REVEAL: Retrieval-Augmented Visual-Language Pre-Training with Multi-Source Multimodal Knowledge Memory

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Figure 1. Examples of VQA pairs from OKVQA benchmark that REVEAL correctly generate the answer.

*This work was done when Ziniu was an intern at Google.
A. More Qualitative Examples

We show examples of visual question answering and image captions in Figure 1-3.

For visual question answering, we select four examples that correctly answer the question in Figure 1, and three examples that our model predicts wrongly. For both cases, the REVEAL could learn to retrieve relevant information from diverse knowledge sources. For example, in the first question in Figure 1, REVEAL retrieves two VQA pairs from VQA-v2 datasets relevant to tennis playing to provide information, and in the second question REVEAL correctly retrieves the Wikipedia page about trolleybuses in San Francisco to answer where the bus might appear. The third example utilizes the image caption pairs from CC12M, which encodes the commonsense knowledge that a crowd of people might indicate they are rushing towards the train station to catch up deadline. These examples show that the corpus gating module in REVEAL could help identify the most useful knowledge source for different questions. In addition, the Top-100 retrieved knowledge might come from different knowledge sources, and the model could jointly reason with these diverse knowledge entries to get correct answers.

We are also interested to see whether the retrieved knowledge still makes sense for those QA pairs that REVEAL does not make the correct prediction. In Figure 2 we show such examples. For the first question asking the breed of cows, REVEAL retrieves two species of cow, one from Aberdeen Angus, a formal name for black Angus, and the other is Gloucester. The model’s prediction, i.e., “Black Angus” is mainly based on the Top-1 retrieved knowledge. Though this prediction is not listed in the ground-truth answers, it is very close to the ground-truth short-horn Angus. Similarly, in the second question that asks the name of surfing equipment, our model retrieves both the Wikipedia page and Wikidata triplets about surfboard and generates this as the answer. Though it is not exactly the same as a ground-truth answer, i.e., “surfer”, we think it is another way to say about this equipment. Similar to these two examples, there are many other ones that our model retrieves relevant information but the predicted results are not the same as the ground-truth. Also there are several examples in which the retrieved knowledge is less useful. For example, in the third question that
asks which baseball team is in the image, though our model retrieves several other baseball teams, they are not the same as the ground-truth ones. For these complex questions, it is still space for our model to improve and learn the subtle
Hyperparameter Sensitivity Analysis

Analyzing number of retrieved knowledge \( K \)  From the results, we can first see that increasing number of retrieved knowledge \( K \) could consistently improve the performance, and the improvement is not significantly different from 50 and 100. This fits our hypothesis that we require to jointly reason over multiple knowledge to make correct prediction.

Analyzing numbers of compressed tokens \( c \)  Regarding value compression, we first compare different numbers of compressed tokens \( c \) for the Perceiver model. For each different \( c \) we pre-train the ReVEAL-Base from scratch and report their fine-tuning results. As is shown in the table, \( c = 32 \) achieves the best performance, even higher than \( c = 64 \). This is probably because 32 tokens are enough to encode the knowledge information via proper modeling and disentangle regularization. By further increasing the number of tokens, the added capacity will not bring more critical information. Therefore, we choose \( c = 32 \) throughout our study.

Analyzing regularization for Perceiver  Besides, we also conduct ablation of the two regularization loss we added to guide learning a more informative compression model. We report the result pre-trained without de-correlation loss \( L_{\text{decor}} \) and without alignment loss \( L_{\text{align}} \). As shown in the second block of the table, each regularization loss plays an important role in the final performance, and incorporating both could lead to optimal performance.

Another baseline for knowledge compression  We further add another naive baseline for compression: take the first 32 tokens from the encoder, i.e., \( b(z)[:,32] \). As is illustrated, this method performs much worse than Perceiver, probably because the first 32 tokens in the input sentence are not always the best summarization of the whole knowledge. At the same time, Perceiver could use cross-attention to query the whole sequence properly, and keep the most important information.

Ablation on Pre-Training Corpus

To strike a balance between performance and efficiency, we choose to use \( K = 100 \) for all fine-tuning tasks.

<table>
<thead>
<tr>
<th>Pre-Training Corpus</th>
<th>OKVQA Accuracy</th>
</tr>
</thead>
<tbody>
<tr>
<td>WIT (5M)</td>
<td>51.1</td>
</tr>
<tr>
<td>WIT w/o ( L_{\text{contra}} )</td>
<td>47.6</td>
</tr>
<tr>
<td>CC12M (12M)</td>
<td>53.6</td>
</tr>
<tr>
<td>Web-Image-Text (1.3B)</td>
<td>55.2</td>
</tr>
</tbody>
</table>

Table 2. Ablation on Pre-Training Corpus: We pre-train ReVEAL-Base on WIT and CC12M dataset, and report the fine-tuned OKVQA performance.
for retrieving necessary knowledge. Comparing with the frozen ViT, the trained ViT achieve +2.3 and +2.6 higher performance on the two settings. This shows that our retrieval-augmented training is also useful for getting better retriever, even we directly start from strong ViT checkpoint.

E. More Implementation Details of Model

In this section, we provide more details of our model architecture, specifically the Perceiver, Attentive fusion module and online distributed MIPS retrieval.

E.1. Perceiver as Value Compression Head

As we described in the method section of the submission, we propose to compress the full token embedding sequence into a shorter sequence by using the Perceiver model [?].

Perceiver is a standard Transformer Decoder model that uses a learnable latent embedding $\text{Emb}_{\text{Latent}}$ as input query, and the full embedding sequence to be compressed $b(z)$ as key and value. For each layer, the perceiver first uses a cross-attention module to compress a $l$-length full embedding sequence $b(z) \in \mathbb{R}^{l \times d}$ into the $c$-length queries by $\text{Emb}_{\text{Latent}} \in \mathbb{R}^{c \times d}$, followed by self-attention in the latent space. We write the full compression operation as below:

$$
\begin{align*}
\text{Input: } Z^0 &= \text{Emb}_{\text{Latent}} \in \mathbb{R}^{c \times d}, \\
B &= \text{LayerNorm}(b(z)) \in \mathbb{R}^{l \times d}, \\
\text{for layer } l \text{ for each Perceiver layers do} \\
Z^l &= \text{LayerNorm}(Z^{l-1}) \\
\hat{Z}^l &= \text{Cross-Attn} (\text{Query} = \hat{Z}^l, \text{Key&Value} = B) + Z^{l-1} \\
\hat{Z}^l &= \text{Self-Attn} \left( \text{LayerNorm}(\hat{Z}^l) \right) + \hat{Z}^l \\
Z^l &= \text{MLP} \left( \text{LayerNorm}(\hat{Z}^l) \right) + \hat{Z}^l \\
\text{end for} \\
\text{Return: } \psi(b(z)) = Z^L \in \mathbb{R}^{c \times d}
\end{align*}
$$

We denote $Z^l$ as $l$-th layer’s output, and $\hat{Z}^l$ as intermediate representation. After stacking $L$ Perceiver layers, we could learn a meaningful short $c$-length compressed embedding sequence $Z^L$ to represent the original full sequence. To implement Perceiver that is consistent with the remaining model architecture, we use the standard T5 Decoder with randomly initialized latent embedding $\text{Emb}_{\text{Latent}}$.

F. Attentive Fusion

In this section, we provide more details about the Attentive fusion module in our model. The attentive fusion module aims to allow end-to-end training of the retriever and generator weights. Without this fusion module, the retriever is not involved in the final answer generation procedure and will not receive gradients. Some of the previous work [? ,?] utilize alternative training signals for updating retriever. They
We use one knowledge entry at a time instead of using all Top-K and use the corresponding generation accuracy as the training signal. This approach is not guaranteed to be optimal for multi-knowledge retrieval. It is also very inefficient if we want to retrieve up-to-hundred knowledge items.

Our solution is to inject the retrieval score as a soft attention mask into the fusion and decoding process, as illustrated in Figure 4. At each Transformer Layer before attention calculation, we multiply the retrieval probability \( p(z_i|x) \) to each token embedding belonging to knowledge \( z_i \). We denote the concatenated query embedding and memory values as \( X = [b(x), \psi(b(z_1)), \ldots, \psi(b(z_K))] \in \mathbb{R}^{(I+c-K) \times d} \), where \( I \) is the number of tokens of the input query \( x \) and \( c \) is the number of compressed tokens. Based on the top-\( K \) retrieved knowledge \( Z = [z_1, \ldots, z_K] \) with key and value embeddings, we could calculate the probability over these top-\( K \) knowledge similar to eq.(3):

\[
\begin{align*}
p(z_i | x) &= \frac{\exp \left( \text{Gate}_{\mathcal{M}Z}(z_i) \cdot \text{Rel}(x,z_i)/\tau \right)}{\sum_{j=1}^{K} \exp \left( \text{Gate}_{\mathcal{M}Z}(z_j) \cdot \text{Rel}(x,z_j)/\tau \right)},
\end{align*}
\]

where \( \text{Rel}(x,z_i) = \text{Emb}_{\text{Query}}(x)^T \cdot \text{Emb}_{\text{Key}}(z_i) \)\] (2)

\[
\phi_{\text{query}}(b(x))^{T} \cdot \phi_{\text{key}}(b(z_i)) \)\] (3)

Here we denote \( \mathcal{M}Z(z_i) \) as the indicator function returning corpus ID of retrieved knowledge \( z_i \), such that \( \mathcal{M}Z = \mathcal{M}Z(z_i) \). Note that the difference of this probability within Top-K results differ with eq.(2) in that we only summing over the \( K \) subset results, and also we merge the gating score into the softmax to make the output a probability that summing to one. We then construct a latent soft attention mask over \( X \) as:

\[
\text{Mask}_{\text{att}} = \left[ \frac{1}{l}, \ldots, \frac{1}{l} \right], \left[ p(z_1 | x), \ldots, p(z_1 | x) \right], \ldots, \left[ p(z_K | x), \ldots, p(z_K | x) \right], \ldots,
\]

Then, within the attentive fusion module, we multiply this attention mask \( \text{Mask}_{\text{att}} \) to the whole embedding sequence. We write the full attentive fusion operation as below:

\begin{algorithm}[H]
\caption{Attentive Fusion Operation (\( F(\cdot) \))}
\begin{algorithmic}
\State \textbf{Input:} \( X^0 = [b(x), \psi(b(z_1)), \ldots, \psi(b(z_K))] \).
\State \textbf{Calculate} \( \text{Mask}_{\text{att}} \in \mathbb{R}^{(I+c-K) \times 1} \) \text{following Eq.}(4).
\For{layer \( l \) for each Fusion layers}
\State \( \hat{X}^l = \text{Mask}_{\text{att}} \cdot \text{LayerNorm}(X^{l-1}) \)
\State \( \hat{X}' = \text{Self-Attention}(\hat{X}^l) + X^{l-1} \)
\State \( X^l = \text{MLP}(\text{LayerNorm}(\hat{X}^l)) + \hat{X}' \)
\EndFor
\State \textbf{Return:} \( F(X) = X^L \in \mathbb{R}^{(I+c-K) \times d} \)
\end{algorithmic}
\end{algorithm}

We denote \( X^l \) as \( l \)-th layer’s output, and \( \hat{X}^l \) as intermediate representation. The critical difference is shown in eq.(4), in which we multiply \( \text{Mask}_{\text{att}} \) to the pre-normalized representation (T5 utilizes pre-norm which satisfies our purpose). In this way, when we calculate the attention within the self-attention operation, the attention scores each knowledge sends to other position \( c_{i,j} \) is proportional to \( p(z_i|x) \). This reflects the importance of this knowledge \( z_i \) to make the final prediction. By multiplying the retrieval score as prior and through end-to-end training, the retriever could be learned to identify those samples that are more important to final output generation. This is similar to adopting a posterior estimation \( p(z|x,y) \), which takes output answer \( y \) as condition, to optimize the retriever model better.

This modified retrieval injected fusion layer is also similar to the Mixture-of-Expert (MOE) model, in which the retrieval is like a gating layer to select knowledge, and the knowledge representation serves as the expert. In this way, we turn the discrete knowledge retrieval/selection learning into a continuous learning problem, and the whole model could be learned end-to-end.

**F.1. Online Distributed MIPS Retrieval**

To strike a balance between training efficiency and scalability, we store the key embedding memory on TPU, and store the value sequence embeddings (each sequence contains \( c = 32 \) token embeddings) and raw dataset in the local host’s CPU memory. Then, when doing retrieval, each device first conduct MIPS operation over on-device memory to find local Top-K entry ID, then syncs the results across TPU devices to get global Top-K, and then returns the corresponding results. The detailed procedure is as follows:

This distributed retrieval could be done in a hierarchical manner if we group multiple TPUs into the same host, so we could first find Top-K by syncing within each host, and then syncing across host to find global Top-K, which further reduce the communication redundancy.
Algorithm 3 Online Distributed MIPS Retrieval

Input: Batch query $\text{Emb}_{\text{query}} \in \mathbb{R}^{b_{\text{bsz}} \times d}$, Local On-TPU key embeddings $\text{Key}(\mathcal{M}) \in \mathbb{R}^{\mid\mathcal{M}\mid \times d}$, Local On-CPU values $\text{DB}(\mathcal{M})$.

For each TPU device:

$\hat{\text{Emb}}_{\text{query}} = \text{Gather}(\text{Emb}_{\text{query}})$

$\text{local\_scores} = \hat{\text{Emb}}_{\text{query}}^T \cdot \text{Emb}_{\text{key}}(\mathcal{M})$

$\text{local\_ids} = \text{Approx\_Top\_K}(\text{local\_scores})$

$\text{local\_vals} = \text{DB}(\mathcal{M}).\text{Lookup}(\text{local\_ids})$

$\text{global\_scores} = \text{Gather}(\text{local\_scores})$

$\text{global\_ids} = \text{Top\_K}(\text{global\_scores})$

Return: $\text{Gather}(\text{local\_scores}).\text{Batch\_Select}(\text{global\_ids})$