

Towards Bridging the Performance Gaps of Joint Energy-based Models

Supplementary Material

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A. Experimental Details

To have a fair comparison, we largely follow the settings of JEM [2] and JEM++ [5], and train our models based on the Wide-ResNet 28x10 architecture [6] for 200 epochs. We use SGD for CIFAR10 and CIFAR100 with an initial learning rate of 0.1 and 0.01, respectively, and decay the learning rate by 0.2 at epoch [60, 120, 180] for most cases. Apart from this, we find that the cosine learning rate scheduler can be adopted for SADA-JEM, which achieves much better accuracy and FID on CIFAR10.¹ The hyper-parameters used in our experiments are listed in Table 1.

Table 1. Hyper-parameters of SADA-JEM for CIFAR10 and CIFAR100.

Variable	Value
Number of SGLD steps K	5, 10, 20
Buffer size $ \mathbb{B} $	10,000
Reinitialization freq. γ	5%
SGLD step-size α	1
SGLD noise σ	0
SAM noise radius ρ	0.2

B. Visualizing Generated Images

Table 1 in the main text reports the quantitative performance comparison of different stand-alone generative models and hybrid models. Here in Figure 1 we provide a qualitative comparison of generated images from (a) SADA-JEM, (b) VERA [3], and (c) DiffuRecov [1]. As we can see, the perceived image qualities of them are comparable even though DiffuRecov has a much better FID score than that of VERA (9.58 vs. 30.5), indicating that visualizing generated images is less effective to evaluate image quality.

¹This is because the combination of SAM and single branched DA improves the training stability significantly. As a result, the cosine learning rate decay can be adopted to improve the overall performance. JEM, JEM++ and other SADA-JEM ablation configurations are less stable to enable the cosine learning rate decay.

C. Energy Landscapes

Figure 2 illustrates the energy landscapes of different models trained on CIFAR10. The energy landscape is generated by visualizing $E(\theta) = \sum_{x \in X} E_\theta(x)$ with the technique introduced in [4], where X is a 10% random samples from CIFAR10 training data. As we can see, SADA-JEM’s energy landscapes are much smoother than those of the competing methods (see different scales of the y-axes).

D. Out-of-Distribution Detection

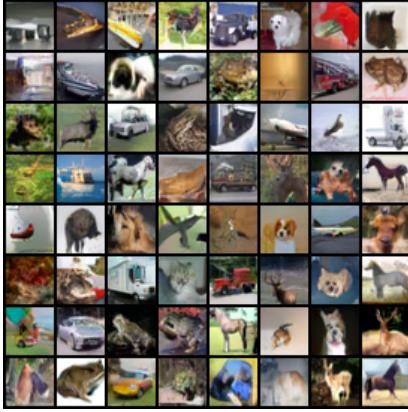
Table 2 reports the OOD detection performances of different models and SADA-JEM with different K s, where the input density $\log p_\theta(x)$ is used as $s_\theta(x)$ for OOD detection on CIFAR10.

E. Additional Generated Samples

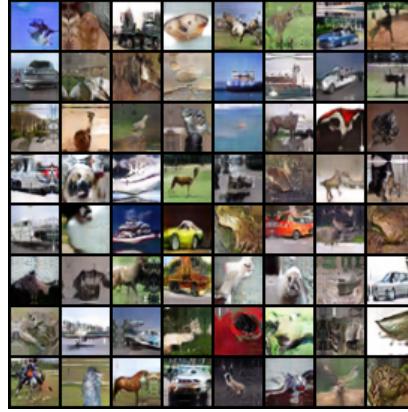
Additional SADA-JEM generated class-conditional (best and worst) samples of CIFAR10 are provided in Figures 3-12.

References

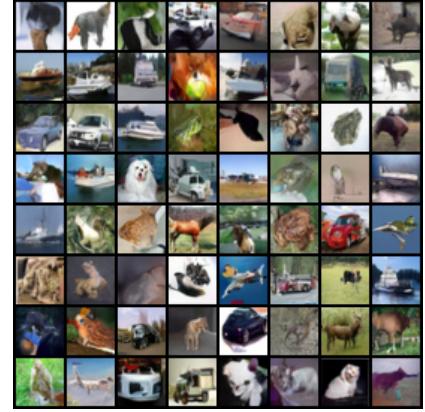
- [1] Ruiqi Gao, Yang Song, Ben Poole, Ying Nian Wu, and Diederik P. Kingma. Learning Energy-Based Models by Diffusion Recovery Likelihood. In *ICLR*, 2021. [1](#)
- [2] Will Grathwohl, Kuan-Chieh Wang, Joern-Henrik Jacobsen, David Duvenaud, Mohammad Norouzi, and Kevin Swersky. Your classifier is secretly an energy based model and you should treat it like one. In *International Conference on Learning Representations (ICLR)*, 2020. [1](#)
- [3] Will Sussman Grathwohl, Jacob Jin Kelly, Milad Hashemi, Mohammad Norouzi, Kevin Swersky, and David Duvenaud. No memc for me: Amortized sampling for fast and stable training of energy-based models. In *ICLR*, 2021. [1](#)
- [4] Hao Li, Zheng Xu, Gavin Taylor, Christoph Studer, and Tom Goldstein. Visualizing the Loss Landscape of Neural Nets. In *Neural Information Processing Systems (NeurIPS)*, 2018. [1](#)
- [5] Xiulong Yang and Shihao Ji. JEM++: Improved Techniques for Training JEM. In *International Conference on Computer Vision (ICCV)*, 2021. [1](#)
- [6] Sergey Zagoruyko and Nikos Komodakis. Wide residual networks. In *BMVC*, 2016. [1](#)



(a) SADA-JEM

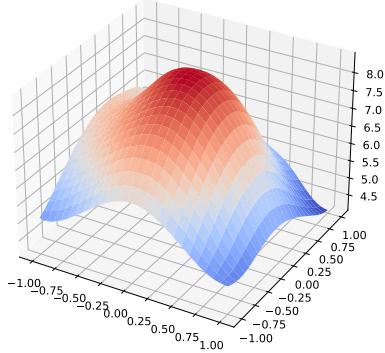


(b) VERA

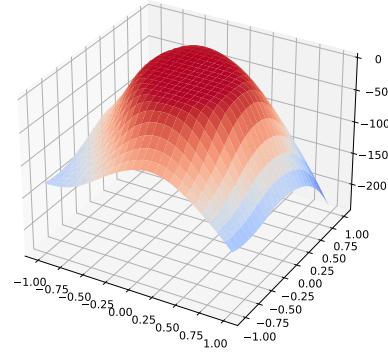


(c) DiffuRecov

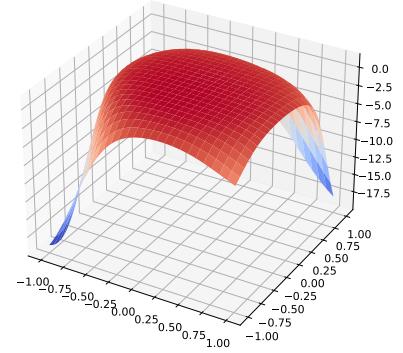
Figure 1. Generated images from SADA-JEM, VERA, and DiffuRecov.



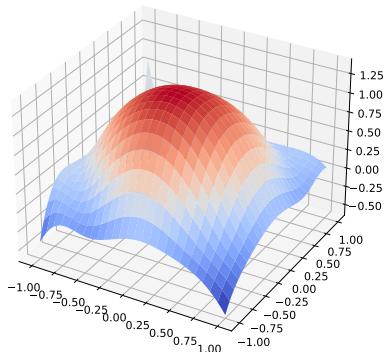
(a) Classifier



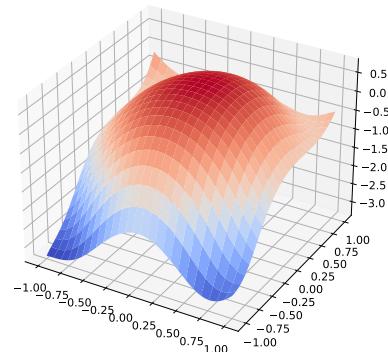
(b) JEM



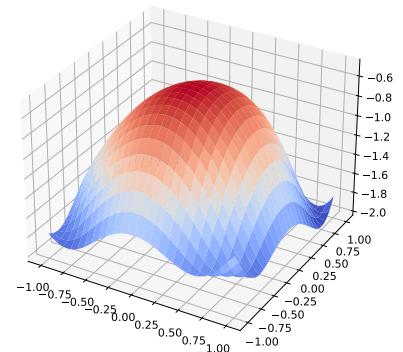
(c) JEM+SAM



(d) SADA-JEM (K=5)



(e) SADA-JEM (K=10)



(f) SADA-JEM (K=20)

Figure 2. Energy landscapes of different models trained on CIFAR10. Please note the different scales of the y-axes.

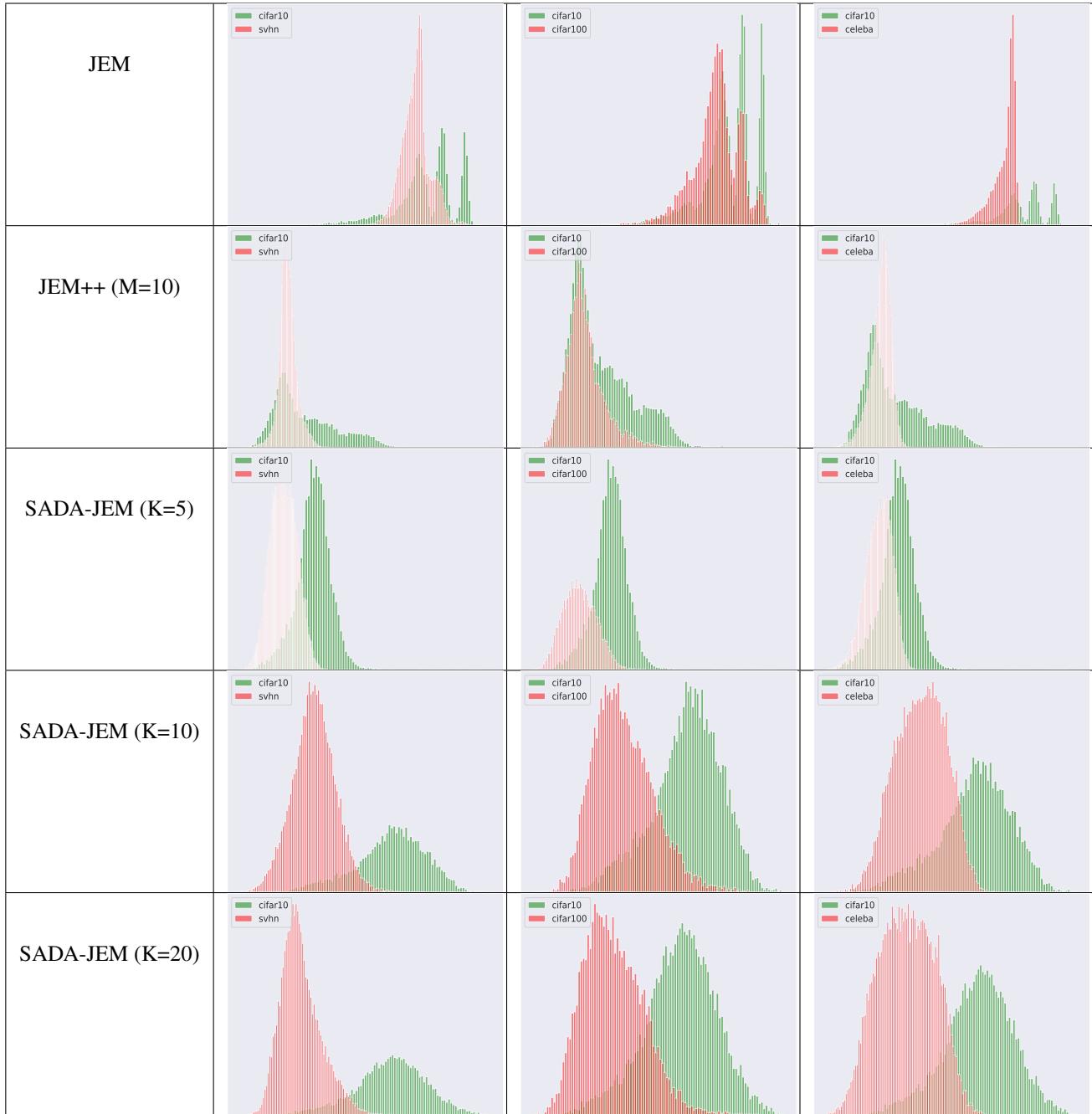


Table 2. Histograms of $\log p_{\theta}(\mathbf{x})$ for OOD detection. Green corresponds to in-distribution dataset, while red corresponds to OOD dataset.



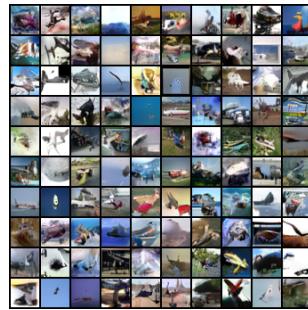
(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$

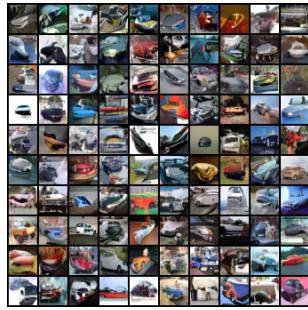


(d) Samples with lowest $p(y|\mathbf{x})$

Figure 3. SADA-JEM generated class-conditional samples of **Plane**.



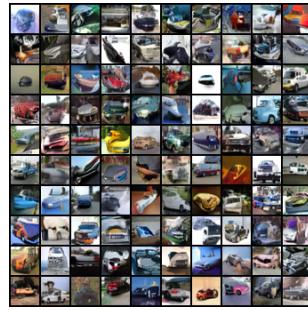
(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 4. SADA-JEM generated class-conditional samples of **Car**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 5. SADA-JEM generated class-conditional samples of **Bird**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 6. SADA-JEM generated class-conditional samples of **Cat**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$

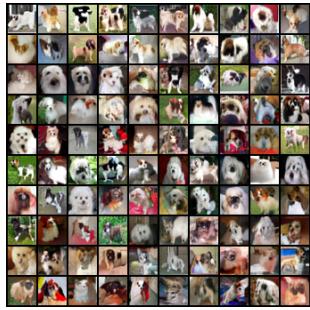


(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 7. SADA-JEM generated class-conditional samples of **Deer**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 8. SADA-JEM generated class-conditional samples of **Dog**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 9. SADA-JEM generated class-conditional samples of **Frog**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 10. SADA-JEM generated class-conditional samples of **Horse**.



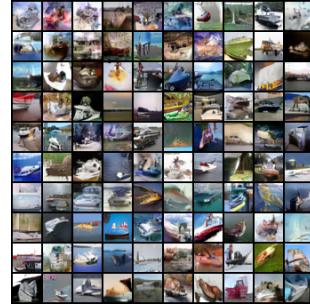
(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 11. SADA-JEM generated class-conditional samples of **Ship**.



(a) Samples with highest $p(\mathbf{x})$



(b) Samples with lowest $p(\mathbf{x})$



(c) Samples with highest $p(y|\mathbf{x})$



(d) Samples with lowest $p(y|\mathbf{x})$

Figure 12. SADA-JEM generated class-conditional samples of **Truck**.