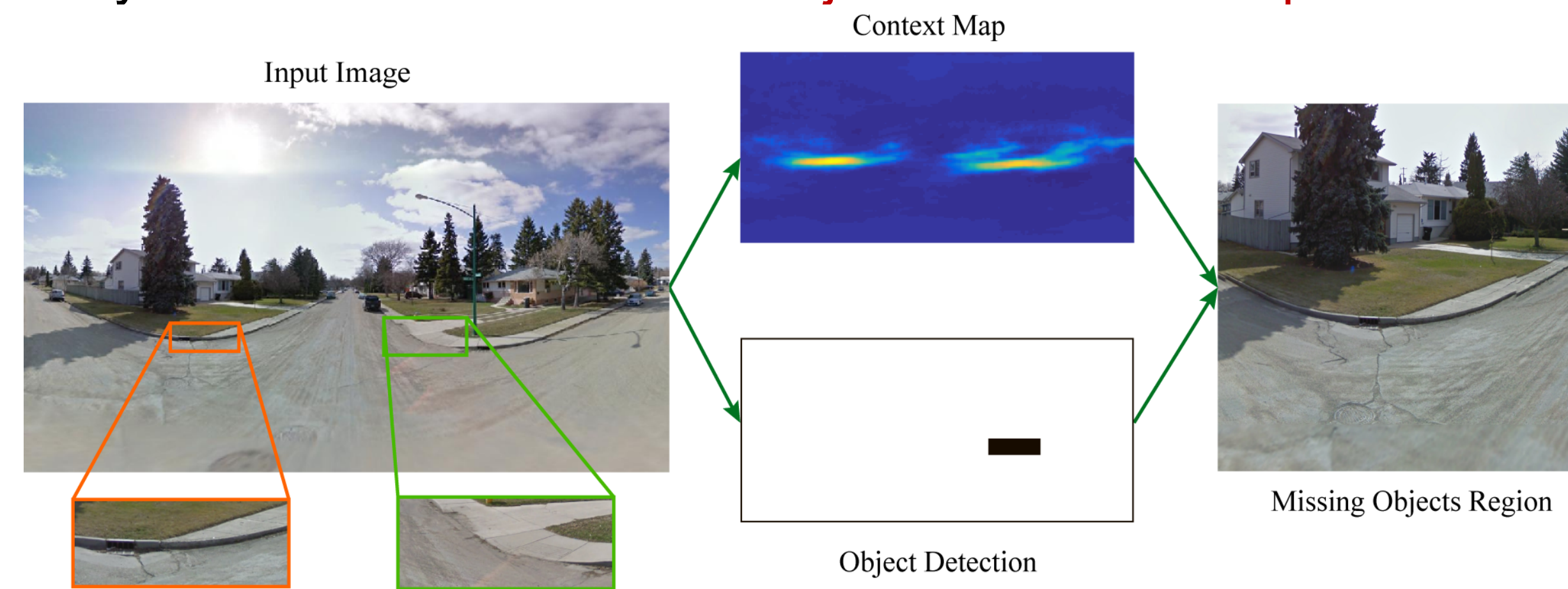
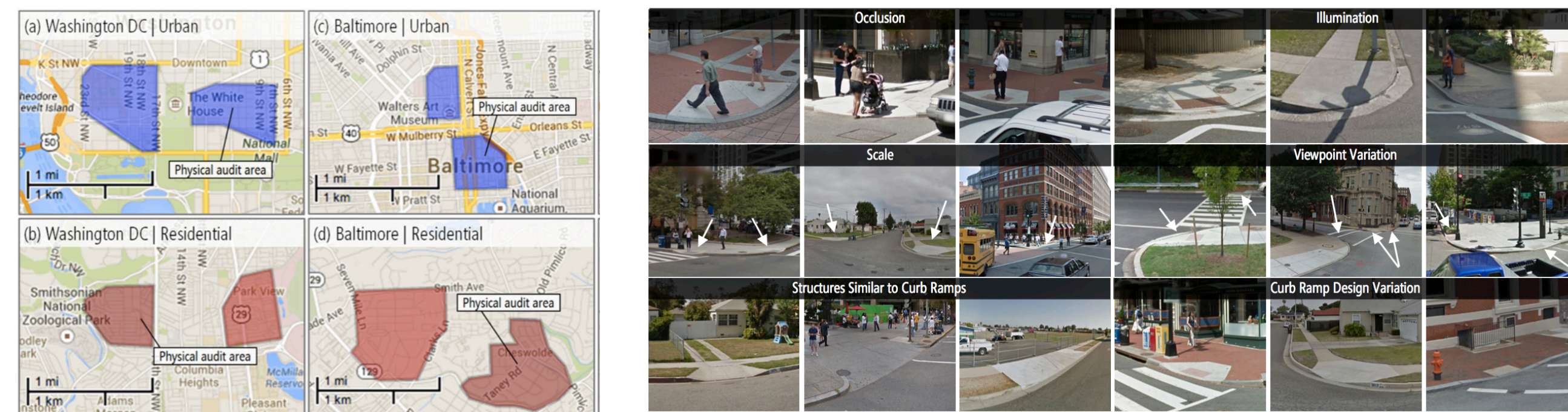


Introduction:

- ❑ Most of computer vision focuses on what is in an image.
- ❑ We train a standalone object-centric context representation to perform the *opposite* task: seeing what is not there.
- ❑ Missing objects region: where context says yes but the detector says no. **Our core idea is the object-context decomposition.**



- ❑ A challenging curb ramp dataset of four cities with large variations.

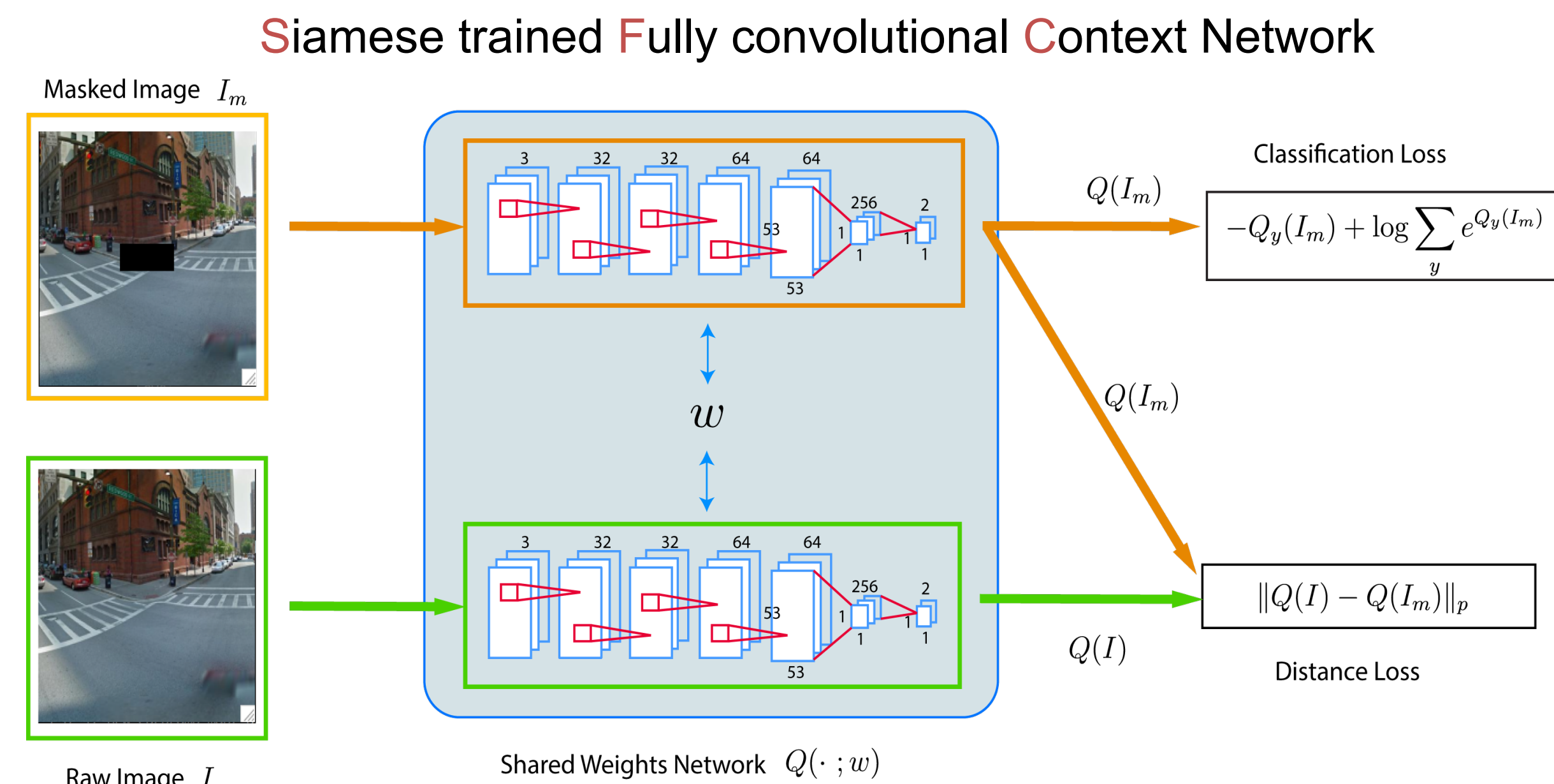


- ❑ Context plays a critical role in finding curb ramps: the appearance alone can be ambiguous.



Approach:

- ❑ With a specially designed training strategy, our Convolutional Neural Network model learns to ignore objects and focus on context only. It is fully convolutional thus highly efficient.

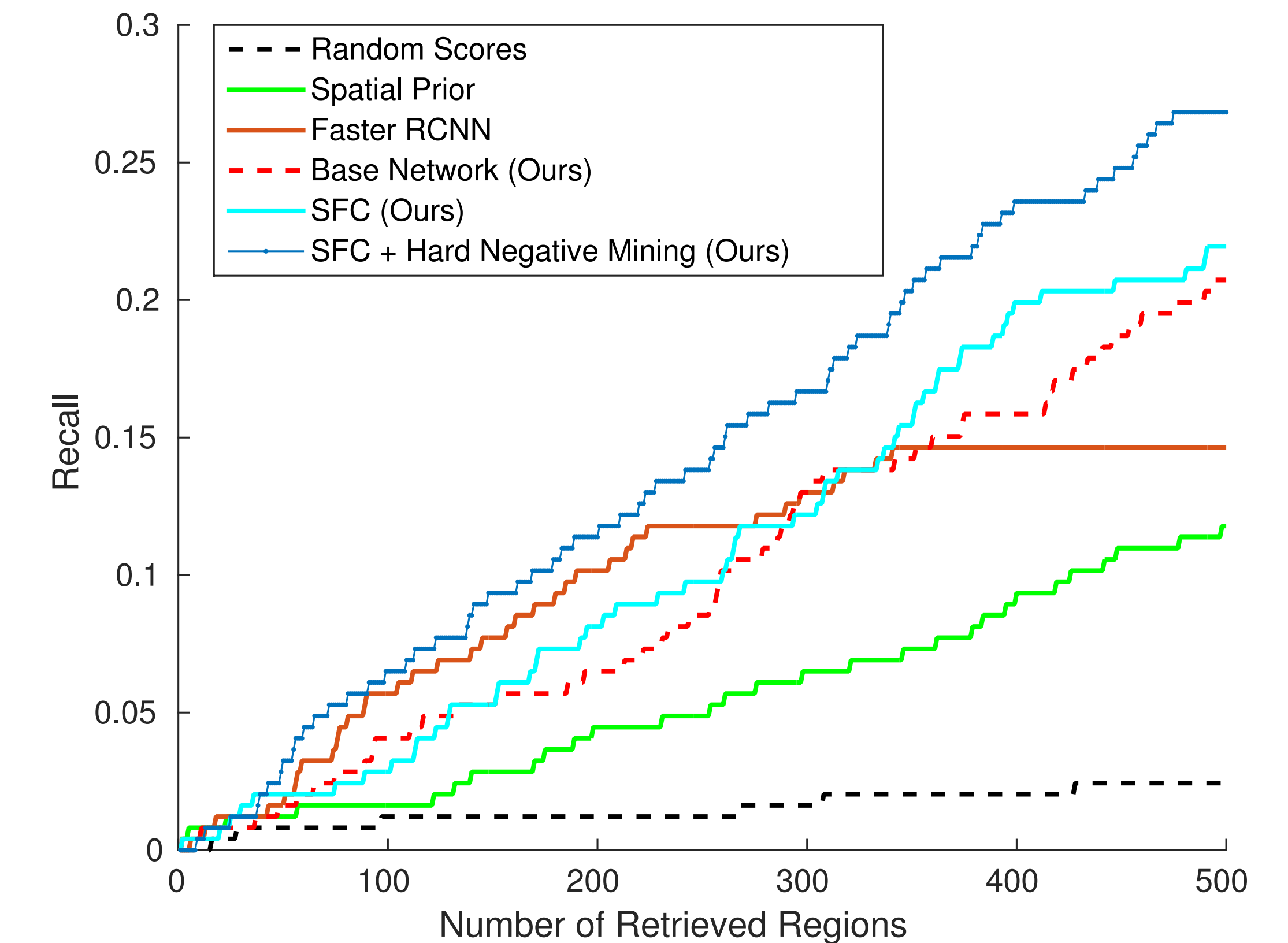


- The **classification loss** encourages the learning of useful context-only features with objects being masked out.
 - The **distance loss** enforces the network to extract same features regardless of whether an image is masked or not.
 - The SFC network is fully convolutional and doesn't require masks during testing: this gives a **speed-up** of a factor of 60, comparing to a naïve approach of directly training a classifier with masked images.
 - During training, the efficient fully convolutional structure allows us to do **hard negative mining** for improved performance.
- ❑ For a given Google Street View panorama image, the SFC network produces a high resolution probabilistic map of where a curb ramp should exist.



Results:

- ❑ Experiments show the effectiveness of the SFC network in finding missing curb ramp regions: our best method (SFC + Hard Negative Mining) can find 27% of true missing curb ramp regions.



- ❑ Note that the SFC network doesn't need any missing curb ramp labels! We learn context from normal curb ramp labels, which are more abundant and much easier to collect.
- ❑ Efficiency:
 - 20 mins human time → 500 regions → 27% recall.
 - 2,820 intersections in Manhattan (1.6 million population) → a few hours.
- ❑ Examples of found missing curb ramp regions:

