Learnable Irrelevant Modality Dropout for Multimodal Action Recognition on Modality-Specific Annotated Videos

(Supplementary Material)

1. Semantic Audio-Video Label Dictionary (SAVLD)

For building the SAVLD, we use **BERT-base uncased** in which the label text is lowercased before tokenizing it. Therefore, as a preprocessing step, we first normalized all textual labels into lowercase form. Notably, the resulting label dictionary SAVLD is not very accurate since the semantic gap between video and audio datasets is still large. It is also because the number of classes on video/audio datasets is still considered small (i.e. Kinetics400 has 400 labels and AudioSet has 527 label). However, using SAVLD dictionaries, our framework narrows the input noise by using the audio predictions. Then, it matches the audio scene to its closest similar visual class regardless of the fact that many audio classes do not have large relevance. In the training phase, the labeling process is guided by applying the IOU function between the AST predictions and the corresponding audio labels to the video label in the SAVLD dictionary. Table 3 shows a small part of the Kinetics 400-Audio Set label dictionary when k=5. Additionally, we visualize the AudioSet labels' relevance to Kinetics400 and UCF-101 labels in Fig. 2 and Fig. 4, respectively. The most frequent mapped audio labels to the vision-specific dataset labels are shown in Fig. 1 and Fig. 3 for Kinetics400 and UCF-101 datasets, respectively.¹

2. Further Results and Analysis

2.1. Experiments on HMDB51 and Kinetics-Sounds

We further evaluate our method against relevant methods for video-based action recognition in two more datasets

¹We implemented our framework in Pytorch in which we borrowed several parts from the following codebases: https://github.com/huggingface/transformers

https://github.com/YuanGongND/ast

https://github.com/facebookresearch/SlowFast

https://github.com/facebookresearch/TimeSformer

https://github.com/rwightman/pytorch-image-models

https://github.com/unixpickle/audioset

https://github.com/ekazakos/temporal-binding-network

https://github.com/marl/13embedding

https://github.com/johnarevalo/gmu-mmimdb

HMDB51 [6] and Kinetics-Sounds [8]. HMDB51 [6] is split into three overlapped splits. It contains 6,766 videos of 51 classes with an average length of 3 seconds. Kinetics-Sounds [1] is a subset from the original Kinetics400 [2] dataset. It contains 34 classes in which each class videos have a remarkable sound signature. Since Kinetics dataset editions are downloadable from YouTube, its size may vary by time as some videos may get removed. Herein, we use 19,627 videos for training and 1,344 videos for evaluation. length of 3 seconds. The average video length in this dataset is 10 seconds.

Table 1. Performance comparison to relevant visual-based methods (RGB + Optical Flow) on HMDB51 dataset.

Model	Top-1 (%)	
CoViAR [10]	59.1	
Two-stream fusion [5]	65.4	
TSN [9]	69.4	
I3D [2]	66.4	
CoViAR + OF [10]	70.2	
IMD-B (ours)	71.3	

Table 2. Performance comparison to relevant methods on Kinetics-Sounds dataset.

Model	P-train	Top-1 (%)
L3-Net [1]	IN-1K	74.0
SlowFast R101 [4]	IN-1K	77.9
AVSlowFast, R101 [11]	IN-1K	85.0
MBT (AV) [7]	IN-21K	85.0
IMD-B (ours)	IN-21K	90.48
IMD-B [⋆] (ours)	IN-21K	91.44

Table 1 reports the performance of several visual action recognition methods including CoViAR [10], Two-stream fusion [5], TSN [9], I3D [2], and CoViAR + OF [10]. Notably, our method provides a slight performance boost on HMDB51 because our method is a Transformer-based framework that shows better improvement on large datasets

Table 3. Samples of the most relevant AudioSet labels to video labels retrieved by semantic sentence-based embeddings mapping by BERT when K=5.

Dataset	Label	Relevant AudioSet Labels
Kinetics400	playing guitar applauding belly dancing canoeing or kayaking clean and jerk country line dancing driving car feeding birds gargling kissing pumping gas recording music scrambling eggs sniffing sneezing tickling yawning writing whistling welding	bass guitar;acoustic guitar;guitar;chopping food;electric guitar speech;applause;whistling;chime;clapping rapping;yodeling;synthetic singing;child singing;frying food rowboat, canoe, kayak;motorboat, speedboat;skateboard;folk music;sailboat, sailing ship fill with liquid;pump liquid;filing rasp;rumble;rustle female singing;dance music;male singing;salsa music;drum roll emergency vehicle;motor vehicle road;filing rasp;car;engine starting wild animals;insect;mosquito;bird;patter gargling;gurgling;snoring;reversing beeps;yodeling whispering;typing;cheering;laughter;breathing frying food;pump liquid;sawing;sanding;filing rasp vocal music;music;soundtrack music;wedding music;jingle music singing bowl;spray;thunder;wheeze;tools whimper;growling;cheering;whispering;rattle gurgling;snoring;babbling;gargling;rapping whispering;rustle;cheering;growling;screaming babbling;rapping;frying food;gurgling;snoring writing;speech;typing;chatter;mechanisms whistling;humming;whistle;whip;siren gears;scissors;drill;boiling;bicycle

in terms of number of videos per class. However, our framework provides top-1 of 71.3% which is better compared with CoViAR + OF [10] with a performance boost of $\sim 1.1\%$. We compare our method with several methods on the visual-audio annotated dataset Kinetics-Sounds. This dataset was first used in [1] as a subset of the main Kinetics400 dataset [2]. Our framework provides a significant boost in this dataset, where it provides top-1 of 90.48% and 91.44% with and without intra-class cross-modality augmentation, respectively. Since this dataset is an audio-video annotated in which audio and video are mostly relevant in each video, the cross-modality augmentation does not improve the performance. This interprets our finding regarding this augmentation method, where it provides most performance boosts on datasets with low audio-video relevance. Therefore, in our method, cross-modality augmentation is particularly applied for improving the video-based human activity recognition on vision-specific videos.

2.2. Visual Two-Stream Transformer Variants

In this part, we report the performance of three Transformer variants of the proposed two-stream visual Transformer. In order to leverage the pretrained ImageNet knowledge, we have adopted several parts from ViT [3] in terms of number of Transformer encoder blocks, embedding size, number of self-attention heads, input dimensions. Our Transformer scales properties are almost similar to the [3],

Table 4. Performance of the proposed visual two-stream Transformer with different size. Three Transformer instances are trained, where each of which is initialized with its ViT corresponding ImageNet-21K weights. The performance is reported on Kinetics400. Number of parameters is reported in million.

T. Size	Top-1 (%)	Top-5 (%)	Params	GFLOPs
Small	78.8	92.8	47.9×2	2,871
Base	81.1	94.3	88.6×2	4,464
Large	82.6	95.2	173.7×2	8,232

i.e. small, base, and large, except the spatiotemporal encoder blocks. We used one spatiotemporal block on the small encoder instance as it involves 8 blocks, whereas we add 2 and 4 spatiotemporal blocks for base and large instances as they involve 12 and 24 blocks, respectively. Table 4 reports the recognition performance on Kinetics400 dataset as well as the Transformer instances' costs in terms of number of parameters and GFLOPs.

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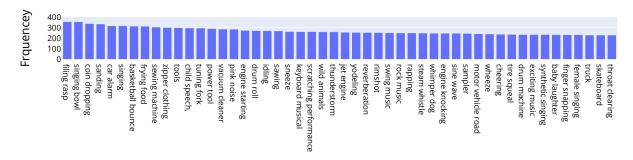


Figure 1. The most 50 frequent audio labels in AudioSet mapped to Kinetics 400 labels when k = 50.



Figure 2. The heatmap of the semantic relevance estimated by BERT between Kinetics400 labels and AudioSet labels. The darker the more relevant.

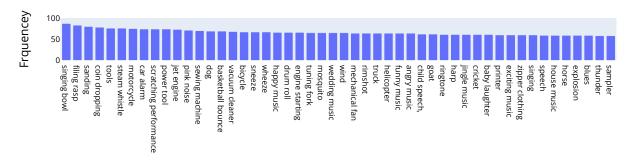


Figure 3. The most 50 frequent audio labels in AudioSet mapped to UCF-101 labels when k=50.

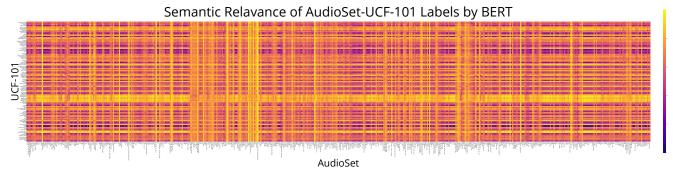


Figure 4. The heatmap of the semantic relevance estimated by BERT between UCF-101 labels and AudioSet labels. The darker the more relevant.

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