

GSVA: Generalized Segmentation via Multimodal Large Language Models

Supplementary Materials

A. Discussions

A.1. Comparison to Concurrent Works

NEX-T-Chat [22] decodes boxes and masks from the \langle trigger \rangle token, showing promising capabilities in many grounded understanding tasks. However, it falls short of explicitly rejecting non-existing objects in user’s queries. SESAME [20] is adept at correcting the wrong referents and segmenting the closest object in the image by adjusting the input prompt with an alternative to the empty target, while GSVA tackles it with [REJ] tokens in a unified output space. When there are multiple empty targets, GSVA can seamlessly reject them, while SESAME could have undefined behaviors. In summary, the aforementioned concurrent works consider the challenge of multiple and empty targets in the area of segmentation LLMs to a certain extent, while GSVA studies the problem **more systematically via weight-sharing SEG tokens and the novel REJ token.**

A.2. GSVA and Reasoning Segmentation

We evaluate GSVA on ReasonSeg [11] with a generalized configuration. Table A1 demonstrates the capability of GSVA to handle instructions with complex logic, showing competitive results to LISA¹. Figure A1 exemplifies that GSVA can segment the ReasonSeg referent while rejecting the additional empty target, while LISA fails to make the rejection, which further verifies the efficacy of GSVA.

A.3. Support of Various Question Types

For simplicity, we show one type of question in the example in the paper. In contrast, the prompt types are diversified during training, including “Please segment {objs} in this image”, “Can you segment {objs} in the image”, *etc.* Besides, the training data also contains VQA and Reasoning Segmentation, which include various questions and

Method	gIoU	cIoU
LISA-7B (ft)	50.5	53.2
GSVA-7B (ft)	50.5	56.4

Table A1. Results of LISA and GSVA on ReasonSeg dataset.

Question	gIoU	cIoU	N-acc.
“What”	63.32	61.70	56.44
“Where”	63.43	61.57	56.98
“Show”	63.05	61.35	56.48
“Outline”	63.16	61.51	56.27

Table A2. GRES results with different types of questions.



Figure A1. Generalized Reasoning Segmentation Example.



Figure A2. Example of different types of questions.

answers. As shown in Table A2, apart from the substituted “Where” question of “What,” we also examine the robustness of GSVA by testing the pretrained model with the unseen “Show” and “Outline” questions, short for “Show me {objs} in the image with segmentation masks” and “Outline {objs} in this image with segmentation masks,” respectively. As demonstrated in Figure A2, different question forms do not impact much performance deviation as long as they are reasonable.

A.4. Multiple Objects in One Expression

In GSVA, each expression is separated with a comma in the prompt, corresponding to a segmentation map or rejection token. If more than one object is stated in the expression, a single [SEG] token will guide a segmentation mask to cover all objects. The common practice of GRES is merging all masks of the objects referred to into one as the ground truth for evaluation, which we follow for fair comparisons. Since there exist numerous expressions containing both present and absent objects, GSVA learns to predict the mask of the union of the referents so the absent objects will not occur.

A.5. Failure Cases on N-acc.

Although GSVA achieves a **state-of-the-art** level of N-acc on the GRES task and outperforms both Non-LLM and LLM models, we still observe that several failure cases are relatively small and vague fragments in the images, easily leading to misperception. As shown in Figure A3, there is

¹Results reproduced by the open-source code of LISA.



Figure A3. Failure case example of GSVA in terms of N-acc., where empty targets are incorrectly predicted with [SEG] tokens.

no fridge obviously at the top left, but the model proposes a nearer fridge instead. It is hard for the model to tell whether in the corner stands a fridge, especially at low input resolution. This suggests using higher-resolution vision encoders, which will be an interesting future direction.

B. Implementation Details

We elaborate on the implementation details of GSVA and the settings of the experiments and list all the hyper-parameters in Table A3 for easy reproduction of the results. **Pretraining.** In the pretraining stages, GSVA starts from a pretrained MLLM, *e.g.*, LLaVA-Vicuna-7B [13] and a pretrained SFM, *e.g.*, SAM-ViT-H [10]. As shown in Figure 2 in the main paper, the mask decoder F_{mask} , the segmentation query projector ψ , the LoRA [6] adapter weights on query and value projections in the LLM, and the token embeddings in the vocabularies are trainable. During training, the cross entropy language modeling loss on the output text sequence \tilde{y}_{txt} and the ground truth response y_{txt} , the output mask \tilde{y}_{mask} is supervised by the combination of a binary cross entropy loss and a DICE loss to minimize the error to the ground truth mask y_{mask} . To summarize, the final objective is

$$\mathcal{L}_{\text{total}} = \lambda_1 \mathcal{L}_{\text{LM}}(\tilde{y}_{\text{txt}}, y_{\text{txt}}) + \lambda_2 \mathcal{L}_{\text{BCE}}(\tilde{y}_{\text{mask}}, y_{\text{mask}}) + \lambda_3 \mathcal{L}_{\text{DICE}}(\tilde{y}_{\text{mask}}, y_{\text{mask}}), \quad (\text{A1})$$

where $\lambda_1, \lambda_2, \lambda_3$ are the weight of the above losses, following LISA [11] set to 1.0, 2.0, and 0.5, respectively.

In the pretraining phase, we mainly adopt the mixed dataset configurations in LISA [11] to mix four types of datasets and sample in training splits by the ratio 9 of Semantic Segmentation (SemSeg), 6 of Referring Expression Segmentation (RES), 3 of Visual Question Answering (VQA), and 1 of Reasoning Segmentation (ReasonSeg). This ratio of 9:6:3:1 is almost kept from LISA for a fair comparison, except for the increment of RES to weight gRefCOCO [12] more. For each task, the sample is uniformly sampled across the dataset. The semantic segmentation datasets consist of ADE20K [23], COCO-Stuff [1], Mapillary Vistas [17], PACO-LVIS [19], and PASCAL-Part [2]. The RES datasets include RefCOCO, RefCOCO+ [9], RefCOCOg [16], RefCLEF [9],

and gRefCOCO [12]. VQA and reasoning segmentation adopt LLaVA-Instruct-150K [13] and ReasonSeg [11] as the datasets, respectively.

We train all three model variants (Vicuna-7B, Vicuna-13B, and Llama2-13B) on 8 Tesla A100 GPUs (80GB) for 50,000 steps with a batch size of 2 per device. The learning rate is set to 3×10^{-4} with a gradient accumulation of 10. The weight decay is set to 0, and the gradients are clipped to 1 by the maximum norm. The learning rate is warmed up in 100 steps and linearly decayed. To reduce the GPU memory footprints, we adopt the AdamW [14] optimizer with stage 2 ZeRO [18]. As for LoRA, we pick 8 as the LoRA rank for the 7B variant and 64 for the 13B variants.

Finetuning on GRES task. We finetune the pretrained models on gRefCOCO [12] dataset to improve the GRES performances further. For all variants of GSVA, we load the weights of the respective model in pretraining and train another 10 epochs on gRefCOCO. This is slightly different from pretraining because we go through the whole training set once per epoch without sampling data from it. In the finetuning experiments, we use a lower learning rate 1×10^{-4} , keeping other configurations unchanged.

Finetuning on classic RES task. For classic RES, including RefCOCO, RefCOCO+ [9], and RefCOCOg [16], we choose the mixed classic RES dataset during training aside from gRefCOCO. In addition to reducing the learning rate to 1×10^{-4} , the other hyper-parameters remain unchanged.

C. GSVA on Ref-ZOM

Ref-ZOM dataset. Proposed by DMMI [7], Ref-ZOM is a similar dataset to gRefCOCO [12], posing the challenges of one-to-one, one-to-many, and one-to-zero referring expression to targets in the image relationships in RES. The one-to-one is the case of classic RES where the referring expression is matched with only one target in the image, while the one-to-many and one-to-zero are the multi-target and empty-target cases, respectively. Ref-ZOM contains 55,075 images and 74,942 annotated objects, among which there are 56,972 one-to-one cases, 21,290 one-to-many cases, and 11,937 one-to-zero cases. DMMI provides a default split of training set and test set of Ref-ZOM. There are 43,749 images in the training set and 11,329 images in the test set.

Setups. We regard Ref-ZOM [7] as a kind of GRES, and use a similar protocol to gRefCOCO [12] to evaluate LISA and GSVA on Ref-ZOM dataset. For Ref-ZOM, gIoU and cIoU are substituted to the equivalent metrics, mIoU and oIoU. Different from gRefCOCO, mIoU, and oIoU only count for non-empty targets. For one-to-zero, *i.e.*, empty targets, the accuracy is one if the predicted mask is strictly all-zero. LISA [11] and our proposed GSVA with Vicuna-7B [3] are evaluated, including the pretrained versions and the finetuned versions with 1 epoch on the training split.

Results. As shown in Table A4, without finetuning on Ref-

Experiment	Configuration	Model		
		GSVA-Vicuna-7B	GSVA-Vicuna-13B	GSVA-Llama2-13B
Pretraining	Dataset Types	SemSeg, RES, VQA, ReasonSeg		
	SemSeg Datasets	ADE20K [23], COCO-Stuff [1], Mapillary Vistas [17], PACO-LVIS [19], Pascal-Part [2]		
	RES Datasets	RefCOCO [9], RefCOCO+ [9], RefCOCOg [16], RefCLEF [9], gRefCOCO [12]		
	VQA Datasets	LLaVA-Instruct-150K [13]		
	ReasonSeg Datasets	ReasonSeg [11]		
	Epochs / Steps	50,000 steps, gradient accumulation: 10 steps / update		
	Optimizer	AdamW [14], learning rate: 3×10^{-4} , weight decay: 0.0, gradient clip: 1.0		
	ZeRO [18]	Stage: 2		
Batch size	2 samples / GPU \times 8 GPUs			
LoRA [6] rank	8	64	64	
Finetuning on gRefCOCO [12]	Dataset Types	RES		
	SemSeg Datasets	-		
	RES Datasets	gRefCOCO [12]		
	VQA Datasets	-		
	ReasonSeg Datasets	-		
	Epochs / Steps	10 epochs, gradient accumulation: 10 steps / update		
	Optimizer	AdamW [14], learning rate: 1×10^{-4} , weight decay: 0.0, gradient clip: 1.0		
	ZeRO [18]	Stage: 2		
Batch size	2 samples / GPU \times 8 GPUs			
LoRA [6] rank	8	64	64	
Finetuning on classic RES	Dataset Types	RES		
	SemSeg Datasets	-		
	RES Datasets	RefCOCO [9], RefCOCO+ [9], RefCOCOg [16], RefCLEF [9]		
	VQA Datasets	-		
	ReasonSeg Datasets	-		
	Epochs / Steps	50,000 steps, gradient accumulation: 10 steps / update		
	Optimizer	AdamW [14], learning rate: 1×10^{-4} , weight decay: 0.0, gradient clip: 1.0		
	ZeRO [18]	Stage: 2		
Batch size	2 samples / GPU \times 8 GPUs			
LoRA [6] rank	8	64	64	

Table A3. Detailed configurations and hyper-parameters of GSVA in pretraining and finetuning stages. “steps” mean the model is trained for given steps, which is implemented by fixing the steps in each epoch and sample data from the datasets, while “epochs” mean the model is trained across the whole dataset in each epoch.

ZOM, GSVA surpasses LISA by clear margins in oIoU and mIoU of over 6%. Also, GSVA approaches close to the SOTA, DMMI [7], which is the SOTA proposed along with the Ref-ZOM dataset. After finetuning for 1 epoch, LISA quickly catches up GSVA with less 2% IoU metrics, while GSVA achieves 94.59% accuracy in classifying empty targets, keeping a competitive performance to DMMI.

D. GSVA on Semantic Segmentation

To verify the vanilla semantic segmentation ability, we include an extra evaluation of the pretrained GSVA-Vicuna-7B and LISA-Vicuna-7B on the ADE20K [23] validation dataset. Since the pretraining covers the training set of ADE20K, we only evaluate them to see if they are capable of segmenting semantic regions rather than some specific objects. We prompt the models with the instruction as *User: What is {classname} in this image? Assistant: Sure, [SEG].*, where each {classname} is filled with the class name that

Method	Ref-ZOM [7] Test Set		
	oIoU	mIoU	Acc
MCN [15]	55.03	54.70	75.81
CMPC [8]	56.19	55.72	77.01
VLT [4]	60.21	60.43	79.26
LAVT [21]	64.45	64.78	83.11
DMMI [7]	68.77	68.21	87.02
LISA-Vicuna-7B [11]	60.14	61.46	72.58
GSVA-Vicuna-7B	67.12	67.98	82.66
LISA-Vicuna-7B [11] (ft)	66.41	65.39	93.39
GSVA-Vicuna-7B (ft)	68.29	68.13	94.59

Table A4. GRES results on the test split of Ref-ZOM [7] dataset. oIoU and mIoU are only computed on the samples containing targets, while the correct prediction of Acc is the mask of all zeros for empty targets. Baselines are excerpted from Hu et al. [7].

exists in this image. We report the mIoU of the predictions and the ground truths, in Table A5. LISA achieves 60.11 mIoU whereas our GSVA slightly improves to 60.56.

Model	mIoU(ss)
LISA-Vicuna-7B [11]	60.11
GSVA-Vicuna-7B	60.56

Table A5. Semantic Segmentation Results of GSVA and LISA [11] on ADE20K validation dataset. The mIoU is different from the one in the closed-set segmentation, which is computed with the existing classes, and resembles the recall to some extent.

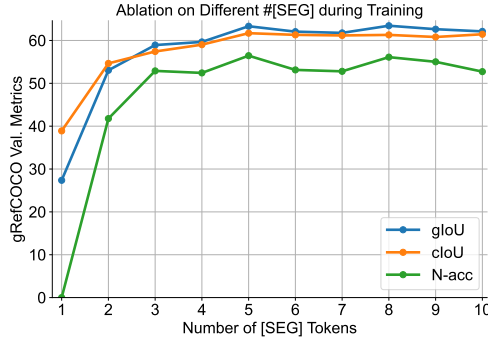


Figure A4. Ablation on how many [SEG] tokens are used during training. Metrics including gIoU, cIoU, and N-acc on gRefCOCO [12] dataset are reported.

E. More Ablation Study

The number of targets in training. We study the effect on how many [SEG] tokens are adopted in training GSVA. In GSVA, the number of [SEG]s controls the number of targets processed by GSVA, which impacts the final capacity of multiple target segmentation. We sweep this hyperparameter from 1 to 10 and report the results of GSVA-Vicuna-7B on gRefCOCO [12] validation set in Figure A4. On the one hand, from the figure, all the metrics include gIoU, cIoU, and N-acc. increases as the number of [SEG] grows from 1 to 5, and the model performances saturate after 5 [SEG] tokens are involved. On the other hand, the memory footprints keep rising as more [SEG] tokens are used and exceed 24GB (RTX3090 / RTX4090) after 6 [SEG] tokens. Considering the performance saturation and the memory consumption, we pick 5 as the default.

Weight sharing for different [SEG] tokens. Another design choice considering multiple [SEG] tokens is to use a set of individual [SEG] embeddings rather than sharing weights in GSVA. We adopt 8 tokens from [SEG000] to [SEG007] to study this design. In case of more than 8 targets, we dispatch the targets based on the remainder after divided by 8. However, this design poses convergence difficulties, as shown in Table A6. We attribute the intensive performance degradation to the slow convergence of the [SEG] token embedding, which is that too many [SEG] token embeddings could interfere with each other. Therefore, it is reasonable to share weights between [SEG] tokens.

Different SAM Backbones. We alter the default pretrained SAM-ViT-H [10] vision encoder to SAM-ViT-L and SAM-

Model	gRefCOCO Val.		
	gIoU	cIoU	N-acc.
GSVA (weight sharing)	63.32	61.70	56.45
w/ 8 individual embeddings	16.13	23.11	0.00

Table A6. Ablation study on weight sharing of [SEG] tokens.

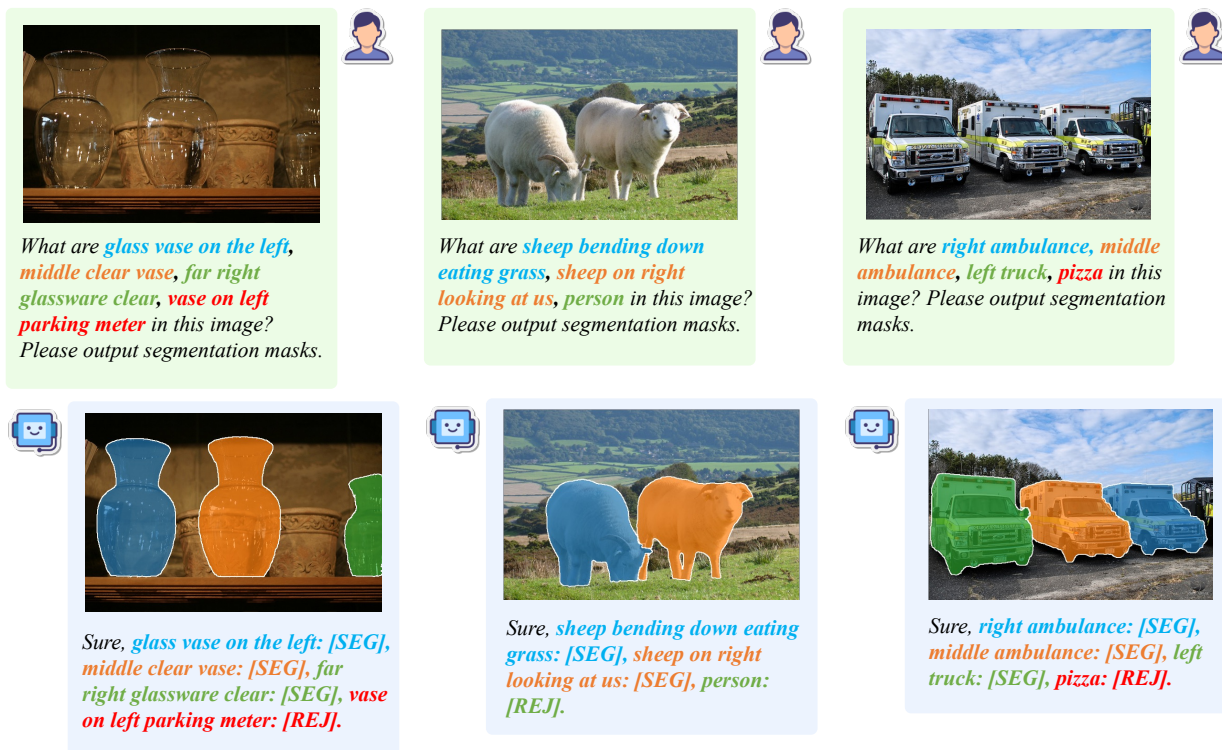
Vision Encoder F_{V_2} in SFM	gRefCOCO Val.		
	gIoU	cIoU	N-acc.
SAM-ViT-H (GSVA)	63.32	61.70	56.45
SAM-ViT-L	61.67	60.46	56.04
SAM-ViT-B	59.20	56.36	58.57

Table A7. Ablation study on Different SAM [10] ViT backbones.

ViT-B, to verify the effectiveness of GSVA that is stable to the change of segmentation vision encoder F_{V_2} . As shown in Table A7, when we substitute the ViT-H [5] backbones with SAM pretrained ViT-B/L, the segmentation performances decreases by 4%~5% while the accuracy of empty targets change mildly and even increases to 58.57% with ViT-B. The slight drops in gIoU and cIoU scores could be attributed to the usages of more miniature vision encoders, and the stable, even higher N-acc implies that generating [REJ] token by MLLM consistently works well with SFMs in different capacities. These results also demonstrate the effectiveness of the design that rejects the empty targets by a special token rather than predicting an all-zero mask.

F. More Visualizations

We provide more visualization results in Figure A5 to further show the effectiveness of our GSVA in GRES task.



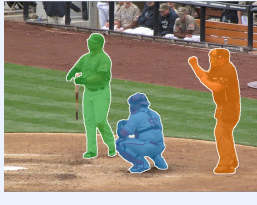
(a) Examples of GSVA on gRefCOCO [12] test set A and B. (I)



(b) Examples of GSVA on gRefCOCO [12] test set A and B. (II)

 <p>What are right giraffe, left giraffe, airplane, top giraffe orange in this image? Please output segmentation masks.</p>	 <p>What are animal on left, right sheep, animal on left under the bowl, right potted plant in this image? Please output segmentation masks.</p>	 <p>What are left dude, man in the red in middle, second from right guy, man right, dog in this image? Please output segmentation masks.</p>
 <p>Sure, right giraffe: [SEG], left giraffe: [SEG], airplane: [REJ], top giraffe orange: [REJ].</p>	 <p>Sure, animal on left: [SEG], right sheep: [SEG], animal on left under the bowl: [REJ], right potted plant: [REJ].</p>	 <p>Sure, left dude: [SEG], man in the red in middle: [SEG], second from right guy: [SEG], man right: [SEG], dog: [REJ].</p>

(c) Examples of GSA on gRefCOCO [12] test set A and B. (III)

 <p>What are woman right, blond woman, right sheep, left lamb, cow in this image? Please output segmentation masks.</p>	 <p>What are right guy, second from the right, man in middle jeans and T-shirt, young lady, boy on left, left guy left to the donut in this image? Please output segmentation masks.</p>	 <p>What are catcher, umpire, batter, cow in this image? Please output segmentation masks.</p>
 <p>Sure, woman right: [SEG], blond woman: [SEG], right sheep: [SEG], left lamb: [SEG], cow: [REJ].</p>	 <p>Sure, right guy: [SEG], second from the right: [SEG], man in middle jeans and T-shirt: [SEG], young lady: [SEG], boy on left: [SEG], left guy left to the donut: [REJ].</p>	 <p>Sure, catcher: [SEG], umpire: [SEG], batter: [SEG], cow: [REJ].</p>

(d) Examples of GSA on gRefCOCO [12] test set A and B. (IV)



(e) Examples of GSVAs on gRefCOCO [12] test set A and B. (V)



(f) Examples of GSVAs on gRefCOCO [12] test set A and B. (VI)

Figure A5. Visualization of GSVAs in GRES task, the inputs and outputs are presented in the form of dialogues between human user and the chatbot. The examples are selected from gRefCOCO [12] test set A and B. Zoom in for best view.

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