

# The Wisdom of Crowds: Temporal Progressive Attention for Early Action Prediction – Supplementary Material

Table S1. Ablation studies across scales  $n = \{1, 2, 3, 4\}$  on UCF-101 over different observation ratios ( $\rho$ ). Methods are grouped w.r.t. the backbone used. The best overall performance per  $\rho$  is in **bold** and the second best results are underlined.

Method	Backbone	dim	Observation ratios ( $\rho$ )								
			0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
<b>TemPr – (ours)</b>	X3D <sub>M</sub>	3D	84.8	91.8	92.3	92.6	93.0	93.4	93.5	93.6	93.6
<b>TemPr = (ours)</b>			85.3	92.3	92.8	93.7	93.9	93.9	94.2	94.4	94.3
<b>TemPr <math>\leq</math> (ours)</b>			87.4	93.3	93.9	94.4	94.0	94.2	94.4	94.9	94.9
<b>TemPr <math>\leq</math> (ours)</b>			<u>87.9</u>	<u>93.4</u>	<u>94.5</u>	<u>94.8</u>	95.1	<b>95.2</b>	<b>95.6</b>	<u>96.4</u>	<b>96.3</b>
<b>TemPr – (ours)</b>	MoViNet-A4	3D	85.2	92.1	92.5	92.9	93.3	93.7	93.5	93.8	93.7
<b>TemPr = (ours)</b>			85.6	92.9	93.6	94.5	94.4	94.2	94.2	94.6	94.8
<b>TemPr <math>\leq</math> (ours)</b>			87.3	93.1	<b>94.9</b>	94.6	<u>95.2</u>	<u>94.9</u>	94.6	95.1	95.0
<b>TemPr <math>\leq</math> (ours)</b>			<b>88.6</b>	<b>93.5</b>	<b>94.9</b>	<b>94.9</b>	<b>95.4</b>	<b>95.2</b>	<u>95.3</u>	<b>96.6</b>	<u>96.2</u>

Table S2. Top tower predictors per class and observation ratio for TemPr  $\leq$ . Towers  $\mathcal{T}_1 \leq$ ,  $\mathcal{T}_2 \leq$ ,  $\mathcal{T}_3 \leq$  and  $\mathcal{T}_4 \leq$  are highlighted for better readability.

class name	Observation ratios $\rho$					
	0.1	0.2	0.3	0.5	0.7	0.9
Putting smthng similar to other things ...	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$
Showing smthng behind smthng	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$
Holding smthng	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$
Poking ... smthng without ... collapsing	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$
Pretending to sprinkle air onto smthng	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$
Pulling two ends of smthng ... stretched	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$
Putting smthng into smthng	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_4$
Pretending to turn smthng upside down	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_4$
Poking a stack of smthng ... collapses	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_e$
Pulling smthng from left to right	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_e$
Pushing smthng from left to right	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_4$
Pretending to open smthng without ...	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_2$
Opening smthng	$\mathcal{T}_4$	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_2$
Showing a photo of smthng ...	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_1$
Stuffing smthng into smthng	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_2$
Putting smthng on the edge of smthng ...	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_4$	$\mathcal{T}_2$	$\mathcal{T}_1$	$\mathcal{T}_1$
Picking smthng up	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_1$	$\mathcal{T}_2$
Closing smthng	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_3$	$\mathcal{T}_2$
Putting smthng upright on the table	$\mathcal{T}_4$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_1$	$\mathcal{T}_2$	$\mathcal{T}_2$
Turning smthng upside down	$\mathcal{T}_3$	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_1$
Pulling two ends of smthng ... two pieces	$\mathcal{T}_3$	$\mathcal{T}_2$	$\mathcal{T}_1$	$\mathcal{T}_2$	$\mathcal{T}_2$	$\mathcal{T}_2$

notable improvements on smaller observation ratios. For  $\rho = 0.1$  TemPr  $\leq$  demonstrates a +3.1% improvement from TemPr – on X3D<sub>M</sub> and +3.6% on MoViNet-A4.

**Top tower predictor per class.** To better understand the performance of individual towers  $\mathcal{T}_i$ , we compare their performance across SSsub21 classes. In Table S2, we present the top-performing tower for each class across observation ratios. Overall, we observe that towers trained on larger scales ( $\mathcal{T}_3 \leq$  and  $\mathcal{T}_4 \leq$ ) are better suited for classes that also include long-term dependencies. E.g. classes such as *Poking a stack of something without the stack collapsing*, *Pretending to sprinkle air onto something*, *Showing something behind something*, or *Putting something into something*, require a larger part of the action to be observable to become distinguishable. In contrast, towers for smaller scales, are better suited for classes such as *Picking something up*, *Closing something*, or *Turning something upside down*, which are distinguishable from only a few frames.

**SSsub21 class accuracies.** To further determine the performance of tower predictors in Table S2, we show in Figure S1 the per-class accuracies of all towers for  $\rho = 0.3$ . Overall, because features are more motion-based compared to UCF-101, coarser scales perform better. Considering the *Putting something on the edge of something so it is not supported and falls down* class, the object will typically fall down only at the end of the action. Therefore, such information is better captured by the coarser scales. Similarly, for *Pretending to sprinkle air onto something*, pretending can only be captured over a longer temporal scale. Fine scales perform more favorably for shorter actions such as *Closing something*, *Picking something up*, and *Turning something*

## S1. Cross-scale accuracy and class predictions

**Scale configurations.** Supplementary to Table 1 in the main text, we consider the two top-performing backbones in Table S1 and ablate over four scale configurations on UCF-101.

For both models, and across observation ratios, TemPr  $\leq$  outperforms all other scale configurations with the most

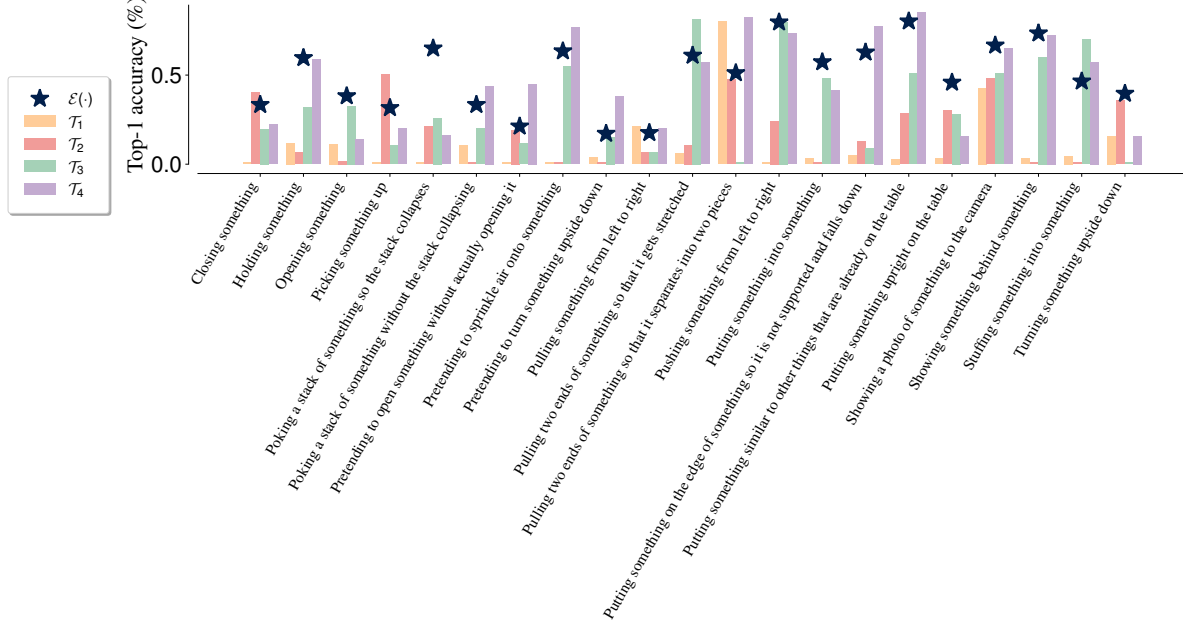


Figure S1. **TemPr**  $\frac{1}{2}$  SSsub21 class accuracies over observation ratio  $\rho = 0.3$ .

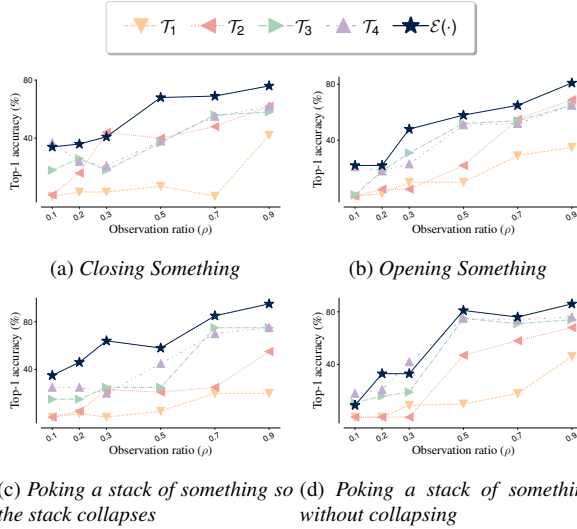


Figure S2. **TemPr**  $\frac{1}{2}$  SSsub21 tower accuracies across observation ratios for classes (a) *Closing Something*, (b) *Opening Something*, (c) *Poking a stack of something so the stack collapses* and (d) *Poking a stack of something without collapsing*.

*upside down*. For the majority of these classes, informative motions only last a few frames and are thus better addressed by finer scales. Additionally, in Figure S2 we observe that **TemPr**  $\frac{1}{2}$  relies more on coarser scales to capture the differences between visually similar classes. Considering the pairs *Closing something* from Figure S2a and *Open-*

Table S3. Tower acc. UCF101.

$\mathcal{T}/\mathcal{E}$	$\rho$					
	0.1	0.2	0.3	0.5	0.7	0.9
$\mathcal{T}_4 \frac{1}{2}$	78.5	82.3	86.3	84.1	89.3	87.7
$\mathcal{E}(\cdot)$	<b>84.3</b>	<b>90.2</b>	<b>90.4</b>	<b>91.2</b>	<b>92.1</b>	<b>92.4</b>

Table S4. Tower acc. SSsub21.

$\mathcal{T}/\mathcal{E}$	$\rho$					
	0.1	0.2	0.3	0.5	0.7	0.9
$\mathcal{T}_4 \frac{1}{2}$	26.0	31.6	34.1	36.9	40.6	45.2
$\mathcal{E}(\cdot)$	<b>28.4</b>	<b>34.8</b>	<b>37.9</b>	<b>41.3</b>	<b>45.8</b>	<b>48.6</b>

*ing something* from Figure S2b, as well as *Poking a stack of something so the stack collapses* from Figure S2c and *Poking a stack of something without the stack collapsing* in Figure S2d, there is a stronger reliance to  $\mathcal{T}_4 \frac{1}{2}$  and  $\mathcal{T}_3 \frac{1}{2}$ , with  $\mathcal{T}_2 \frac{1}{2}$  only performing better for specific  $\rho$ .

**UCF-101 class accuracies.** In Figure S3, we present accuracies for the first 30 classes on UCF-101. Overall, the performance of the aggregation function is equivalent to that of the top-performing tower. For the *BreastStroke* class, the finer scale  $\mathcal{T}_1 \frac{1}{2}$  outperforms other tower predictors. This is also the case for the *Billiards* class which shows a similar trend with  $\mathcal{T}_1 \frac{1}{2}$  achieving the best performance. We believe the high accuracy over the fine scales of both *BreastStroke* and *Billiards* classes, is due to their unique appear-

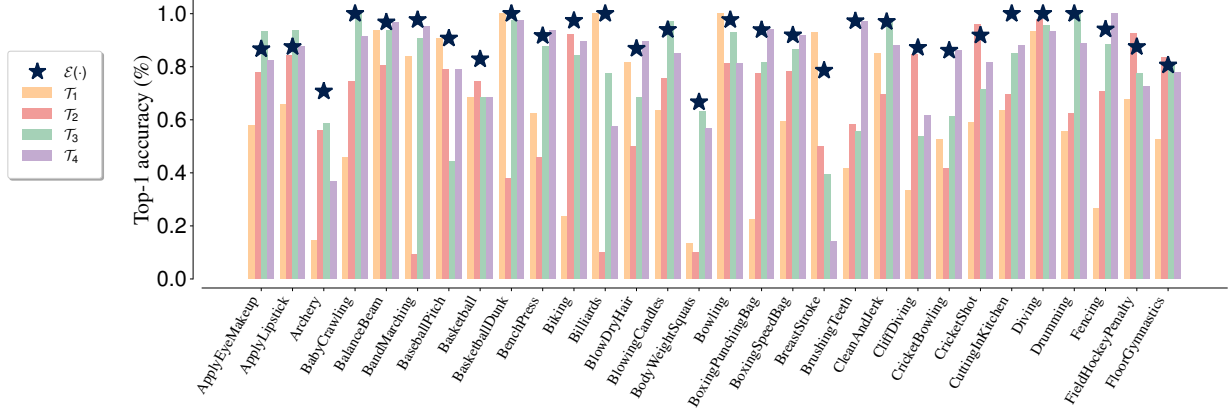


Figure S3. **TemPr**  $\underline{\mathbf{u}}$  UCF-101 class accuracies for the first 30 classes over observation ratio  $\rho = 0.3$ .

Table S5. **Tower designs.**

Tower design	$\rho$	
	0.2	0.4
MLP $\times 4$	72.4	81.1
MLP $\times 8$	73.1	81.3
<b>(ours)</b>	90.2	90.9

Table S6. **Bottleneck size comparison** based on latent array ( $\mathbf{u}$ ) index dimension ( $d$ ) used by the cross-attention blocks.

$d$	Mem. (GB)	Observation ratios ( $\rho$ )			
		0.2	0.4	0.6	0.8
128	1.65	89.1 (-1.1)	89.6 (-1.3)	90.1 (-1.7)	90.7 (-2.3)
256	3.01	90.2	90.9	91.8	92.3
512	5.74	<b>90.7 (+0.3)</b>	<b>91.3 (+0.4)</b>	<b>92.1 (+0.3)</b>	<b>92.4 (+0.1)</b>

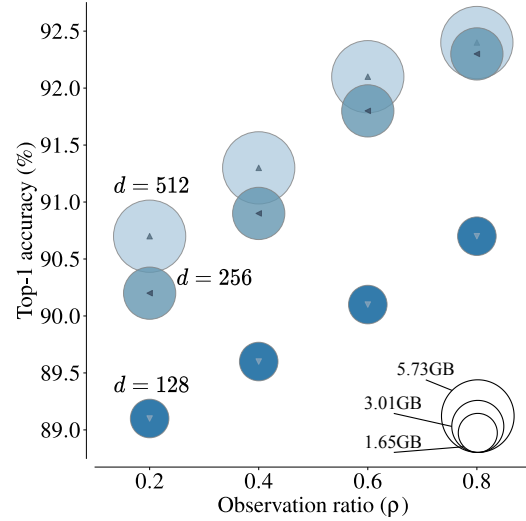


Figure S4. **Bottleneck size** ( $d$ ) for latent array ( $\mathbf{u}$ ).

ance and motion features. Thus, for only a small portion of the video, the ongoing action can be correctly predicted.

**Tower and aggregation function accuracies.** Motivated by class accuracy trends observed in Figure S3 and Figure S1 for UCF-101 and SSsub21, we compare the performance of the final attention tower  $\mathcal{T}_4$  to that of the  $\mathcal{E}(\cdot)$  aggregator from TemPr  $\underline{\mathbf{u}}$ . Results for UCF-101 are presented in Table S3 and for SSsub21 in Table S4. Consistent improvements are observed by the predictor ensemble compared to the predictions made from individual towers.

## S2. Further ablations

As with the ablation results in Section 4.3 of the main text, we use TemPr  $\underline{\mathbf{u}}$  with ResNet-18 backbone on UCF-101 for all experiments in this section.

**Cross-attention layer replacements.** We include tower ablations in Table S5 with  $\times 4/8$  MLP layers to assess if the

improvements are indeed due to our design. A notable drop is observed with the replacement of the attention towers.

**Latent array  $\mathbf{u}$  size:** In Figure S4 we present performance results on UCF-101 given different latent array  $\mathbf{u}$  sizes  $d$ . Size  $d = 256$  is shown to be the most cost-effective size as improvements over  $d = 128$  range between (1.1-2.3)% while requiring  $\sim 50\%$  less memory than  $d = 512$ . We additionally detail numerically these individual performances in Table S6. In terms of memory,  $d = 128$  requires 1.36GB less than  $d = 256$ , while  $d = 512$  uses 2.73GB more.

**Number of self attention blocks.** Table S7 demonstrates the impact of the Self MAB number on the accuracy. Increasing the number of self-attention blocks improves accuracy mostly in small observation ratios, while marginally increasing the complexity and memory requirements. We, therefore, adopt  $L = 8$  for our model.

Table S7. Number of self attention blocks (L)

L	Latency (secs)	Pars	FLOPs	Mem.	$\rho$				
	I ( $\downarrow$ )	B ( $\uparrow$ )	(M)	(G)	(GB)	0.2	0.4	0.6	0.8
1	0.31	1.07	20.3	1.29	2.74	70.9	74.8	80.4	86.2
2	0.31	1.09	20.6	1.32	2.78	77.2	76.3	82.8	86.7
4	0.32	1.12	21.5	1.37	2.85	83.4	84.9	85.1	87.4
6	0.32	1.16	22.2	1.42	2.93	88.7	89.5	89.8	90.1
8	0.34	1.27	23.0	1.47	3.01	<b>90.2</b>	<b>90.9</b>	<b>91.8</b>	<b>92.3</b>

Table S8. Ablation on aggregation function.

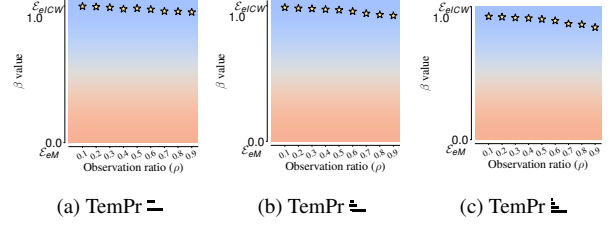
(a) SSsub21.			(b) EK-100.						
Aggregation	$\rho$		Aggregation	$\rho$					
	0.2	0.5		0.2	0.4	0.6	0.8	0.2	0.5
avg	32.3	38.6	avg	21.5	23.9	8.8	51.3	42.2	27.5
softmax	31.4	36.8	softmax	19.4	23.1	8.3	50.7	41.4	24.6
ICW	32.4	38.8	adapt. $\mathcal{E}(\cdot)$	<b>22.5</b>	<b>25.5</b>	<b>9.8</b>	<b>54.2</b>	<b>43.4</b>	<b>28.9</b>
adapt. $\mathcal{E}(\cdot)$	<b>34.8</b>	<b>41.3</b>							

Table S9. Ablating contributions with individual and combined replacement.

replacement(s)			Obs. ratio ( $\rho$ )			
I.	II.	III.				
$s_{1,\dots,n}$	$f(\hat{\mathbf{z}}_i)$	$\mathcal{E}(\mathbf{y}_{1,\dots,n})$				
$\downarrow$	$\downarrow$	$\downarrow$				
$s_n \times n$	$f(\mathbf{z}_i)$	$f(\hat{\mathbf{z}})$	0.2	0.4	0.6	0.8
<b>Proposed</b>			<b>90.2</b>	<b>90.9</b>	<b>91.8</b>	<b>92.3</b>
<b>X</b>			86.4	88.3	88.8	89.0
	<b>X</b>		69.4	73.2	78.6	85.5
		<b>X</b>	89.5	90.1	90.6	91.2
<b>X</b>	<b>X</b>		64.3	69.8	75.9	83.4
	<b>X</b>	<b>X</b>	67.4	72.8	77.3	84.7
<b>X</b>		<b>X</b>	84.2	87.0	87.4	88.3
<b>X</b>	<b>X</b>	<b>X</b>	61.4	67.2	73.5	79.3

**SSsub21 and EK-100 aggregation functions.** Supplementary to the results in Table 3b for different aggregation functions on UCF-101, we induce additional ablations for SSsub21 and EK-100 in Table S8a and Table S8b respectively. Across both datasets, our proposed adaptive predictor accumulation  $\mathcal{E}(\cdot)$  performs favorably compared to other aggregation methods. An average improvement of +5.4% and +3.8% is observed for UCF-101 and SSsub21.

**Combined ablations.** Motivated by Table 3 in the main paper, we present combined changes in the model configuration based on our contributions. Setting I. replaces the progressive scales with  $n$  copies of the observable video,  $s_{1,\dots,n} \rightarrow s_n \times n$ . In setting II. the class predictions are made from the extracted CNN features without the utilization of the attention towers  $f(\hat{\mathbf{z}}_i^L) \rightarrow f(\mathbf{z}_i)$ . For setting III. the predictor aggregation function is replaced by averaging classifier predictions  $\mathcal{E}(f(\hat{\mathbf{z}}_{1,\dots,n})) \rightarrow f(\hat{\mathbf{z}})$ . On average, a 14.63% accuracy reduction is observed across ratios when

Figure S5. Post-training  $\beta$  values over obs. ratios on UCF-101.

predictions are made directly from CNN features. This drop is further amplified when progressive sampling is not used, demonstrating the importance of both the proposed architecture and sub-sampling approach.

### S3. Predictor aggregation $\beta$ values

Our proposed adaptive predictor aggregation function relies on a combination of the similarity of predictor probability distributions and their confidences. The trainable parameter of the function defined in Eq. 7 is  $\beta$  which determines the portion of  $\mathcal{E}(\cdot)$  and  $\mathcal{E}(\cdot)$  that are used for composing the final aggregated probability distribution.

We visualize the values of the  $\beta$  parameter, for each TemPr configuration that employs multiple scales ( $-$ ,  $-$ ,  $-$ ,  $-$  and  $-$ ) across observation ratios in Figure S5. We use the UCF-101 TemPr models with MoViNet-A4. In general, the  $\beta$  value remains high within 0.98–0.84 for all observation ratios. A small decrease is observed in larger  $\rho$ , as independent predictors are exposed to larger portions of the video and can better predict the ongoing action individually.

### S4. Additional Qualitative results over tower predictions

We have presented and discussed qualitative results over TemPr  $-$ ,  $-$ ,  $-$ ,  $-$  configurations and individual towers  $\mathcal{T}_1$ ,  $\mathcal{T}_2$ ,  $\mathcal{T}_3$ ,  $\mathcal{T}_4$  in Section 4.3. Here we provide additional examples in the same format as Figure 4, where predictions differ across TemPr  $-$  towers.

As shown in Figure S6, presented over 2 pages, our proposed progressive scales can benefit feature modeling for a variety of action instances e.g. for the *Lunges* instance, the finer scales ( $\mathcal{T}_1$  and  $\mathcal{T}_2$ ) focus on smaller motions and thus are less influenced by global motion in the video. For *Lunges* and *IceDancing* (from UCF-101), these global motions are similar to those performed for *BodyWeightSquats* and *SalsaSpin*. On the other hand, for the *HighJump* and *SkateBoarding* instances from UCF-101, as well as *hoping* in NTU-RGB and *Pretending to turn something upside down* and *Closing something* in SSsub21, coarse scales are better suited, as motions over larger temporal lengths are more descriptive of the action performed. Failure cases for



coarse scales are evident in the chosen examples of *Shaving Beard* from UCF-101, *wipe face* in NTU-RGB, and *turn-off tap* in EPIC-KITCHENS-100, where motions that are descriptive for the class, are performed fast and over shorter temporal durations.

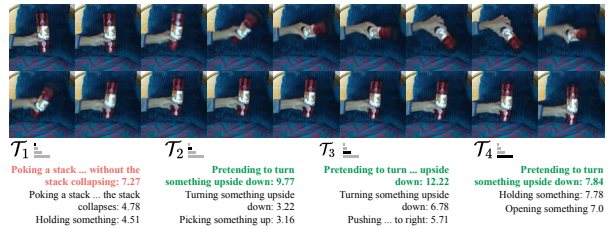
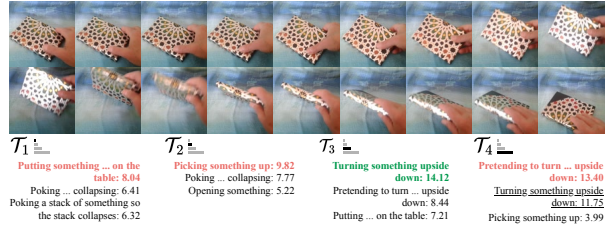
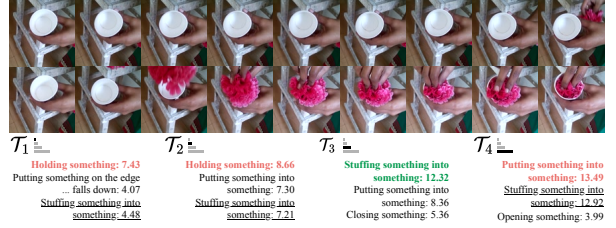
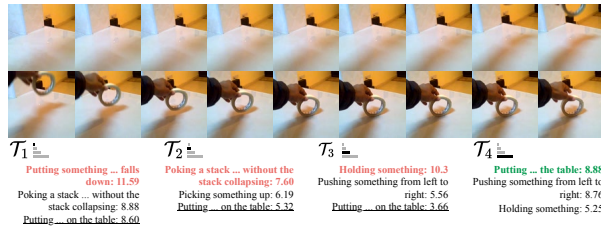
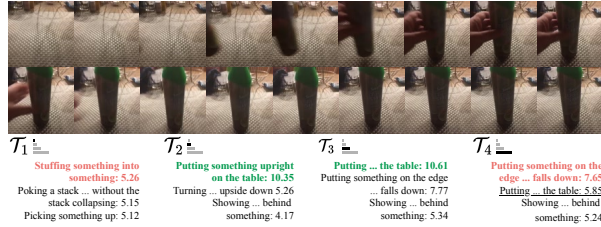
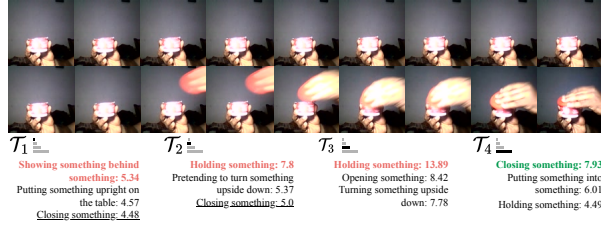
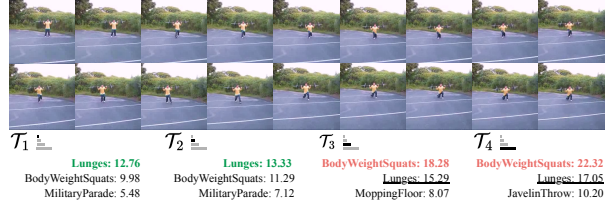
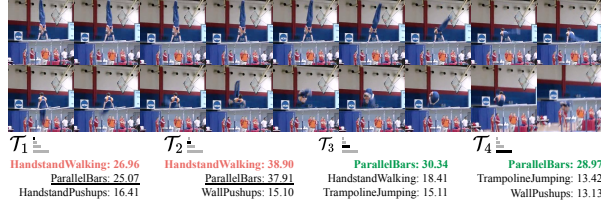
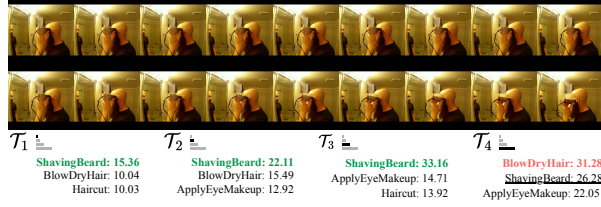
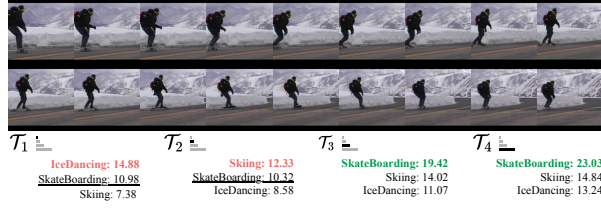


Figure S6. Instances over UCF-101, SSsub21, NTU-RGB and EK-100. Top 3 action labels are reported for individual tower predictors  $\mathcal{T}_i$  (continues to the next page).

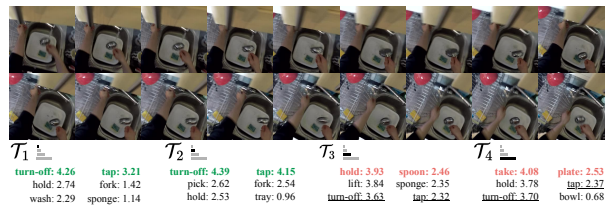
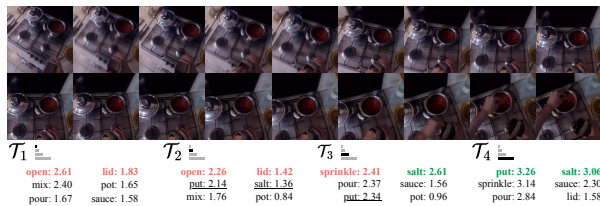
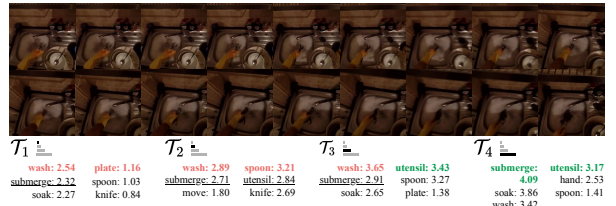
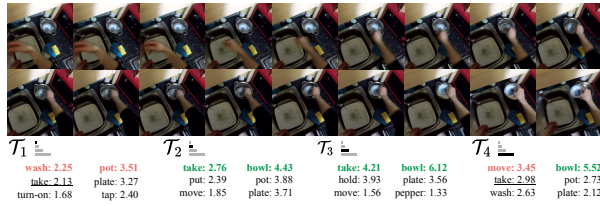
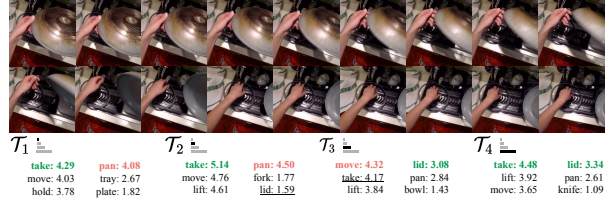
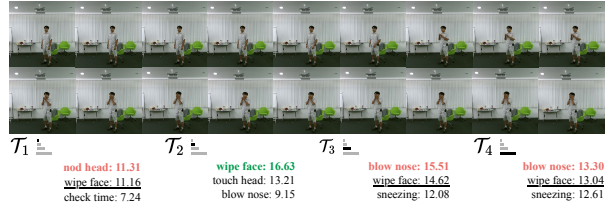
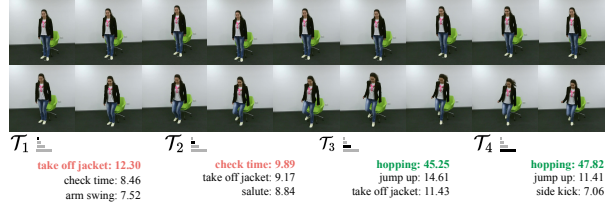
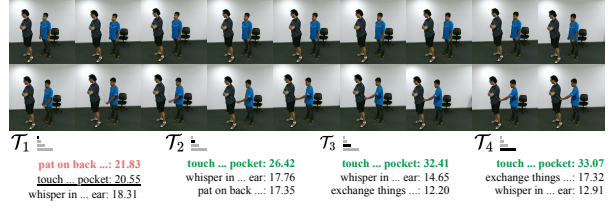
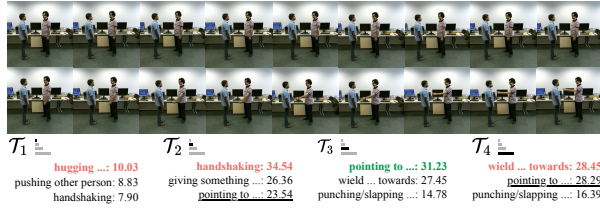
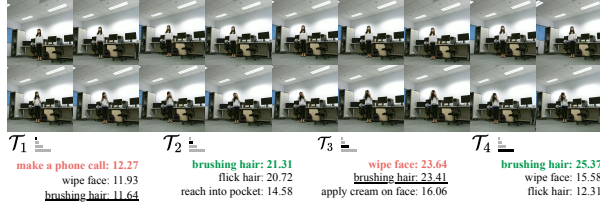
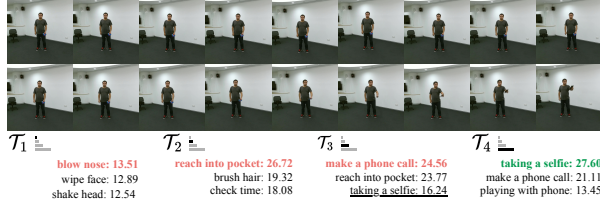


Figure S6. Instances over UCF-101, SSsub21, NTU-RGB and EK-100. Top 3 action labels are reported for individual tower predictors ( $\mathcal{T}_i$ ).