

# On-Sensor Binarized Fully Convolutional Neural Network for Localisation and Coarse Segmentation

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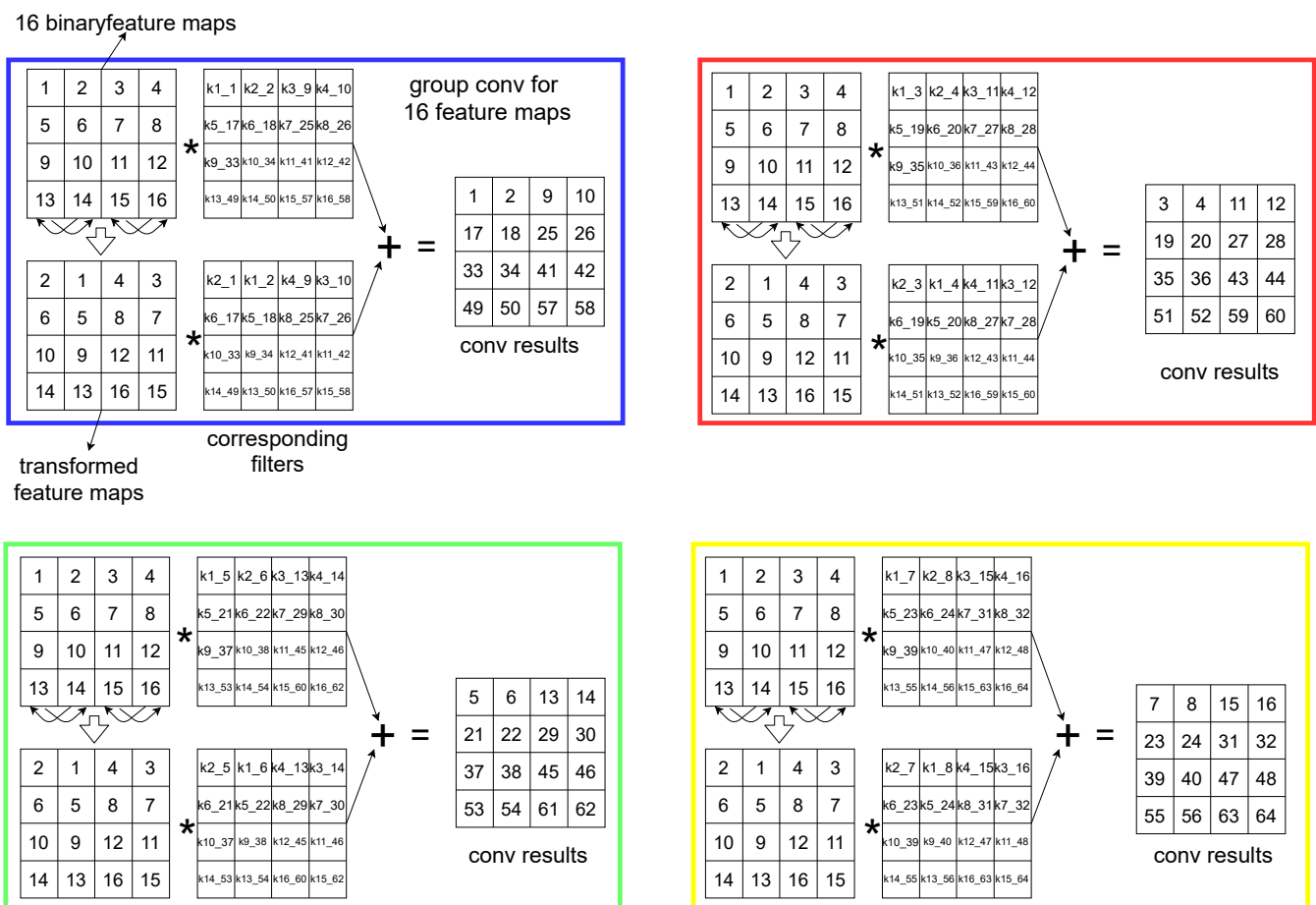


Figure 1. 64 feature map generation on sensor after group convolution.

Fig. 1 shows the layouts and operations of input 16 binary feature maps, 128 kernel filters, 64 generated feature maps.