

## A. Implementation Details

For the single-view 3D reconstruction experiment, we closely orient ourselves on the setup by Liu *et al.* [1]. We use the same model architecture [1] and also train with a batch size of 64 for 250 000 steps using the Adam optimizer [2]. We also schedule the learning rate to  $10^{-4}$  for the first 150 000 steps and use a learning rate of  $3 \cdot 10^{-5}$  for the remaining training. At this point (after the first 150 000 steps), we also decrease the temperature  $\tau$  by a factor of 0.3.

Using different learning rates (as an ablation) did not improve the results.

## B. Distributions

In this section, we define each of the presented distributions / sigmoid functions. Figure 5 displays the respective CDFs and PDFs.

Note that, for each distribution, the PDFs  $f$  is defined as the derivative of the CDF  $F$ . Also, note that a reversed (Rev.) CDF is defined as  $F_{\text{Rev.}}(x) = 1 - F(-x)$ , which means that  $F_{\text{Rev.}} = F$  for symmetric distributions. The square-root distribution  $F_{\text{sq}}$  is defined in terms of  $F$  as in Equation (5). Therefore, in the following, we will define the distributions via their CDFs  $F$ .

### Heaviside

$$x \mapsto \begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{otherwise} \end{cases} \quad (6)$$

### Uniform

$$x \mapsto \begin{cases} 0 & \text{if } x < -1 \\ 0.5 \cdot (1 + x) & \text{if } -1 \leq x \leq 1 \\ 1 & \text{otherwise} \end{cases} \quad (7)$$

### Cubic Hermite

$$x \mapsto \begin{cases} 0 & \text{if } x < -1 \\ 3y^2 - 2y^3 & \text{if } -1 \leq x \leq 1 \\ 1 & \text{otherwise} \end{cases} \quad (8)$$

where  $y := (x + 1)/2$ .

### Wigner Semicircle

$$x \mapsto \begin{cases} 0 & \text{if } x < -1 \\ \frac{1}{2} + \frac{x\sqrt{1-x^2}}{\pi} + \frac{\arcsin(x)}{\pi} & \text{if } -1 \leq x \leq 1 \\ 1 & \text{otherwise} \end{cases} \quad (9)$$

### Gaussian

$$x \mapsto \frac{1}{2} \left( 1 + \text{erf} \left( \frac{x}{\sqrt{2}} \right) \right) \quad (10)$$

### Laplace

$$x \mapsto \begin{cases} \frac{1}{2} \exp(x) & \text{if } x \leq 0 \\ 1 - \frac{1}{2} \exp(-x) & \text{if } x \geq 0 \end{cases} \quad (11)$$

### Logistic

$$x \mapsto \frac{1}{1 + \exp(-x)} \quad (12)$$

### Hyperbolic secant / Gudermannian

$$x \mapsto \frac{2}{\pi} \arctan \left( \exp \left( \frac{\pi}{2} x \right) \right) \quad (13)$$

### Cauchy

$$x \mapsto \frac{1}{\pi} \arctan(x) + \frac{1}{2} \quad (14)$$

### Reciprocal

$$x \mapsto x/(2 + 2|x|) + 1/2 \quad (15)$$

### Gumbel-Max

$$x \mapsto e^{-e^{-x}} \quad (16)$$

### Gumbel-Min

$$x \mapsto e^{-e^x} \quad (17)$$

### Exponential

$$x \mapsto 1 - e^{-x} \quad (18)$$

### Levy

$$x \mapsto 2 - 2\Phi \left( \sqrt{\frac{1}{x}} \right) \quad (19)$$

where  $\Phi$  is the CDF of the standard normal distribution.

### Gamma

$$x \mapsto \frac{1}{\Gamma(p)} \gamma(p, x) \quad (20)$$

where  $\gamma(p, x)$  is the lower incomplete gamma function and  $p > 0$  is the shape parameter.

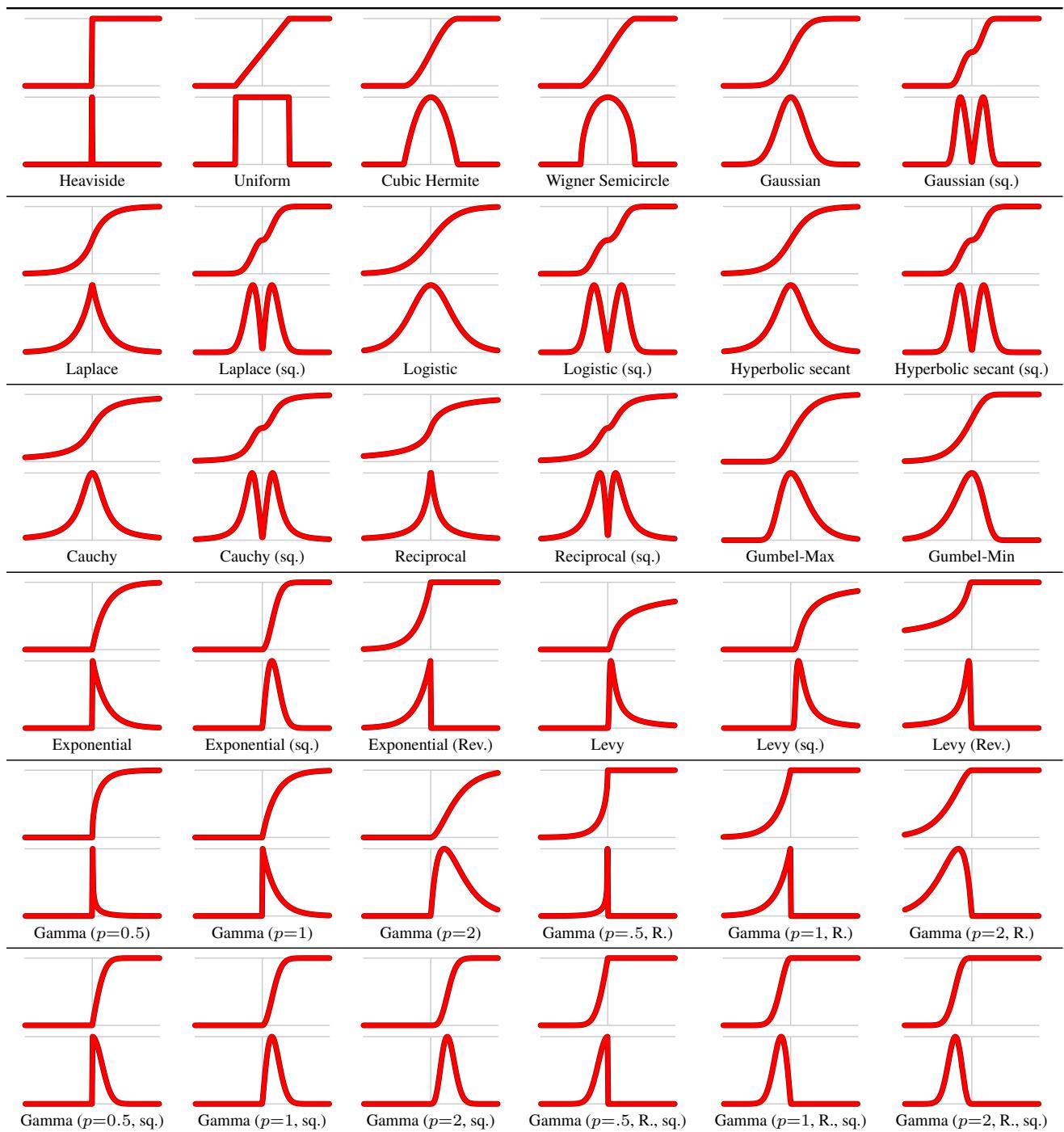


Table 5. Visualization of CDFs (top) and PDFs (bottom) for different distributions.

## C. T-Norms and T-Conorms

The axiomatic approach to multi-valued logics (which we need to combine the occlusions by different faces in a “soft” manner) is based on defining reasonable properties for truth functions. We stated the axioms for multi-valued generalizations of the disjunction (logical “or”), called T-conorms, in Definition 2. Here we complement this with the axioms for multi-valued generalizations of the conjunction (logical “and”), which are called T-norms.

**Definition 6** (T-norm). A T-norm (triangular norm) is a binary operation  $\top : [0, 1] \times [0, 1] \rightarrow [0, 1]$ , which satisfies

- *associativity*:  $\top(a, \top(b, c)) = \top(\top(a, b), c)$ ,
- *commutativity*:  $\top(a, b) = \top(b, a)$ ,
- *monotonicity*:  $(a \leq c) \wedge (b \leq d) \Rightarrow \top(a, b) \leq \top(c, d)$ ,
- *1 is a neutral element*:  $\top(a, 1) = a$ .

Clearly these axioms ensure that the corners of the unit square, that is, the value pairs considered in classical logic, are processed as with a standard conjunction: neutral element and commutativity imply that  $(1, 1) \mapsto 1$ ,  $(0, 1) \mapsto 0$ ,  $(1, 0) \mapsto 0$ . From one of the latter two and monotonicity it follows  $(0, 0) \mapsto 0$ . Analogously, the axioms of T-conorms ensure that the corners of the unit square are processed as with a standard disjunction. Actually, the axioms already fix the values not only at the corners, but on the boundaries of the unit square. Only inside the unit square (that is, for  $(0, 1)^2$ ) T-norms (as well as T-conorms) can differ.

Minimum	$\top^M(a, b) = \min(a, b)$
Probabilistic	$\top^P(a, b) = ab$
Einstein	$\top^E(a, b) = \frac{ab}{2-a-b+ab}$
Hamacher	$\top_p^H(a, b) = \frac{ab}{p+(1-p)(a+b-ab)}$
Frank	$\top_p^F(a, b) = \log_p \left( 1 + \frac{(p^a - 1)(p^b - 1)}{p-1} \right)$
Yager	$\top_p^Y(a, b) = \max \left( 0, 1 - ((1-a)^p + (1-b)^p)^{\frac{1}{p}} \right)$
Aczél-Alsina	$\top_p^A(a, b) = \exp \left( -( \log(a) ^p +  \log(b) ^p)^{\frac{1}{p}} \right)$
Dombi	$\top_p^D(a, b) = \left( 1 + \left( \left( \frac{1-a}{a} \right)^p + \left( \frac{1-b}{b} \right)^p \right)^{\frac{1}{p}} \right)^{-1}$
Schweizer-Sklar	$\top_p^S(a, b) = (a^p + b^p - 1)^{\frac{1}{p}}$

Table 6. (Families of) T-norms.

In the theory of multi-valued logics, and especially in fuzzy logic [3], it was established that the largest possible T-norm is the minimum and the smallest possible T-conorm is the maximum: for any T-norm  $\top$  it is  $\top(a, b) \leq \min(a, b)$  and for any T-conorm  $\perp$  it is  $\perp(a, b) \geq \max(a, b)$ . The other extremes, that is, the smallest possible T-norm and the largest possible T-conorm are the so-called drastic T-norm, defined as  $\top^\circ(a, b) = 0$  for  $(a, b) \in (0, 1)^2$ , and the drastic T-conorm, defined as  $\perp^\circ(a, b) = 1$  for  $(a, b) \in (0, 1)^2$ . Hence it is  $\top(a, b) \geq \top^\circ(a, b)$  for any T-norm  $\top$  and  $\perp(a, b) \leq \perp^\circ(a, b)$  for any T-conorm  $\perp$ . We do not consider the drastic T-conorm for an occlusion test, because it clearly does not yield useful gradients.

As already mentioned in the paper, it is common to combine a T-norm  $\top$ , a T-conorm  $\perp$  and a negation  $N$  (or complement, most commonly  $N(a) = 1 - a$ ) so that DeMorgan’s laws hold. Such a triplet is often called a *dual triplet*. In Tables 6 and 7 we show the formulas for the families of T-norms and T-conorms, respectively, where matching lines together with the standard negation  $N(a) = 1 - a$  form dual triplets. Note that, for some families, we limited the range of values for the parameter  $p$  (see Table 2) compared to more general definitions [3].

### C.1. T-conorm Plots

Figures 7 and 8 display the considered set of T-conorms.

Maximum	$\perp^M(a, b) = \max(a, b)$
Probabilistic	$\perp^P(a, b) = a + b - ab$
Einstein	$\perp^E(a, b) = \perp_2^H(a, b) = \frac{a+b}{1+ab}$
Hamacher	$\perp_p^H(a, b) = \frac{a+b+(p-2)ab}{1+(p-1)ab}$
Frank	$\perp_p^F(a, b) = 1 - \log_p \left( 1 + \frac{(p^{1-a}-1)(p^{1-b}-1)}{p-1} \right)$
Yager	$\perp_p^Y(a, b) = \min \left( 1, (a^p + b^p)^{\frac{1}{p}} \right)$
Aczél-Alsina	$\perp_p^A(a, b) = 1 - \exp \left( -( \log(1-a) ^p +  \log(1-b) ^p)^{\frac{1}{p}} \right)$
Dombi	$\perp_p^D(a, b) = \left( 1 + \left( \left( \frac{1-a}{a} \right)^p + \left( \frac{1-b}{b} \right)^p \right)^{-\frac{1}{p}} \right)^{-1}$
Schweizer-Sklar	$\perp_p^S(a, b) = 1 - ((1-a)^p + (1-b)^p - 1)^{\frac{1}{p}}$

Table 7. (Families of) T-conorms.

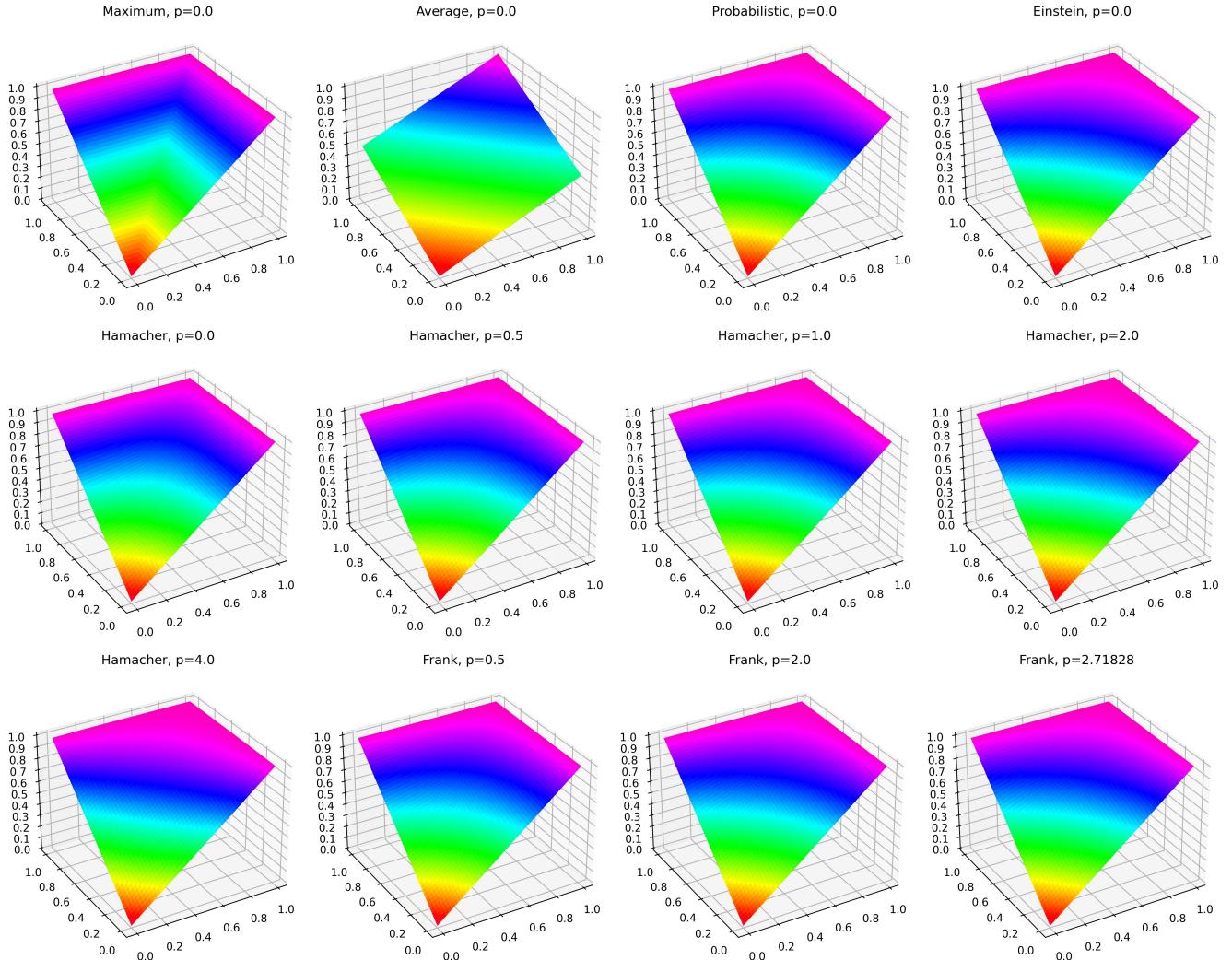


Figure 7. T-conorm plots (1/2). Note that ‘Average’ is not a T-conorm and just included for reference. Also, Note how ‘Probabilistic’ is equal to ‘Hamacher  $p = 1$ ’ and ‘Einstein’ is equal to ‘Hamacher  $p = 2$ ’.

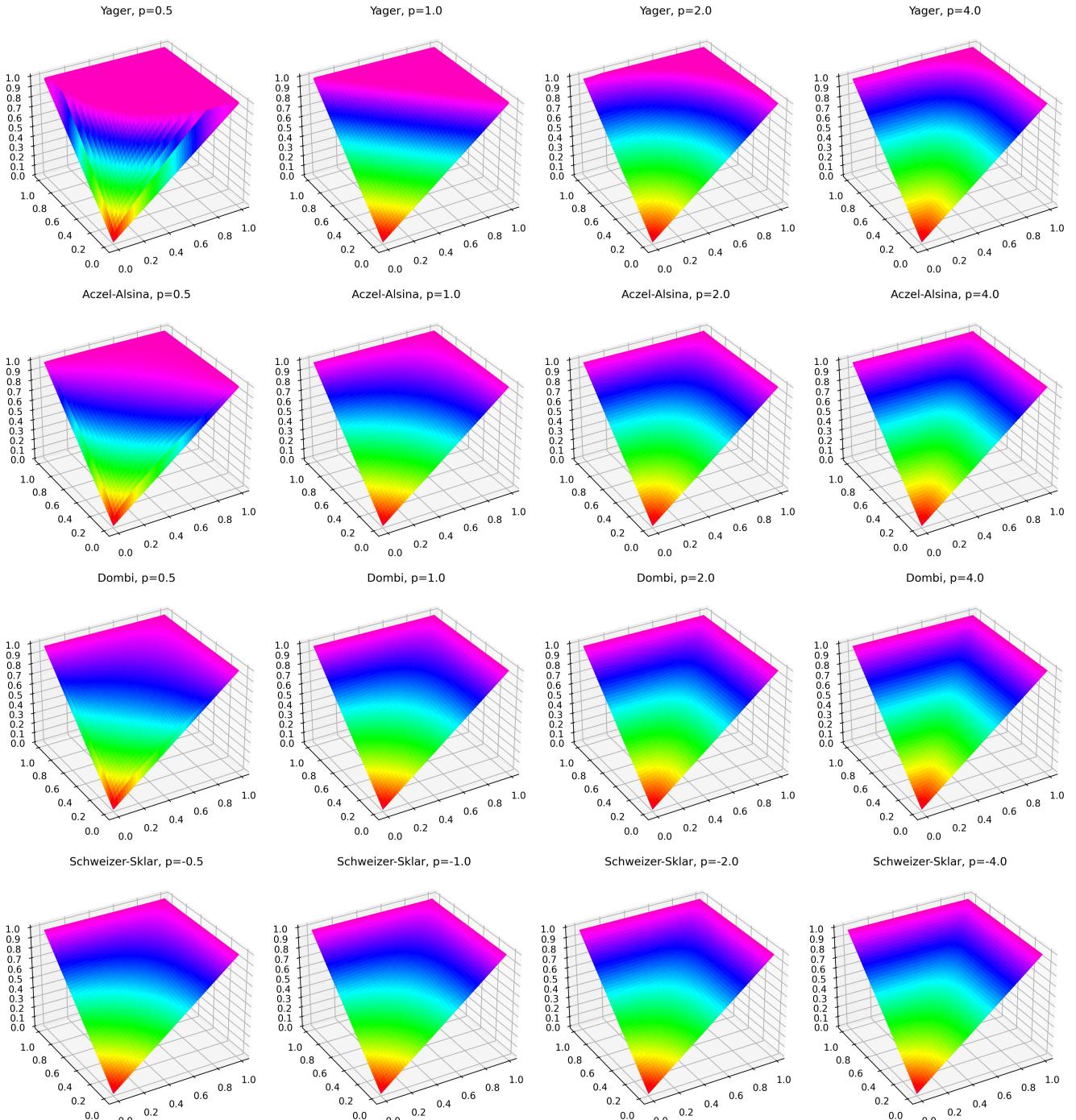


Figure 8. T-conorm plots (2/2).

## D. Additional Plots

See Figures 9 and 10.

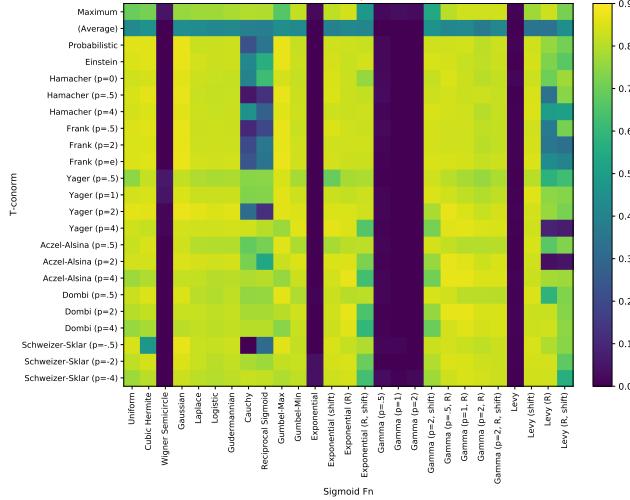


Figure 9. Results for the tea pot camera pose optimization task for the respective square-root distribution  $F_{\text{sq}}$ .

## References

- [1] S. Liu, T. Li, W. Chen, and H. Li, “Soft Rasterizer: A Differentiable Renderer for Image-based 3D Reasoning,” in *Proc. International Conference on Computer Vision (ICCV)*, 2019.
- [2] D. Kingma and J. Ba, “Adam: A method for stochastic optimization,” in *International Conference on Learning Representations (ICLR)*, 2015.
- [3] G. J. Klir and B. Yuan, *Fuzzy Sets and Fuzzy Logic — Theory and Applications*. Upper Saddle River, New Jersey: Prentice Hall, 1995.

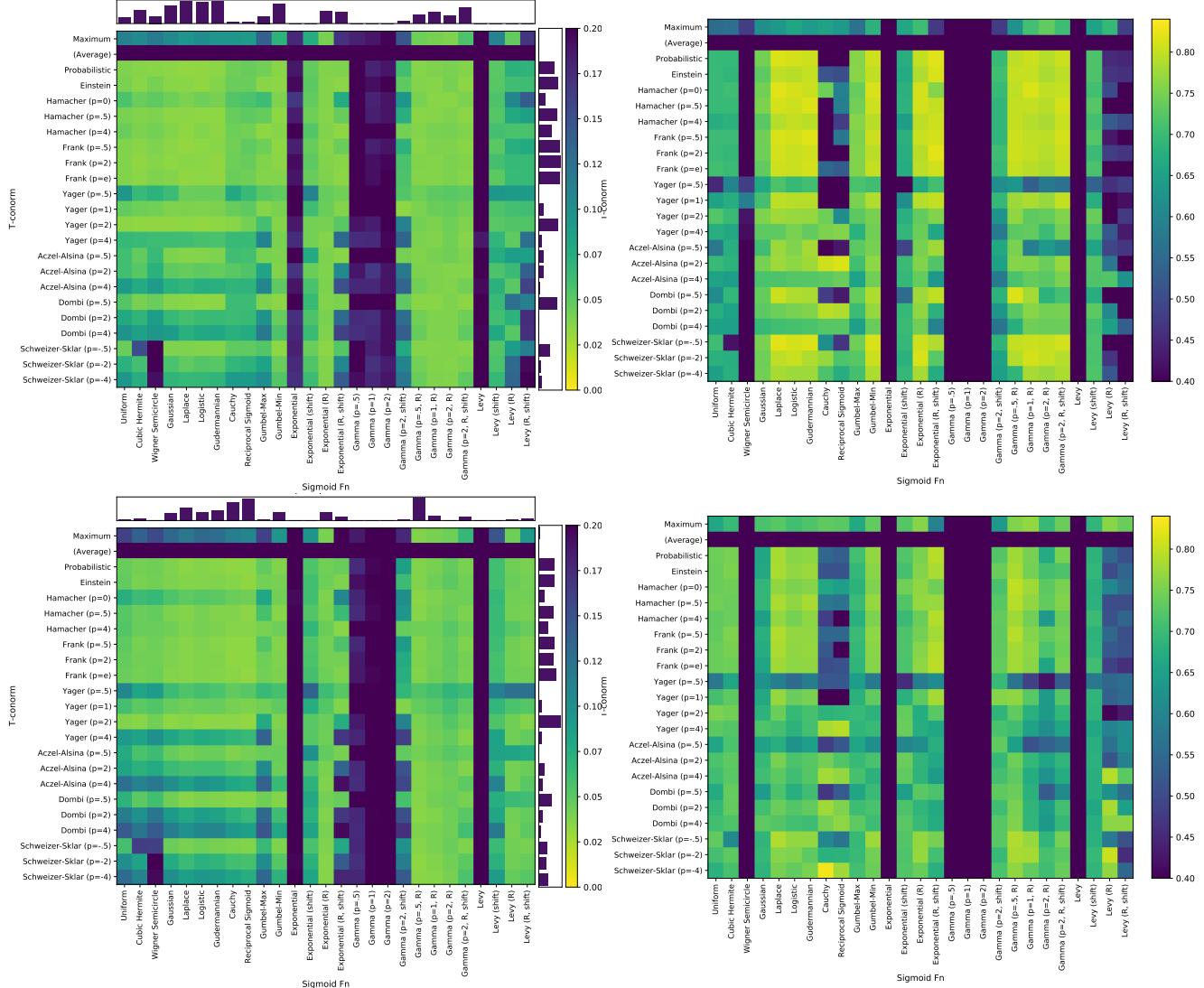


Figure 10. Shape optimization (left) and camera pose optimization (right) applied to a model of a chair. Top: set of original distributions  $F$ . Bottom: set of the respective square-root distributions  $F_{\text{sq}}$