Supplementary Material Progressive Divide-and-Conquer via Subsampling Decomposition for Accelerated MRI

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In this supplementary material, we include more implementation details of the architecture of the proposed degradation predictor (Section A) and the severity conditioning module (Section B). Besides, we provide a visualization of each intermediate result in PDAC iterations in Section C and more visual examples on multi-coil reconstruction on fastMRI knee and Stanford2D FSE datasets in Section D.

A. Architecture of Degradation Predictor

During each iteration of PDAC, we learn the decomposed degradation as an auxiliary task along the reconstruction process. In the context of accelerated MRI, this decomposed degradation corresponds to the Cartesian sampling mask M_t on the k-space, which could be simply represented using a binary vector m_t . Specifically, we introduce a degradation predictor \mathcal{P}_{θ_t} to estimate a probability vector $p_t \in \mathbb{R}^{1 \times d}$ indicating the reconstruction confidence on each frequency column in the current recovered k-space $\tilde{Z}_t \in \mathbb{C}^{C \times H \times W}$, d = W. The detailed architecture of \mathcal{P}_{θ_t} is illustrated in Figure A. Consequently, m_t can be obtained by adding extra support, indicating the location of frequency columns to preserve, on the previous mask m_{t-1} . Such support is selected from the indices of several top largest values in p_t .



Figure A. The detailed architecture of the proposed degradation predictor \mathcal{P}_{θ_t} . It estimates the probability p_t indicating the confidence on each frequency column in the reconstruction \tilde{Z}_t .

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B. Architecture of Severity Conditioning Module

During each iteration in PDAC, the network input z_{t-1} suffers from a specific degradation pattern in the k-space which is characterized by M_{t-1} . Therefore, we propose to integrate such information on the degradation severity indicated by m_{t-1} together with the previous probability vector p_t using a severity conditioning module E_{θ_t} . The detailed architecture of E_{θ_t} is shown in Figure B, where the information of masked probability $m_{t-1} \odot p_{t-1}$ is embedded via the adaptive layer norm (adaLN) [2] into the network.



Figure B. The detailed architecture of the proposed severity conditioning module E_{θ_t} . It integrates the information in the masked confidence $m_t \odot p_t$ via adaptive layer norm (adaLN) into the Swin transformer blocks [2].

C. Visualization of Progressive Reconstruction

Figure C demonstrates the each intermediate results of decomposed degradation M_t , reconstructed k-space z_t and reconstructed MR images x_t , respectively, with total iteration T = 8. With the merit of the proposed progressive divide-andconquer, each iteration in PDAC selectively retrieves information within specific segments of the null space. The information in the k-space is restored progressively from low frequencies, which is easier to recover, to more challenging high frequencies, as shown in the second row in Figure C. Note that the artifact on the boundary of the images x_t is due to the fact that the training loss and evaluation metrics are only calculated on the central 320×320 part of the images, following the previous setting [1, 4].



Figure C. Visualization of each intermediate results of decomposed degradation M_t , reconstructed k-space z_t and reconstructed MR images x_t , respectively, with total iteration T = 8.

D. More Visual Examples

We provide more visual results of $8 \times$ accelerated MRI reconstruction on multi-coil fastMRI knee dataset in Figures D&E and Stanford2D FSE dataset in Figures F&G.



Figure D. Visual examples of $8 \times$ accelerated MRI reconstruction on multi-coil fastMRI knee dataset with zero-filled, U-Net [3], E2E-VarNet [4], HUMUSNet [1], ours and ground truth.



Zero-filled

U-Net

E2E-VarNet



HUMUSNet



Ours



GT



HUMUSNet

Ours

GT

Figure E. Visual examples of $8 \times$ accelerated MRI reconstruction on multi-coil fastMRI knee dataset with zero-filled, U-Net [3], E2E-VarNet [4], HUMUSNet [1], ours and ground truth.



Zero-filled



HUMUSNet



Ours



GT







HUMUSNet

Ours

GT

Figure F. Visual examples of $8 \times$ accelerated MRI reconstruction on multi-coil Stanford2D FSE dataset with zero-filled, U-Net [3], E2E-VarNet [4], HUMUSNet [1], ours and ground truth.



Zero-filled

U-Net

E2E-VarNet



HUMUSNet



Ours



GT





Figure G. Visual examples of $8 \times$ accelerated MRI reconstruction on multi-coil Stanford2D FSE dataset with zero-filled, U-Net [3], E2E-VarNet [4], HUMUSNet [1], ours and ground truth.

References

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