

Classic Video Denoising in a Machine Learning World: Robust, Fast, and Controllable

Supplementary Material

1. Qualitative Results

We provide test results of various methods from the main paper, along with a comparative web demo. The demo allows users to compare different methods and adjust brightness, contrast, and saturation to achieve better comparative results. Additionally, we provide a web demo based on different denoising strengths, allowing users to explore the results of spatial and temporal denoising and compare the detail preservation capabilities under varying denoising levels. Please refer to these demos from our project page: <https://srameo.github.io/projects/levd>.

2. More Quantitative Results

We provide the LPIPS [17] and SSIM [15] scores of different methods on the CRVD benchmark in Tab. 3.

3. More Ablative Experiments

As summarized in Tab. 1 (top and middle), we also tried using ResNet-101 [5] and SDXL VAE [8] as the backbone as well as RAFT [13] and PWC-Net [11] as the motion estimator. These ablations do not offer too much signal other than that our initial choices for these are reasonable.

Our experimental results show that while RAFT [13] offers slightly better performance (PSNR improvement of 0.17, SSIM improvement of 0.0057), its runtime is more than 5 times that of SpyNet [9] (24.53 ms vs 4.56 ms) as shown in Tab. 2. PWC-Net [11], though faster than RAFT, is still 3 times slower than SpyNet and performs slightly worse than our method. Therefore, we chose SpyNet as our optical flow estimator, primarily considering the optimal balance between performance and speed.

For the backbone selection, as shown in Tab. 1, ConvNext [7] outperforms ResNet-101 [5] and SDXL VAE [8] across all metrics. ResNet-101 shows a decrease of 0.17 in PSNR, 0.0024 in SSIM, and an increase of 0.0109 in LPIPS; while SDXL VAE exhibits an even more significant performance drop. These results confirm the rationale behind our choice of ConvNext as the backbone.

As shown in Fig. 1, omitting H.264 transcoding from the data pipeline results in numerous temporal compression artifacts in the denoising results. These artifacts primarily manifest as inconsistencies between video frames, significantly degrading the final visual quality.

As shown in Fig. 2, the denoising results with different anchor frame choices are similar though the noise level of the anchor frames differs a lot.

| | PSNR | delta | SSIM | delta | LPIPS | delta |
|-----------------|-------|-------|--------|---------|--------|---------|
| ConvNext - Ours | 36.04 | - | 0.9472 | - | 0.0763 | - |
| ResNet-101 | 35.87 | -0.17 | 0.9448 | -0.0024 | 0.0872 | +0.0109 |
| SDXL VAE | 35.79 | -0.25 | 0.9439 | -0.0033 | 0.0949 | +0.0186 |
| SpyNet - Ours | 36.04 | - | 0.9472 | - | 0.0763 | - |
| RAFT | 36.22 | +0.17 | 0.9529 | +0.0057 | 0.0801 | +0.0038 |
| PWC-Net | 35.96 | -0.09 | 0.9464 | -0.0007 | 0.0919 | +0.0156 |

Table 1. Additional experiments on the CRVD (sRGB) dataset.

| | Flow + Align | $\mathcal{P}(\cdot; \theta)$ | Temp. Denoise | Spat. Denoise |
|---------------|--------------|------------------------------|---------------|---------------|
| SpyNet - Ours | 4.56 ms | 1.15 ms | 6.20 ms | 2.37 ms |
| RAFT | 24.53 ms | 1.19 ms | 6.17 ms | 2.32 ms |
| PWC-Net | 14.29 ms | 1.22 ms | 6.13 ms | 2.36 ms |

Table 2. Runtime for each denoising stage at a 720p resolution.

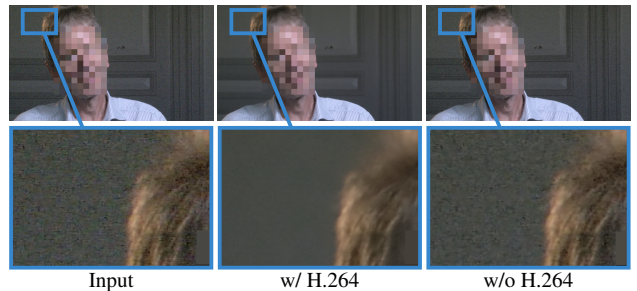


Figure 1. Our approach w/ and w/o H.264 augmentation.

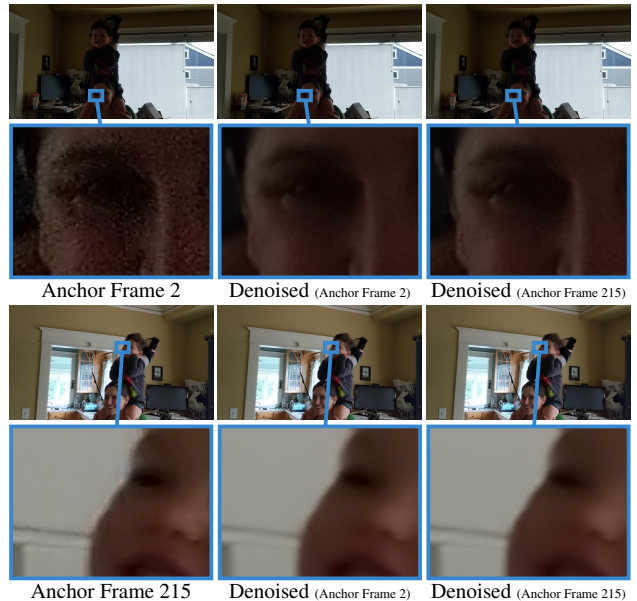


Figure 2. Denoising results with different anchor frames choices.

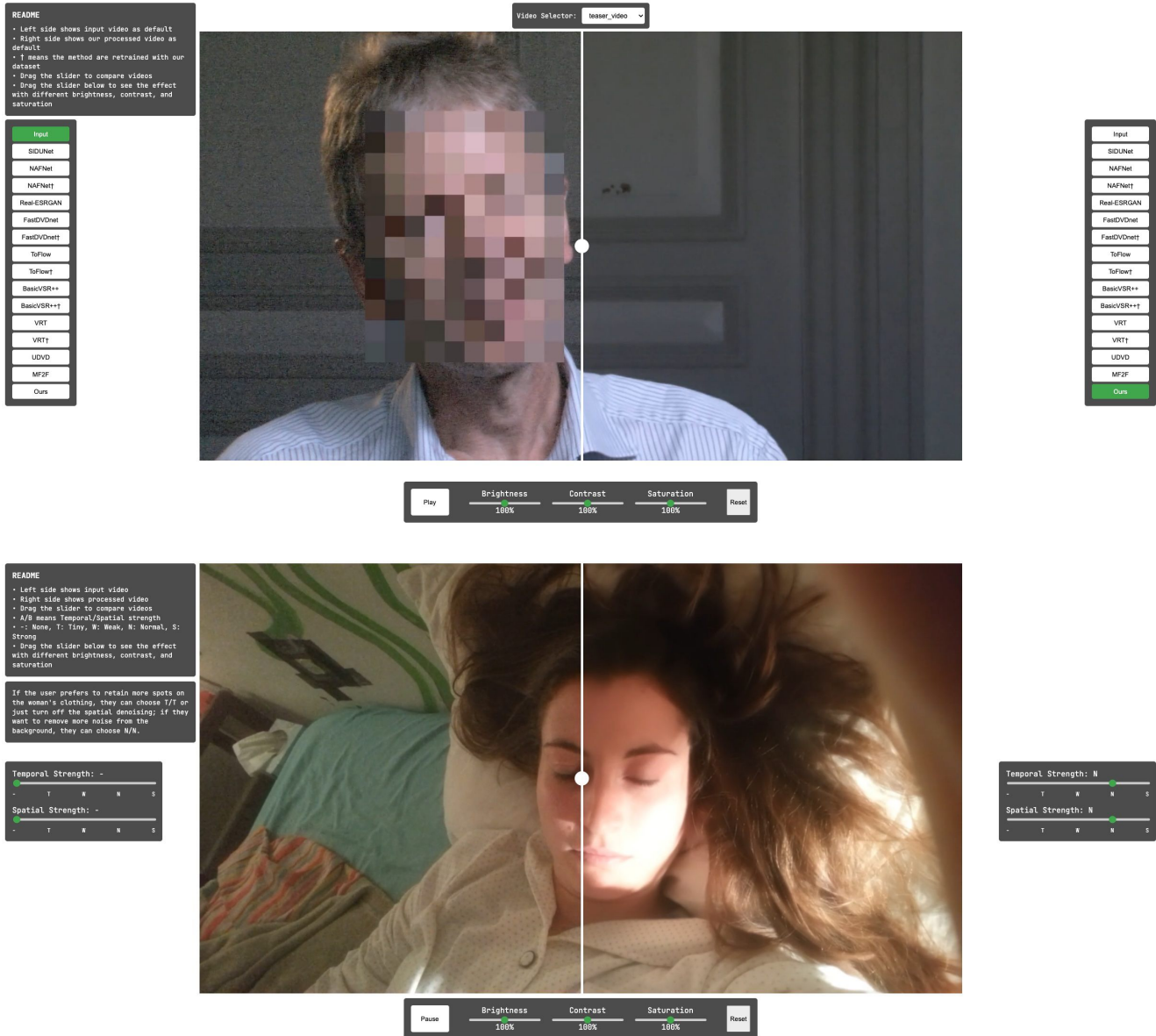


Figure 3. Screenshots of our interactive web demos. Top: a comparison interface that allows users to examine and compare results from different denoising methods side-by-side. Bottom: a control interface that enables users to interactively adjust spatial and temporal denoising strengths to explore the trade-off between detail preservation and noise reduction.

References

- [1] Kelvin CK Chan, Shangchen Zhou, Xiangyu Xu, and Chen Change Loy. Basicvsr++: Improving video super-resolution with enhanced propagation and alignment. In *CVPR, 2022*. 3
- [2] Chen Chen, Qifeng Chen, Jia Xu, and Vladlen Koltun. Learning to see in the dark. In *CVPR, 2018*. 3
- [3] Liangyu Chen, Xiaojie Chu, Xiangyu Zhang, and Jian Sun. Simple baselines for image restoration. In *ECCV, 2022*. 3
- [4] Valéry Dewil, Jérémy Anger, Axel Davy, Thibaud Ehret, Gabriele Facciolo, and Pablo Arias. Self-supervised training for blind multi-frame video denoising. In *WACV, 2021*. 3
- [5] Kaiming He, Xiangyu Zhang, Shaoqing Ren, and Jian Sun. Deep residual learning for image recognition. In *CVPR, 2016*. 1
- [6] Jingyun Liang, Jiezhong Cao, Yuchen Fan, Kai Zhang, Rakesh Ranjan, Yawei Li, Radu Timofte, and Luc Van Gool. Vrt: A video restoration transformer. *IEEE TIP, 2024*. 3
- [7] Zhuang Liu, Hanzi Mao, Chao-Yuan Wu, Christoph Feichtenhofer, Trevor Darrell, and Saining Xie. A convnet for the 2020s. In *CVPR, 2022*. 1
- [8] Dustin Podell, Zion English, Kyle Lacey, Andreas

| | ISO 1600 | | ISO 3200 | | ISO 6400 | | ISO 12800 | | ISO 25600 | | Overall | | Speed | |
|------------------------------|-------------------------|------------------------|-------------------------|------------------------|-------------------------|------------------------|-------------------------|------------------------|-------------------------|------------------------|-------------------------|------------------------|------------------------|------------------------|
| | SSIM | rank | SSIM | rank | SSIM | rank | SSIM | rank | SSIM | rank | SSIM | rank | FPS | rank |
| | (higher SSIM is better) | | (higher SSIM is better) | | (higher SSIM is better) | | (higher SSIM is better) | | (higher SSIM is better) | | (higher SSIM is better) | | (higher FPS is better) | |
| SID [2] [†] | 0.9689 | 6 th of 10 | 0.9622 | 6 th of 10 | 0.9522 | 4 th of 10 | 0.9289 | 3 rd of 10 | 0.8162 | 4 th of 10 | 0.9257 | 3 rd of 10 | 6.95 | 3 rd of 10 |
| NAFNet [3] [†] | 0.9727 | 3 rd of 10 | 0.9663 | 3 rd of 10 | <u>0.9580</u> | 1 st of 10 | 0.9345 | 2 nd of 10 | 0.8531 | 2 nd of 10 | 0.9369 | 2 nd of 10 | 1.69 | 7 th of 10 |
| Real-ESRGAN [14] | 0.8906 | 10 th of 10 | 0.8612 | 10 th of 10 | 0.8542 | 10 th of 10 | 0.8541 | 9 th of 10 | 0.8521 | 3 rd of 10 | 0.8624 | 9 th of 10 | 0.24 | 8 th of 10 |
| FastDVDNet [12] [†] | 0.9712 | 5 th of 10 | 0.9651 | 4 th of 10 | 0.9510 | 5 th of 10 | 0.9135 | 5 th of 10 | 0.7685 | 7 th of 10 | 0.9139 | 5 th of 10 | 5.72 | 4 th of 10 |
| TOFlow [16] [†] | 0.9636 | 8 th of 10 | 0.9557 | 8 th of 10 | 0.9408 | 7 th of 10 | 0.9000 | 6 th of 10 | 0.7573 | 8 th of 10 | 0.9035 | 6 th of 10 | 2.84 | 6 th of 10 |
| BasicVSR++ [1] [†] | 0.9721 | 4 th of 10 | 0.9664 | 2 nd of 10 | 0.9425 | 6 th of 10 | 0.8568 | 8 th of 10 | 0.6285 | 9 th of 10 | 0.8733 | 8 th of 10 | 7.41 | 2 nd of 10 |
| VRT [6] [†] | 0.9730 | 2 nd of 10 | 0.9644 | 5 th of 10 | 0.9287 | 8 th of 10 | 0.8133 | 10 th of 10 | 0.5601 | 10 th of 10 | 0.8479 | 10 th of 10 | 0.05 | 10 th of 10 |
| UDVD [10] | 0.9461 | 9 th of 10 | 0.9352 | 9 th of 10 | 0.9147 | 9 th of 10 | 0.8819 | 7 th of 10 | 0.7831 | 6 th of 10 | 0.8922 | 7 th of 10 | 0.16 | 9 th of 10 |
| MF2F [4] | 0.9657 | 7 th of 10 | 0.9612 | 7 th of 10 | 0.9537 | 3 rd of 10 | 0.9271 | 4 th of 10 | 0.7960 | 5 th of 10 | 0.9207 | 4 th of 10 | 4.62 | 5 th of 10 |
| Ours | <u>0.9740</u> | 1 st of 10 | <u>0.9665</u> | 1 st of 10 | 0.9560 | 2 nd of 10 | <u>0.9381</u> | 1 st of 10 | <u>0.9013</u> | 1 st of 10 | <u>0.9472</u> | 1 st of 10 | <u>31.66</u> | 1 st of 10 |

| | ISO 1600 | | ISO 3200 | | ISO 6400 | | ISO 12800 | | ISO 25600 | | Overall | | Speed | |
|------------------------------|-------------------------|------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-----------------------|------------------------|
| | LPIPS | rank | LPIPS | rank | LPIPS | rank | LPIPS | rank | LPIPS | rank | LPIPS | rank | FPS | rank |
| | (lower LPIPS is better) | | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower LPIPS is better) | (lower FPS is better) | |
| SID [2] [†] | 0.0307 | 5 th of 10 | 0.0358 | 7 th of 10 | 0.0558 | 4 th of 10 | 0.0901 | 3 rd of 10 | 0.2767 | 4 th of 10 | 0.0978 | 3 rd of 10 | 6.95 | 3 rd of 10 |
| NAFNet [3] [†] | 0.0240 | 3 rd of 10 | 0.0353 | 6 th of 10 | 0.0475 | 2 nd of 10 | 0.0886 | 2 nd of 10 | 0.2495 | 2 nd of 10 | 0.0890 | 2 nd of 10 | 1.69 | 7 th of 10 |
| Real-ESRGAN [14] | 0.1466 | 10 th of 10 | 0.1808 | 10 th of 10 | 0.1964 | 10 th of 10 | 0.2077 | 8 th of 10 | 0.2622 | 3 rd of 10 | 0.1987 | 10 th of 10 | 0.24 | 8 th of 10 |
| FastDVDNet [12] [†] | 0.0309 | 6 th of 10 | 0.0349 | 5 th of 10 | 0.0577 | 5 th of 10 | 0.1315 | 5 th of 10 | 0.3628 | 7 th of 10 | 0.1236 | 5 th of 10 | 5.72 | 4 th of 10 |
| TOFlow [16] [†] | 0.0393 | 8 th of 10 | 0.0489 | 8 th of 10 | 0.0811 | 6 th of 10 | 0.1604 | 6 th of 10 | 0.4048 | 8 th of 10 | 0.1469 | 6 th of 10 | 2.84 | 6 th of 10 |
| BasicVSR++ [1] [†] | 0.0264 | 4 th of 10 | 0.0349 | 4 th of 10 | 0.0870 | 7 th of 10 | 0.2078 | 9 th of 10 | 0.4812 | 9 th of 10 | 0.1675 | 8 th of 10 | 7.41 | 2 nd of 10 |
| VRT [6] [†] | 0.0229 | 2 nd of 10 | 0.0347 | 2 nd of 10 | 0.1034 | 8 th of 10 | 0.2584 | 10 th of 10 | 0.5405 | 10 th of 10 | 0.1920 | 9 th of 10 | 0.05 | 10 th of 10 |
| UDVD [10] | 0.0750 | 9 th of 10 | 0.0877 | 9 th of 10 | 0.1222 | 9 th of 10 | 0.1738 | 7 th of 10 | 0.3593 | 6 th of 10 | 0.1636 | 7 th of 10 | 0.16 | 9 th of 10 |
| MF2F [4] | 0.0347 | 7 th of 10 | 0.0349 | 3 rd of 10 | <u>0.0449</u> | 1 st of 10 | 0.0952 | 4 th of 10 | 0.3522 | 5 th of 10 | 0.1124 | 4 th of 10 | 4.62 | 5 th of 10 |
| Ours | <u>0.0198</u> | 1 st of 10 | <u>0.0304</u> | 1 st of 10 | 0.0513 | 3 rd of 10 | <u>0.0861</u> | 1 st of 10 | <u>0.1940</u> | 1 st of 10 | <u>0.0763</u> | 1 st of 10 | <u>31.66</u> | 1 st of 10 |

Table 3. Video denoising results on the CRVD (sRGB) benchmark. The results demonstrate that our approach not only achieves the best overall performance but is also four times faster than the second-fastest method. For detailed PSNR metrics on the CRVD dataset, please refer to Tab. 2 of the main paper.

- Blattmann, Tim Dockhorn, Jonas Müller, Joe Penna, and Robin Rombach. SdXL: Improving latent diffusion models for high-resolution image synthesis. *ICLR*, 2024. 1
- [9] Anurag Ranjan and Michael J. Black. Optical flow estimation using a spatial pyramid network. In *CVPR*, 2017. 1
- [10] Dev Yashpal Sheth, Sreyas Mohan, Joshua L Vincent, Ramon Manzorro, Peter A Crozier, Mitesh M Khapra, Eero P Simoncelli, and Carlos Fernandez-Granda. Unsupervised deep video denoising. In *ICCV*, 2021. 3
- [11] Deqing Sun, Xiaodong Yang, Ming-Yu Liu, and Jan Kautz. Pwc-net: Cnns for optical flow using pyramid, warping, and cost volume. In *CVPR*, 2018. 1
- [12] Matias Tassano, Julie Delon, and Thomas Veit. Fastdvdnet: Towards real-time deep video denoising without flow estimation. In *CVPR*, 2020. 3
- [13] Zachary Teed and Jia Deng. Raft: Recurrent all-pairs field transforms for optical flow. In *ECCV*, 2020. 1
- [14] Xintao Wang, Liangbin Xie, Chao Dong, and Ying Shan. Real-esrgan: Training real-world blind super-resolution with pure synthetic data. In *ICCV Workshop*, 2021. 3
- [15] Zhou Wang, Alan C Bovik, Hamid R Sheikh, and Eero P Simoncelli. Image quality assessment: from error visibility to structural similarity. *IEEE TIP*, 2004. 1
- [16] Tianfan Xue, Baian Chen, Jiajun Wu, Donglai Wei, and William T Freeman. Video enhancement with task-oriented flow. *IJCV*, 2019. 3
- [17] Richard Zhang, Phillip Isola, Alexei A Efros, Eli Shechtman, and Oliver Wang. The unreasonable effectiveness of deep features as a perceptual metric. In *CVPR*, 2018. 1