

EditGuard: Versatile Image Watermarking for Tamper Localization and Copyright Protection

Xuanyu Zhang^{1,2}, Runyi Li¹, Jiwen Yu¹, Youmin Xu¹, Weiqi Li¹, Jian Zhang^{1,2} ✉

¹ School of Electronic and Computer Engineering, Peking University

² Peking University Shenzhen Graduate School-Rabbitpre AIGC Joint Research Laboratory

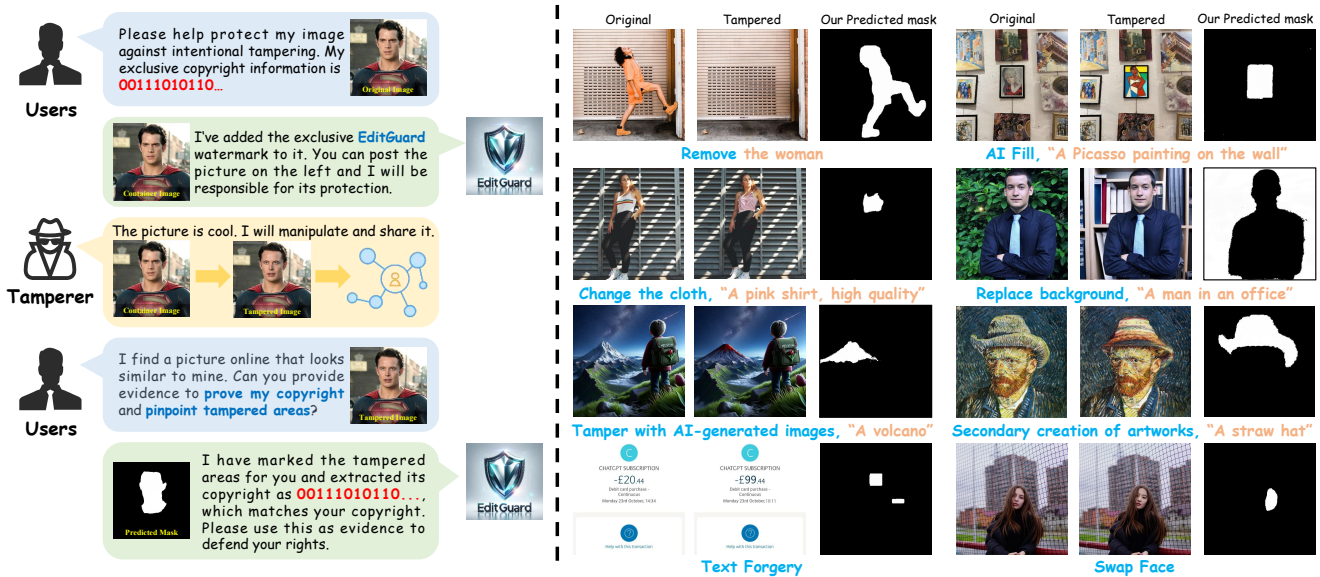


Figure 1. We propose a versatile proactive forensics framework **EditGuard**. The application scenario is shown on the left, wherein users embed invisible watermarks to their images via EditGuard in advance. If suffering tampering, users can defend their rights via the tampered areas and copyright information provided by EditGuard. Some supported tampering methods (marked in blue) and localization results of EditGuard are placed on the right. Our EditGuard can achieve over **95%** localization precision and nearly **100%** copyright accuracy.

Abstract

In the era of AI-generated content (AIGC), malicious tampering poses imminent threats to copyright integrity and information security. Current deep image watermarking, while widely accepted for safeguarding visual content, can only protect copyright and ensure traceability. They fall short in localizing increasingly realistic image tampering, potentially leading to trust crises, privacy violations, and legal disputes. To solve this challenge, we propose an innovative proactive forensics framework **EditGuard**, to unify copyright protection and tamper-agnostic localization, especially for AIGC-based editing methods. It can offer a meticulous embedding of imperceptible watermarks and precise decoding of tampered areas and copyright information. Leveraging our observed fragility and locality of image-into-image steganography, the realization of Edit-

Guard can be converted into a united image-bit steganography issue, thus completely decoupling the training process from the tampering types. Extensive experiments verify that our EditGuard balances the tamper localization accuracy, copyright recovery precision, and generalizability to various AIGC-based tampering methods, especially for image forgery that is difficult for the naked eye to detect.

1. Introduction

Owing to the advantageous properties of diffusion models and the bolstering of extensive datasets, AI-generated content (AIGC) models like DALL-E 3 [14], Imagen [52], and Stable Diffusion [51], can produce lifelike and wondrous images, which brings great convenience to photography enthusiasts and image editors. Nonetheless, the remarkable capabilities of these models come with a double-edged sword, presenting new challenges in copyright protection and information security. The efficiency of image manipulation [43, 47, 49, 51, 55, 68, 72] has blurred the

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line between fact and forgery, ushering in myriad security and legal concerns. For instance, artistic works are vulnerable to malicious tampering or unauthorized AI-facilitated recreations, making it challenging to protect their original creations [13]. Meanwhile, forged images may be spread online or used as court evidence, causing adverse effects on public opinion, ethical issues, and social stability.

Given the challenges of preventing image tampering from the source, image watermarking has become a consensus for proactive forensics [54]. However, most prevalent forensic image watermarking [12, 15, 44, 62] still focus on detecting image authenticity or protecting image copyrights, but fall short when it comes to advanced demands, such as localizing tampered areas. Tamper localization facilitates an evaluation of the severity of the image manipulation, and provides an understanding of the intent of attackers, potentially allowing for the partial reuse of the tampered images. However, most passive forensics methods such as previous black-box localization networks [8, 56, 61] tend to seek anomalies like artifacts or flickers in images but struggle to detect more realistic textures and more advanced AIGC models. Moreover, they inevitably need to introduce tampered data during the training and focus solely on specific “CheapFake” tampering like slicing and copy-and-paste [8, 45, 56], or on “DeepFake” targeting human faces [2, 50], restricted in generalizability. Thus, it is vital to develop an integrated watermarking framework that unites tamper-agnostic localization and copyright protection.

To clarify our task scope, we re-emphasize the definition of dual forensics tasks as illustrated in Fig. 1: **(1) Copyright protection:** “Who does this image belong to?” We aspire to accurately retrieve the original copyright of an image, even suffering various tampering and degradation. **(2) Tamper localization:** “Where was this image manipulated?” We aim to precisely pinpoint the tampered areas, unrestrained by specific tampering types. To the best of our knowledge, no existing method accomplishes these two tasks simultaneously, while maintaining a balance of high precision and extensive generalizability.

To address this urgent demand, we propose a novel proactive forensics framework, dubbed **EditGuard**, to protect copyrights and localize tamper areas for AIGC-based editing methods. Specifically, drawing inspiration from our observed locality and fragility of image-into-image (I2I) steganography and inherent robustness of bit-into-image steganography, we can transform the realization of EditGuard into a joint image-bit steganography issue, which allows the training of EditGuard to be entirely decoupled from tampering types, thereby endowing it with exceptional generalizability and locate tampering in a zero-shot manner. In a nutshell, our contributions are as follows:

□ (1) We present the first attempt to design a deep versatile proactive forensics framework **EditGuard** for univer-

sal tamper localization and copyright protection. It embeds dual invisible watermarks into original images and accurately decodes tampered areas and copyright information.

□ (2) We have observed the fragility and locality of I2I steganography and innovatively convert the solution of this dual forensics task into training a united Image-Bit Steganography Network (IBSN), and utilize the core components of IBSN to construct EditGuard.

□ (3) We introduce a prompt-based posterior estimation module to enhance the localization accuracy and degradation robustness of the proposed framework.

□ (4) The effectiveness of our method has been verified on our constructed dataset and classical benchmarks. Compared to other competitive methods, our approach has notable merits in localization precision, generalization abilities, and copyright accuracy without any labeled data or additional training required for specific tampering types.

2. Related works

2.1. Tamper Localization

Prevalent passive image forensic techniques have focused on localizing specific types of manipulations [25, 33, 34, 53, 61, 75]. Meanwhile, some universal tamper localization methods [5, 23, 31, 35, 63, 65–67] also tend to explore artifacts and anomalies in tampered images. For instance, MVSS-Net [8] employed multi-view feature learning and multi-scale supervision to jointly exploit boundary artifacts and the noise view of images. OSN [61] proposed a novel robust training scheme to address the challenges posed by lossy operations. Trufor [17] used a learned noise-sensitive fingerprint and extracted both high-level and low-level traces via transformer-based fusion. HiFi-Net [18] utilized multi-branch feature extractor and localization modules for both CNN-synthesized and edited images. SAFL-Net [56] constrained a feature extractor to learn semantic-agnostic features with specific modules and auxiliary tasks. However, the above-mentioned passive localization methods are often limited in terms of generalization and localization accuracy, which usually work on known tampering types that have been trained. Although MaLP [2] used template matching for proactive tamper localization, it still requires a large number of forgery images and cannot fully decouple the network training from the tamper types.

2.2. Image Watermarking

Image watermarking can be broadly used for the verification, authenticity, and traceability of images. Although traditional fragile watermarking [6, 24, 29, 36, 37, 48] can also achieve block-wise tamper localization, their localization accuracy and flexibility are unsatisfactory. How to realize joint pixel-level tamper localization and copyright protection remains largely unexplored. Owing to the development

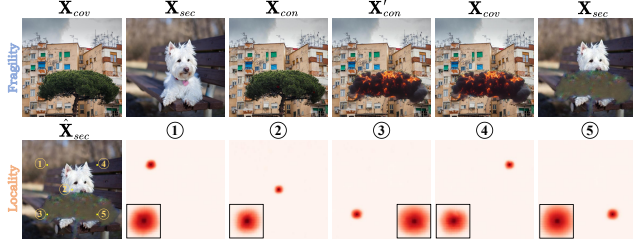


Figure 2. Fragility and locality of I2I steganography. The first line shows that when X'_{con} is changed, \hat{X}_{sec} will also be fragilely damaged. The second line plots the attribution maps $\frac{1}{|\mathbb{S}|} \sum_{(i,j) \in \mathbb{S}} \frac{\partial \hat{X}_{sec}^{[i,j]}}{\partial X'_{con}}$ of five point sets \mathbb{S} (marked by ①-⑤) in \hat{X}_{sec} . We observed that \hat{X}_{sec} almost only has a strong response at the corresponding positions of X'_{con} and its neighborhoods.

of deep learning, deep image watermarking has attracted increased attention. For instance, HiDDeN [74] firstly introduced a deep encoder-decoder network to hide and recover bitstream. Moreover, many distortion layers such as differentiable JPEG and screen-shooting [1, 10, 40, 62] were designed to enhance its robustness. Flow-based models [11, 44] were also utilized to further improve the fidelity of container images. Recently, researchers [7, 12, 27, 59, 73] have designed specialized watermarking mechanisms for large-scale image generation models [51], to merge watermarking into the generation process. However, these deep watermarking methods have a singular function and cannot accurately localize the tampered areas.

3. Overall Framework of EditGuard

3.1. Motivation

Challenges of existing methods: (1) How to equip existing watermark methods, which are solely for copyright protection, with the ability to localize tampering is the crux of EditGuard. We will solve it via the framework design in Sec. 3.2. (2) Most previous tamper localization methods inevitably introduce specific tampering data during network training but tend to raise generalization concerns in unknown tampering types, which will be addressed in Sec. 3.3.

Our observations: Fortunately, we observed that image-into-image (I2I) steganography exhibits distinct fragility and locality, possessing great potential to address these issues. Concretely, I2I steganography [3, 28, 42, 46, 64, 69] aims to hide a secret image X_{sec} into a cover image X_{cov} to produce a container image X_{con} , and reveal \hat{X}_{sec} and \hat{X}_{cov} with minimal distortion from the received image X'_{con} . We discover that when X'_{con} undergoes significant alteration compared to X_{con} , \hat{X}_{sec} will also be damaged and generate artifacts (the first row of Fig. 2), which is called **fragility**. Furthermore, we notice that the artifacts in \hat{X}_{sec} are almost pixel-level corresponding to the changes in X'_{con} relative to X_{con} , which is called **locality**. To demonstrate this locality,

we select five 7×7 point sets on \hat{X}_{sec} and calculated their attribution maps with respect to X'_{con} . As plotted in the second row of Fig. 2, \hat{X}_{sec} only exhibits a strong response at the corresponding locations of X'_{con} and their immediate vicinity, almost irrelevant to other pixels. These properties inspire us to treat X_{sec} as a special localization watermark and embed it within existing watermarking frameworks.

3.2. Framework Design and Forensics Process

To realize united tamper localization and copyright protection, EditGuard is envisioned to embed both a 2D localization watermark and a 1D copyright traceability watermark into the original image in an imperceptible manner, which allows the decoding end to obtain the copyright of the images and a binary mask reflecting tampered areas. However, designing such a framework needs to solve the compatibility issue of two types of watermarks.

(1) **Local vs. Global:** The localization watermark is required to be hidden in the corresponding pixel positions of the original image, while the copyright watermark should be unrelated to spatial location and embedded in the global area redundantly. (2) **Semi-fragile vs. Robust:** The desired attribute of the localization watermark is semi-fragile, which means it is fragile to tampering but robust against some common degradations (such as Gaussian noise, JPEG compression, and Poisson noise) during network transmission. However, the copyright should be extracted nearly losslessly, irrespective of tampering or degradation.

To address the two pivotal conflicts, EditGuard employs a “**sequential encoding and parallel decoding**” structure, which comprises a dual-watermark encoder, a tamper locator, and a copyright extractor. As shown in Fig. 3, the dual-watermark encoder will sequentially add pre-defined localization watermark and global copyright watermark w_{cop} provided by users to the original image I_{ori} , forming the container image I_{con} . Our experiments have proved that parallel encoding cannot effectively add dual watermarks into images (in supplementary materials (S.M.)). In contrast, sequential embedding effectively prevents cross-interference by hiding these two watermarks. Furthermore, we model the network transmission process in which the received (tampered) image I_{rec} is transformed from I_{con} as:

$$I_{rec} = \mathcal{D}(I_{con} \odot (\mathbf{1} - \mathbf{M}) + \mathcal{T}(I_{con}) \odot \mathbf{M}), \quad (1)$$

where $\mathcal{T}(\cdot)$, $\mathcal{D}(\cdot)$ and \mathbf{M} respectively denote the tamper function, degradation operation, and tempered mask. Moreover, the parallel decoding processes allow us to flexibly train each branch under different levels of robustness and obtain the predicted mask $\hat{\mathbf{M}}$ via the tamper locator and traceability watermark \hat{w}_{cop} via the copyright extractor. We can categorize the dual forensic process of EditGuard into the following scenarios.

□ **Case 1:** If $\hat{w}_{cop} \not\approx w_{cop}$, suspicious I_{rec} is either not

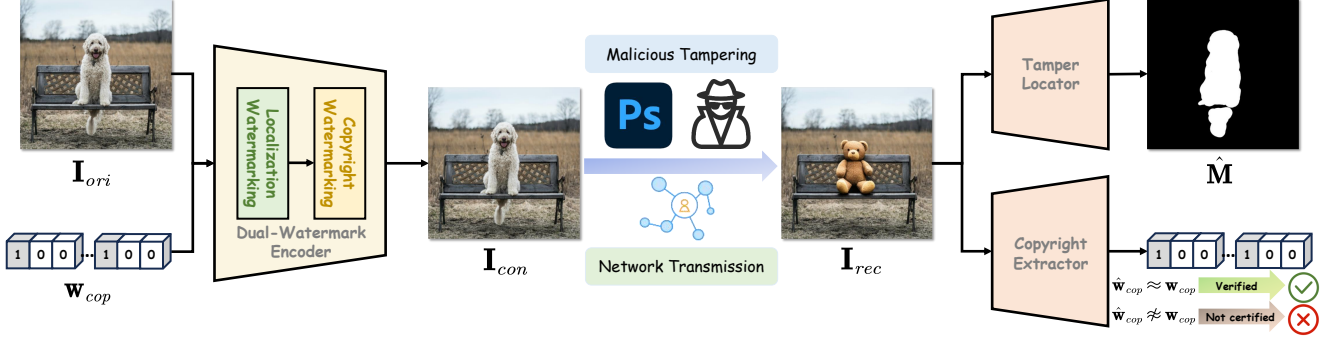


Figure 3. Illustration of the proposed proactive forensics framework EditGuard. The dual-watermark encoder sequentially embeds the pre-defined localization watermark and copyright watermark \mathbf{w}_{cop} into the original image \mathbf{I}_{ori} , generating the container image \mathbf{I}_{con} . After encountering potential malicious tampering and degradation during network transmission, tampered mask $\hat{\mathbf{M}}$ and copyright information $\hat{\mathbf{w}}_{cop}$ are respectively extracted via the tamper locator and copyright extractor from the received image \mathbf{I}_{rec} .

registered in our EditGuard or underwent extremely severe global tampering, rendering it unreliable as evidence.

□ **Case 2:** If $\hat{\mathbf{w}}_{cop} \approx \mathbf{w}_{cop}$ and $\hat{\mathbf{M}} \neq \mathbf{0}$, suspicious \mathbf{I}_{rec} has undergone tampering, disqualifying it as valid evidence. Users may infer the intention of tamperers based on $\hat{\mathbf{M}}$ and decide whether to reuse parts of the image.

□ **Case 3:** If $\hat{\mathbf{w}}_{cop} \approx \mathbf{w}_{cop}$ and $\hat{\mathbf{M}} \approx \mathbf{0}$, \mathbf{I}_{rec} remains untampered and trustworthy under the shield of EditGuard.

3.3. Transform Dual Forensics into Steganography

To realize universal and tamper-agnostic localization, we resort to our observed locality and fragility of I2I steganography. As described in Sec. 3.1, localization watermarking and tamper locator in Fig. 3 can be effectively realized via image hiding and revealing. Meanwhile, combining with the robustness of current bit-into-image steganography, copyright watermarking and extractor in Fig. 3 are achieved via bit encryption and recovery. Thus, we can convert the realization of the dual forensics framework EditGuard into a united image-bit steganography network. **Our training objective is just a self-recovery mechanism, meaning it only needs to ensure the input and output of the steganography network maintain high fidelity under various robustness levels, with no need to introduce any labeled data or tampered samples.** During inference, it can naturally locate tampering via simple comparisons in a zero-shot manner and extract copyright exactly.

4. United Image-bit Steganography Network

4.1. Network Architecture

As plotted in Fig. 4, the proposed IBSN includes an image hiding module (IHM), a bit encryption module (BEM), a bit recovery module (BRM), and an image revealing module (IRM). First, the IHM aims to hide a localization watermark $\mathbf{W}_{loc} \in \mathbb{R}^{H \times W \times 3}$ into the original image $\mathbf{I}_{ori} \in \mathbb{R}^{H \times W \times 3}$, resulting in an intermediate output $\mathbf{I}_{med} \in \mathbb{R}^{H \times W \times 3}$. Subsequently, \mathbf{I}_{med} is fed to the BEM for feature refinement,

while the copyright watermark $\mathbf{w}_{cop} \in \{0, 1\}^L$ is modulated into the BEM, forming the final container image $\mathbf{I}_{con} \in \mathbb{R}^{H \times W \times 3}$. After network transmission, the BRM will faithfully reconstruct the copyright watermark $\hat{\mathbf{w}}_{cop}$ from the received container image \mathbf{I}_{rec} . Meanwhile, \mathbf{I}_{rec} predicts the missing information $\hat{\mathbf{Z}}$ via the prompt-based posterior estimation and uses it as the initialization for the invertible blocks, producing $\hat{\mathbf{I}}_{ori}$ and semi-fragile watermark $\hat{\mathbf{W}}_{loc}$.

4.2. Invertible Blocks in IHM and IRM

Given the inherent capacity of flow-based models to precisely recover multimedia information, we harness stacked invertible blocks to construct image hiding and revealing modules. The original image $\mathbf{I}_{ori} \in \mathbb{R}^{H \times W \times 3}$ and localization watermark $\mathbf{W}_{loc} \in \mathbb{R}^{H \times W \times 3}$ will undergo discrete wavelet transformations (DWT) to yield frequency-decoupled image features. We then employ enhanced additive affine coupling layers to project the original image and its corresponding localization watermark branches. The transformation parameters are generated from each other. The enhanced affine coupling layer is composed of a five-layer dense convolution block [46] and a lightweight feature interaction module (LFIM) [4]. The LFIM can enhance the non-linearity of transformations and capture the long-range dependencies with low computational cost. More details are presented in S.M. Finally, the revealed features are then transformed to the image domain via the inverse DWT.

4.3. Prompt-based Posterior Estimation

To bolster the fidelity and robustness of the image hiding and revealing module, we introduce a degradation prompt-based posteriori estimation module (PPEM). Since the encoding network tends to compress $[\mathbf{I}_{ori}; \mathbf{W}_{loc}] \in \mathbb{R}^{H \times W \times 6}$ into the container image $\mathbf{I}_{con} \in \mathbb{R}^{H \times W \times 3}$, previous methods [42, 64] typically utilized a random Gaussian initialization or an all-zero map at the decoding end to compensate for the lost high-frequency channels. Yet, our observations suggest that discarded information lurks within the

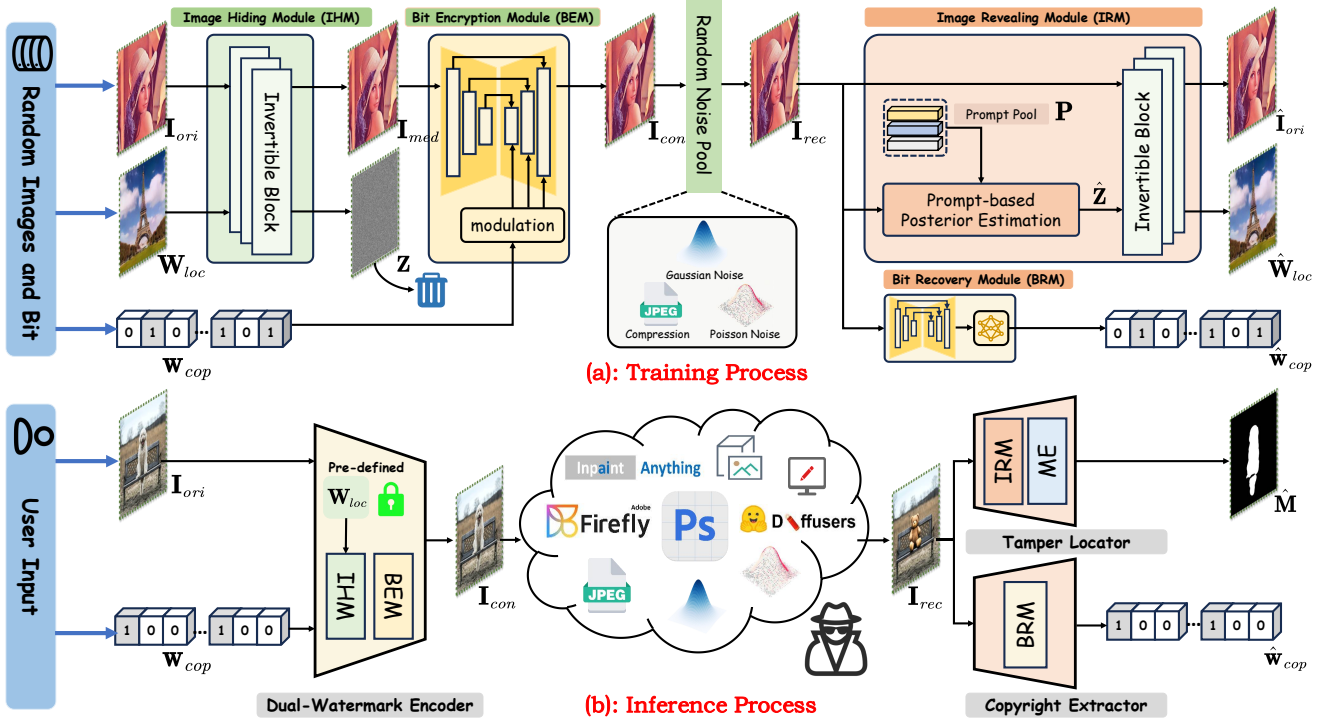


Figure 4. Illustration of the united Image-bit Steganography Network (IBSN). In the training process, we randomly sample original image I_{ori} , localization watermark W_{loc} (a natural RGB image) and copyright watermark w_{cop} and expect the IBSN to recover \hat{I}_{ori} , \hat{W}_{loc} and \hat{w}_{cop} with high fidelity. In the inference process, we use core components of the pre-trained IBSN with a mask extractor (ME) to construct our EditGuard, and pre-define a simple solid color image as a localization watermark.

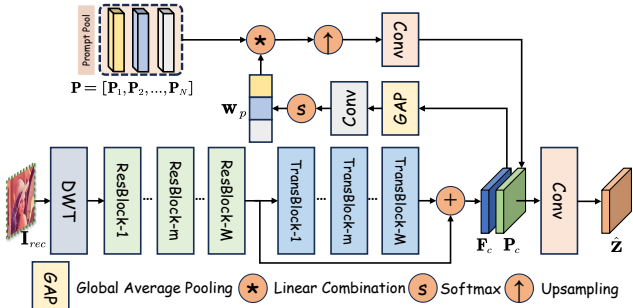


Figure 5. Illustration of the proposed prompt-based posterior estimation. It will dynamically fuse degraded representations and extracted features to obtain posterior mean $\hat{Z} = \mathbb{E}[Z|I_{rec}]$.

edges and textures of the container image. Thus, deploying a dedicated network proves to be a more potent strategy in predicting the posterior mean of the vanished localization watermark information $\hat{Z} = \mathbb{E}[Z|I_{rec}]$. Specifically, as shown in Fig. 5, we stack M residual blocks $\text{Res}(\cdot)$ [19] and M channel-wise transformer blocks $\text{Trans}(\cdot)$ [70] to extract the local and non-local features F_c .

$$F_c = \text{Trans}(\text{Res}(\text{DWT}(I_{rec}))) + \text{Res}(\text{DWT}(I_{rec})). \quad (2)$$

Considering that the container image is prone to various degradations during network transmission, we pre-define N learnable embedding tensors as degradation prompts $\mathbf{P} = [P_1, P_2, \dots, P_N]$, where N denotes the number of degradation types and is set to 3. These learned prompts \mathbf{P} can

adaptively learn a diverse range of degradation representations and are integrated with the intrinsic features extracted from I_{rec} , enabling the proposed IBSN to handle multiple types of degradations using a single set of parameters. To better foster the interaction between the input features F_c and the degradation prompt \mathbf{P} , the features F_c are passed to a global average pooling (GAP) layer, a 1×1 convolution, and a softmax operator to produce a set of dynamic weight coefficients. Each degradation prompt P_i is combined using these dynamic coefficients $w_{p \otimes i}$ and subsequently integrated via an upsampling operator \uparrow and 3×3 convolution to obtain the enhanced representation P_c .

$$P_c = \text{Conv}_{3 \times 3} \left(\left(\sum_{i=1}^N w_{p \otimes i} P_i \right) \uparrow \right), \quad (3)$$

$$\text{where } w_p = \text{Softmax}(\text{Conv}_{1 \times 1}(\text{GAP}(F_c))).$$

Finally, we utilize a 3×3 convolution to fuse the learned degradation representation conditioned on the extracted features F_c to enrich the degradation-specific context, obtaining \hat{Z} . This process can be formulated as:

$$\hat{Z} = \text{Conv}_{3 \times 3}([P_c; F_c]) \in \mathbb{R}^{\frac{H}{2} \times \frac{W}{2} \times 12}. \quad (4)$$

4.4. Bit Encryption and Recovery Modules

As shown in Fig. 4, to encode the copyright watermark w_{cop} into I_{med} , we firstly expand $w_{cop} \in \{0, 1\}^L$ via stacked MLPs and reshape it into several $L \times L$ message feature

Table 1. Localization precision (F1-Score) and bit accuracy (BA) comparison with other competitive methods on [9, 16, 20, 58].

Method	CAISAv1 [9]		Coverage [58]		NIST16 [16]		Columbia [20]	
	F1	BA(%)	F1	BA(%)	F1	BA(%)	F1	BA(%)
ManTraNet [63]	0.320	-	0.486	-	0.225	-	0.650	-
SPAN [22]	0.169	-	0.428	-	0.363	-	0.873	-
CAT-Net v2 [32]	<u>0.852</u>	-	0.582	-	0.417	-	<u>0.923</u>	-
OSN [61]	0.676	-	0.472	-	0.449	-	0.836	-
MVSS-Net [8]	0.650	-	0.659	-	0.372	-	0.781	-
PSCC-Net [39]	0.670	-	0.615	-	0.210	-	0.760	-
TruFor [17]	0.822	-	<u>0.735</u>	-	<u>0.470</u>	-	0.914	-
EditGuard (Ours)	0.954	99.91	0.955	100	0.911	99.88	0.988	99.93

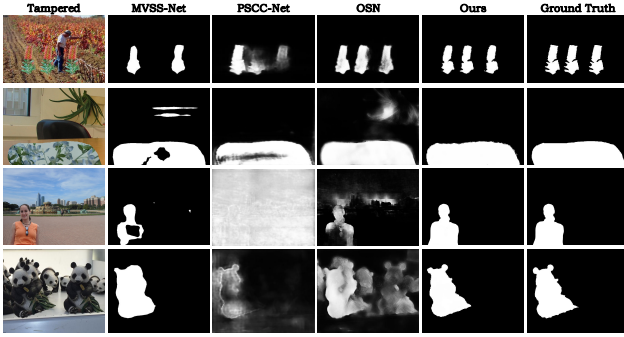


Figure 6. Localization precision comparisons of our EditGuard and competitive methods [8, 39, 61] on four classical benchmarks.

maps. Meanwhile, \mathbf{I}_{med} is fed to a U-style feature enhancement network to extract features of each downsampling and upsampling layer. Finally, the message features will be up-scaled and integrated with multi-level image features via the fusion mechanism [21, 62], achieving the modulation of bit-image information. In the decoding end, \mathbf{I}_{rec} is fed into a U-shaped sub-network and downsampled to a size of $L \times L$. The recovered copyright watermark $\hat{\mathbf{w}}_{cop}$ is then extracted via an MLP. More details are presented in **S.M.**.

4.5. Construct EditGuard via the IBSN

To stabilize the optimization of the proposed IBSN, we propose a bi-level optimization strategy. Given an arbitrary original image \mathbf{I}_{med} and watermark \mathbf{w}_{cop} , we first train the bit encryption and recovery module via the ℓ_2 loss.

$$\ell_{cop} = \|\mathbf{I}_{con} - \mathbf{I}_{med}\|_2^2 + \lambda \|\hat{\mathbf{w}}_{cop} - \mathbf{w}_{cop}\|_2^2, \quad (5)$$

where λ is set to 10. Furthermore, we freeze the weights of BEM and BRM and jointly train the IHM and IRM. Given a random original image \mathbf{I}_{ori} , localization watermark \mathbf{W}_{loc} and copyright watermark \mathbf{w}_{cop} , the loss function is:

$$\ell_{loc} = \|\hat{\mathbf{I}}_{ori} - \mathbf{I}_{ori}\|_1 + \alpha \|\mathbf{I}_{con} - \mathbf{I}_{ori}\|_2^2 + \beta \|\hat{\mathbf{W}}_{loc} - \mathbf{W}_{loc}\|_1, \quad (6)$$

where α and β are respectively set to 100 and 1. During training, we only introduced degradations to \mathbf{I}_{con} without being exposed to any tampering. After acquiring a pre-trained IBSN, we can construct the proposed EditGuard via the components of IBSN. As plotted in Fig. 4, the dual-watermark encoder of EditGuard is composed of IHM and BEM, which correspond to the localization and copyright watermarking in Fig. 3 respectively. The copyright extractor strictly corresponds to BRM. The tamper locator

Table 2. Visual quality of the container image \mathbf{I}_{con} and bit accuracy comparison with other pure watermarking methods.

Method	Image Size	M. L.	PSNR (dB)	SSIM	NIQE(↓)	BA(%)
MBRS [26]	128×128	30	26.57	0.886	7.219	100
CIN [44]	128×128	30	41.35	0.981	7.171	<u>99.99</u>
PIMoG [10]	128×128	30	36.22	0.941	7.113	<u>99.99</u>
SepMark [62]	128×128	30	35.42	0.931	<u>7.095</u>	99.86
EditGuard	128×128	30	<u>36.93</u>	<u>0.944</u>	5.567	99.89
EditGuard	512×512	64	37.77	0.949	4.257	99.95

includes IRM and a mask extractor (ME). Note that we need to pre-define a localization watermark \mathbf{W}_{loc} , which is shared between the encoding and decoding ends. The choice of \mathbf{W}_{loc} is very general to our method. It can be any natural image or even a solid color image. Finally, by comparing the pre-defined watermark \mathbf{W}_{loc} with the decoded one $\hat{\mathbf{W}}_{loc}$, we can obtain a binary mask $\hat{\mathbf{M}} \in \mathbb{R}^{H \times W}$:

$$\hat{\mathbf{M}}[i, j] = \theta_\tau(\max(|\hat{\mathbf{W}}_{loc}[i, j, :] - \mathbf{W}_{loc}[i, j, :]|)). \quad (7)$$

where $i \in [0, H)$ and $j \in [0, W)$. $\theta_\tau(z) = 1$ ($z \geq \tau$). τ is set to 0.2. $|\cdot|$ is an absolute value operation.

5. Experiments

5.1. Implementation Details

We trained our EditGuard via the training set of COCO [38] **without any tampered data**. Thus, for tamper localization, our method is actually zero-shot. The Adam [30] is used for training 250K iterations with $\beta_1=0.9$ and $\beta_2=0.5$. The learning rate is initialized to 1×10^{-4} and decreases by half for every 30K iterations, with the batch size set to 4. We embed a 64-bit copyright watermark and a simple localization watermark such as a pure blue image ($[R, G, B] = [0, 0, 255]$) to original images. Following [8, 17, 39], F1-score, AUC, IoU, and bit accuracy are used to evaluate localization and copyright protection performance. Since no prior methods can simultaneously achieve this dual forensics, we conducted separate comparisons with tamper localization and image watermarking methods.

5.2. Comparison with Localization Methods

For a fair comparison with tamper localization methods, we conducted extensive evaluations on four classical benchmarks [9, 16, 20, 58], as reported on Tab. 1. Since EditGuard is a proactive approach, we initially embed watermarks into authentic images and then paste the tampered areas into the container images. Remarkably, even for tamper types that existing methods specialize in, the localization accuracy of EditGuard consistently outperforms the SOTA method [17] across four datasets by margins of **0.102, 0.116, 0.441, and 0.065 in F1-score without any labeled data or tampered samples required**, which verifies the superiority of our proactive localization mechanism. As shown in Fig. 6, our EditGuard can precisely pinpoint pixel-level tampered areas but other methods can only produce a rough outline or are only effective in some cases. Mean-

Table 3. Comparison with other competitive tamper localization methods under different AIGC-based editing methods. Note that † denotes the network finetuned in our constructed AGE-Set-C.

Method	Stable Diffusion Inpaint [51]			Controlnet [72]			SDXL [49]				RePaint [43]				Lama [57]				FaceSwap [60]					
	F1	AUC	IoU	BA(%)	F1	AUC	IoU	BA(%)	F1	AUC	IoU	BA(%)	F1	AUC	IoU	BA(%)	F1	AUC	IoU	BA(%)				
MVSS-Net [8]	0.178	0.488	0.103	-	0.178	0.492	0.103	-	0.037	0.503	0.028	-	0.104	0.546	0.082	-	0.024	0.505	0.022	-	0.285	0.612	0.192	-
OSN [61]	0.174	0.486	0.101	-	0.191	0.644	0.110	-	0.200	0.755	0.118	-	0.183	0.644	0.105	-	0.170	0.430	0.099	-	0.308	0.791	0.171	-
PSCC-Net [39]	0.166	0.501	0.112	-	0.177	0.565	0.116	-	0.189	0.704	0.115	-	0.140	0.469	0.109	-	0.132	0.329	0.104	-	0.157	0.346	0.180	-
IML-VIT [45]	0.213	0.596	0.135	-	0.200	0.576	0.128	-	0.221	0.603	0.145	-	0.103	0.497	0.059	-	0.105	0.465	0.064	-	0.105	0.465	0.064	-
HiFi-Net [18]	0.547	0.734	0.128	-	0.542	0.735	0.123	-	0.633	0.828	0.261	-	0.681	0.896	0.339	-	0.483	0.721	0.029	-	0.781	0.890	0.478	-
MVSS-Net† [8]	0.694	0.939	0.575	-	0.678	0.925	0.558	-	0.482	0.884	0.359	-	0.185	0.529	0.111	-	0.393	0.829	0.275	-	0.459	0.739	0.333	-
EditGuard (Ours)	0.966	0.971	0.936	99.95	0.968	0.987	0.940	99.96	0.965	0.989	0.936	99.96	0.967	0.977	0.938	99.95	0.965	0.969	0.934	99.95	0.896	0.943	0.876	99.86

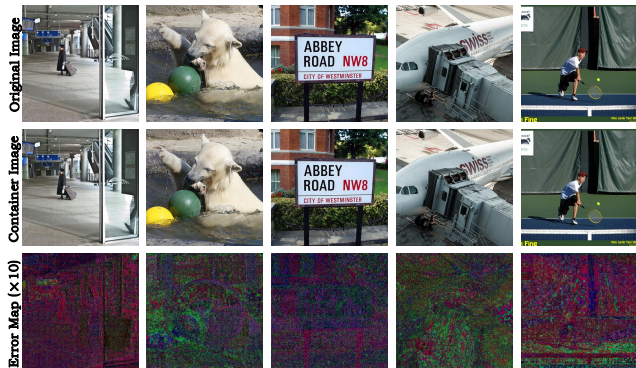


Figure 7. Visual results of the container image I_{con} and the error map of the proposed EditGuard. Here, localization and copyright watermarks are randomly selected from the dataset.

while, our bit accuracy remains over **99.8%** while all other methods can not realize effective copyright protection.

5.3. Comparison with Watermarking Methods

To evaluate the visual quality of I_{con} , we compared EditGuard with other watermarking methods on $1K$ testing images from COCO [38] under the tampering of stable diffusion inpaint [51]. For a fair comparison, we also retrained our EditGuard on 128×128 original images and 30 bits. Tab. 2 reports that the fidelity of our container image far surpasses that of SepMark [62], PIMoG [10], and MBRS [26] but is slightly inferior to CIN [44]. Meanwhile, our method exhibits the best performance in perceptual quality measures like NIQE. As shown in Fig. 7, dual-watermarked images do not have noticeable artifacts and noise, making them imperceptible to the human eyes. When suffer malicious tampering, our method outperforms SepMark and is very close to PIMoG and CIN in bit accuracy. Note that other competitive methods only hide 30 bits, with a capacity of $30/(128 \times 128)$. In contrast, our EditGuard hides both an RGB localization watermark and a 1D copyright watermark, with a capacity far greater than $30/(128 \times 128)$. Here, we do not claim to achieve the best visual quality and bit accuracy, but just to demonstrate that our method is comparable to the current image watermarking methods.

5.4. Extension to AIGC-based Editing Methods

Dataset Preparation: We constructed a dataset tailored for AIGC Editing methods, dubbed AGE-Set, comprising two sub-datasets. The first AGE-Set-C is a batch-processed coarse tamper dataset. Its original images are sourced from

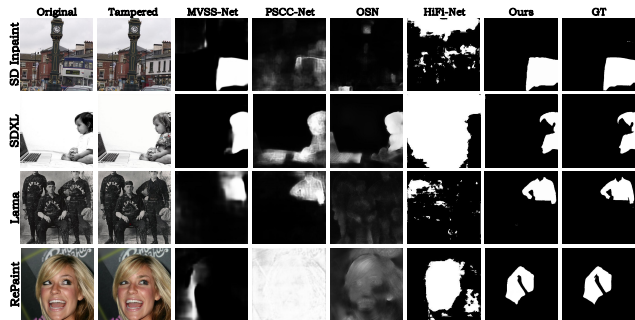


Figure 8. Localization performance comparisons of our EditGuard and other methods [8, 18, 39, 61] on our constructed AGE-Set-C.

COCO 2017 [38] and CelebA [41], containing $30K$ training images and $1.2K$ testing images. We used some SOTA editing methods such as Stable Diffusion Inpaint [51], Controlnet [72], SDXL [49] to manipulate images with the prompt to be “None”, and employed some unconditional methods like Repaint [43], Lama [57], and Faceswap [60]. **Note that we only use the tampered data to train other methods, not our EditGuard.** The second sub-dataset AGE-Set-F includes 100 finely edited images. It is edited manually via some sophisticated software such as SD-Web-UI, Photoshop, and Adobe Firefly. These AIGC-based editing methods can achieve a good fusion of the tampered and unchanged areas, making it hard for the naked eye to catch artifacts. More details are presented in S.M.

AGE-Set-C: Tab. 3 presents the comparison of our EditGuard and some SOTA tamper localization methods [8, 18, 39, 45, 61]. We observe that the F1-scores of other passive forensic methods are generally lower than 0.7 when applied to AGE-Set-C. Meanwhile, even when we try our best to finetune MVSS-Net using AGE-Set-C, the accuracy of MVSS-Net† remains unsatisfactory, and they exhibit catastrophic forgetting across various tamper methods. In contrast, our method can guarantee an F1-score and AUC of over **95%**, maintaining around **90%** IOU, regardless of tampering types. As shown in Fig. 8, our EditGuard can accurately capture these imperceptible tampering traces produced by AIGC-based editing methods, but other methods are almost ineffective. Moreover, our EditGuard can effectively recover copyright information with a bit accuracy exceeding **99.8%**. Noting that none of the comparison methods offer copyright protection capabilities.

AGE-Set-F: To further highlight the practicality of our EditGuard, we conducted subjective comparisons with other methods on the meticulously tampered AGE-Set-F.

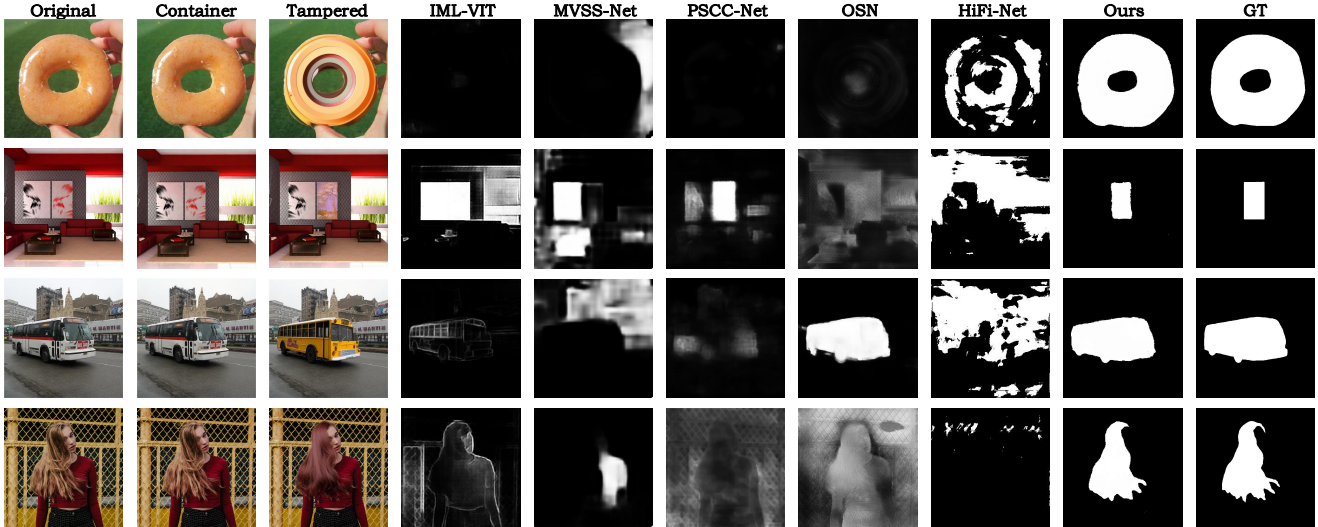


Figure 9. Localization precision comparisons of our EditGuard and other competitive methods on the meticulously tampered AGE-Set-F.

Table 4. Localization and bit recovery performance of our EditGuard and MVSS-Net[†] [8] under different levels of degradations.

Methods	Metrics	Clean	Gaussian Noise		JPEG			Poisson
			$\sigma=1$	$\sigma=5$	$Q=70$	$Q=80$	$Q=90$	
MVSS-Net [†] [8]	F1	0.694	0.644	0.619	0.458	0.507	0.558	0.652
	BA(%)	-	-	-	-	-	-	-
EditGuard (Ours)	F1	0.966	0.937	0.932	0.920	0.920	0.925	0.943
	BA(%)	99.95	99.94	99.37	97.69	98.16	98.23	99.91

The tamper types in this subset did not appear in the training set. As shown in Fig. 9, when faced with real-world tampering, even the most powerful tamper localization methods almost entirely fail. This is due to their mechanisms to look for image artifacts and explore instance-wise semantic information. However, our EditGuard, which locates tampered masks via the natural fragility and locality of I2I steganography, can still clearly annotate the tampered area.

5.5. Robustness Analysis

As shown in Tab. 4, we conducted robustness analysis on the tampering of “Stable Diffusion Inpaint” [51] under Gaussian noise with $\sigma=1$ and 5, JPEG compression with $Q=70$, 80 and 90, and Poisson noise with $\alpha=4$ [71]. We observed that our method still maintains a high localization accuracy (F1-score >0.9) and bit accuracy with a very slight performance decrease under various levels of degradations, while MVSS-Net[†] [8] exhibits a noticeable performance degradation compared to its results in clean conditions. It is attributed to our prompt-based estimation that can effectively learn the degradation representation.

5.6. Ablation Study

To verify the effectiveness of each component of the EditGuard, we conducted ablation studies on bi-level optimization (BO), lightweight feature interaction module (LFIM), transformer block (TB), and prompt-based fusion (PF) under the tampering of “Stable Diffusion Inpaint”. As listed in Tab. 5, without BO, the joint training of all components

Table 5. Ablation studies on the core components of EditGuard.

Case	Degradation Type $\mathcal{D}(\cdot)$	PF	TB	LFIM	BO	F1	AUC	IoU	BA(%)
(a)	Clean	✓	✓	✓	-	-	-	-	49.17
(b)	Clean	✓	✓	✓	✓	0.950	0.960	0.904	99.73
(c)	Clean	✓	✓	✓	✓	0.957	0.966	0.927	99.51
(d)	Random Degradations	✓	✓	✓	✓	0.903	0.933	0.841	99.12
Ours	Clean	✓	✓	✓	✓	0.966	0.971	0.936	99.95
	Random Degradations	✓	✓	✓	✓	0.938	0.964	0.887	99.36

cannot converge effectively, resulting in bit accuracy that is close to random guessing. Without LFIM and TB, the IoU of EditGuard will suffer 0.032 and 0.009 declines since these two modules can better perform feature fusion. Without PF, the robustness of the EditGuard will significantly decline. We observed that the F1/AUC/IoU of our method far surpasses that of case (d) by 0.035/0.031/0.046 under “Random Degradations”, which indicates that the PF effectively enables a single network to support watermark recovery under various degradations. “Random Degradations” denotes that we randomly set the $\mathcal{D}(\cdot)$ to various levels of Gaussian noise, Poisson noise, and JPEG compression.

6. Conclusion

We present the first attempt to design a deep versatile watermarking mechanism **EditGuard**. It enhances the credibility of images by embedding imperceptible localization and copyright watermarks, and decoding accurate copyright information and tampered areas, making it a reliable tool for artistic creation and legal forensic analysis. In the future, we will focus on improving the robustness of EditGuard and strive not only to offer pixel-wise localization results but also to provide semantic-wise outcomes. Additionally, we plan to further expand EditGuard to a broader range of modalities and applications, including video, audio, and 3D scenes. Our efforts at information authenticity serve not only the AIGC industry, but the trust in our digital world, ensuring that every pixel tells the truth and the rights of each individual are safeguarded.

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