

Supplementary Material: Similarity Metric Learning For RGB-Infrared Group Re-Identification

Jianghao Xiong¹, Jianhuang Lai^{1,2,3,4*}

¹School of Computer Science and Engineering, Sun Yat-Sen University, China

²Guangdong Province Key Laboratory of Information Security Technology, China

³Key Laboratory of Machine Intelligence and Advanced Computing, Ministry of Education, China

⁴Key Laboratory of Video and Image Intelligent Analysis and Application Technology,
Ministry of Public Security, China

xiongjh7@mail2.sysu.edu.cn, stsljh@mail.sysu.edu.cn

1. Overview

In this supplementary material, we provide more experiment details and ablation studies of CPM and CPD. Note that we do not optimize the hyper-parameters and all the networks can be tuned for better performance.

- We visualize several retrieval results by CPM on CM-Group.
- We conduct further ablation studies for different backbones with CPD on CSG.
- We present more comparisons with state-of-the-arts in Group ReID.

2. Retrieval Results by CPM on CM-Group

We present six retrieval results by CPM on CM-Group in Fig. 1. It is clear that all true matches have large variations in viewpoints and group layout. In addition, challenging situations such as clothes change (row 2), scale change (row 3 and row 6) and occlusions (row 5) can be effectively handled by our CPM.

Method	Task	Rank1	Rank10	Rank20	mAP
Swin Transformer [7]	R	32.2	57.0	63.8	19.1
Swin Transformer [7]+CPD	G	59.6	78.7	83.2	34.5
DenseNet-121 [2]	R	59.0	81.8	86.2	34.9
DenseNet-121 [2]+CPD	G	87.9	96.1	97.6	51.1
HRNet-18 [8]	R	60.2	82.1	86.1	35.5
HRNet-18 [8]+CPD	G	88.2	95.9	96.8	51.6

Table 1. Results of three different backbones in terms of CMC (%) and mAP (%) performances on CSG. “R/G” stands for ReID and G-ReID respectively.

3. Ablation Studies for different backbones

We test three different backbones Swin Transformer [7], DenseNet-121 [2] and HRNet-18 [8] with CPD on CSG. As shown in Tab. 1, the performance of HRNet-18 is best on CSG (ReID) and the G-ReID performance with CPD is best among the three backbones. The results also indicate that with a better feature extraction network, our CPM is supposed to gain better performance in G-ReID task.

*Corresponding Author

4. More Comparisons with State-of-the-arts in Group ReID

We compare our modified CPM with more state-of-the-arts methods on CSG and RoadGroup for G-ReID. As shown in Tab. 2, our modified CPM achieves outstanding performances on both G-ReID datasets. It also demonstrates that our CPM framework is flexible to be applied to G-ReID task.

Method	Venue	CSG				RoadGroup			
		Rank1	Rank5	rank10	mAP	Rank1	Rank5	rank10	mAP
CRRRO-BRO [11]	BMVC 2009	10.4	25.8	37.5	-	17.8	34.6	48.1	-
Covariance [1]	ICPR 2010	16.5	34.1	47.9	-	38.0	61.0	73.1	-
PREF [6]	ICCV 2017	19.2	36.4	51.8	-	43.0	68.7	77.9	-
BSC+CM [12]	ICIP 2016	24.6	38.5	55.1	-	58.6	80.6	87.4	-
DotGNN [3]	MM 2019	-	-	-	-	74.1	90.1	92.6	-
GCGNN [13]	TMM 2020	-	-	-	-	81.7	94.3	96.5	-
MGR [5]	TCYB 2021	57.8	71.6	76.5	-	80.2	93.8	96.3	-
DotSCN [4]	TCSVT 2021	-	-	-	-	84.0	95.1	96.3	-
MACG [9]	TPAMI 2020	63.2	75.4	79.7	-	84.5	95.0	96.9	-
3DT [10]	CVPR 2022	92.9	97.3	98.1	92.1	91.4	97.5	98.8	94.3
CPM*(Ours)	-	88.6	94.1	95.3	51.5	92.6	98.8	98.8	95.4

Table 2. Comparisons with state-of-the-arts methods on CSG and RoadGroup.



Figure 1. Examples of retrieval results by CPM on CM-Group. In each row, the leftmost image is the query followed by top-10 nearest neighboring images. The green digits indicate true matches while the red digits indicate false matches. Images are resized for better visualization.

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