

# CORES: Convolutional Response-based Score for Out-of-distribution Detection

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## Abstract

Deep neural networks (DNNs) often display overconfidence when encountering out-of-distribution (OOD) samples, posing significant challenges in real-world applications. Capitalizing on the observation that responses on convolutional kernels are generally more pronounced for in-distribution (ID) samples than for OOD ones, this paper proposes the CONvolutional REsponse-based Score (CORES) to exploit these discrepancies for OOD detection. Initially, CORES delves into the extremities of convolutional responses by considering both their magnitude and the frequency of significant values. Moreover, through backtracking from the most prominent predictions, CORES effectively pinpoints sample-relevant kernels across different layers. These kernels, which exhibit a strong correlation to input samples, are integral to CORES’s OOD detection capability. Comprehensive experiments across various ID and OOD settings demonstrate CORES’s effectiveness in OOD detection and its superiority to the state-of-the-art methods.

## 1. Introduction

Deep neural networks (DNNs) [17, 36, 37] have achieved significant success in various tasks. Nevertheless, DNNs often suffer performance drop when exposed to novel, unforeseen categories of data, termed as out-of-distribution (OOD) samples, owing to their initial design for static, closed-world scenarios [1]. Indeed, many recent studies have demonstrated that DNN classifiers suffer from the issue of making overconfident predictions on OOD samples [6, 26, 35]. Hence, OOD detection is crucial for ensuring the safety and reliability of DNN deployments [10, 39].

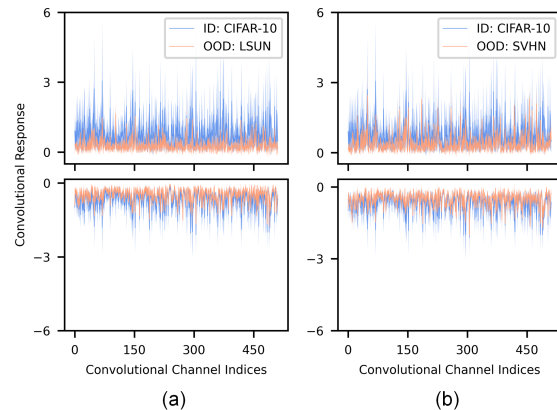


Figure 1. Response visualization of convolutional kernels in the penultimate layer of ResNet-18. Responses to in-distribution (ID) CIFAR-10 data are contrasted with OOD data from: (a) LSUN; and (b) SVHN. The  $x$ -axis enumerates the convolutional channel indices, and the  $y$ -axis shows the maximum positive and minimum negative values of the responses. It is evident that ID displays higher positive and lower negative responses than OOD.

A prevalent direction for OOD detection involves enhancing classifiers through exposure to auxiliary OOD samples [11, 18]. However, these approaches may lead to increased training costs and potentially compromise model performance. As a result, post-hoc methods that examine the inference process offer advantages in real-world applications. Existing post-hoc methods typically fall into two main categories: 1) those utilizing in-distribution (ID) samples, such as training data, and 2) those that do not rely on ID samples. Specifically, the first category aims to measure the difference between a test image and training samples [19, 27, 30, 34, 41]. In many real-world scenarios, access to training data is limited, and even when available, it may not comprehensively represent the entire ID domain, potentially causing inaccuracies in calculated discrepancies.

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The second ID-free category concentrates on the model’s intrinsic characteristics rather than depending on training data, demonstrating potential for effective OOD detection.

In the realm of ID-free methodologies for OOD detection, researchers have investigated a plethora of signals as potential indicators. These include the maximum probabilities derived from softmax layers [10], its subsequent enhancements [21, 22], post-processed outputted features [32, 33], the norm of the gradient [14] and the norm of features [46]. However, these signals, which were primarily designed for ID categorization, may not be ideally suited for a totally different task, i.e., distinguishing between ID and OOD samples. Therefore, we aim to identify signals inherent within the DNNs’ functioning that can assist in determining whether samples are ID or OOD, without leaning on category-specific data. Given that convolutional kernels in DNNs, generally exhibit more pronounced responses to ID samples, see Fig. 1, these responses are anticipated to be reliable signals for distinguishing OOD from ID.

In this paper, we present **CONvolutional REsponse-based Score (CORES)**, a unique ID-free method that exploits responses of convolutional kernels for OOD detection. CORES harnesses the most pronounced responses of convolutional kernels in a layer, specifically the peak and trough values, to mitigate the impact of noise. We derive the OOD detection score from these extreme values, considering both their magnitude and frequency. Given that kernels yielding the strongest (either highest or lowest) confidence results are inherently relevant to the input samples, we trace back from these outputs to pinpoint a trajectory of sample-relevant kernels across layers. By collecting responses from these specific kernels, we establish the final CORES metric. We demonstrate the effectiveness of CORES across multiple DNN architectures, under diverse settings of ID and OOD datasets, encompassing both conventional OOD and near-OOD scenarios. Extensive experiments substantiate the robustness of CORES in OOD detection, and its superiority to the state-of-the-art methods.

Overall, our contribution is summarized as follows:

- We are the first to explore convolutional responses as ID-free signals for OOD detection.
- We develop a novel OOD score based on extreme response values on a trajectory of sample-relevant kernels.
- We show by experiments that CORES outperforms the state-of-the-art OOD detection methods.

## 2. Related Work

**OOD Detection.** The OOD overconfidence issue, where OOD samples are assigned excessively high confidence scores, poses a significant challenge for numerous DNNs [8, 9, 38, 44]. To mitigate it, a spectrum of strategies has been employed during DNN training, e.g., incorporating random noise and image shuffling [18], auxiliary datasets [9], and

advanced generative models like Chamfer GAN [35] to simulate OOD samples resembling ID data closely. Alternatively, methods such as VOS [5] and NPOS [40] generate virtual features rather than actual OOD instances. These approaches, however, confront obstacles such as the need for extensive OOD data and the potential for intensive fine-tuning to detrimentally affect performance.

Consequently, the focus has shifted to post-hoc OOD scoring techniques that differentiate model responses to OOD and ID data through analysis of feature discrepancies [24], Mahalanobis distance computation [19], and detection of anomalies in patterns and predictions [30]. Despite Sun et al.’s development of a purportedly assumption-free method, the necessity for some ID samples persists, presenting challenges when only pre-trained models are available without corresponding training data or when such data inadequately represents the ID space [34]. Our research, therefore, prioritizes advancing post-hoc OOD detection methods that operate independently of ID data access.

**Post-hoc ID-free OOD Detection.** Hendrycks et al. [10] pioneered the use of maximum softmax probability, observing that classifiers typically exhibit lower confidence for OOD samples than for ID ones. Expanding on this, ODIN [21] integrates input preprocessing and temperature scaling to sharpen the distinction between ID and OOD samples. Energy Score [22] employs an energy-based model to reduce prediction bias. Further advancements include ReAct [33], LHAct [47], and DICE [32], which refine outputted features through activation rectification or selective sparsification for improved discrimination. Recognizing the notable gradient intensity in ID data, Gradient-Norm [14] utilizes the vector norm of gradients for OOD detection. Similarly, FeatureNorm [46] leverages the norm of feature maps from a strategically chosen block for identifying OOD samples.

However, these signals, primarily tailored for ID categorization, may falter when redirected to other tasks, such as differentiating between ID and OOD samples. Differently, our chosen signal, specifically the convolutional response, is not crafted for categorization purposes. It focuses exclusively on expressing the inherent characteristics of the samples, resulting in enhanced performance in OOD detection.

**Convolutional Response.** Convolutional responses, the output feature maps from each convolutional kernel on input data such as images, illuminate key attributes including edges, textures, and colors. Analyzing these responses deepens understanding of the features learned by deep convolutional networks [23, 49] and supports model refinement through the identification and pruning of ineffective kernels, thus conserving computational resources [20]. Our research presents a novel OOD detection approach based on the observation that convolutional kernels exhibit more pronounced responses to ID data compared to OOD data.

### 3. Problem Formulation

**Preliminaries.** This work considers the setting in multi-category classification problems. Given an input image  $x$ , the DNN classifier  $f$ , which consists of  $L$  convolutional layers, processes it as follows:

$$f : x \rightarrow \mathcal{R}^{(1)} \rightarrow \mathcal{R}^{(2)} \rightarrow \dots \rightarrow \mathcal{R}^{(L)} \rightarrow \mathcal{O}$$

Here,  $\mathcal{R}^{(i)}$  represents the convolutional responses at the  $i$ -th layer, and  $\mathcal{O}$  denotes the final output.

By identifying which category in  $\mathcal{O}$  has the highest prediction confidence,

$$c_{\max} = \arg \max_i \mathcal{O}_i$$

$f$  predicts  $x$  to be in the  $c_{\max}$ -th category. However, in some open-world scenarios, when the input  $x$  is out-of-distribution (OOD),  $f$  still classifies it into the predefined categories. As a result, it is essential to conduct OOD detection in practical applications.

A prevalent strategy for OOD detection entails the construction of a score, i.e.,  $\text{Score}_{\text{OOD}}$ , subsequently utilizing thresholding to discriminate between in-distribution (ID) and OOD samples [10],

$$g_{\gamma}(\mathbf{x}) = \begin{cases} \text{ID} & \text{Score}_{\text{OOD}} \geq \gamma \\ \text{OOD} & \text{Score}_{\text{OOD}} < \gamma \end{cases} \quad (1)$$

where  $\gamma$  is a threshold.

**Discussion.** Existing methodologies for  $\text{Score}_{\text{OOD}}$  largely hinge on the derived probability or logit outputs, such as maximum softmax probabilities (MSP) [10], or the Energy Score [22], as well as on particular feature characteristics, as seen in FeatureNorm [46]. However, these indicators, crafted for categorizing ID classes, may falter when applied to a fundamentally different task, namely, distinguishing between ID and OOD samples. Consequently, our goal is to derive signals from the DNNs' inference phase, that are not principally used for categorization but rather dedicated to capturing the inherent properties of the samples, irrespective of their classification as ID or OOD.

**Response-based OOD Detection.** We observe that the convolutional kernels in a trained deep neural network are inherently attuned to extracting the fundamental attributes of samples. These kernels exhibit a strong response to patterns they recognize — those consistent with ID inputs. In contrast, their response diminishes with patterns they do not recognize, characteristic of OOD inputs. Thus, we suggest that the significant difference in the responses, represented as  $\{\mathcal{R}^{(i)}\}_{i=1:L}$ , is a strong indicator for determining if inputs are ID or OOD,

$$\{\mathcal{R}^{(i)}\}_{i=1:L} \rightarrow \text{Score}_{\text{OOD}} \quad (2)$$

### 4. Convolutional Response-based Score

In this section, we first detail the convolutional response-based score (CORES), derived from the responses of a single, specified layer. We then elaborate on the method for pinpointing a trajectory of sample-relevant kernels in different layers. Finally, we combine these elements to unveil the final version of CORES.

#### 4.1. Single-layer CORES

Given  $c$  channels of convolutional kernels in the  $l$ -th layer of a trained deep neural network, we calculate  $\text{Score}_{\text{OOD}}$  utilizing the responses from these kernels, i.e.,  $\mathcal{R}^{(l)} = \{R_1^{(l)}, R_2^{(l)}, \dots, R_c^{(l)}\}$ . For clarity, we will omit the superscript ( $l$ ) unless specific distinction is required.

Since DNNs are trained on ID data, their responses  $\mathcal{R}^{(l)}$  align better with ID than OOD inputs. This difference in response strength helps identify ID and OOD inputs. Recognizing the intrinsic noise in the responses, we emphasize that extreme values in a kernel often convey more pertinent information. Thus, we exclusively concentrate on the highest positive value and the lowest negative value for each kernel. Specifically, we design  $\text{Score}_{\text{OOD}}$  to capture both the *magnitude* of these extreme values and their *frequency* within the entire response spectrum.

**Response Magnitude.** Convolutional kernels are generally more responsive to ID inputs than to OOD ones, producing stronger responses. To capture this, we introduce a metric focusing on the maximum positive and minimum negative values of the response:

$$RM^+(\mathcal{R}) = \frac{1}{|\mathcal{R}|} \sum_{i=1}^{|\mathcal{R}|} \max(\max(R_i) - \tau_+, 0) \quad (3)$$

$$RM^-(\mathcal{R}) = \frac{1}{|\mathcal{R}|} \sum_{i=1}^{|\mathcal{R}|} \max(\tau_- - \min(R_i), 0)$$

Here,  $\tau_+$  and  $\tau_-$  are thresholds that help decide if the response strength is significant.

**Frequency of Significant Responses.** Convolutional kernels typically produce more distinct responses to ID inputs than to OOD ones. To capture this, we introduce a metric that calculates the frequency of these significant responses:

$$RF^+(\mathcal{R}) = \frac{1}{|\mathcal{R}|} \mathbb{1}(\max(R_i) > \tau_+) \quad (4)$$

$$RF^-(\mathcal{R}) = \frac{1}{|\mathcal{R}|} \mathbb{1}(\min(R_i) < \tau_-)$$

**Definition of Single-layer CORES.** We integrate the above metrics to define a straightforward OOD score:

$$S(\mathcal{R}) = RM^+(\mathcal{R})^{\lambda_1} \times RM^-(\mathcal{R})^{\lambda_1} \times RF^+(\mathcal{R})^{\lambda_2} \times RF^-(\mathcal{R})^{\lambda_2} \quad (5)$$

where  $\lambda_1$  and  $\lambda_2$  are weighting hyperparameters.

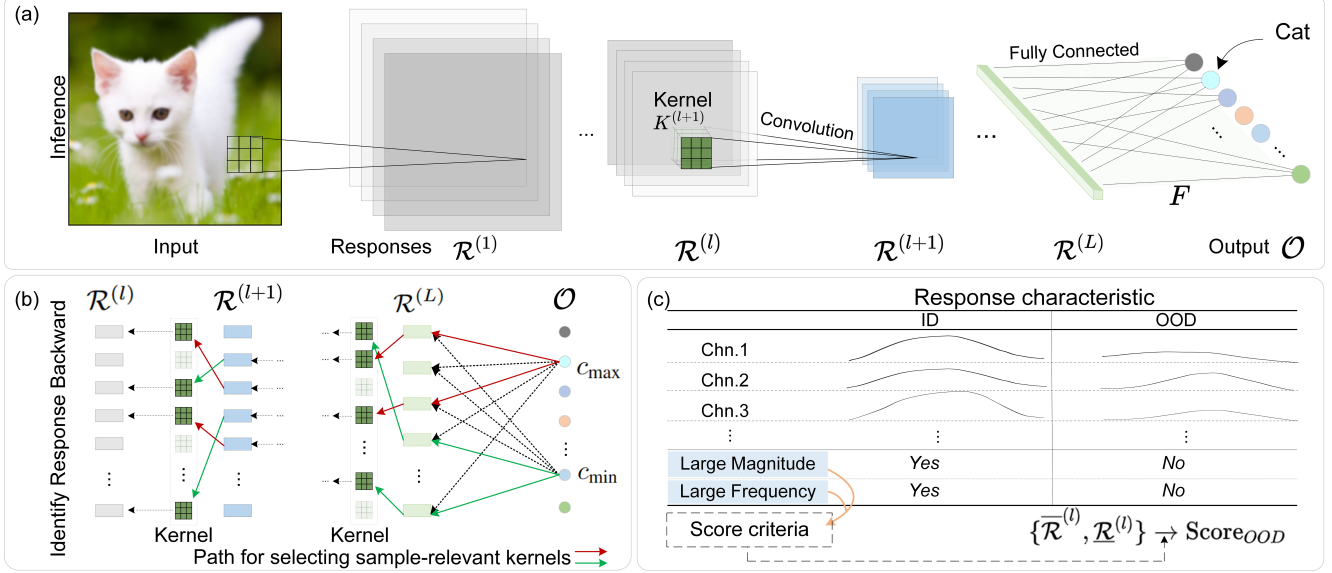


Figure 2. Illustration of CORES for OOD detection. (a) Inference pathway in neural networks, with an input progressing through convolutional layers to the final classification. (b) Backward retracing from extreme predictions to identify sample-relevant kernels. (c) Strategy for deriving the OOD score based on response magnitude and frequency, highlighting differences between ID and OOD characteristics.

## 4.2. Selection of Sample-relevant Kernels

In DNNs, there are many convolutional kernels across different layers. However, only a few of these kernels play a key role in making a prediction for a given input. Specifically, kernels leading to extreme predictions such as  $c_{\max}$  and  $c_{\min}$  tend to have a stronger connection or mismatch with the input. Signals on these sample-relevant kernels tend to be more reliable for OOD detection. Hence, we focus on these kernels by retracing from the extreme predictions through the network’s layers.

**Selection for the Last Convolution Layer.** We define the weight matrix of the fully-connected (FC) layer that connects the last convolutional layer’s responses to the output  $\mathcal{O}$  as  $F \in \mathbb{R}^{o \times c}$ , where  $o$  is the category number and  $c$  is the kernel number. To identify kernels in the last convolution layer—preceding the FC layer—that are relevant to the sample, we focus on the weights in  $F$  corresponding to the highest and lowest confidence categories,  $c_{\max}$  and  $c_{\min}$ . The selection process is as follows:

$$\begin{aligned} \bar{I}^{(L)} &= \text{TopK}(\{F_{c_{\max},j}\}_{j=1:c}) \\ \underline{I}^{(L)} &= \text{TopK}(\{F_{c_{\min},j}\}_{j=1:c}) \end{aligned} \quad (6)$$

Indices  $\bar{I}$  and  $\underline{I}$ , derived from  $F$ , indicate the kernel indices from the last convolutional layer that are associated with  $c_{\max}$  and  $c_{\min}$ , respectively. The operation TopK selects a subset of entries with the largest values.

We assume that the responses from the last convolutional layer have a  $1 \times 1$  dimension before connecting to the fully-connected layer. If the response is of a larger dimension, say

$t \times t$  where  $t > 1$ , flattening is required. Before conducting the TopK operation, we average each  $t \times t$  block of weights.

In summary, the responses from the kernels deemed relevant to the sample in the last convolutional layer are identified as follows:

$$\begin{aligned} \bar{\mathcal{R}}^{(L)} &= \{R_i^{(L)} | i \in \bar{I}^{(L)}\} \\ \underline{\mathcal{R}}^{(L)} &= \{R_i^{(L)} | i \in \underline{I}^{(L)}\} \end{aligned} \quad (7)$$

**Selection for Intermediate Convolutional Layers.** To trace the indices of sample-relevant kernels from the  $l + 1$ -th to the  $l$ -th layer, we employ the weight matrix  $K \in \mathbb{R}^{c^{(l+1)} \times c^{(l)} \times w \times h}$ , which represents the inter-layer connections. Here,  $c^{(l)}$  and  $c^{(l+1)}$  denote the number of kernels in the  $l$ -th and  $l + 1$ -th layers, respectively, while  $w \times h$  indicates the kernel size. We select kernels in the  $l$ -th layer based on their influence on the subsequent layer’s kernels. The selection process is as follows:

$$\begin{aligned} \bar{I}^{(l)} &= \text{TopK} \left( \left\{ \sum_{i \in \bar{I}^{(l+1)}} \max(K_{i,j,:,:}) \right\}_{j=1:c^{(l)}} \right) \\ \underline{I}^{(l)} &= \text{BotK} \left( \left\{ \sum_{i \in \underline{I}^{(l+1)}} \min(K_{i,j,:,:}) \right\}_{j=1:c^{(l)}} \right) \end{aligned} \quad (8)$$

The function BotK is defined as the operation selecting a subset of entries with the lowest values. Fig. 3 illustrates this selection process. Utilizing these indices, we can deter-

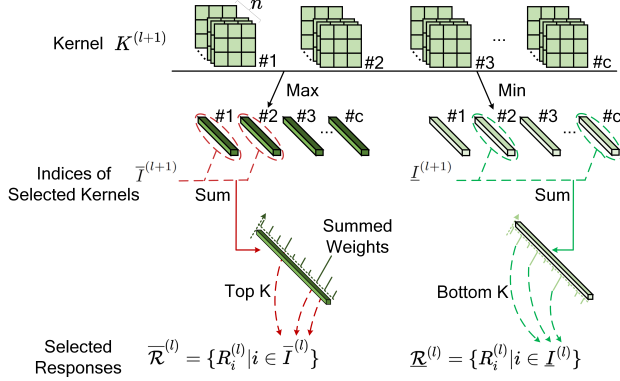


Figure 3. Demonstration of identifying sample-relevant kernels in the  $l$ -th layer, leveraging those kernels in the  $l + 1$ -th layer.

mine the responses of the sample-relevant kernels at the  $l$ -th layer, as detailed in Eq. (7).

### 4.3. Final CORES

Leveraging responses from sample-relevant kernels, we refine Eq. (5) to establish a revised OOD score for the pertinent layer:

$$S(\overline{\mathcal{R}} \cup \underline{\mathcal{R}}) = RM^+(\overline{\mathcal{R}})^{\lambda_1} \cdot RM^-(\underline{\mathcal{R}})^{\lambda_1} \cdot RF^+(\overline{\mathcal{R}})^{\lambda_2} \cdot RF^-(\underline{\mathcal{R}})^{\lambda_2} \quad (9)$$

Practically, we aggregate responses from the sample-relevant kernels at multiple layers. The formula is applied to each respective layer to calculate individual scores, which are then averaged to yield the final OOD score.

## 5. Experimental Results

### 5.1. Experimental Setup

**Implementation.** The parameters  $\lambda_1$  and  $\lambda_2$  are set to 10 and 1. In the process of selecting sample-relevant kernels, the TopK and BotK operations are configured to select entries corresponding to the top and bottom 20% of kernels, respectively. For CORES construction, 4 convolutional layers are utilized for models on CIFAR-10, while 5 layers are used for models on CIFAR-100 and ImageNet. We tune the thresholds  $\tau_+$  and  $\tau_-$  by calibrating them to minimize the false positive rate of Gaussian noise and uniform noise. All experiments are implemented in PyTorch [28] and conducted on a workstation equipped with dual 2.40 GHz CPU, 128 GB of RAM, and four NVIDIA RTX 3090Ti GPUs.

**ID/OOD Settings.** We investigate four ID/OOD scenarios: (1) *Small-scale Common OOD Setting*: CIFAR-10 and CIFAR-100 [16] serve as ID datasets. SVHN [25], Textures [2], LSUN-R [45], iSUN [43], and TinyImageNet-R are employed as OOD datasets, with “-R” denoting the resized variants. All images are uniformly resized to a  $32 \times 32$  resolution. (2) *Large-scale Common OOD Setting*: We designate ImageNet-1k [4] as the ID dataset and

select OpenImage-O [41], SUN [42], Places [50], and Textures [2] as OOD datasets. (3) *Small-scale Near-OOD Setting*: CIFAR-10 is utilized as the ID dataset, with CIFAR-100 acting as the OOD dataset, reflecting the semantic closeness of the categories. (4) *Large-scale Near-OOD Setting*: ImageNet-1k [4] is the ID dataset, while ImageNet-O [12] is adopted as the OOD dataset. In particular, the term “near-OOD” is applied to samples that bear semantic resemblance to ID samples [29].

**Setup.** For CIFAR benchmarks [16], we employ ResNet-18 [7], DenseNet-101 [13], and WideResNet-28-10 (WRN-28) [48]. For ImageNet-1k benchmark [4], we utilize VGG-16 [31] and SqueezeNet [15]. The overall settings are consistent with [32, 33, 46].

**Baselines.** We select seven post-hoc OOD detection methods as baselines, including maximum softmax probability (MSP) [10], ODIN [21], Energy [22], ReAct [33], DICE [32], TFEM [51] and FeatureNorm [46].

**Evaluation Metrics.** We evaluate OOD detection using the area under the receiver operating characteristic curve (AUROC) [3] and the false positive rate at a true positive rate of 95% (FPR95) [21], both expressed as percentages.

### 5.2. Experimental Results

**Performance on OOD Detection.** Tab. 1 presents the OOD detection results for ResNet-18, DenseNet-101, and WRN-28 on small-scale datasets. It is evident that our CORES outperforms all competing approaches across different cases. Notably, on the CIFAR-10 dataset, CORES achieves a reduction in average FPR95 of 19.97%, 10.01%, and 5.37% over the next best method, while for CIFAR-100, the reductions are 27.99%, 18.67%, and 13.91%, respectively. These findings underscore CORES’s effectiveness and its pronounced advantage in OOD detection.

Furthermore, Tab. 2 reports the OOD detection performance of VGG-16 and SqueezeNet on large-scale datasets, which pose a greater challenge. Despite this, our CORES still attains the lowest FPR95 and highest AUROC in most cases, underscoring its strong generalization capabilities on large-scale datasets.

**Performance on Near-OOD Detection.** We evaluate our method’s robustness in near-OOD scenarios. Tab. 3 presents the performance with CIFAR-10 as ID and CIFAR-100 as OOD, using ResNet-18 and WRN-28 as the DNN classifiers. In this challenging setting, our method consistently outperforms others, despite a general decline in metrics.

For large-scale datasets, Tab. 4 confirms a similar trend, with our method exhibiting considerable improvements over existing techniques. The MSP baseline shows over a 95% FPR95 for VGG-16 and SqueezeNet, indicating a near-complete breakdown in detection. In contrast, our method achieves at least a 2% better FPR95 and a 4% higher AUROC than any alternative. These findings underscore

Table 1. Comparison on the OOD detection performance of different methods under the small-scale setting.

ID	Model	Method	OOD										Average	
			SVHN		Textures		LSUN-R		iSUN		TinyImageNet-R			
			FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑
CIFAR-10	ResNet-18	MSP	52.12	92.20	59.47	89.56	48.35	93.07	50.30	92.58	59.70	90.48	53.99	91.58
		ODIN	33.83	93.03	45.49	90.01	20.05	96.56	23.09	96.01	19.82	96.63	28.46	94.45
		Energy	30.47	94.05	45.83	90.37	23.62	95.93	27.14	95.34	38.80	93.50	33.17	93.84
		ReAct	40.54	90.54	48.61	88.44	27.01	94.74	30.57	93.95	32.87	94.56	35.92	92.45
		DICE	25.95	94.66	47.22	89.82	27.70	95.01	31.07	94.42	40.86	93.17	34.56	93.42
		TFEM	38.42	93.53	43.81	92.32	19.85	96.59	23.43	96.00	33.78	94.05	31.86	94.50
		FeatureNorm	7.13	98.65	31.18	92.31	27.08	95.25	26.02	95.38	33.91	94.31	25.06	95.18
		Ours	<b>3.92</b>	<b>99.24</b>	<b>10.92</b>	<b>97.85</b>	<b>2.42</b>	<b>99.31</b>	<b>2.13</b>	<b>99.37</b>	<b>6.08</b>	<b>98.76</b>	<b>5.09</b>	<b>98.91</b>
	DenseNet-101	MSP	47.24	93.48	64.15	88.15	42.10	94.51	42.31	94.52	50.34	93.14	49.23	92.76
		ODIN	25.29	94.57	57.50	82.38	3.09	99.02	3.98	98.90	5.97	98.73	19.17	94.72
		Energy	40.61	93.99	56.12	86.43	9.28	98.12	10.07	98.07	18.25	96.99	26.87	94.72
		ReAct	41.64	93.87	43.58	92.47	11.46	97.87	12.72	97.72	18.25	96.99	25.53	95.78
		DICE	25.99	95.90	41.90	88.18	3.91	99.20	4.36	99.14	9.08	98.33	17.05	96.15
		TFEM	30.78	95.27	50.89	90.09	8.15	98.24	8.81	98.21	15.89	97.21	22.90	95.80
		FeatureNorm	16.53	95.81	30.43	90.76	8.66	98.20	10.36	97.94	14.23	97.09	16.04	95.96
		Ours	<b>6.07</b>	<b>98.75</b>	<b>13.10</b>	<b>96.92</b>	<b>2.30</b>	<b>99.39</b>	<b>2.79</b>	<b>99.30</b>	<b>5.90</b>	<b>98.77</b>	<b>6.03</b>	<b>98.63</b>
	WRN-28	MSP	42.10	91.85	53.30	87.45	37.81	93.71	40.11	93.05	42.51	92.12	43.17	91.64
		ODIN	37.08	88.36	47.58	82.85	20.51	95.04	22.95	94.22	28.60	90.24	31.34	90.14
		Energy	33.11	90.54	46.06	85.09	22.68	94.90	25.12	94.17	32.29	92.88	31.85	91.52
		ReAct	15.92	97.06	44.38	91.97	27.98	94.75	31.52	94.17	35.64	93.76	31.09	94.34
		DICE	37.84	86.99	50.77	79.70	26.30	92.89	28.30	92.14	31.70	91.67	34.98	88.68
		TFEM	50.60	89.50	45.30	91.18	11.98	97.70	26.14	94.70	32.29	92.88	33.26	93.19
		FeatureNorm	3.83	99.18	14.23	97.06	8.13	98.32	5.98	98.71	10.91	97.86	8.62	98.23
		Ours	<b>2.80</b>	<b>99.50</b>	<b>6.03</b>	<b>98.79</b>	<b>1.66</b>	<b>99.52</b>	<b>1.27</b>	<b>99.59</b>	<b>4.50</b>	<b>99.06</b>	<b>3.25</b>	<b>99.29</b>
CIFAR-100	ResNet-18	MSP	81.32	77.74	85.11	73.36	82.46	75.73	82.26	76.16	80.07	77.89	82.24	76.18
		ODIN	40.94	93.29	83.63	72.37	79.61	82.13	76.66	83.51	75.35	84.40	71.24	83.14
		Energy	81.74	84.56	85.87	74.94	73.57	82.99	73.36	83.80	71.68	84.76	77.24	82.21
		ReAct	70.81	88.24	59.15	87.96	54.47	89.56	51.89	90.12	54.10	89.44	58.08	89.06
		DICE	50.84	91.15	72.68	76.71	75.29	81.20	74.06	82.14	73.30	83.11	69.23	82.86
		TFEM	61.48	90.63	52.36	89.72	52.68	90.04	48.48	90.94	51.97	89.73	53.39	90.21
		FeatureNorm	22.82	95.33	48.51	83.92	96.73	62.34	94.32	65.30	90.78	67.01	70.63	74.78
		Ours	<b>6.78</b>	<b>98.47</b>	<b>24.38</b>	<b>94.61</b>	<b>34.27</b>	<b>93.57</b>	<b>30.01</b>	<b>94.36</b>	<b>31.58</b>	<b>93.60</b>	<b>25.40</b>	<b>94.92</b>
	DenseNet-101	MSP	81.70	75.40	84.79	71.48	85.24	69.18	85.99	70.17	82.67	73.97	84.08	72.04
		ODIN	41.35	92.65	82.34	71.48	65.22	84.22	67.05	83.84	54.50	87.55	62.09	83.95
		Energy	87.46	81.85	84.15	71.03	70.65	80.14	74.54	78.95	68.45	80.84	77.05	78.56
		ReAct	83.81	81.41	77.78	78.95	60.08	87.88	65.27	86.55	64.84	84.88	70.36	83.93
		DICE	54.65	88.84	65.04	76.42	49.40	91.04	48.72	90.08	43.58	90.96	52.28	87.47
		TFEM	66.99	88.24	59.49	85.95	48.02	91.40	51.10	91.10	48.52	91.33	54.82	89.61
		FeatureNorm	48.39	90.98	48.60	84.89	79.34	83.27	69.93	85.99	63.05	87.38	61.86	86.50
		Ours	<b>25.57</b>	<b>94.50</b>	<b>30.07</b>	<b>92.48</b>	<b>40.06</b>	<b>91.94</b>	<b>38.39</b>	<b>92.09</b>	<b>30.07</b>	<b>92.48</b>	<b>33.61</b>	<b>92.68</b>
	WRN-28	MSP	75.31	81.68	81.13	78.25	79.85	76.69	80.02	75.54	80.47	73.65	79.36	77.16
		ODIN	27.39	94.39	74.29	76.66	65.74	81.62	66.36	81.26	67.08	79.47	60.17	82.68
		Energy	70.93	82.94	80.11	79.04	74.42	79.35	75.56	78.02	76.82	75.72	75.57	79.01
		ReAct	66.05	86.61	68.51	83.00	73.27	74.45	72.92	73.77	75.94	70.91	71.34	77.75
		DICE	68.37	83.14	79.27	78.90	74.17	79.45	75.14	78.13	77.75	75.49	74.94	79.02
		TFEM	71.01	87.50	80.46	78.42	57.01	88.04	72.78	81.48	76.03	78.14	71.46	82.72
		FeatureNorm	19.90	96.40	57.96	79.15	81.92	80.02	81.87	79.11	80.54	78.09	64.44	82.55
		Ours	<b>9.47</b>	<b>98.17</b>	<b>31.86</b>	<b>92.88</b>	<b>65.46</b>	<b>86.63</b>	<b>61.25</b>	<b>87.22</b>	<b>63.27</b>	<b>86.32</b>	<b>46.26</b>	<b>90.24</b>

our approach’s effectiveness and confirm its superiority in near-OOD detection.

### 5.3. Ablation Studies and More Analysis

**Effect of Four Metrics in CORES.** To assess the influence of the four metrics in CORES, we use CIFAR-10 as the ID dataset and contrasting it with a suite of OOD

datasets including SVHN, Textures, LSUN-R, iSUN, and TinyImageNet-R, with WRN-28 serving as the classifier. We consider five configurations of CORES: without the frequency of significant responses (w/o RF), without the magnitude of responses (w/o RM), ignoring negative convolutional responses, disregarding positive convolutional responses, and the complete CORES framework.

Table 2. Comparison on the OOD detection performance of different methods under the large-scale setting.

ID	Model	Method	OOD								Average	
			OpenImage-O		SUN		Places		Textures		FPR95↓	AUROC↑
			FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑	FPR95↓	AUROC↑		
ImageNet-1k	VGG-16	MSP	74.29	81.24	75.66	78.31	77.89	77.60	64.84	81.66	73.17	79.70
		ODIN	68.96	82.88	61.31	86.51	67.33	83.87	44.57	89.82	60.54	85.77
		Energy	70.06	84.74	59.34	86.82	66.27	83.95	43.90	89.94	59.89	86.36
		ReAct	97.83	47.58	99.87	35.01	99.25	37.54	96.45	49.12	98.35	42.31
		DICE	71.81	74.02	58.42	86.71	68.97	83.04	38.95	90.66	59.54	83.61
		TFEM	65.64	76.29	44.03	91.50	48.67	88.84	37.94	88.99	49.07	86.41
		FeatureNorm	57.11	82.91	28.09	94.37	41.78	90.21	23.53	95.05	37.63	90.64
		Ours	<b>51.58</b>	<b>87.24</b>	<b>23.36</b>	<b>95.02</b>	<b>38.49</b>	<b>90.61</b>	<b>14.11</b>	<b>97.26</b>	<b>31.89</b>	<b>92.53</b>
	SqueezeNet	MSP	86.12	71.15	83.03	72.25	87.27	67.00	94.61	41.84	87.76	63.06
		ODIN	80.27	73.21	78.32	78.37	83.23	73.31	92.25	43.43	83.52	67.08
		Energy	74.15	74.28	56.41	87.88	67.74	82.73	67.16	64.51	66.37	77.35
		ReAct	75.75	68.66	87.57	66.37	88.80	66.20	51.05	76.57	75.79	69.45
		DICE	71.81	74.02	50.55	87.46	60.14	83.19	39.89	87.53	55.60	83.05
		TFEM	67.46	79.18	44.61	91.40	56.64	<b>86.38</b>	<b>19.63</b>	<b>96.18</b>	47.08	88.29
FeatureNorm	68.72	77.99	43.91	90.20	56.95	84.83	24.15	94.47	48.43	86.87		
Ours	<b>67.35</b>	<b>80.99</b>	<b>40.23</b>	<b>91.70</b>	<b>54.63</b>	85.78	20.55	95.99	<b>45.69</b>	<b>88.62</b>		

Table 3. Performance comparison of near-OOD detection using CIFAR-10 as ID and CIFAR-100 as OOD.

Method	Model			
	ResNet-18		WRN-28	
	FPR95↓	AUROC↑	FPR95↓	AUROC↑
MSP	64.99	88.35	52.06	88.31
ODIN	52.83	88.57	60.08	73.79
Energy	50.32	89.77	44.92	88.36
ReAct	50.60	90.03	48.03	88.66
DICE	66.95	84.40	44.90	86.48
TFEM	50.04	89.73	44.92	88.35
FeatureNorm	76.17	79.96	58.33	86.64
Ours	<b>47.39</b>	<b>90.25</b>	<b>43.98</b>	<b>91.64</b>

Table 4. Performance comparison of near-OOD detection using ImageNet-1k as ID and ImageNet-O as OOD.

Method	Model			
	VGG-16		SqueezeNet	
	FPR95↓	AUROC↑	FPR95↓	AUROC↑
MSP	96.90	52.29	97.35	52.22
ODIN	87.50	67.94	94.30	60.21
Energy	95.25	64.08	89.65	62.07
ReAct	98.80	39.53	82.60	61.12
DICE	95.25	64.08	85.60	65.46
TFEM	90.85	56.77	80.55	71.81
FeatureNorm	80.20	74.81	81.40	72.65
Ours	<b>72.20</b>	<b>79.10</b>	<b>77.70</b>	<b>78.10</b>

Tab. 5 reveals that each metric is essential to CORES’s performance, with their removal impairing the model’s OOD detection capabilities. The elimination of response magnitude metrics,  $RM^+$  and  $RM^-$ , notably affects performance more than that of frequency metrics,  $RF^+$  and  $RF^-$ , highlighting the value of response magnitudes. The absence of metrics associated with positive responses is particularly detrimental, leading to an approximate 3% in-

Table 5. Ablation study on the four CORES metrics, using the WRN-28 model trained on CIFAR-10 as the DNN classifier. The values are averaged over multiple OOD datasets.

$RM^+$	$RM^-$	$RF^+$	$RF^-$	FPR95↓	AUROC↑
✓	✓			3.81	99.18
		✓	✓	6.33	98.72
✓		✓	✓	5.04	99.02
	✓		✓	5.46	98.79
✓	✓	✓	✓	<b>3.25</b>	<b>99.29</b>

crease in the FPR95 metric. This analysis underscores the integral role each metric plays within CORES, where they contribute collectively to its success.

**Effect of Sample-relevant Kernel Selection.** We evaluate the influence of kernel selection on OOD detection efficacy by analyzing the CORES OOD score distributions. Using CIFAR-10 and CIFAR-100 as ID datasets, we implement models WRN-28, DenseNet-101, and ResNet-18, with LSUN-R as the OOD dataset. For ImageNet-1k, VGG-16 is utilized with Textures as the OOD dataset. Fig. 4 demonstrates that applying kernel selection within CORES significantly diminishes the overlap between ID and OOD score distributions, leading to a notable decrease in FPR95. This reduction is especially marked for CIFAR-100, where FPR95 decreases by approximately 55%, highlighting the benefits of kernel selection in improving model discernment between ID and OOD samples.

**Analysis of CORES Metric Values.** To illustrate the efficacy of the four CORES metrics, we present a visualization of  $RM^+$ ,  $RM^-$ ,  $RF^+$ , and  $RF^-$  across ID and OOD images. Utilizing WRN-28, we select an ID image from each of the CIFAR-10 categories and two OOD images from each of SVHN, LSUN-R, iSUN, TinyImageNet-R, and Textures. As depicted in Fig. 5, ID images consistently show higher values for  $RM^+$ ,  $RM^-$ ,  $RF^+$ , and  $RF^-$  compared

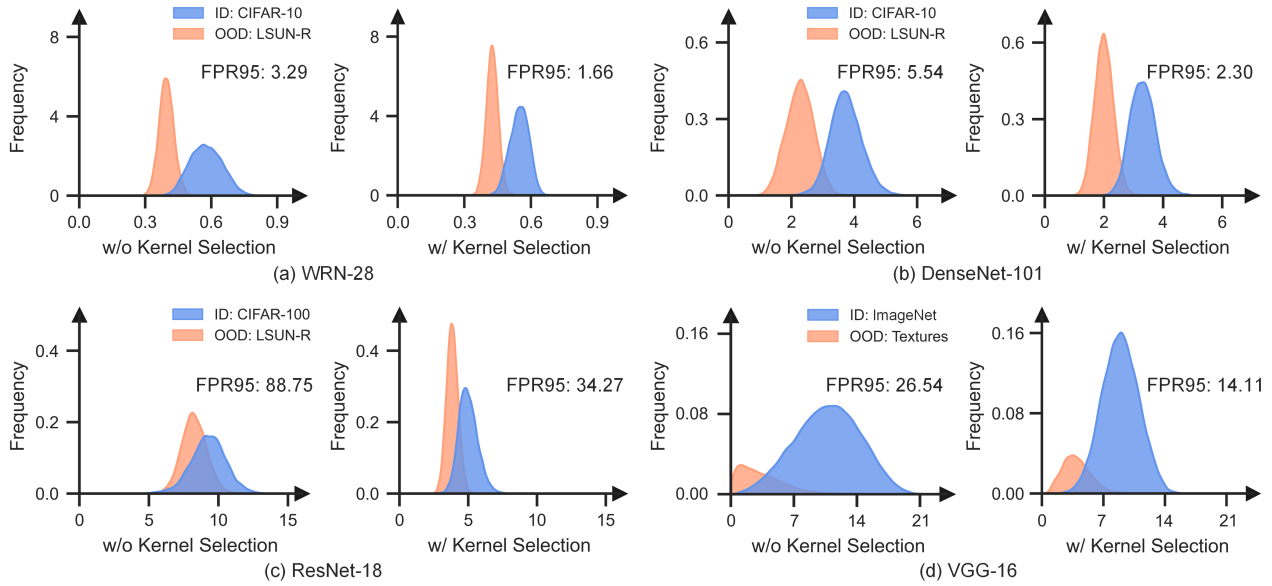


Figure 4. Comparison on the OOD score distributions and FPR95 values of CORES with and without applying sample-relevant kernel selection using different DNN models: (a) WRN-28, (b) DenseNet-101, (c) ResNet-18, and (d) VGG-16.

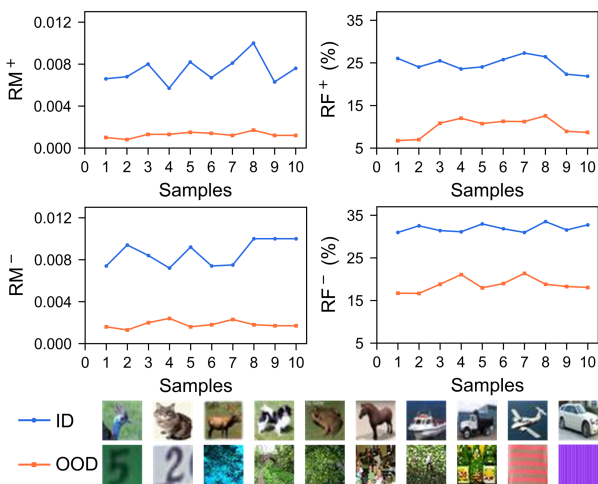


Figure 5. Comparative analysis of four CORES metrics across ID (CIFAR-10) and OOD (SVHN, LSUN-R, iSUN, TinyImageNet-R, Textures) images using WRN-28 as the DNN classifier.

to OOD images, confirming that the CORES metrics proficiently differentiate between ID and OOD samples.

**Effect of Convolutional Layer Count.** To assess how the convolutional layer count influences the performance of CORES in OOD detection, we experiment with the DenseNet-101 network, comparing CIFAR-10 and CIFAR-100 as ID datasets with various OOD datasets. Fig. 6 shows that CORES achieves the lowest performance with a single convolutional layer. Performance improves as more layers are included, with the FPR95 value decreasing and stabilizing at four layers for CIFAR-10 and five layers for CIFAR-

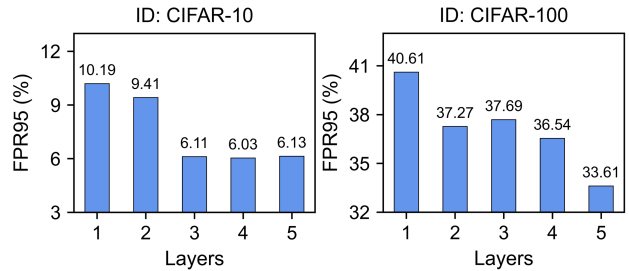


Figure 6. Comparison of CORES's OOD detection performance using different numbers of convolutional layers in DenseNet-101. FPR95 values are averaged over multiple OOD datasets.

100. These findings confirm that CORES is more effective when leveraged across multiple convolutional layers.

## 6. Conclusion

In this paper, we have proposed a novel Convolutional Response-based Score (CORES) for OOD detection. The rationale is that convolutional kernels generally produce more pronounced responses for ID samples compared to OOD ones, as the kernels are trained for fitting ID samples. Extensive experiments validate the effectiveness of CORES in OOD detection, and its superiority to the state-of-the-art methods. Future plans include applying convolutional responses to more security issues, such as adversarial attacks.

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