hat{Q}(i) - Q_{GT}(i)) \right\|_2^2 + \lambda \ln(1 + \|h(i)\|_1) \right\}$$

Experiment

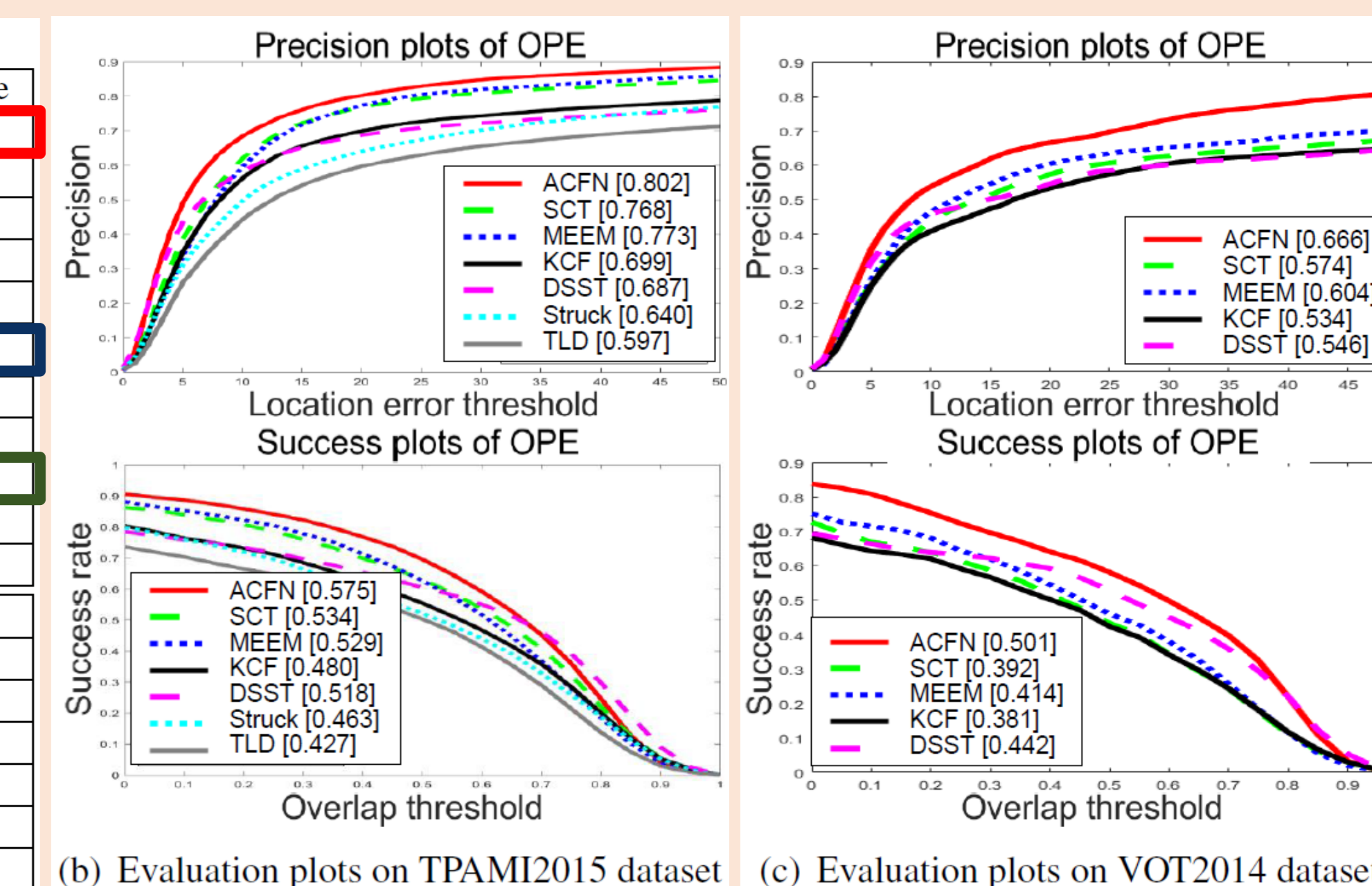
Implementation

- Tensorflow (CF-Net) + MATLAB (At-Net) (By socket communication)
- i7-6900K CPU, 32GB RAM, NVIDIA GTX1070 GPU

Quantitative Results

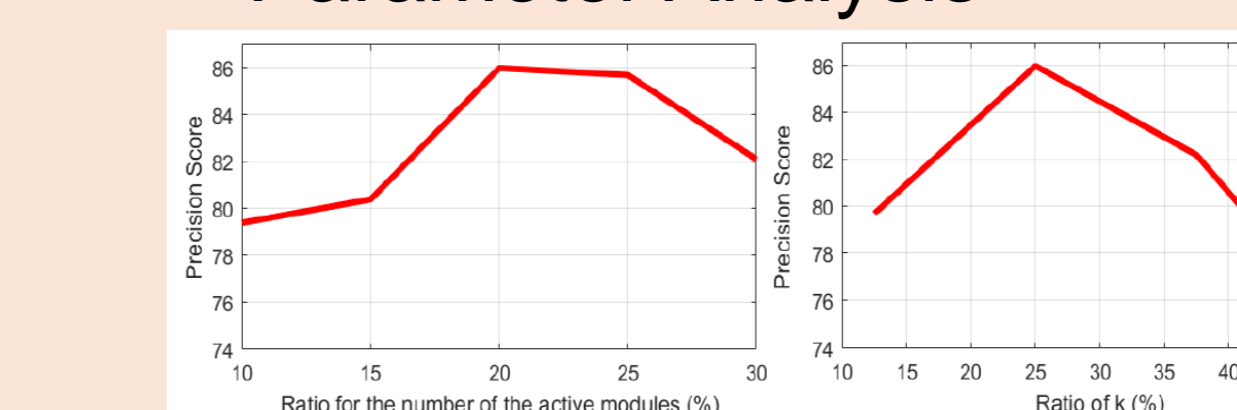
Table 1. Quantitative results on the CVPR2013 dataset [38]

Algorithm	Pre. score	Mean FPS	Scale
ACFN	86.0%	15.0	O
CFN+predNet	82.3%	14.4	O
CFN	81.3%	6.9	O
CFN+simpleSel.	79.4%	15.7	O
CFN	78.4%	15.5	O
SCT [3]	84.5%	40.0	X
MEEB [42]	81.4%	19.5	X
KCF [16]	74.2%	223.8	X
DSST [5]	74.0%	25.4	O
Struck [15]	65.6%	10.0	O
TLD [19]	60.8%	21.7	O
C-COT [8]	89.9%	<1.0	O
MDNet-N [29]	87.7%	<1.0	O
MUSTer [18]	86.5%	3.9	O
FCNT [35]	85.6%	3.0	O
D-SRDCF [6]	84.9%	<1.0	O
SRDCF [7]	83.8%	5	O
STCT [36]	78.0%	2.5	O

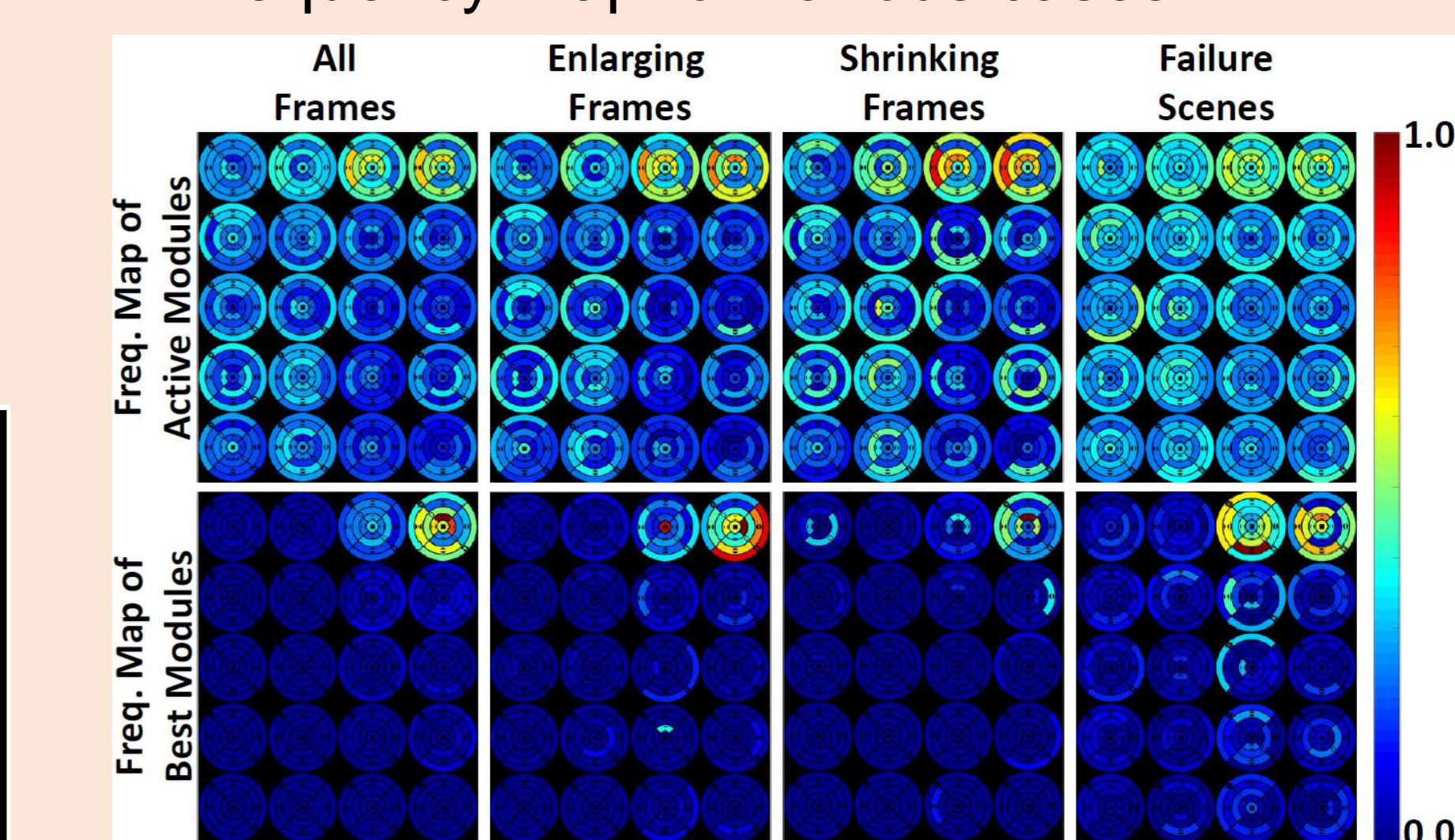


Analysis

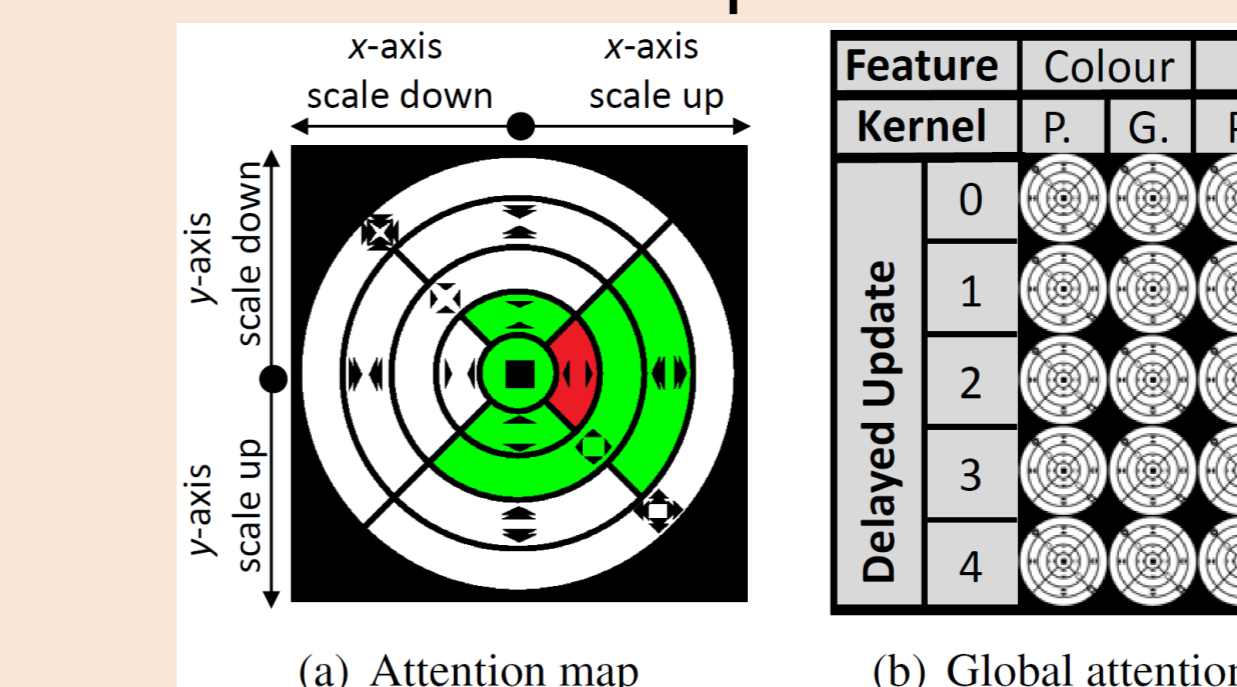
Parameter Analysis



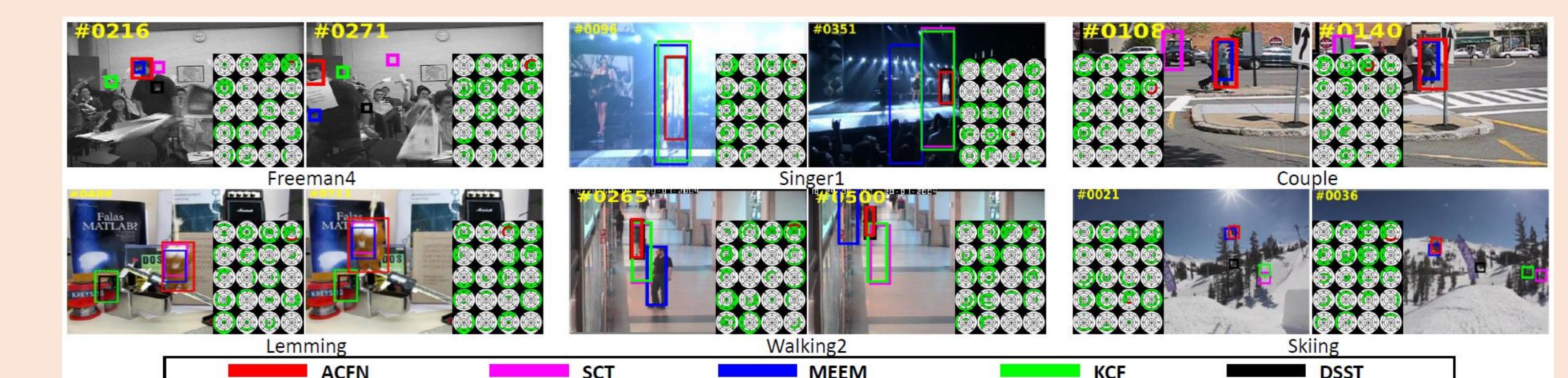
Frequency map for various cases



Attention Map Definition



Qualitative Results



Reference

[1] Choi et al., "Visual tracking using attention-modulated disintegration and integration", CVPR2016