

Table 3. Dataset statistics.

Dataset	#Nodes	#Edges	#Features	#Classes
Cora	2,485	5,429	1,433	7
Citeseer	2,110	3,757	3,703	6
BlogCataLog	5,196	343,486	8,189	6

Algorithm 1 Certified robustness inspired PGD (CR-PGD) graph evasion attack to GNNs

Input: Node classifier f , graph $G(\mathbf{A})$, testing nodes \mathcal{V}_{Te} , perturbation budget Δ , total iterations T , #samples N , noise parameter β , confidence level $1 - \alpha$, a , interval INT .
Output: Adversarial graph perturbation $\delta^{(T)}$.
Initialize: $t = 0$; graph perturbation $\delta^{(0)} = 0$;
while $t < T$ **do**
 // Stage 1: Obtaining the CR inspired loss
 if $t \bmod INT \neq 0$ **then**
 Reuse the node weights: $w^{(t)}(v) = w^{(t-1)}(v)$;
 else
 Define the perturbed graph: $\mathbf{A}^{(t)} = \mathbf{A} \oplus \delta^{(t)}$;
 Sample N noise matrices $\{\epsilon^j\}_{j=1}^N$ from the noise distribution Equation 7 with parameter β ;
 for each node $v \in \mathcal{V}_{Te}$ **do**
 Compute the frequency N_{y_v} for label y_v : $N_{y_v} = \sum_{j=1}^N \mathbb{I}(f(\mathbf{A}^{(t)} \oplus \epsilon^j; v) = y_v)$;
 Estimate the low bound probability p_{y_v} with confidence $1 - \alpha$: $p_{y_v} = B(\alpha; N_{y_v}, N - N_{y_v} + 1)$;
 Calculate the certified perturbation size $K(p_{y_v})$ using p_{y_v} and algorithm in [35];
 Assign a weight $w(v)$ to each node v : $w^{(t)}(v) = \frac{1}{1 + \exp(a \cdot K(p_{y_v}))}$;
 end
 end
 Define the certified robustness inspired test loss:

$$\mathcal{L}_{CR}(f, \mathbf{A}^{(t)}, \mathcal{V}_{Te}) = \sum_{v \in \mathcal{V}_{Te}} w^{(t)}(v) \ell(f(\mathbf{A}^{(t)}; v), y_v);$$

 // Stage 2: Running the PGD attack with CR loss
 $\delta^{(t+1)} = \text{Proj}_{\mathbb{B}}(\delta^{(t)} + \eta \cdot \nabla_{\delta^{(t)}} \mathcal{L}_{CR}(f, \mathbf{A}^{(t)}, \mathcal{V}_{Te}))$;
 Update $t = t + 1$.
end
return $\delta^{(T)}$

Algorithm 2 Certified robustness inspired Minmax (CR-Minmax) graph poisoning attack to GNNs

Input: GNN algorithm \mathcal{A} , Graph $G(\mathbf{A})$, training nodes \mathcal{V}_{Tr} , perturbation budget Δ , number of samples N , noise parameter β , confidence level $1 - \alpha$, a , interval INT .
Output: Adversarial graph perturbation $\delta^{(T)}$.
Initialize: $t = 0$; $\delta^{(0)} = 0$; random/pretrained GNN model $\theta^{(0)}$;
while $t < T$ **do**
 // Stage 1: Obtaining the CR inspired loss
 if $t \bmod INT \neq 0$ **then**
 Reuse the node weights: $w^{(t)}(v) = w^{(t-1)}(v)$;
 else
 Define the perturbed graph: $\mathbf{A}^{(t)} = \mathbf{A} \oplus \delta^{(t)}$;
 Sample N noise matrices $\{\epsilon^j\}_{j=1}^N$ from the noise distribution Equation 7 with parameter β ;
 Train N node classifiers $\{\tilde{f}^n\}$ with current perturbed graph $\mathbf{A}^{(t)}$ with the N sampled noisy matrices $\{\epsilon^n\}$:

$$\tilde{f}^1 = \mathcal{A}(\mathbf{A}^{(t)} \oplus \epsilon^1, \mathcal{V}_{Tr}), \dots, \tilde{f}^N = \mathcal{A}(\mathbf{A}^{(t)} \oplus \epsilon^N, \mathcal{V}_{Tr})$$

 for each node $v \in \mathcal{V}_{Tr}$ **do**
 Compute the frequency N_{y_v} for label y_v : $N_{y_v} = \sum_{j=1}^N \mathbb{I}(\tilde{f}^j(\mathbf{A}^{(t)} \oplus \epsilon^j; v) = y_v)$;
 Estimate the low bound probability p_{y_v} with confidence $1 - \alpha$: $p_{y_v} = B(\alpha; N_{y_v}, N - N_{y_v} + 1)$;
 Calculate the certified perturbation size $K(p_{y_v})$ using p_{y_v} and algorithm in [35];
 Assign a weight $w(v)$ to each node v : $w^{(t)}(v) = \frac{1}{1 + \exp(a \cdot K(p_{y_v}))}$;
 end
 end
 Define the certified robustness inspired training loss:

$$\mathcal{L}_{CR}(f, \mathbf{A}^{(t)}, \mathcal{V}_{Tr}) = \sum_{v \in \mathcal{V}_{Tr}} w_v^{(t)} \cdot \ell(f(\mathbf{A}^{(t)}; v), y_v);$$

 // Stage 2: Running the Minmax attack with CR loss
 Step 1: Inner minimization over model parameter θ : $\theta^{(t+1)} = \theta^{(t)} - \eta_1 \nabla_{\theta} \mathcal{L}_{CR}(f_{\theta^{(t)}}, \mathbf{A}^{(t)}, \mathcal{V}_{Tr})$;
 Step 2: Outer maximization over graph perturbation δ :

$$\delta^{(t+1)} = \text{Proj}_{\mathbb{B}}(\delta^{(t)} + \eta_2 \nabla_{\delta} \mathcal{L}_{CR}(f_{\theta^{(t+1)}}, \mathbf{A}^{(t)}, \mathcal{V}_{Tr}))$$
;
 Update $t = t + 1$.
end
return $\delta^{(T)}$
