# **Unsegment Anything by Simulating Deformation**

# Supplementary Material

The supplementary material is organized as follows: In Sec. 1, we present our findings regarding the challenges of transferring prompt-specific attacks to unseen prompts. We offer additional ablation studies in Sec. 2, covering topics including (1) the combination with other transferability methods, and (2) the impact of source models. These sections aim to enhance the reader's comprehension of our approach's underlying mechanisms. In Sec. 5, we offer visualizations of our attacks and baseline attacks from a panoramic perspective to provide a more straightforward comparison. In Sec. 4, we provide a table listing all the notations used throughout this paper. Finally, in Sec. 6, we discuss the limitations of our work and the potential societal impact that may arise from our research.

### 1. Prompt-Specific Attack Fail to Transfer

We present visualizations of adversarial noises alongside their corresponding segmentation results for various prompts in Fig. 7. These visualizations underscore the heterogeneous nature of prompt-specific adversarial noises.

Notably, the adversarial noises induced by spatial prompts (the first three rows) exhibit distinct characteristics compared to those induced by semantic prompts (the last row). The adversarial noises from the spatial prompts share similarities, characterized by shattered and random-noiselike patterns. Conversely, the adversarial noise stemming from the semantic prompt aligns closely with essential image features.

Furthermore, we observe that the generated adversarial examples tend to exhibit overfitting to the specific prompts used during their generation. Consequently, these adversarial examples struggle to generalize to unseen prompts. Attacks generated using spatial prompts have minimal impact on segmentation results driven by text prompts. Similarly, the adversarial sample generated from a text prompt has little effect on box prompts.

**Results.** We present the histogram of feature similarities between TAP and AA attacks in Fig. 2. The findings reveal that both targeted and untargeted feature disruption attacks effectively alter features in the source model. However, untargeted attacks are notably less effective on the target model. We hypothesize this is due to the high-dimensional nature of the data, which often leads these attacks to stray from the image distribution. As a result, in the target model, adversarial features appear similar to normal features, indicating lower transferability for untargeted attacks.

#### 2. Ablation Studies

## 2.1. Study 1: Combining Transferability Methods

Previous research on the transferability of adversarial examples has highlighted four distinct technical approaches, as discussed in Section 5. These approaches encompass feature disturbance, gradient momentum, input augmentation, and model ensembling. Notably, our UAD method falls under the category of feature disturbance. In the precondition of not introducing external model information (we will investigate the impact of model ensembling in the next subsection), we concentrate on exploring how gradient momentum and input augmentation could potentially help us to reach our objective.

As recently demonstrated in a comprehensive benchmark study [58], under a fair and rigorous comparison, the most effective gradient momentum and input augmentation methods are, in fact, the most classic ones, specifically MI [6] and DI [47], respectively. In Table 1, we have already presented results indicating that the inclusion of both of these techniques does not significantly enhance attack performance. Now we will separately integrate each of these techniques into our method, given that they should operate independently of each other, and examine their combined effects in conjunction with our proposed approach in Tab. 2.

Contrary to our expectations, our method, when used alone without the inclusion of MI or DI tricks, yielded the best results. The addition of gradient momentum proved to be more effective than data augmentation. However, combining both techniques resulted in a drop in performance.

#### 2.2. Study 2: Source Model Selection

Previous research findings provide valuable insights: (1) Adversarial examples generated by high-capacity (more over-parameterized) models exhibit higher transferability to low-capacity networks, in contrast to adversarial samples crafted by low-capacity networks, which have limited success when transferred to high-capacity networks; (2) Employing an ensemble of networks proves to be more effective in generating transferable adversarial samples.

To evaluate the upper limits of our approach in tackling the *anything unsegmentable* task, we conducted an ablation study to assess the enhanced transferability of adversarial examples generated from a more capable model.

In Table 1, we performed all experiments using SAM-B as the source model, which has one of the smallest parameter sizes (91 M). Now, we aim to generate adversarial samples based on larger and more powerful models, such



Figure 7. We claim that prompt-specific attacks exhibit fundamental differences in the adversarial noise they generate, and their transferability is limited to a narrow range of prompts. Adversarial examples tend to overfit to the prompts used during the attack phase and have limited impact on unseen prompts.

Approach	SAM-B (source)			SAM-L			SAM-H			FastSAM		
	mIoU↓	ASR@50↑	ASR@10↑	mIoU↓	ASR@50↑	ASR@10↑	mIoU↓	ASR@50↑	ASR@10 $\uparrow$	mIoU↓	ASR@50↑	ASR@10↑
UAD	51.53	43.89	20.79	66.07	26.44	12.27	68.96	23.42	10.23	28.83	69.95	59.63
UAD + DI [47]	56.74	41.01	18.51	70.19	24.54	11.07	71.25	22.15	8.83	28.88	65.38	56.69
UAD + MI [6]	55.99	44.29	21.54	67.79	25.29	11.80	69.62	23.22	9.97	27.44	70.97	59.81
UAD + MI [6] + DI [47]	56.49	42.06	19.24	67.94	24.76	11.32	69.26	23.03	9.51	27.60	70.36	59.58

Table 2. Results of combining our method with gradient momentum and input augmentation.

as SAM-L (308 M parameters) and SAM-H (636 M parameters). Additionally, we conducted experiments by ensembling SAM-B and SAM-L. We couldn't ensemble SAM-H due to its high GPU memory consumption, as we have limited computational resources.

As indicated in Table 3, our attack, much like many other adversarial attacks, demonstrates a tendency to overfit to the source model. Specifically, when the source and target models are identical, the attack performs significantly better when the source model does not encompass the target model. Interestingly, model ensembling further enhances attack results; for instance, ensembling SAM-B and SAM-L surpasses the performance of using SAM-B alone by a considerable margin. Ensembling exhibits a stronger impact on the global results, leading to a lower mean IoU (mIoU).

## 3. Algorithm Pseudo-code

We present the pseudo-code of our attack in Alg.1.

### 4. Notations

We put all symbols appeared in this paper in Tab. 4 for reference.

## 5. More visualization results

We visualize the attack effect under segment everything mode (which provides a panoramic view without prompts) on SAM-B and SAM-H models in Fig.8, Fig. 9 and 10. We

Target Models Source Models	SAM-B			SAM-L			SAM-H			FastSAM		
	mIoU↓	ASR@50 $\uparrow$	ASR@10↑	mIoU↓	ASR@50↑	ASR@10↑	mIoU↓	ASR@50↑	ASR@10↑	mIoU↓	ASR@50↑	ASR@10↑
SAM-B (91 M)	51.53	43.89	20.79	66.07	26.44	12.27	68.96	23.42	10.23	28.83	69.95	59.63
SAM-L (308 M)	61.67	35.65	13.45	55.41	28.50	15.53	68.98	23.37	10.41	31.27	63.23	52.27
SAM-H (636 M)	61.06	35.69	13.87	63.92	24.32	13.04	63.31	25.85	12.61	30.60	64.59	53.75
SAM-B + SAM-L (Ensemble)	50.54	44.18	22.61	59.67	26.88	14.40	68.35	23.81	11.35	27.36	71.38	60.90

Table 3. Ablation study on source models used to craft adversarial examples.

Algorit	thm 1 Unsegment Anything by Simulating Deforma-	
-		
Input:	Input image: <i>I</i> ;	
	Deformation parameters: $w$ ;	
	Maximal deformation iterations: $T_D$ ;	
	Maximal proxy perturbation iteration: $T_f$ ;	
	Maximal perturbation iterations: T;	
	Perturbation step size: $\alpha$ ;	
	Perturbation range: $\epsilon$ ;	
Outpu	t: Adversarial perturbation: r	
1: <b>pr</b>	ocedure UAD $(I, w, T_D, T_f, T, \alpha, \epsilon)$	Var
2:	$I' = I, r = 0, t_D = 0, t = 0;$	
3:	Initialize $w$ so that $D_w$ produces identity mapping;	
4:	<b>While</b> $t_D < T_D$ <b>do</b> $\triangleright$ Stage 1: Deformation	P
5:	$I = \mathcal{D}_w(I);$ $\triangleright$ Get deformed image	M
6:	I'' = I;	$J_{\theta^{I}}$
7:	$t_f = 0;$	$n_{\theta^P}$
8:	While $t_f < T_f$ do $\triangleright$ proxy adversarial sample	$g_{\theta^M}$
9:	$I'' = I'' - \alpha \cdot sign(\nabla_{I''} \mathcal{L}_F(I, I''));$	w D
10:	$I'' = clip_{\epsilon}(I'' - I) + I$	$\hat{D}_w$
11:	$I'' = clip_{0,1}(I'')$	1
12:	end While	$w_{ff}$
13:	$\mathcal{L}(w) = \mathcal{L}_D(I, I) + \mathcal{L}_C(w) + \mathcal{L}_F(I, I'')$	$w_{ff}^{(\iota),.}$
14:	$w = w - \nabla_w \mathcal{L}(w)$ > Update deformation	$\nabla u$
pai	cameters	$\nabla v$
15:	end While	r .
16:	$I = \mathcal{D}_w(I); \triangleright$ End of stage 1, deformed target fixed	I' =
17:	While $t < T$ do $\triangleright$ Stage 2: Simulation	$T_D$
18:	$I' = I' - \alpha \cdot sign(\nabla_{I'}\mathcal{L}_F(I, I'))$	$T_f$
19:	$I' = clip_{\epsilon}(I' - I) + I$	T
20:	$I' = clip_{0,1}(I')$	$\alpha$
21:	end willle $T' T$	$\epsilon$
22:	r = 1 - 1	$\mathcal{L}_D$
23: 24: 07:	ICIUIII / d procedure	$\mathcal{L}_C$
24: <b>en</b>		$\mathcal{L}_F$

Table 4. Notation Table

Variable	Description
Ι	Original clean image
P	Prompt
M	Mask
$f_{\theta^I}$	Image encoder of the promptable segmentation model
$h_{\theta^P}$	Prompt encoder of the promptable segmentation model
$g_{\theta^M}$	Prompt encoder of the promptable segmentation model
w	Deformation control parameters
$\mathcal{D}_w$	Deformation function
$\hat{I}$	Deformed (target) image
$w_{ff}$	Parameters of flow field which controls deformation
$w_{ff}^{(i,j)}$	Flow vector of position $(i, j)$ in $w_{ff}$
$\nabla u$	Movement in width indicated by flow field
$\nabla v$	Movement in height indicated by flow field
r	Adversarial perturbation (adversarial noise)
I' = I + r	Adversarial image
$T_D$	Deformation iterations
$T_f$	Proxy adversarial update iterations
T	Adversarial update iterations
$\alpha$	Adversarial perturbation step size
$\epsilon$	Adversarial perturbation range
$\mathcal{L}_D$	Deformation loss
$\mathcal{L}_C$	Control loss
$\mathcal{L}_F$	Fidelity loss

compare the attack results with Attack-SAM and PATA++ to highlight the difference in failure patterns and our effectiveness.













Figure 8. Visualizations of attack results in panoramic view(I)



SAM-B-400 adversarial example

UAD adversarial example

Original image



PATA++ result (SAM-B)

SAM-B-400 result (SAM-B)



UAD result (SAM-B)



UAD result (SAM-H)



27 



SAM-B-400 result (SAM-H)











Figure 9. Visualizations of attack results in panoramic view(II)











PATA++ result (SAM-B)



SAM-B-400 adversarial example

UAD adversarial example



Ground-truth mask



UAD result (SAM-B)

- 7

11 





PATA++ result (SAM-H)





Figure 10. Visualizations of attack results in panoramic view(III)

## 6. Limitation and social impact

### Limitation

While we have made a progressive step in the task of "Anything Unsegmentable", successfully creating an attack that is effective and transferable across several models trained under the Segment Anything task, we found it challenging when evaluating our attack on Segment Everything Everywhere Models (SEEM) [61]. The reason behind this lack of transferability may stem from fundamental differences in training data and tasks: SEEM is trained on COCO2017 [30] with panoptic segmentation annotations. Consequently, the feature space of the SEEM model inherently contains rich information about semantic labels, which is significantly different with SAM family. We believe that this divergence in feature space is the primary reason our attack did not transfer successfully.

However, we are optimistic about the potential for improvement. By introducing additional loss term that targets the category feature space, we anticipate the development of new and more powerful adversarial attacks capable of simultaneously compromising SAM, SEEM, and even more promptable segmentation models.

#### **Social Impact**

Our primary goal is to protect the personal digital content from potential copyright infringement and privacy breaches. We envision users employing our approach to preprocess their digital assets before uploading them to public websites, thereby reducing the risk of misuse or theft of their photos and digital creations.

An alternative approach, instead of incorporating adversarial attacks, could involve implementing protective measures directly within the segmentation models themselves. For instance, model publishers might consider adopting a consensus not to perform valid segmentations on protected data. However, establishing and enforcing such a consensus is a complex challenge. Moreover, addressing the issue of models that have already been downloaded and deployed by potential adversaries presents its own set of difficulties.

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