TEA: Test-time Energy Adaptation

Supplementary Material

6. Appendix Summary

The appendix contains the following sections:

- (1) Additional Experiments and Analyses (Sec. 7):
 - Detailed Results for Energy Reduction (Sec. 7.1)
 - Detailed Results for Image Corruption (Sec. 7.2)
 - Hyper-parameters Sensitivity (Sec. 7.3)
- (2) Detailed Settings (Sec. 8):
 - Datasets(Sec. 8.1)
 - Evaluation Metrics(Sec. 8.2)
 - Hyper-parameters(Sec. 8.3)
 - Computing Resources (Sec. 8.4)
- (3) Limitations and Future Explorations (Sec. 9).

7. Additional Experiments

7.1. Detailed Results for Energy Reduction

This section serves as an extension of the energy analysis (Sec. 4.3.1) in the main text, presenting the relationship between TEA's energy reduction and the enhancement of generalizability across all types of corruption. The detailed results are shown in Figs. 7 and 8, where each corruption type is analyzed at five levels of severity, with the analysis examining the correlation between the extent of energy reduction and performance improvements, both before and after adaptation, as severity levels increase.

In our experiments, TEA generally reduced energy and enhanced generalization across various corruptions. Yet, for mild corruptions like "Brightness" at level one, i.e., the mildest in CIFAR-10-C, generalization did not improve and occasionally deteriorated slightly. Correspondingly, energy did not decrease and even increased marginally. These outcomes indicate a strong correlation between generalizability enhancement and energy reduction. However, it is possible that our method may not reduce energy as anticipated for distributions with some less severe corruption types. This may be attributed to these distributions being closely aligned with the original, already at a low energy state. The uniform hyperparameters used in our adaptation may not be optimal for such cases. Addressing this discrepancy will be a priority in future research.

7.2. Detailed Results for Image Corruption

This section serves as an extension of the main adaption results (Sec. 4.2) in the main text, presenting the detailed performance for each corruption type at the most severe corruption level. The detailed results are shown in Tab. 7. In our evaluation, TEA consistently achieves the highest accuracy for every corruption type on CIFAR-10-C and CIFAR- 100-C datasets. On TinyImageNet, our model exhibits superior performance on the majority of corruptions. However, it is slightly outperformed by SHOT on a few corruption types. The performance difference might be because the corruptions are mild and similar to the source data, which benefits pseudo-label methods like SHOT that rely on this similarity to produce accurate labels.

7.3. Hyper-parameters Sensitivity

This section provide a new experiments on hyperparameters sensitivity of our proposed TEA. The main hyper-parameters for TEA are the step and learning rate for Stochastic Gradient Langevin Dynamics (SGLD). Fig. 9 illustrates the variation in model accuracy as the SGLD learning rate is incrementally adjusted from 0.001 to 0.4, while Fig. 10 demonstrates the impact on accuracy when the SGLD step is increased from 1 to 200. The results reveal that the performance of TEA is consistently state-of-the-art under a wide range of hyper-parameters choices, across all types of corruption on CIFAR-10-C.

8. Detailed Settings

8.1. Datasets

We perform experiments on four datasets across two tasks. Image corruption task include CIFAR-10(C), CIFAR-100(C), and TinyImageNet(C) datasets. Domain generalization task include PACS datasets.

Dataset of Clean Distribution Clean distribution of CIFAR-10, CIFAR-100 [29] and TinyImageNet [31] are datasets of clean distribution. CIFAR-10 and CIFAR-100 datasets consist of 60,000 color images, each of size 3x32x32 pixels. CIFAR-10 is categorized into 10 distinct classes with 6000 images per class. CIFAR-100 is more challenging, as these images are distributed across 100 classes, with 600 images per class. TinyImageNet datasets consist of 110,000 color images, each of size 3x64x64 pixels, which are categorized into 200 distinct classes with 550 images per class. Both CIFAR-10 and CIFAR-100 are subdivided into a training set of 50,000 images and a test set of 10,000 images.

Dataset of Corrupted Distributions CIFAR-10-C, CIFAR-100-C and TinyImageNet-C[17] are variants of the original CIFAR-10, CIFAR-100 and TinyImageNet datasets that have been artificially corrupted into 19 types

Table 4. Summary of Clean & Corruption Datasets

Dataset	#Train	#Test	#Corr.	#Severity	#Class.
CIFAR-10	50,000	10,000	1	1	10
CIFAR-100	50,000	10,000	1	1	100
TinyImageNet	100,000	10,000	1	1	200
CIFAR-10-C	-	950,000	15	5	10
CIFAR-100-C	-	950,000	15	5	100
TinyImageNet-C	-	750,000	15	5	200

Table 5. Summary of PACS Datasets

Domain	#Sample	#Class	Size
Photo	1,670	7	3x227x227
Art	2,048	7	3x227x227
Cartoon	2,344	7	3x227x227
Sketch	3,929	7	3x227x227

of corruptions at five levels of severity, resulting in 95 corrupted versions of the original test set images. The corruptions include 15 main corruptions: Gaussian noise, shot noise, impulse noise, defocus blur, glass blur, motion blur, zoom blur, snow, frost, fog, brightness, contrast, elastic, pixelation, and JPEG. All these corruptions are simulations of shifted distributions that models might encounter in real-world situations.

Datsset of PACS PACS[35] is an image dataset popular used in transfer learning, which consist of four domains, namely Photo (1,670 images), Art Painting (2,048 images), Cartoon (2,344 images) and Sketch (3,929 images). Each domain contains seven categories.

8.2. Evaluation Metrics

For evaluation on corruption datasets, we employ Average Accuracy and Mean Corruption Error (mCE) [17] as evaluation metrics. For clean and PACS datasets, we employ Accuracy as evaluation metric. These metrics provide a comprehensive evaluation of a model's generalization in handling diverse distributions, thereby offering a multi-faceted perspective on model performance.

Average Accuracy Average Acc is the accuracy averaged over all severity levels and corruptions. Consider there are a total of C corruptions, each with S severities. For a model f, let $\mathcal{E}_{s,c}(f)$ denote the top-1 error rate on the corruption c with severity level s averaged over the whole test set,

$$\operatorname{AverAcc}_{f} = 1 - \frac{1}{C \cdot S} \sum_{c=1}^{C} \sum_{s=1}^{S} \mathcal{E}_{s,c}(f).$$
(9)

Mean Corruption Error mCE is a metric used to measure the performance improvement of model f compared to a baseline model f_0 . We use the model without adaptation as the baseline model,

Table 6. Summary of Hyper-parameters

Data		Con	TEA-SGLD							
2.000	Step	LR	BS	Optim	Step	LR	Std			
CIFAR-10-C	1	0.001	200	Adam	20	0.1	0.01			
CIFAR-100-C	1	0.001	500	Adam	20	0.1	0.01			
TinyImageNet-C	1	0.0001	1000	Adam	20	0.1	0.01			
PACS-P	10	0.001	full	Adam	20	0.1	0.01			
PACS-A	10	0.001	full	Adam	20	0.1	0.01			
PACS-C	10	0.002	full	Adam	20	0.1	0.01			
PACS-S	20	0.002	full	Adam	20	0.1	0.01			

$$mCE_{f} = \frac{1}{C} \sum_{c=1}^{C} \frac{\sum_{s=1}^{S} \mathcal{E}_{c,s}(f)}{\sum_{s=1}^{S} \mathcal{E}_{c,s}(f_{0})}$$
(10)

8.3. Hyper-parameters

This section outlines the hyper-parameters chosen for our experiments. These settings enable the reproducibility of the results presented in our study. For common hyperparameters, we align with those used in Tent [60]. For TEA-specific hyper-parameters, we adjust them following the parameter choices from JEM [13].

8.4. Computing resources

All our experiments are performed on RedHat server (4.8.5-39) with Intel(R) Xeon(R) Gold 5218 CPU @ 2.30GHz4, $4 \times$ NVIDIA Tesla V100 SXM2 (32GB) and $3 \times$ NVIDIA Tesla A800 SXM4 (80GB).

9. Limitation and Future Works

Our study has identified key aspects for improvement and future research, which are outlined below: (1) The use of Stochastic Gradient Langevin Dynamics sampling is both time-consuming and unstable. However, ongoing research in energy-based models is addressing these issues through various methods, such as gradient clipping [66], diffusion process [40], additional gradient term [8] and ordinary differential equation based sampling [42]. One of our future directions is to enhance TEA by incorporating these advanced sampling techniques. (2) Overemphasizing the model's sensitivity to the data distribution may significantly impact its discriminative ability. This trade-off between transferability and discriminability is a common theme in TTA research [11, 30]. Another direction for our future work is to explore how to enhance the model's perception of data distribution while maintaining or even improving its discriminative power. We acknowledgethat the limitations identified may present challenges. Nevertheless, we remain confident that our study represents a pioneering effort to integrate energy-based training into test time adaptation. We believe that any future advancements in the training of energy-based models will likely enhance and refine the outcomes we have demonstrated in our research.



Figure 7. The relationship between TEA's energy reduction and the enhancement of generalizability on CIFAR-10-C, under different types of distribution and different severity level of distribution shifts. Each subfigure plots corruption severity level on the x-axis, energy reduction on the left y-axis, and accuracy on the right y-axis. The accuracy axis contains two bars: the red bar denotes our TEA' accuracy, while the transparent bar denotes baseline's accuracy.



Figure 8. The relationship between TEA's energy reduction and the enhancement of generalizability on CIFAR-100-C, under different types of distribution and different severity level of distribution shifts. Each subfigure plots corruption severity level on the x-axis, energy reduction on the left y-axis, and accuracy on the right y-axis. The accuracy axis contains two bars: the red bar denotes our TEA' accuracy, while the transparent bar denotes baseline's accuracy.

tecture or each verage		ΣE(↓)	00.00	2.02 0.78	6.98	3.19	8.13	2.64	2.02 1.94	3.69	0.00	3.54	2.12	8.01	9.42	4.52	3.75	10.6	6.07	00.00	3.42	1.22	0.16	5.52	4.12	4.09	7.87	7.99
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oloy the curacy reflect ance.		Acc(1	56.47	80.10	51.42	74.77	81.4]	79.58	7.67 77.67	83.3	35.39	60.06	53.4(56.53	63.09	59.82	60.2	-6-70	65.10	21.2]	27.74	28.26	29.1	26.31	27.28	27.28	28.2	31.6
dels emj ed on Ac our TEA perform		JPEG	69.71 77.70	73.80	69.63	73.19	75.77	72.69	72.79	78.99	42.82	47.46	50.34	51.09	53.93	48.34	49.67	67.70	55.32	46.19	35.72	46.75	46.85	33.33	34.82	35.09 22.02	19.05	41.31
lated mo are base nance of r the top		Pixel	41.56 80.22	80.70	31.61	75.34	82.77	80.37	80.33 80.41	84.90	30.19	64.56	59.41	62.54	66.81	64.40	64.24 67.26	07.10	68.65	49.00	40.81	51.76	51.99	37.77	39.55	39.87	41.16	46.38
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ageNet-C arison. Eva he reported ed with bol		Contrast	53.37	62.90 85.90	43.49	82.20	87.91	87.32	87.20 87.20	88.98	27.43	71.31	57.29	63.96	73.59	71.15	71.61	66.61	75.71	1.95	6.04	2.03	1.91	5.68	5.93	5.87	0.30	6.89
Tiny-Ima air comp mance. T e indicate		Bright	90.70 01.61	92.40	91.05	89.68	92.16	91.60	91.61 91.90	92.37	71.42	75.89	75.98	75.12	75.14	73.40	74.48	C7.0/	76.74	29.75	32.58	34.87	36.01	30.08	31.86	31.94	33.31	36.83
0-C and nsure a fi ll perfori esults ar		Fog	73.98	86.90	79.35	82.35	86.30	84.77	c/.18 85.07	87.61	45.07	66.08	62.92	65.01	68.41	66.03	65.14 69.40	00.40	86.69	14.18	25.58	22.44	23.52	24.76	25.42	25.39	20.32	29.02
IFAR-10 0-C to e for overa notable 1	Veather	Frost	58.68 87.61	82.50	55.01	78.24	83.81	82.58	82.61 82.66	85.29	39.07	62.96	59.47	60.75	65.30	61.73	62.53 55 25	<i>cc.c</i> 0	67.14	31.88	30.26	35.01	35.68	28.56	29.87	29.67	30.62	34.19
-10-C, C CIFAR-1 nCE %) The most		Snow	74.87	83.20	76.46	79.03	84.06	82.73	82.73 83.08	85.56	51.13	63.00	60.42	61.42	64.88	62.51	62.94 64.06	04.90	67.78	26.79	27.59	30.19	30.95	26.21	27.11	27.03	28.31	31.43
n CIFAR ench for (n Error (r 0.1%. T		Zoom	57.99 87 80	07.09 88.40	60.49	83.16	89.24	87.89	87.89 88.06	89.77	44.20	71.25	67.74	69.86	71.63	70.24	70.68	14.40	74.20	19.38	33.41	33.66	34.63	31.36	32.85	32.84	33.87	39.06
models o RobustBo Corruptio tion unde		Motion	65.24 05.02	85.40	66.70	82.39	86.27	85.84	86.00 86.00	87.87	46.92	69.04	65.36	67.42	71.54	67.76	68.13 71.06	/1.00	72.63	20.71	35.20	36.07	36.78	33.21	34.59	34.83 22 22	66.65	41.72
baseline ced from (), Mean ard devia	Blur	Glass	45.67	04.72 65.10	31.29	61.64	68.22	64.70	65.20	71.31	20.56	47.36	40.81	45.52	51.17	47.52	47.49 50.10	01.00	53.78	5.67	18.46	14.42	15.17	17.54	18.25	18.41	18.44	21.14
nd various ts are sour ncy (Acc % mum stand		Defocus	53.01 87.10	86.90	44.27	82.85	88.00	87.21	87.19 87.39	88.89	35.57	70.94	64.06	67.90	71.69	69.66	69.29	12.24	72.96	6.63	28.43	17.28	18.74	27.05	28.05	27.68	28.80	32.76
of TEA an del weigh age Accura ith a maxi		Impulse	27.07 63 74	64.70	14.48	46.41	67.03	63.72 22 -	63.74 64.11	70.94	4.15	37.15	14.99	21.27	45.53	38.05	39.47	14 .02	48.59	5.55	18.22	11.41	14.54	18.68	18.00	17.95	18.87	20.58
mparison Irom. Mc Il as Aver. seeds, w	Noise	Shot	34.25 72 00	75.40	17.77	66.15	76.52	73.88	74.14	79.87	11.58	48.62	34.09	39.68	54.12	50.95	51.60 51.00	04.00	56.55	16.07	25.82	25.99	27.10	25.29	25.76	25.55	20.33	29.35
hensive col ith BatchN ion, as wel ith varying		Gaussian	27.68 71.02	72.60	14.46	62.91	75.20	72.21	71.95	78.33	9.87	46.53	29.54	37.50	53.44	48.64	48.76	+c.1c	54.29	12.37	24.00	20.75	22.25	23.80	24.44	24.48	25.10	25.50
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Figure 9. Hyper-parameter stability with respect to the Stochastic Gradient Langevin Dynamics (SGLD) learning rate. The x-axis is the SGLD learning rate varying from 0.001 to 0.4, while the y-axis measures model performance in terms of accuracy.



Figure 10. Hyper-parameter stability with respect to the Stochastic Gradient Langevin Dynamics (SGLD) step. The x-axis is the SGLD step varying from 1 to 200, while the y-axis measures model performance in terms of accuracy.

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