

# Enhancing Vision-Language Compositional Understanding with Multimodal Synthetic Data

## Appendix

The Appendix is organized as follows:

- Section A1 presents additional details about SPARCL.
- Section A2 provides further details on the experimental setup.
- Section A3 includes additional experimental results.

### A1. Details of SPARCL

The prompts used as input to the LLM for generating negative and positive captions are presented in Figure A1.

You are an assistant assigned to help a human user edit a given sentence that describes an image. Make a minor change to the sentence by randomly altering, omitting, inserting, or replacing one word or phrase. Although the change should be minor, it must result in a significant difference in the sentence’s meaning, making it unable to describe the original image. Use the provided template and respond with a single, valid sentence.

User: {}

Assistant: Sure! Here’s my edit:

(a) Prompts used to generate negative captions.

You are an assistant assigned to help a user edit a sentence that describes an image. Make a minor change to the sentence by randomly altering, omitting, inserting, or replacing one word or phrase. The new sentence must strictly retain the same meaning as the original sentence. Use the provided template and respond with a single, valid sentence.

User: {}

Assistant: Sure! Here’s my edit:

(b) Prompts used to generate positive captions.

Figure A1. Prompts used to generate negative and positive captions.

### A2. Experimental Setup

**Data Synthesis.** For caption generation, we utilize the Llama-2-Chat 13B model<sup>1</sup>, with the temperature set to 0.9, top-k set to 100, and top-p set to 0.9 for sampling. For image generation, we use the LCM model<sup>2</sup> for its swift inference with few steps [61]. The pretrained CLIP ViT-L/14

[74] is used as the image feature extractor for injecting image features. We perform 8 inference steps with LCM to generate each image.

**Hyperparameter Selection.** First, we use only real training samples to select  $\tau$  and  $b$ . The optimal values are determined by searching for the ones that minimize the training loss at the first training step, aiming to preserve the output distribution from the pretrained model. After searching, we set  $\tau = 0.01$  and  $b = -30.0$ . Next, we select the base learning rate, weight decay, and LoRA adapter rank based on performance on the COCO-2014 validation set, in which the model is trained exclusively on real samples. According to the performance on the validation set, these hyperparameters are set to a base learning rate of 0.01, weight decay of 0.5, and LoRA adapter rank of 16. Then, we construct a validation set composed of the CIFAR-10 [47] test set and a randomly selected 5% of samples from ARO-Attribute and ARO-Relation, to balance the performance on coarse-grained and fine-grained tasks. Using this validation set, we train the model on both real and synthetic samples and use the validation performance to determine the remaining hyperparameters:  $m_0$ ,  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\lambda$ . The effects of these hyperparameters are shown in Table A5.

### A3. Experimental Results

**Performance on each subset of the four benchmarks.** Table A1, A2 and A3 present the performance of different methods on each subset of the four benchmarks.

**Comparison with other images generation methods.** We compare our image generation method with StyleAligned [27]. For a fair comparison, we use an ablated version #7 of SPARCL (Sec. 4.4, main paper) without the adaptive margin loss. Both methods use synthetic captions that we generate. As shown in Table A4, StyleAligned performs about 1% worse than our method on the four compositional benchmarks, which illustrates the effectiveness of image feature injection in SPARCL. In Figure A2, we show two synthetic images from StyleAligned, where it fails to align the generated content with the synthetic captions. We hypothesize that the diffusion trajectory of the real image imposes strong constraints on the image generation model, making StyleAligned difficult to edit the image to match the synthetic caption. This issue is similar to the zero-shot image editing methods [6, 22, 63], which provide incorrect guidance during model training and lead to limited improvements on compositional understanding tasks. More-

<sup>1</sup><https://huggingface.co/meta-llama/Llama-2-13b-chat>

<sup>2</sup>[https://huggingface.co/SimianLuo/LCM\\_Dreamshaper\\_v7](https://huggingface.co/SimianLuo/LCM_Dreamshaper_v7)

Table A1. Comparison of accuracy (%) between SPARCL and baselines on ARO and VL-CheckList. “img” represents images, “cap” represents captions, “syn” represents synthetic data.

Method	Training Data					ARO			VL-CheckList			
	Source	# real img	# real cap	# syn img	# syn cap	Relation	Attribute	Average	Attribute	Relation	Object	Average
CLIP-ZeroShot[74]	-	-	-	-	-	59.22	62.86	61.03	67.05	66.71	85.72	73.16
CLIP-Finetune[74]	COCO	82K	410K	0	0	63.02	65.16	64.09	66.74	64.43	86.86	72.78
SDS-CLIP [3]	COCO	82K	410K	0	0	53.0	62.0	57.5	-	-	-	-
[79]	COCO	0	0	82K	82K	-	-	-	70.7	53.8	85.1	69.87
AMR-NegCLIP [83]	COCO	100K	100K	0	500K	83.2	75.6	79.4	-	-	-	-
NegCLIP [106]	COCO	100K	100K	0	500K	81.0	71.0	76.0	70.9	68.9	84.1	74.6
MosaiCLIP [85]	COCO	109K	109K	0	981K	82.6	78.0	80.3	70.1	71.3	89.0	76.8
FSC-CLIP [68]	COCO	100K	100K	0	1.5M	-	-	-	-	-	-	77.20
CE-CLIP [109]	COCO	82K	410K	0	2M	83.00	76.40	79.70	72.62	71.75	84.65	76.34
COMO [49]	COCO	113K	567K	567K	567K	-	-	-	73.44	71.16	86.20	76.93
SPARCL	COCO	82K	410K	820K	820K	80.10	74.19	77.15	73.72	72.99	90.76	79.16
SPEC [70]	LAION	20K	20K	20K	20K	73.7	66.4	70.1	-	-	-	-
[18]	CC3M	3M	3M	0	9M	-	-	-	71.97	68.95	85.00	75.31
CE-CLIP+ [109]	COCO+CC3M	3M	3M	0	15M	83.6	77.1	80.35	76.76	74.70	86.30	79.25
CLOVE [11]	LAION-COCO	>1B	>1B	0	>1B	69.0	77.4	73.2	-	-	-	-
syn-CLIP [9]	SyViC	0	0	>1M	>1M	71.40	66.94	69.17	70.37	69.39	84.75	74.84
FiGCLIP [45]	VidSitu	20K videos	0	0	0	68.01	65.99	67.00	-	-	-	-

Table A2. Comparison of accuracy (%) between SPARCL and baselines on SugarCrepe. “img” represents images, “cap” represents captions, “syn” represents synthetic data.

Method	Training Data					Add		Replace			Swap		Average
	Source	# real img	# real cap	# syn img	# syn cap	Attribute	Object	Attribute	Object	Relation	Attribute	Object	
CLIP-ZeroShot[74]	-	-	-	-	-	69.22	77.40	80.33	90.98	69.49	64.71	61.63	73.39
CLIP [74] (Finetune)	COCO	82K	410K	0	0	78.03	88.12	85.79	93.58	73.83	71.77	68.29	79.92
AMR-NegCLIP [83]	COCO	100K	100K	0	500K	-	-	-	-	-	-	-	79.92
NegCLIP [106]	COCO	100K	100K	0	500K	82.80	88.80	85.91	92.68	76.46	75.38	75.20	82.46
FSC-CLIP [68]	COCO	100K	100K	0	1.5M	-	-	-	-	-	-	-	85.10
CE-CLIP [109]	COCO	82K	410K	0	2M	93.4	92.4	88.8	93.1	79.0	77.0	72.8	85.2
SPARCL	COCO	82K	410K	820K	820K	93.49	92.43	88.95	95.82	78.94	81.38	78.77	87.11
CounterCurate [108]	Flickr	30K	30K	150K	150K	86.71	90.35	87.94	95.94	76.24	73.57	68.57	82.76
CE-CLIP+ [109]	COCO+CC3M	3M	3M	0	15M	94.9	93.8	90.8	93.8	83.2	79.3	76.8	87.5
CLOVE [11]	LAION-COCO	>1B	>1B	0	>1B	-	-	-	-	-	-	-	79.92
IL-CLIP [114]	CC12M	12M	12M	0	0	-	-	-	-	-	-	-	70.34
SF-CLIP [80]	YFCC15M	15M	15M	0	0	-	-	-	-	-	-	-	71.20
FiGCLIP [45]	VidSitu	20K	videos	0	0	72.5	77.4	81.1	91.8	69.4	66.1	63.8	74.6

over, StyleAligned requires DDIM inversion to obtain the inverted diffusion trajectory from the real image, making it computationally expensive and impractical for large-scale image generation.

**Effects of image feature injection.** In Figure A3 and A4, we present examples of synthetic images to illustrate how image feature injection helps mitigate unintended changes. In Figure A3, we observe that feature injection helps to gen-

erate images with similar object size and viewing angle to the real image. For example, in (a), the real image depicts a wide shot of a girl, while the synthetic image without feature injection produces a close-up shot despite aligning with the caption. With feature injection, the synthetic image maintains a wide shot, resembling the real image. Similar effects are seen in (b) and (c). In (d), the synthetic image with feature injection preserves the viewing angle of the real image, whereas the one without feature injection devi-

Table A3. Comparison of accuracy (%) between SPARCL and baselines on SugarCrep++. “img” represents images, “cap” represents captions, “syn” represents synthetic data.

Method	Training Data					Replace			Swap		Average
	Source	# real img	# real cap	# syn img	# syn cap	Attribute	Object	Relation	Attribute	Object	
CLIP-ZeroShot[74]	-	-	-	-	-	65.61	86.80	56.26	45.21	45.18	59.81
CLIP-Finetune[74]	COCO	82K	410K	0	0	69.03	90.61	56.33	49.24	46.21	62.27
NegCLIP[106]	COCO	100K	100K	0	500K	69.41	89.53	52.27	57.99	55.25	64.89
SPARCL	COCO	82K	410K	820K	820K	68.90	89.76	52.34	57.95	61.63	66.12
[18]	CC3M	3M	3M	0	9M	56.98	80.93	47.30	48.4	42.98	55.32

Table A4. Performance comparison (%) between SPARCL and StyleAligned.

Variant	ARO	VL-CheckList	SugarCrep	SugarCrep++	Average
StyleAligned [27]	72.60	75.03	85.70	65.25	74.65
SPARCL (#7)	74.12	76.35	85.40	66.44	75.58

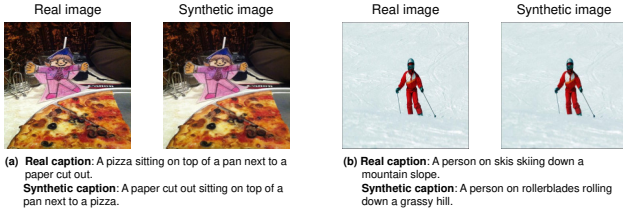


Figure A2. Examples of synthetic samples from StyleAligned. The algorithm did not alter the image content according to the caption.

ates from it. In Figure A4, we observe that feature injection helps generate backgrounds that resemble the real image. For example, in (a), the real image and the synthetic image without feature injection depicts an outdoor street scene, creating a noticeable difference. With feature injection, the single-colored background makes the synthetic image more similar to the real one. In (b), the sky occupies much of background in the real image as well as the image generated with feature injection, whereas the one without feature injection shows little sky. Also, the basketball is present in both the real and the synthetic image with feature injection but not in the middle image. Similar effects are observed in (c) and (d). These examples show that image feature injection reduces unintended variations not captured by the caption, enhancing the usefulness of synthetic samples for training VLMs.

**Effects of hyperparameters.** Table A5 presents the performance of SPARCL with different hyperparameter settings. For  $\lambda$ , we observe that  $\lambda = 0.01$  achieves the highest av-

Table A5. Performance of SPARCL with different hyperparameters. “ARO-Rel” refers to the ARO-Relation validation subset, and “ARO-Att” refers to the ARO-Attribute validation subset, both consisting of a randomly selected 5% of the full set, as described in Sec. A2.

$\lambda$	$\alpha$	$m_0$	$\beta$	$\gamma$	Validation				Test Average
					CIFAR-10	ARO-Rel	ARO-Att	Average	
0.0	0.0	-	-	-	86.56	78.79	76.52	80.62	75.58
0.001	0.0	0.01	0.0	0.0	85.02	78.21	72.72	78.65	75.95
0.01	0.0	0.01	0.0	0.0	83.66	81.77	76.46	80.63	76.78
0.1	0.0	0.01	0.0	0.0	85.02	81.29	78.94	80.47	76.94
0.01	1.0	0.01	0.0	0.0	83.18	81.10	76.52	80.27	77.21
0.01	10.0	0.01	0.0	0.0	86.46	81.89	75.05	81.13	77.27
0.01	100.0	0.01	0.0	0.0	87.64	74.93	75.19	79.25	75.28
0.01	10.0	0.005	0.0	0.0	85.91	79.87	78.76	81.51	77.08
0.01	10.0	0.01	0.0	0.0	86.46	81.89	75.05	81.13	77.27
0.01	10.0	0.02	0.0	0.0	84.85	79.41	75.28	79.85	76.79
0.01	10.0	0.005	-0.02	1.0	86.46	80.08	78.90	81.81	77.38
0.01	10.0	0.005	-0.03	1.0	86.75	81.08	76.43	81.42	77.25
0.01	10.0	0.005	-0.02	3.0	87.31	80.79	76.52	81.54	77.23

erage validation accuracy, leading us to select it for subsequent experiments. Similarly, for  $\alpha$ , the best performance is obtained with  $\alpha = 10.0$ , which is used in other experiments. When evaluating different values of  $m_0$ , we find that  $m_0 = 0.005$  yields the best results. Finally, we examine various combinations of  $\beta$  and  $\gamma$  and observe that  $\beta = -0.02$  and  $\gamma = 1.0$  provide the best validation performance. Thus, this combination is selected as the optimal hyperparameter setting.

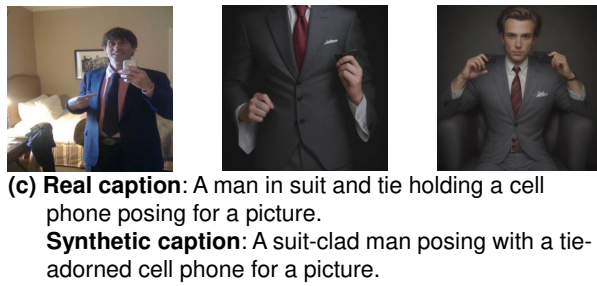
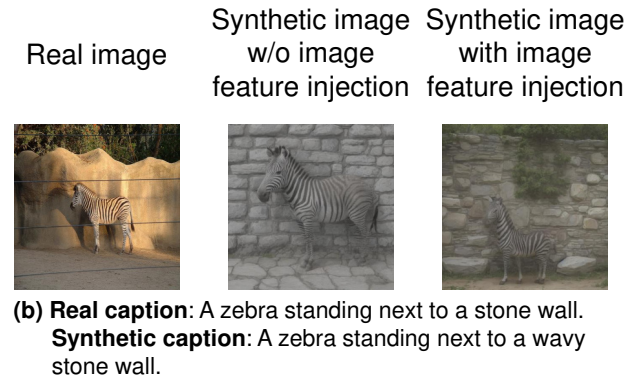


Figure A3. Examples of synthetic samples without and with image feature injection. In these examples, the image feature injection technique achieves alignment of the subject size and the viewing angle with those in real images.

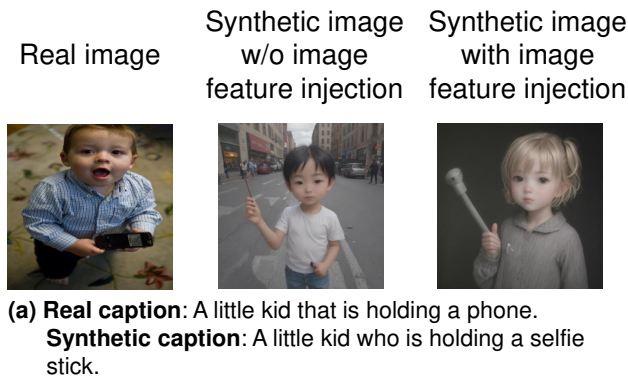


Figure A4. Examples of synthetic samples without and with image feature injection. In these examples, the image feature injection primarily helps to generate backgrounds that resemble those in real images. For example, in (d), both the first and the third images show the ground, whereas the second image does not.



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