# Boosting Domain Incremental Learning: Selecting the Optimal Parameters is All You Need Supplementary Materials

# A. Appendix

#### A.1. Training and Inference Algorithms

Algorithm 1 illustrates the training and inference details of the SOYO framework, which are discussed in Sec. 3.2.

Algorithm 1 SOYO Algorithms for Domain Incremental Learning

**Input**: Training set  $(\mathcal{X}_t, \mathcal{Y}_t)$ , test set  $(\mathcal{X}'_t)$ , backbone network f

**Output**: The predicted results y' of the test set

1: #1. Training stage

2: **for** t = 1 to T **do** 

- 3: for (x, y) in  $(\mathcal{X}_t, \mathcal{Y}_t)$  do
- 4: Train the additional parameters  $\phi_t$
- 5: Compress the domain features  $\mathbf{X}^D$  as Gaussian distribution parameters  $\theta = \{\lambda_k, \mu_k, \Sigma_k\}_{k=1}^K$  using Eq. (4) and Algorithm 2

7: **if** t > 1 **then** 

- 8: Resample the pseudo-domain features  $\tilde{\mathbf{X}}^D$  with parameters  $\theta$  using Eq. (5)
- 9: **for**  $\tilde{\mathbf{x}}^D$  in  $\tilde{\mathbf{X}}^D$  **do**
- 10: Train the MDFN parameters  $\Delta = \{\delta_1, \delta_2, \delta_3\}$ using Eq. (2)
- 11: end for
- 12: **end if**
- 13: end for
- 14: # 2. Inference stage

15: **for** t = 1 to T **do** 

- 16: **for** x' in  $\{X_t'\}_{t=1}^T$  **do**
- 17: Predict the domain label of x' as  $\hat{t}$  using MDFN
- 18: Output the results using the backbone network fand the additional parameters  $\phi_{\hat{t}}$  as y'
- 19: **end for**

20: **end for** 

### A.2. Expectation-Maximization Algorithm

Algorithm 2 presents the Expectation-Maximization (EM) algorithm used in the Gaussian mixture compressor. We abbreviate  $\{\mathbf{x}_{\tau,i}^l\}_{i=1}^{N_{\tau}}$  as  $\{x_1, x_2, \dots, x_N\}$  for brevity.

## A.3. Details of Evaluation Metrics

The average classification accuracy,  $A_T$ , represents the mean test accuracy across the first T domains after training on the T-th domain. It is calculated as:

$$A_T = \frac{1}{T} \sum_{i=1}^{T} B_{i,T},$$
(7)

where  $B \in \mathbb{R}^{T \times T}$  is an upper triangular matrix, and  $B_{i,j}$  indicates the test accuracy of the *i*-th domain after training on the *j*-th domain.

The forgetting degree,  $F_T$ , measures the performance degradation on previous domains caused by learning new domains. It is calculated as:

$$F_T = \frac{1}{T-1} \sum_{i=1}^{T-1} BWT_i,$$
(8)

$$BWT_i = \frac{1}{T-i} \sum_{j=i+1}^{T} (B_{i,j} - B_{i,i}),$$
(9)

where  $BWT_i$  represents the mean backward transfer degradation for the *i*-th domain.

The parameter selection accuracy,  $S_T$ , reflects the accuracy of predicting domain-specific parameters, which is equivalent to the domain label prediction accuracy.  $S_T$  is defined as the average parameter selection accuracy across the first T domains, computed as:

$$S_T = \frac{1}{T} \sum_{i=1}^T S'_i,$$
 (10)

where  $S_i'$  denotes the parameter selection accuracy for the i-th domain.

Algorithm 2 EM Algorithm for Gaussian Mixture Compressor

**Require:** Dataset  $\{x_1, x_2, \ldots, x_N\}$ , number of Gaussian components K, convergence threshold  $\epsilon$ **Ensure:** Estimated parameters  $\theta = \{\lambda_k, \mu_k, \Sigma_k\}_{k=1}^K$ 1: Initialize parameters  $\lambda_k^{(0)}, \ \mu_k^{(0)}, \ \Sigma_k^{(0)}$  for k = $1, 2, \dots, K$ 2: Set iteration counter  $t \leftarrow 0$ 3: repeat **E-step (Expectation step):** 4: 5: for i = 1 to N do 6: for k = 1 to K do Compute the responsibility 7:  $\gamma_{ik}^{(t)} = \frac{\lambda_k^{(t)} \cdot \mathcal{N}(x_i \mid \mu_k^{(t)}, \Sigma_k^{(t)})}{\sum_{j=1}^K \lambda_j^{(t)} \cdot \mathcal{N}(x_i \mid \mu_j^{(t)}, \Sigma_j^{(t)})}$ end for 8: end for 9: M-step (Maximization step): 10: for k = 1 to K do 11: Compute the effective number of samples  $N_k^{(t)} = \sum_{i=1}^N \gamma_{ik}^{(t)}$ 12: Update the mixing coefficient  $\lambda_k^{(t+1)} = \frac{N_k^{(t)}}{N}$ 13: Update the mean  $\mu_k^{(t+1)} = \frac{1}{N_k^{(t)}} \sum_{i=1}^N \gamma_{ik}^{(t)} x_i$ 14: Update the covariance matrix  $\Sigma_k^{(t+1)}$  $\frac{1}{N_k^{(t)}} \sum_{i=1}^N \gamma_{ik}^{(t)} (x_i - \mu_k^{(t+1)}) (x_i - \mu_k^{(t+1)})^\top$ 15: end for 16:  $\begin{array}{l} \text{Compute the log-likelihood } \ln L^{(t+1)} = \\ \sum_{i=1}^{N} \ln \left( \sum_{k=1}^{K} \lambda_k^{(t+1)} \cdot \mathcal{N}(x_i \mid \mu_k^{(t+1)}, \Sigma_k^{(t+1)}) \right) \end{array}$ 17: Compute the log-likelihood increment  $\Delta L' = |\ln L^{(t+1)} - \ln L^{(t)}|$ 18: Update the iteration counter  $t \leftarrow t + 1$ 19: 20: until  $\Delta L < \epsilon$