

# Generalized Single-Image-Based Morphing Attack Detection Using Deep Representations from Vision Transformer: Supplementary Material

Haoyu Zhang<sup>1\*</sup>

Raghavendra Ramachandra<sup>1</sup>

Kiran Raja<sup>1</sup>

Christoph Busch<sup>1,2</sup>

<sup>1</sup> Norwegian University of Science and Technology, Norway

<sup>2</sup> Darmstadt University of Applied Sciences, Germany

{haoyu.zhang, raghavendra.ramachandra, kiran.raja, christoph.busch}@ntnu.no  
christoph.busch@h-da.de

## 1. Complete tables of MAD performances

In this section, detailed results of quantitative MAD performance are included. Statistical analysis and discussions are in the main body of the paper. In each table, the intra-dataset testing case with the same training and testing dataset is marked with blue colour. Within each cross-dataset testing case (e.g., trained with Landmarks-I in the digital type of images, tested with Landmarks-II in the digital type of images), the best-performed value is marked in bold.

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Table 1. Quantitative performance of MAD on FRGC morph database. Training morphing type: Landmarks-I [4].

Testing Morphing Type	MAD Algorithms	Digital			Print-scan			Print-scan with compression		
		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =	
			5.00%	10.00%		5.00%	10.00%		5.00%	10.00%
Landmarks-I [4]	Ensemble Features [9]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	2.35	1.45	0.96	2.58	1.71	1.54
	Hybrid Features [6]	0.16	<b>0.00</b>	<b>0.00</b>	1.85	0.85	0.34	2.25	1.12	0.51
	Deep Features [5]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	2.85	1.25	0.17	2.05	1.02	0.17
	Steerable Features [7]	5.48	6.12	3.60	23.59	62.90	46.48	27.14	71.52	57.28
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	0.52	1.42	0.71	0.17
	Residual AutoEncoder [2]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	0.86	<b>0.00</b>	<b>0.00</b>	0.69	<b>0.00</b>	<b>0.00</b>
	Multi-level Deep Features [8]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	1.37	0.51	0.17	1.53	0.51	0.17
	<b>Proposed Method</b>	0.51	<b>0.00</b>	<b>0.00</b>	2.23	0.86	0.52	1.89	1.03	0.69
Landmarks-II [1]	Ensemble Features [9]	49.55	92.22	88.85	41.93	81.45	76.25	42.15	83.88	77.64
	Hybrid Features [6]	49.16	99.31	97.59	44.17	86.48	80.24	46.49	88.38	81.95
	Deep Features [5]	42.36	88.46	77.28	41.90	85.04	72.30	41.58	91.17	71.11
	Steerable Features [7]	50.00	99.48	98.45	50.00	93.89	88.13	47.39	92.14	83.68
	Multi-Modality [3]	41.51	80.61	71.86	35.37	79.64	73.92	37.86	84.46	76.96
	Residual AutoEncoder [2]	44.86	82.82	82.82	<b>29.65</b>	99.48	94.85	30.63	97.94	87.97
	Multi-level Deep Features [8]	26.08	59.86	46.31	30.22	<b>65.44</b>	<b>55.32</b>	<b>30.07</b>	<b>64.93</b>	<b>54.51</b>
	<b>Proposed Method</b>	<b>23.50</b>	<b>49.57</b>	<b>40.99</b>	40.10	85.59	75.35	37.26	88.21	79.03
StyleGAN [10]	Ensemble Features [9]	0.22	<b>0.00</b>	<b>0.00</b>	13.36	27.44	16.46	14.77	27.27	19.38
	Hybrid Features [6]	0.16	<b>0.00</b>	<b>0.00</b>	44.96	83.70	75.47	9.44	14.57	9.14
	Deep Features [5]	0.16	<b>0.00</b>	<b>0.00</b>	1.08	0.17	<b>0.00</b>	8.92	12.00	8.17
	Steerable Features [7]	7.16	9.77	4.63	3.46	2.42	1.54	38.91	87.30	79.58
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	5.34	<b>5.35</b>	3.21
	Residual AutoEncoder [2]	0.17	<b>0.00</b>	<b>0.00</b>	6.36	8.76	4.64	6.03	6.19	3.78
	Multi-level Deep Features [8]	0.32	<b>0.00</b>	<b>0.00</b>	3.95	2.05	0.51	<b>5.32</b>	5.83	<b>2.74</b>
	<b>Proposed Method</b>	2.57	1.37	0.34	12.35	23.16	14.75	12.35	25.56	14.07
MIPGAN-I [11]	Ensemble Features [9]	39.16	73.14	65.35	9.45	14.57	8.74	8.95	15.26	9.26
	Hybrid Features [6]	46.82	86.62	81.64	12.32	19.72	13.20	9.74	15.95	8.91
	Deep Features [5]	44.94	84.59	74.47	3.73	2.40	1.02	23.83	66.55	49.22
	Steerable Features [7]	50.00	99.82	97.59	3.26	2.22	2.15	28.82	79.24	60.20
	Multi-Modality [3]	41.39	78.79	72.55	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>8.14</b>	<b>10.89</b>	<b>7.14</b>
	Residual AutoEncoder [2]	16.42	29.21	20.45	33.33	96.05	90.03	25.49	98.11	89.00
	Multi-level Deep Features [8]	20.97	46.65	34.13	11.35	29.84	14.57	23.47	62.60	47.34
	<b>Proposed Method</b>	<b>11.15</b>	<b>23.16</b>	<b>12.35</b>	19.38	40.31	28.82	27.62	62.95	48.89
MIPGAN-II [11]	Ensemble Features [9]	34.13	70.49	61.57	5.32	6.68	2.57	6.72	8.16	4.14
	Hybrid Features [6]	44.96	83.7	75.47	5.90	8.42	3.23	5.67	6.18	2.91
	Deep Features [5]	40.37	60.32	50.36	1.36	<b>0.00</b>	<b>0.00</b>	8.37	24.69	16.17
	Steerable Features [7]	50.00	98.77	97.25	6.84	7.54	6.12	31.16	85.42	73.75
	Multi-Modality [3]	35.86	66.72	56.43	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>4.47</b>	<b>3.57</b>	0.35
	Residual AutoEncoder [2]	13.92	21.82	17.01	8.80	77.66	1.03	5.60	8.06	<b>0.17</b>
	Multi-level Deep Features [8]	19.20	39.79	29.50	3.95	2.05	0.51	8.73	26.07	6.34
	<b>Proposed Method</b>	<b>8.40</b>	<b>12.52</b>	<b>6.35</b>	5.15	5.49	0.86	8.58	24.01	3.77

Table 2. Quantitative performance of MAD on FRGC morph database. Training morphing type: Landmarks-II [1].

Testing Morphing Type	MAD Algorithms	Digital			Print-scan			Print-scan with compression		
		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =	
			5.00%	10.00%		5.00%	10.00%		5.00%	10.00%
Landmarks-I [4]	Ensemble Features [9]	48.57	97.77	95.36	24.19	52.48	43.22	21.64	47.51	36.19
	Hybrid Features [6]	45.67	96.91	94.16	32.26	77.87	66.55	24.51	50.94	40.65
	Deep Features [5]	47.22	89.94	68.98	26.66	55.40	42.53	25.24	51.80	40.99
	Steerable Features [7]	50.00	95.12	91.25	37.72	93.48	82.84	37.13	92.62	83.71
	Multi-Modality [3]	19.54	42.36	31.21	34.29	84.28	73.32	38.19	81.42	71.25
	Residual AutoEncoder [2]	<b>3.59</b>	<b>2.58</b>	<b>1.72</b>	<b>9.85</b>	<b>19.97</b>	<b>9.72</b>	<b>13.82</b>	<b>44.44</b>	<b>21.01</b>
	Multi-level Deep Features [8]	14.92	33.10	22.64	29.40	61.57	51.11	24.02	54.71	44.94
	<b>Proposed Method</b>	14.92	33.10	22.64	37.29	80.41	67.01	26.63	63.75	52.92
Landmarks-II [1]	Ensemble Features [9]	3.62	2.22	0.68	6.32	7.97	2.42	5.57	6.41	2.42
	Hybrid Features [6]	1.53	0.17	<b>0.00</b>	5.21	5.19	3.14	5.37	5.71	3.46
	Deep Features [5]	6.16	6.51	3.94	6.65	9.94	4.88	7.13	12.50	5.55
	Steerable Features [7]	27.78	69.46	53.68	30.55	79.75	68.05	29.54	76.41	63.19
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>1.61</b>	<b>0.53</b>	<b>0.35</b>	<b>1.82</b>	<b>0.35</b>	<b>0.17</b>
	Residual AutoEncoder [2]	2.58	2.06	1.72	7.99	12.15	5.73	9.38	19.97	9.2
	Multi-level Deep Features [8]	10.63	25.21	11.66	5.39	5.93	2.09	6.19	7.46	3.29
	<b>Proposed Method</b>	10.63	25.21	11.66	11.46	19.62	12.15	10.92	25.65	11.96
StyleGAN [10]	Ensemble Features [9]	29.67	61.92	52.48	27.18	61.57	50.60	29.18	62.14	52.48
	Hybrid Features [6]	34.76	74.44	62.95	34.80	67.23	58.14	23.17	49.22	38.25
	Deep Features [5]	30.13	35.19	40.29	1.37	0.17	0.17	26.65	57.10	46.31
	Steerable Features [7]	50.00	98.28	96.56	1.21	0.34	<b>0.00</b>	35.52	85.31	50
	Multi-Modality [3]	25.4	62.09	49.91	<b>0.16</b>	<b>0.00</b>	<b>0.00</b>	15.53	31.96	23.21
	Residual AutoEncoder [2]	<b>9.15</b>	<b>16.84</b>	<b>8.59</b>	8.16	13.19	6.25	<b>8.09</b>	<b>11.81</b>	<b>6.25</b>
	Multi-level Deep Features [8]	22.64	51.97	35.51	4.64	4.45	1.37	25.55	51.28	42.53
	<b>Proposed Method</b>	22.64	51.97	35.51	25.21	60.72	45.97	34.48	73.07	60.38
MIPGAN-I [11]	Ensemble Features [9]	30.23	65.35	53.17	43.92	87.65	79.24	44.24	89.23	82.33
	Hybrid Features [6]	46.29	84.04	77.01	34.16	71.18	64.66	35.50	76.84	65.52
	Deep Features [5]	38.18	77.53	67.92	1.20	0.34	0.17	27.41	65.69	52.65
	Steerable Features [7]	36.51	86.96	76.51	2.61	0.85	<b>0.00</b>	32.73	87.13	74.19
	Multi-Modality [3]	24.75	72.14	42.88	<b>0.37</b>	<b>0.00</b>	<b>0.00</b>	40.51	82.14	73.92
	Residual AutoEncoder [2]	<b>12.89</b>	<b>22.51</b>	<b>15.46</b>	6.45	7.81	3.82	<b>1.44</b>	<b>0.52</b>	<b>0.17</b>
	Multi-level Deep Features [8]	23.67	55.75	42.71	4.10	3.08	0.51	28.58	62.26	51.80
	<b>Proposed Method</b>	23.67	55.75	42.71	19.04	47.86	36.36	23.16	57.29	45.80
MIPGAN-II [11]	Ensemble Features [9]	27.13	58.83	45.45	33.57	77.35	65.52	40.46	84.9	75.47
	Hybrid Features [6]	46.82	83.53	75.81	35.91	77.18	65.24	36.50	79.24	68.78
	Deep Features [5]	36.71	78.73	68.61	1.04	<b>0.00</b>	<b>0.00</b>	34.40	71.18	59.69
	Steerable Features [7]	36.87	90.33	79.41	3.19	1.88	0.34	34.12	89.19	78.91
	Multi-Modality [3]	20.92	33.27	43.05	<b>0.91</b>	<b>0.00</b>	<b>0.00</b>	33.33	77.85	67.5
	Residual AutoEncoder [2]	<b>8.93</b>	<b>14.43</b>	<b>8.59</b>	4.51	4.51	2.60	<b>2.26</b>	<b>1.04</b>	<b>0.17</b>
	Multi-level Deep Features [8]	29.67	67.92	51.11	1.73	<b>0.00</b>	<b>0.00</b>	34.46	68.95	58.14
	<b>Proposed Method</b>	29.67	67.92	51.11	30.53	78.22	63.46	28.47	68.95	55.06

Table 3. Quantitative performance of MAD on FRGC morph database. Training morphing type: StyleGAN [10].

Testing Morphing Type	MAD Algorithms	Digital			Print-scan			Print-scan with compression		
		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =	
			5.00%	10.00%		5.00%	10.00%		5.00%	10.00%
Landmarks-I [4]	Ensemble Features [9]	0.32	<b>0.00</b>	<b>0.00</b>	16.60	28.13	19.89	13.89	22.12	17.66
	Hybrid Features [6]	0.42	<b>0.00</b>	<b>0.00</b>	15.26	<b>26.41</b>	<b>17.66</b>	14.37	22.81	16.92
	Deep Features [5]	0.16	<b>0.00</b>	<b>0.00</b>	24.67	55.74	41.80	13.36	34.30	18.69
	Steerable Features [7]	6.17	7.71	3.94	33.92	81.81	69.46	35.62	83.87	74.19
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	20.00	41.96	29.64	11.97	17.85	12.85
	Residual AutoEncoder [2]	0.17	<b>0.00</b>	<b>0.00</b>	15.02	36.08	22.34	8.93	17.35	7.90
	Multi-level Deep Features [8]	0.16	<b>0.00</b>	<b>0.00</b>	<b>1.37</b>	<b>0.51</b>	<b>0.17</b>	<b>1.53</b>	<b>0.51</b>	<b>0.17</b>
	<b>Proposed Method</b>	5.15	5.15	2.74	14.95	30.24	21.31	12.71	24.74	15.81
Landmarks-II [1]	Ensemble Features [9]	44.72	89.53	80.61	38.31	78.50	69.15	38.84	83.70	74.17
	Hybrid Features [6]	45.65	90.22	84.56	34.18	81.95	70.53	32.93	78.50	64.12
	Deep Features [5]	43.43	95.31	83.12	45.34	96.10	88.48	30.19	65.45	54.68
	Steerable Features [7]	50.00	99.65	99.10	40.81	83.42	72.60	39.13	84.89	74.82
	Multi-Modality [3]	42.69	88.50	78.38	<b>26.72</b>	<b>73.21</b>	<b>56.25</b>	27.87	68.75	57.14
	Residual AutoEncoder [2]	38.94	74.40	<b>58.25</b>	34.72	99.66	93.13	<b>27.32</b>	92.10	83.85
	Multi-level Deep Features [8]	<b>32.17</b>	<b>69.46</b>	60.89	30.22	65.44	55.32	30.07	<b>64.93</b>	<b>54.51</b>
	<b>Proposed Method</b>	37.91	87.48	77.02	43.23	92.53	85.07	40.73	88.03	78.51
StyleGAN [10]	Ensemble Features [9]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Hybrid Features [6]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Deep Features [5]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Steerable Features [7]	3.75	3.43	1.54	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	20.66	56.69	43.39
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Residual AutoEncoder [2]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	0.08	<b>0.00</b>	<b>0.00</b>	0.34	<b>0.00</b>	<b>0.00</b>
	Multi-level Deep Features [8]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	3.95	2.05	0.51	5.32	5.83	2.74
	<b>Proposed Method</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	1.03	0.17	<b>0.00</b>	1.20	<b>0.00</b>	<b>0.00</b>
MIPGAN-I [11]	Ensemble Features [9]	39.97	75.98	68.78	20.21	42.14	33.44	20.73	45.28	36.53
	Hybrid Features [6]	46.45	86.79	77.87	29.34	59.19	47.51	24.87	51.62	41.18
	Deep Features [5]	23.95	48.19	38.25	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	26.40	63.97	44.57
	Steerable Features [7]	50.00	98.45	96.91	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	31.76	82.33	69.46
	Multi-Modality [3]	33.73	69.53	61.69	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>20.07</b>	<b>39.46</b>	<b>30.39</b>
	Residual AutoEncoder [2]	<b>16.61</b>	<b>27.66</b>	<b>20.45</b>	50.00	99.83	99.66	41.20	81.44	75.95
	Multi-level Deep Features [8]	27.21	62.43	48.19	11.35	29.54	14.57	23.47	62.60	47.34
	<b>Proposed Method</b>	21.61	49.91	35.68	37.56	79.07	72.90	32.76	65.87	56.43
MIPGAN-II [11]	Ensemble Features [9]	39.93	73.58	66.89	15.78	28.14	19.38	13.72	28.98	16.63
	Hybrid Features [6]	44.72	82.16	73.75	19.36	43.22	28.64	16.98	32.93	23.84
	Deep Features [5]	42.19	70.42	60.48	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	9.98	20.41	9.94
	Steerable Features [7]	50.00	98.28	95.38	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	31.07	79.41	63.46
	Multi-Modality [3]	37.56	75.98	65.86	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>7.85</b>	<b>12.67</b>	<b>5.17</b>
	Residual AutoEncoder [2]	<b>15.09</b>	<b>26.63</b>	<b>19.76</b>	10.85	95.53	62.89	11.53	58.42	21.82
	Multi-level Deep Features [8]	25.04	57.46	45.28	3.06	0.51	0.17	8.73	26.07	6.34
	<b>Proposed Method</b>	18.01	44.43	32.42	13.72	64.67	30.02	12.52	38.94	17.67

Table 4. Quantitative performance of MAD on FRGC morph database. Training morphing type: MIPGAN-I [11].

Testing Morphing Type	MAD Algorithms	Digital			Print-scan			Print-scan with compression		
		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =	
			5.00%	10.00%		5.00%	10.00%		5.00%	10.00%
Landmarks-I [4]	Ensemble Features [9]	23.66	51.45	39.96	5.82	7.22	2.92	6.17	7.54	3.94
	Hybrid Features [6]	47.15	87.16	79.41	6.50	8.23	4.15	7.91	10.29	6.34
	Deep Features [5]	11.63	23.11	12.56	19.91	34.10	31.38	18.66	37.75	28.64
	Steerable Features [7]	50.00	91.25	85.92	35.86	80.44	70.66	38.60	84.73	74.99
	Multi-Modality [3]	32.43	73.17	61.92	9.65	15.71	8.75	<b>5.01</b>	<b>5.00</b>	<b>3.14</b>
	Residual AutoEncoder [2]	18.70	31.62	25.43	4.12	3.95	1.89	8.02	11.51	7.39
	Multi-level Deep Features [8]	<b>6.01</b>	<b>6.86</b>	<b>3.43</b>	<b>1.37</b>	<b>0.51</b>	<b>0.17</b>	6.01	7.37	7.37
	<b>Proposed Method</b>	7.38	11.84	5.66	8.25	14.43	6.87	12.03	19.42	13.23
Landmarks-II [1]	Ensemble Features [9]	35.38	82.33	68.95	41.67	95.14	83.53	43.68	96.01	85.44
	Hybrid Features [6]	28.62	75.64	61.4	44.38	95.66	85.78	38.18	90.46	78.16
	Deep Features [5]	38.40	89.02	77.70	45.21	86.17	80.27	42.80	96.50	90.48
	Steerable Features [7]	50.00	97.94	93.82	44.36	87.26	81.15	43.92	92.36	86.55
	Multi-Modality [3]	<b>17.14</b>	<b>49.39</b>	<b>29.41</b>	<b>28.80</b>	87.14	<b>58.92</b>	29.65	88.21	67.50
	Residual AutoEncoder [2]	50.00	90.21	85.57	32.08	<b>82.82</b>	71.31	33.51	77.66	68.73
	Multi-level Deep Features [8]	40.49	86.27	74.27	30.22	65.44	55.32	<b>6.01</b>	<b>7.37</b>	<b>3.43</b>
	<b>Proposed Method</b>	32.76	83.53	73.41	39.06	89.41	79.86	35.70	87.69	76.08
StyleGAN [10]	Ensemble Features [9]	17.72	37.22	26.58	12.19	26.24	15.26	11.82	24.69	14.23
	Hybrid Features [6]	31.16	64.32	53.85	11.99	19.20	13.72	9.93	18.15	9.94
	Deep Features [5]	26.86	27.54	24.63	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	10.46	8.74	6.43
	Steerable Features [7]	50.00	92.45	87.15	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	44.12	92.45	86.79
	Multi-Modality [3]	22.81	48.37	37.22	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	5.34	<b>5.53</b>	4.15
	Residual AutoEncoder [2]	10.14	15.12	10.14	11.37	19.24	12.54	10.30	19.93	10.65
	Multi-level Deep Features [8]	<b>6.33</b>	<b>7.54</b>	<b>4.11</b>	3.95	2.05	0.51	<b>5.12</b>	5.66	<b>2.05</b>
	<b>Proposed Method</b>	8.92	16.30	7.89	7.89	10.98	6.69	9.09	14.41	8.58
MIPGAN-I [11]	Ensemble Features [9]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Hybrid Features [6]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Deep Features [5]	1.16	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Steerable Features [7]	29.83	84.21	68.95	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	25.92	72.72	60.14
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Residual AutoEncoder [2]	1.03	<b>0.00</b>	<b>0.00</b>	0.34	<b>0.00</b>	<b>0.00</b>	0.69	<b>0.00</b>	<b>0.00</b>
	Multi-level Deep Features [8]	1.36	0.17	<b>0.00</b>	11.35	29.84	14.57	1.04	1.17	0.17
	<b>Proposed Method</b>	0.51	<b>0.00</b>	<b>0.00</b>	0.86	0.17	0.17	1.20	0.17	0.17
MIPGAN-II [11]	Ensemble Features [9]	2.15	0.17	<b>0.00</b>	0.68	<b>0.00</b>	<b>0.00</b>	0.64	<b>0.00</b>	<b>0.00</b>
	Hybrid Features [6]	1.36	0.34	<b>0.00</b>	0.86	<b>0.00</b>	<b>0.00</b>	0.85	<b>0.00</b>	<b>0.00</b>
	Deep Features [5]	2.01	1.02	0.34	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	28.58	85.93	69.12
	Steerable Features [7]	34.56	88.16	78.38	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	28.58	85.93	69.12
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Residual AutoEncoder [2]	0.03	<b>0.00</b>	<b>0.00</b>	0.30	<b>0.00</b>	<b>0.00</b>	0.53	<b>0.00</b>	<b>0.00</b>
	Multi-level Deep Features [8]	1.04	<b>0.00</b>	<b>0.00</b>	3.06	0.51	0.17	0.48	0.34	0.17
	<b>Proposed Method</b>	2.57	0.69	0.34	0.34	0.17	<b>0.00</b>	0.51	<b>0.00</b>	<b>0.00</b>

Table 5. Quantitative performance of MAD on FRGC morph database. Training morphing type: MIPGAN-II [11].

Testing Morphing Type	MAD Algorithms	Digital			Print-scan			Print-scan with compression		
		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =		D-EER(%)	BPCER @ APCER =	
			5.00%	10.00%		5.00%	10.00%		5.00%	10.00%
Landmarks-I [4]	Ensemble Features [9]	13.08	29.15	15.78	<b>4.28</b>	<b>3.94</b>	<b>2.22</b>	4.28	3.61	2.22
	Hybrid Features [6]	40.14	77.70	67.23	5.49	5.48	2.40	7.21	10.98	4.15
	Deep Features [5]	16.31	39.96	26.17	18.66	37.73	28.64	8.17	13.89	6.88
	Steerable Features [7]	50.00	91.25	86.27	35.86	80.44	70.66	39.09	89.87	79.75
	Multi-Modality [3]	23.82	54.20	37.90	6.18	8.21	3.21	<b>4.16</b>	<b>3.39</b>	<b>1.96</b>
	Residual AutoEncoder [2]	9.15	16.84	8.59	8.16	13.19	6.25	8.09	11.81	6.25
	Multi-level Deep Features [8]	<b>6.21</b>	<b>6.51</b>	<b>4.80</b>	14.25	30.70	18.86	6.70	8.06	3.94
	<b>Proposed Method</b>	7.20	10.12	5.66	11.51	24.05	14.43	36.77	1.12	21.13
Landmarks-II [1]	Ensemble Features [9]	32.37	84.90	70.32	39.20	90.12	82.32	44.17	95.49	88.73
	Hybrid Features [6]	23.88	63.80	45.62	40.22	88.90	79.20	38.96	94.28	82.14
	Deep Features [5]	41.10	90.92	83.87	42.81	96.50	90.40	35.12	76.56	70.13
	Steerable Features [7]	48.94	97.77	92.79	44.36	87.26	81.15	45.47	92.53	88.71
	Multi-Modality [3]	10.62	28.81	11.32	26.8	82.32	64.28	30.15	90.53	73.21
	Residual AutoEncoder [2]	<b>9.15</b>	<b>16.84</b>	<b>8.59</b>	<b>8.16</b>	<b>13.19</b>	<b>6.25</b>	<b>8.09</b>	<b>11.81</b>	<b>6.25</b>
	Multi-level Deep Features [8]	46.13	95.88	99.90	42.03	97.90	93.19	39.24	84.20	74.13
	<b>Proposed Method</b>	35.33	83.36	74.27	44.79	92.36	87.85	42.11	90.99	83.36
StyleGAN [10]	Ensemble Features [9]	12.51	22.29	15.78	13.72	29.67	18.18	14.25	31.73	20.41
	Hybrid Features [6]	24.70	49.74	41.85	12.87	26.58	14.75	11.86	26.92	15.09
	Deep Features [5]	21.70	33.49	23.72	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	7.18	9.43	4.45
	Steerable Features [7]	50.00	95.19	92.45	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	46.30	91.54	90.56
	Multi-Modality [3]	21.15	40.48	30.87	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	6.79	9.28	3.92
	Residual AutoEncoder [2]	9.15	16.84	8.59	8.16	13.19	6.25	8.09	11.81	6.25
	Multi-level Deep Features [8]	<b>5.52</b>	<b>6.51</b>	<b>3.25</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>6.01</b>	<b>7.03</b>	<b>3.25</b>
	<b>Proposed Method</b>	14.07	23.67	16.64	9.78	17.15	9.09	10.63	24.53	11.66
MIPGAN-I [11]	Ensemble Features [9]	1.56	0.68	0.34	2.14	1.22	0.53	2.57	0.85	0.34
	Hybrid Features [6]	2.27	0.85	0.17	4.79	4.80	3.43	4.30	3.60	2.22
	Deep Features [5]	2.41	0.55	0.17	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	7.85	10.97	5.31
	Steerable Features [7]	30.51	83.70	69.29	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	26.24	82.33	62.63
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Residual AutoEncoder [2]	9.15	16.84	8.59	8.16	13.19	6.25	8.09	11.81	6.25
	Multi-level Deep Features [8]	2.05	0.85	0.34	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	4.30	3.60	2.05
	<b>Proposed Method</b>	0.86	0.17	<b>0.00</b>	17.15	39.45	26.59	13.55	26.59	16.64
MIPGAN-II [11]	Ensemble Features [9]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Hybrid Features [6]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Deep Features [5]	2.57	1.02	0.51	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	3.58	1.20	<b>0.00</b>
	Steerable Features [7]	31.84	86.79	70.84	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	26.57	85.59	72.21
	Multi-Modality [3]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>
	Residual AutoEncoder [2]	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	0.86	<b>0.00</b>	<b>0.00</b>	0.69	<b>0.00</b>	<b>0.00</b>
	Multi-level Deep Features [8]	1.85	0.34	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	<b>0.00</b>	2.53	0.85	3.25
	<b>Proposed Method</b>	0.69	<b>0.00</b>	<b>0.00</b>	5.49	6.35	0.17	4.46	3.26	0.17

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