LOCORE: Image Re-ranking with Long-Context Sequence Modeling

Supplementary Material

A. Implementation details

All training is conducted on 8 NVIDIA A100 PCI-E 40GB GPUs. Training on Google Landmark v2 clean set [23] takes 106 hours on LOCORE-base for 5 epochs. Models are trained with AdamW optimizer [10], 5e-5 learning rate and weight decay disabled. Global batch size is set to 128 with 4 gradient accumulation steps. We present the configurations of the different LOCORE variants in Table A. LO-CORE-tiny is initialized from roberta-tiny-cased¹ by migrating weights and repeatedly copying absolute position embedding along the sequence dimension². Lo-CORE-small is initialized from the first 6 layers of longformer-base-4096³, while LoCoRE-base is initialized from the full longformer-base-4096. To accommodate 50 descriptors \times (1 query image + 100 reranking candidates) = 5,050 tokens, the position embeddings in the original models are linearly interpolated to extend their length from 4,096 to 5,120.

When experimenting with local descriptors from DI-NOv2 [12], we use the same training set as AMES [18], which is approximately half the size of the full GLDv2 clean set, *i.e.* 750k images. We adopt the same global-local ensemble scheme as AMES. The ensemble hyper-parameters are selected based on the best-performing configuration on GLDv2 public validation split and applied to $\mathcal{R}Oxf$ and $\mathcal{R}Par$ evaluations. For the training of AMES^{*}, we follow the original training process from AMES, changing only the batch size and learning late to 150 and 1e–5, respectively.

For baseline results on CUB-200 [22], Stanford Online Products (SOP) [17] and In-shop [9], we reproduce them using their official code releases and identical training configuration, except for ProxyNCA++ [20], we change the training image size from 256×256 to 224×224 to use the training image size same as the other baselines.

For the performance benchmark in Section 4.3, we use the Deepspeed [15] profiler on a single NVIDIA A100 GPU to measure key performance metrics of the model per 100 reranked gallery images as follows: the number of parameters (# of Params), floating-point operations (FLOPs), throughput in FLOPs per second, latency, and peak memory consumption. All dynamic metrics are reported with 10 warmup steps followed by 10 measurements for reporting the mean and standard deviation. Parameters of visual backbones are

Model Variants	tiny	small	base
Number of Parameters	19.4M	58.7M	111.8M
Number of Layers	4	6	12
Local Attention Window	1024	512	512
Hidden Size	512	768	768
Intermediate Size	2048	3072	3072
Number of Attention Heads	8	12	12
Max Context Length	5120	5120	5120

Table A. Architectural parameters of LOCORE variants.

excluded from # of Params.

We consider the descriptors to be already extracted and exclude I/O from measuring memory, latency, etc. For the geometric verification (GV) method, we run RANSAC in OpenCV [3] with 1,000 iterations on AMD EPYC 9354 CPU and measure the wall-clock time as the latency and the maximum resident set size (Max RSS) as the peak memory consumption. All models are benchmarked with batched input except CVNet Reranker [5]. It is worth noting that CVNet Reranker does not support batched inference since it computes pair-wise multi-scale correlation on raw feature maps (without resizing) from query and gallery images of different sizes. Thus, CVNet Reranker heavily underutilizes the GPU and achieves extremely low throughput and high latency. The FLOP, latency, and peak memory are measured assuming query and gallery images of 512×512 size in CVNet Reranker.

B. Additional Experimental Results

B.1. Additional comparisons

We present additional experiments with different combinations of global and local features in Table B. We compare with more baseline re-ranking methods, including methods with global, *i.e.* SuperGlobal (SG) Rerank [16], and local, *i.e.* AMES [18], RRT [19], R2Former [24], descriptors. We evaluate the models under different Hard settings, using different global descriptors to generate the shortlist and different backbones for feature extraction. We also test the combination of LOCORE with other re-ranking schemes.

Variations for Hard setup. As mentioned in the main paper, there can be two approaches regarding how to handle *easy* images in the hard setup: (i) **Hard**: *easy* images are used to re-rank and removed before the evaluation (typically used in the literature [16]), and (ii) **Hard***: *easy* images are completely removed from the database. While the two choices (Hard and Hard*) are equivalent for pair-wise

 $^{^{\}rm l} {\rm https:} / / {\rm huggingface.co} / {\rm haisongzhang} / {\rm roberta-tiny-cased}$

²https://github.com/allenai/longformer/blob/ master/scripts/convert_model_to_long.ipynb

³https://huggingface.co/allenai/longformerbase-4096

Clabal	Local	Re-rank	ROxf+1M			<i>R</i>Par+1M		
Global			Medium	Hard	Hard*	Medium	Hard	Hard*
	N/A	N/A^{\dagger}	78.8	6	1.9	83.9	69.1	
		N/A	78.5	61.4		83.6	68.4	
		SG-Rerank [†]	84.4	71.1	N/A	84.9	71.4	N/A
		SG-Rerank	84.0	69.4	63.9	85.2	72.3	75.7
		R2Former	79.9	63.7		83.8	69.7	
		RRT	79.3	62.7		83.6	69.1	
SG	CVNet	AMES	80.7	65.7		84.6	71.8	
		LOCORE	81.9	68.6	64.9	84.6	71.4	70.7
		SG + LOCORE	84.7	71.5	65.6	86.2	74.8	76.1
	DINOv2	R2Former*	81.0	66.2		84.9	72.1	
		RRT*	81.0	66.1		85.5	73.3	
		AMES*	81.3	67.3		85.8	74	1.3
		LOCORE	85.8	75.8	73.2	86.8	75.9	76.5
		SG + LOCORE	86.5	76.3	73.7	87.2	76.9	78.2
DINOv2	N/A	N/A	59.6	35.2		77.0	58.9	
		SG-Rerank	62.2	40.5	31.2	79.8	60.5	65.8
		R2Former*	67.8	44.6		78.6	61.3	
	DINOv2	RRT*	68.8	46.0		79.6	64.0	
		AMES*	68.9	46.8		79.9	64	1.7
		LOCORE	73.4	54.9	52.5	80.9	66.4	66.7
		SG + LOCORE	71.2	54.4	48.7	81.9	68.7	69.5

Table B. Additional results with re-ranking top-400 candidates. Hard^{*}: *easy* images are completely removed from the database. Hard: *easy* images are used to re-rank and removed before the evaluation. †: results in the SuperGlobal paper [16]. LOCORE is reported with the base variant. SG + LOCORE: re-ranking with SG first and then with LOCORE. * indicates models trained with 768 hidden size, serving as a fair comparison with LOCORE. N/A: not available.

re-ranking methods, this is not the case when interactions between database images are considered (*i.e.* LOCORE, SG-rerank). In Table B, it is evident that the two setup lead to significantly different results. In most cases, mAP considerably drops in $\mathcal{R}Oxf$, comparing results in Hard and Hard*; whereas, mAP increases in $\mathcal{R}Par$.

Performance with other backbones. First, we benchmark all models when the shortlist is generated based on DINOv2 global descriptors. It is noteworthy that DINOv2 global descriptors are significantly worse than SG ones. In this setup, LOCORE outperforms all other re-ranking schemes by a vast margin.

Second, we evaluate LOCORE using local descriptors extracted from CVNet backbones. CVNet local descriptors have a higher dimension than that of DINOv2, *i.e.* 1024 vs 768; hence, we used a learnable linear projector to match the embedding dimensionality of the transformer. LOCORE achieves competitive performances compared with the pairwise re-rankers, with only AMES outperforming it in a few cases. Yet, all local-based re-rankers are outperformed by SG-Rerank. Nevertheless, LOCORE with DINOv2 outper-

forms SG-Rerank.

Combination with SG-Rerank. It is straightforward to combine local and global-based re-ranking. To this end, we combine LOCORE with SG-Rerank by applying global re-ranking first, followed by local re-ranking. This combination achieves the best performance when SG is used as global descriptor. However, this combination hurts LOCORE performance on ROxf when DINOv2 is used as global.

Performance per query. To highlight the advantages of our proposed list-wise re-ranking over pair-wise re-ranking, we present several scatter plots in Figure A, showing the average precision of each sample in $\mathcal{R}Oxf+1M$ Hard before and after re-ranking with different re-ranking paradigms. We compare our model with AMES [18], which is considered the state-of-the-art solution for pair-wise re-ranking. In the first two plots, we observe that most data points are concentrated in the upper-left half and above the red reference line, indicating that both re-ranking paradigms improve the ranking accuracy for the majority of query images. However, the list-wise re-ranking method driven by LOCORE has barely any sample points below the red reference line, meaning



Figure A. Average precision per query scatter plot on *ROxf*+1M Hard for global-only vs. AMES (*Left*), global-only vs. LOCORE-small (*Middle*) and AMES vs. LOCORE-small (*Right*). Global descriptors are from RN101-Superglobal, which by itself achieves mAP=61.4%. Re-ranking is performed for top-100 candidates, and the color bar indicates the number of positive images in the shortlist for each query.

Clabal	Local	L	V	ROxf+1M		<i>R</i>Par+1M	
Global			л	Medium	Hard*	Medium	Hard*
		50	100	85.8	73.2	86.8	76.5
SG	DINOv2	100	50	83.9	68.6	85.2	72.5
		25	200	84.5	72.1	85.6	75.1

Table C. Additional results for LOCORE-base with different combinations of the number of local descriptors L and the number of re-ranking candidates K on N = 400 candidates.

the re-ranking only improves the retrieval on the individual query level. The distinction between the two models is most prominent in the final plot, where the number of sample points above the winner reference line far exceeds those below, demonstrating that LoCORE outperforms AMES on more query samples. We also observed that the list-wise reranking method is relatively robust in terms of the number of positive samples included in the shortlist, as the color distribution of the sample points does not exhibit any discernible pattern. This indicates the general versatility of LoCORE.

B.2. Additional ablations

Number of images vs number of descriptors. We explore the relationship between the number of local descriptors and the number of image candidates within a given context window in Table C. Specifically, we set the context window to 5,120 and examine three configurations of LOCORE: (i) using 100 gallery images with 50 local descriptors per image, *i.e.* the default setup, (ii) using 200 gallery images with 25 local descriptors per image, *i.e.* more candidate images but fewer descriptors per image, and (iii) using 50 database images with 100 local descriptors per image, *i.e.* more descriptors per image but fewer candidate images. The LOCORE in the default settings reports the best results.

Comparison with other recurrent models. Other model architectures with no restrictions on context length that could

Ablation Module	$\mathcal{R}@1$	$\mathcal{R}@10$	mAP@R
Global descriptors	80.8	92.1	65.1
LoCoRE-tiny	82.4	93.1	68.0
LoCoRE-small	83.3	92.7	69.4
LoCoRE-base	83.8	92.9	71.0
LoCoRE-RWKV	81.4	92.3	66.7
LoCoRE-Mamba	80.6	92.1	66.4

Table D. Ablation studies for LOCORE recurrent models on the SOP dataset. Re-ranking is performed with the top 100 candidates.

be employed instead of LongFormer are the recently proposed recurrent models Mamba [2] and RWKV [13]. As the causal nature of the recurrence-based model does not align well with our re-ranking motivation and is strictly less expressive than bi-directional encoders [4, 14], we follow the common practice in recurrent visual encoder community [1, 6, 8] to build a bi-directional variant that serves as an efficient sequence encoder. To ensure recurrent models can still handle long-range interactions and alleviate the inherent information bottleneck in the design of recurrent models, we devise a mechanism that resembles the query global attention in Section 3.2 by interleaving recurrent blocks with uni-directional transformer blocks [21]. These transformer blocks compute attention scores between intermediate hidden states of query image tokens and intermediate hidden states of gallery image tokens and produce fused intermediate representations for the following layers to process. The uni-directional attention guarantees that every gallery image has similar difficulty accessing the query image, irrespective of its position in the sequence relative to the query. Although we find that these recurrence-based models could slightly outperform the base global retrieval model, they do not surpass our transformer-based results, as shown in Table D.



Figure B. **Qualitative analysis** on *R*Oxford dataset of LOCORE-base on RN50-DELG descriptors. **Upper:** two hard positive gallery images get assigned with higher ranks while a negative gallery image is put in lower ranks after re-ranking. **Lower:** the first gallery image can be easily identified as positive due to its dense matching with the query image; it can also serve as a perfect anchor image for refining the ranking of the second gallery image due to their transitive relationship.

B.3. Qualitative Results

We illustrate the re-ranking performance of LOCORE in Figure B as qualitative results. The upper example underscores the superior performance of our method, demonstrated by its success in elevating the ranking of two hard positive images and lowering that of the negative gallery image. We also show in the lower example that our model is able to capture the transitive relationship between query and gallery images. The transitive relationship is based on the assumption that generally, if two gallery images are similar and one of them is predicted as positive, then the other should be calibrated with higher confidence. In the lower example, the correspondence between the query image and the first gallery image is easy to catch as the common geometric features are evident, resulting in Easy matching in the figure. However, although the global retriever returns the second gallery image as reranking candidates, the sparse local features focused on the top of the tower make it hard for pair-wise re-ranker to assign this gallery image a high confidence score. This misalignment is calibrated by our list-wise re-ranking paradigm since the windows in both gallery images can serve as the anchor to propagate the positive prediction from the easy candidate to the hard one.

Additionally, in Figure C the easy positive gallery has visual overlap with the query (rooftop). The hard positive gallery has little visual overlap with the query, but larger overlap with the first positive (*e.g.* windows). We wish to answer this question: *Are the local features of the window improving the rank of the hard positive due to a transitive relationship?* We remove local features of the windows (blue crosses), repeat the similarity estimation, and compare the ranks. The decreased similarity score is a sign of LOCORE capturing transitive relationships.



ery Image Easy Positive Gallery Image Hard Positive Gallery Image

Figure C. Visualization of LOCORE capturing transitive relationships in gallery images. We prevent LOCORE from accessing local features of the easy positive corresponding to the windows (blue crosses) and instead randomly sample local features from other negative images. The dropped similarity score indicates LOCORE relies on the transitivity of local features to calibrate predictions for hard positive gallery images.

C. Limitations and Future Work

Despite the merits in efficiency and re-ranking performance, our model is inherently restricted by the context window of existing encoder-only sequence models. A limited context window limits the number of re-ranking candidates in the gallery and the number of local descriptors that LOCORE can use. While recurrent models offer more flexibility with the context window size, we find that they could not capture listwise re-ranking dependencies as well as transformer-based models, resulting in sub-optimal performance. Future work could adopt large-scale decoder-only sequence models which typically have longer context windows and greater capacity for list-wise re-ranking. Additionally, context parallelization techniques (e.g., RingAttention [7], Infini-attention [11]) could help expand the context window of current Transformer encoder models. Lastly, extractive re-ranking as proposed in our work could also be seamlessly adopted for other modalities, e.g. document or video re-ranking.

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