

DocRes: A Generalist Model Toward Unifying Document Image Restoration Tasks

A. Efficiency

As shown in Table 1, we compared the number of parameters and computational complexities of our method with those of other methods. It can be observed that even when compared to certain task-specific models, our method maintains an advantage in both the number of parameters and computational complexity. This advantage is particularly significant when considering that the number of parameters of these task-specific models would multiply several times over if they were to support multitasks. In contrast, our method does not require additional parameter increments.

Table 1. Model size and computational complexities for each method.

Methods	Li et al. [3]	DocShadow [5]	UDoc-GAN [8]	DE-GAN [7]	DocRes (ours)
Params (M) ↓	63.5	29.3	19.6	30	15.2
GFLOPs ↓	262.4	9.7	2.0	109.0	183.0

B. Additional ablation study

To quantify the individual contributions of task synergies and DTSPrompt, we conducted an additional ablation experiment and presented the results in Table 2. From the table, it can be observed that both DTSPrompt and multitask synergy lead to improvements. The improvement brought by multitask synergy may be attributed to the relatively small amount of binarization training data. The incorporation of other task data aids the model in avoiding overfitting to the limited binarization training data.

Table 2. For binarization, we gradually add DTSPrompt and multitask to provide further insights of these factors.

DTSPrompt	Multi-task	DIBCO'18 (FM↑/pFM↑/PSNR↑)
✗	✗	76.5 / 79.5 / 14.4
✓	✗	87.1 / 90.6 / 18.6
✓	✓	89.8 / 94.3 / 19.3

C. Comparison with more SOTA

We provide quantitative comparisons with more state-of-the-art (SOTA) methods for dewarping task in Table 3,

Table 3. Quantitative comparison with existing SOTA task-specific document dewarping methods on the DIR300 [2] benchmark.

Methods	Venue	MS-SSIM↑	LD↓	AD↓
DewarpNet [1]	ICCV'19	0.492	13.94	0.254
DDCP [9]	ICDAR'21	0.552	10.95	0.331
DocTr [1]	MM'21	0.616	7.21	0.254
DocGeoNet [2]	ECCV'22	<u>0.638</u>	<u>6.40</u>	0.242
PaperEdge [6]	SIGGRAPH'22	0.583	8.00	0.255
Li et al. [3]	ICCV'23	0.607	7.68	0.244
LA-DocFlatten [4]	ACM TOG'23	0.651	5.70	0.195
DocRes (ours)	-	0.626	6.83	<u>0.241</u>

which demonstrates the superior performance of DocRes when compared with some of these task-specific methods.

D. More visualized results

In Fig. 1, we present additional visualization results of DocRes across multiple tasks. Additionally, in Fig. 2, we illustrate the potential issue of error accumulation when applying DocRes for end-to-end camera-captured document image enhancement. Due to the iterative nature of DocRes for end-to-end tasks, where each forward pass utilizes the output of the previous pass as input, errors in one task can accumulate and affect the final result. Exploring methods that can accomplish multiple document restoration tasks in a single forward pass would be a meaningful avenue for future research.

E. Further discussions about DTSPrompt

In fact, from the ablation experiments in Table 2 of the main text, it is evident that compared to fixed prompts or task-specific models, DTPrompt does not demonstrate significant advantages and may even perform worse in certain tasks, such as shadow removal and deblurring tasks. This is mainly because document image restoration tasks like deblurring lack recognized prior features that definitively enhance performance. In such tasks, DTPrompt primarily serves as a discriminative cue rather than significantly boosting model performance. As for shadow removal tasks, while shadow maps have been widely proven to be useful, our extraction operations are very simple, involving basic image processing techniques rather than the conventional

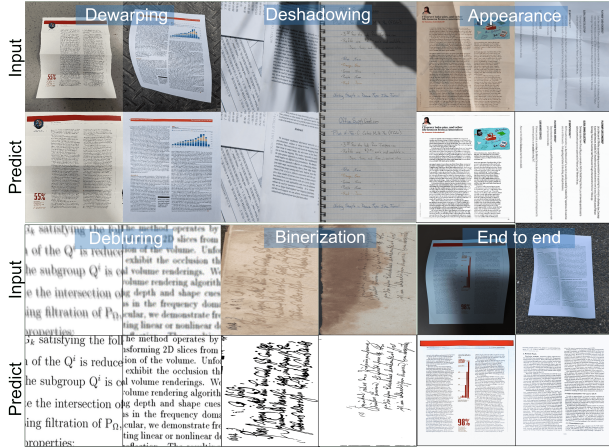


Figure 1. More visualized results from DocRes. Zoom in for best view.

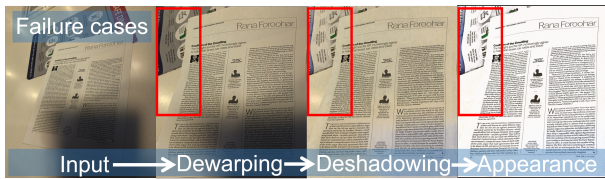


Figure 2. Failure case from DocRes when applying it for end-to-end camera-captured document image enhancement. Zoom in for best view.

approach [10, 11] of using deep models for prediction.

Based on these observations and analyses, future improvements for DTSPrompt could focus on two directions: **1.** Exploring more effective prior features for specific tasks: This entails delving deeper into identifying prior features that are more conducive to enhancing performance for particular tasks, such as deblurring. **2.** Employing a trainable prediction module for the DTSPrompt generator: This would enhance the prior feature extraction capabilities. Importantly, there’s still no necessity to designate a separate DTSPrompt generator for each task. Instead, a single DTSPrompt generator with shared parameters could simultaneously output multiple prior features. During input to the restoration network, different prior features can be chosen for task guidance based on the specific task at hand.

References

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