PVC: Progressive Visual Token Compression for Unified Image and Video Processing in Large Vision-Language Models

Supplementary Material

A. Implementation Details

Our implementation is based on InternVL2 [83]. The visual encoder is a ViT-L/14 [20] whose weights are initialized from InternViT-300M-448px-V1.5 [15]. The progressive encoding is introduced in the last 8 layers of the 24-layer ViT (*i.e.*, $\tilde{L}=8$ and L=24), and the weights of temporal attention (T-MHA) are randomly initialized. The input resolution for the visual encoder is set to 448×448 , with dynamic resolution [15] enabled for image data in both stages. The number of image tiles ranges up to 12, based on the image's aspect ratio and resolution. InternLM2-Chat-1.8B [7] is employed as the LLM for PVC_{InternVL2}-2B, while InternLM2.5-Chat-7B [7] is utilized for PVC_{InternVL2}-8B.

Training settings of the pre-training and instruction tuning stages are listed in Tab. 6.

Table 6. Training settings of PVC.

Training stage	Pre-training	Instruction tuning		
Max sequence length	8192	;		
Max tile/image	12			
Token/frame (tile)	64			
Number of image repeats	4			
Number of video frames	16-96, uniform			
Optimizer	AdamW			
Learning rate	2e-4	4e-5		
Weight decay	0.01 (2B), 0.05 (8B)			
Optimizer momentum	$\beta_1, \beta_2 = 0.9, 0.999$			
Learning rate schedule	constant with warmup	cosine decay		
Warmup steps	100	240		
Training steps	25k	8k		
Batch size	2048	1024		

B. Dataset Details

The data used in the pre-training stage are listed in Tab 7. All image-text data is adopted from InternVL2 [83]. For video datasets, we initially utilize large-scale but mixed-quality datasets including InternVid-10M [90], WebVid-10M [3], TextVR [93] and OpenVid-1M [70] that primarily feature short video captions. To enhance the model's understanding of visual details, we further incorporate densely captioned video-text datasets of varied video lengths including MiraData [35], ShareGPT4Video [14] and the Vript series [94]. To improve capabilities in multi-turn conversation and visual reasoning, we employ VideoGPT+ [62], STAR [91], EgoTaskQA [33], CLEVRER [95] and Me-

Table 7. **Summary of datasets used in the pre-training stage.** *IT refers to the instruction tuning data in VideoChat2.

task	dataset		
Short Caption	Laion (en&zh) [74], COYO [6], COCO [51]		
OCR	Wukong-OCR [23], LaionCOCO-OCR [75]		
Detection	GRIT [72], Objects365 [79]		
Conversation	All-Seeing (en&zh) [87]		
Image-text instruction data (see Tab. 8a)			

(a) Image-text datasets used in the pre-training stage.

task	dataset
Short Caption	InternVid-10M [90], WebVid [3], OpenVid [70], TextVR [93]
Detailed Caption	MiraData [35], ShareGPT4Video [14], Vript [94], Vript_Chinese [94], LSMDC [73]
VQA	STAR [91], VideoGPT+ [62], EgoTaskQA [33] CLEVRER [95], Mementos [89]
Classification	NTU RGB+D [78]
Comprehensive	VideoChat2-IT* [49], FineVideo [21]

(b) Video-text datasets used in the pre-training stage.

mentos [89]. Additionally, NTU RGB+D [78] is used to boost robustness to action recognition. Lastly, to enhance the model's holistic abilities, we utilize comprehensive datasets VideoChat2-IT [49] and FineVideo [21], which aggregate elements of multiple-choice answering, open-ended question-answering, and conversations.

Datasets used for instruction tuning are listed in Tab 8. The image-text data is also adopted from InternVL2 [83]. For video-text data, low-quality datasets used in the pretraining stage are replaced by compositional high-quality datasets like LSMDC[73], TVQA [45], HiREST [99] and LLaVA-Video [103].

In Tab. 9, we list the training data scale of our PVC and some existing image-video general VLMs. Compared to the previous state-of-the-art model, Qwen2-VL, we use significantly less data while achieving similar or better performance on most benchmarks. Compared to other VLMs, our PVC requires more pre-training data since the temporal attention layers in ViT introduce new parameters that are randomly initialized.

C. Appended Ablation Studies

C.1. Number of Tokens per Frame

We adjust token-per-frame while keeping the total number of visual tokens fixed. Reducing tokens per frame increases image repetitions and video input frames. Compared to 256 tokens, 64 tokens perform similarly on image tasks but significantly better on long video tasks (*e.g.*,

Table 8. Summary of datasets used in the instruction tuning stage. *IT refers to the instruction tuning data in VideoChat2.

task	dataset
General QA	VQAv2 [22], GQA [32], OKVQA [64], VSR [54]
Science	AI2D [40], ScienceQA [60], Chemistry Data [48]
Science	TQA [41]
	PMC-VQA [101], VQA-RAD [44], VQA-Med [4]
Medical	Medical-Diff-VQA [29], PathVQA [26],
	SLAKE [52], PMC-CaseReport [92]
	ChartQA [66], LRV-Instruction [55], PlotQA [69]
Chart	Unichart [67], MMC-Inst [56], DVQA [36]
Chart	TableMWP [61], FigureQA [37], MapQA [10]
	SciTSR [16], Fintabnet [104]
	CLEVR [34], MetaMath [96], GeoQA+ [8]
Mathematics	Geometry3k [59], GeoS [76], Unigeo [12]
	Super-CLEVR [50], MathQA [1]
Knowledge	Art500k [63], MovieNet [30], KonIQ-10k [27]
	KVQA [77], ViQuAE [46]
	InfoVQA [68], TextVQA [80], ArT [17]
	CASIA [53], Chart-to-text [38], COCO-text [84]
	CTW [97], EATEN [24], ICDAR2019-LSVT [82]
OCR	ICPR MTWI [25], NAF [19], ReCTS [100]
	TextOCR [81], LLaVAR [102], HME-100k [98]
	POIE [42], SROIE [31], ST-VQA [5]
	EST-VQA [88], IAM [65]
Document	DocVQA [18], DocReason25k [28]
Grounding	RefCOCO [39], RefCOCO+ [39], RefCOCOg [39]
Grounding	RD-BoxCoT [13]
Conversation	ALLaVA [11], LAION-GPT4V [43]
Conversation	MMDU [58], TextOCR-GPT4V [9]
Detection	Objects365 [79], V3Det [85]
(a) Image-tex	t datasets used in the instruction tuning stage.
task	dataset
Detailed Caption	ShareGPT4Video (en&zh) [14], Vript_Chinese [94]
Detailed Caption	Vript [94], LSMDC [73]
VQA	STAR [91], EgoTaskQA [33], Mementos [89]
1 411	TVQA [45], HiREST [99], PerceptionTest [71]
Classification	NTU RGB+D [78]
Comprehensive	VideoChat2-IT* [49], LLaVA-Video [103]
(b) Video-tex	t datasets used in the instruction tuning stage.

Table 9. Training data scale of our PVC and existing VLMs.

Model	# Pre-training samples	# SFT samples
Oryx-MLLM	4.5M	1.3M
LLaVA-OneVision	4.5M	4.8M
InternVL2	45M	7.3M
Qwen2-VL	1.4T tokens	unknown
PVC (ours)	50M (102B tokens)	8.2M (33B tokens)

VideoMME), with a 16% speed decrease. Compressing to 16 tokens performs worse and requires much more computation with more input frames. Therefore, to balance performance and efficiency, we choose 64 tokens per frame as the final setting.

C.2. Number of Temporal Attention Layers

As described in Sec.3.2, we add temporal attention to the last \tilde{L} layers of the ViT. As shown in Tab. 11, $\tilde{L}=8$ performs better than $\tilde{L}=1$ or $\tilde{L}=4$. Setting $\tilde{L}=24$ (adding

Table 10. **Ablation of the number of tokens per frame.** The ablation is conducted on 2B model with shortened pre-training on 10M samples. FPS is tested with the same setting as Tab. 5.

# token	# image	# video	Info	ммр	MVBench	Video	FPS
/frame	repeat.	frame.	VQA	MMB	IVI V DEIICII	MME	1.1.3
256	1	16	58.7	74.8	62.1	45.0	12.7
64	4	64	58.5	74.9	62.4	46.7	10.6
16	16	256	53.3	74.9	61.8	46.4	7.2

Table 11. **Ablation of the number of temporal attention layers in ViT.** The ablation study is conducted on 2B model with shortened pre-training on 10M samples.

# temp. attn. layer (\tilde{L})	MVBench	VideoMME	InfoVQA	MMB
1	61.6	46.3	55.8	74.2
4	62.1	46.6	57.3	74.7
8	62.4	46.7	58.5	74.9
24	62.5	46.7	58.8	74.8

temporal attention to each layer) does not provide significant improvements over $\tilde{L}=8$ but increases computational overhead. Therefore, we choose $\tilde{L}=8$, *i.e.*, adding temporal attention to the last 8 layers of the ViT.

C.3. Training Strategy

During the pre-training phase, we unfreeze the parameters of the ViT and LLM, which differs from existing methods [2, 15, 47, 57, 83, 86]. The ablation results in the Tab. 12 empirically explain why we adopt this training strategy. For InternVL2, keeping ViT and LLM fixed or trainable during pre-training has minimal impact on the final performance. However, for our PVC, unfreezing the ViT and LLM during pre-training leads to significantly better performances. We suppose this improvement is due to the following reasons: (1) Training the ViT jointly with the newly added progressive encoding module enables better capture of complementary information and minimizes redundancy. (2) The LLM's inherent capability to process multi-frame videos is limited, especially for integrating different information extracted from the repeated frames of an image. Thus, additional training is needed for effective adaptation.

D. Qualitative Results

Image Progressive Encoding. As shown in Fig. 4, when an image is repeated as multiple frames, our PVC can extract more precise details and supplementary information from the subsequent frames. For instance, the model extracts the title "Goal 15 life on land" from the first frame and corresponding detailed goals from subsequent frames. Incorrect contents, *e.g.* "10% of the total land area", are also corrected using the information extracted from subsequent frames.

Table 12. **Ablation of the training strategy**. The ablation study is conducted on 2B model with shortened pre-training on 10M samples. "Unfreeze ViT & LLM" means unfreezing the parameters of the ViT and LLM during the pre-training stage with a lower learning rate $(\times 0.1)$. * InternVL2 model is trained under our ablation setting.

Model	Unfreeze ViT & LLM	MVBench	VideoMME	MLVU	DocVQA	InfoVQA	MMB
InternVL2*		60.9	44.7	50.0	86.1	58.7	74.2
InternVL2*	\checkmark	61.9	44.9	50.5	86.4	59.1	75.1
$PVC_{InternVL2} \\$		60.6	45.5	53.2	84.8	57.3	74.4
$PVC_{InternVL2} \\$	\checkmark	62.4	46.7	55.1	86.7	58.5	74.9

Video Dynamic Capture. As shown in Fig. 5, the video contains several consecutive collisions, testing the model's ability to capture spatiotemporal dynamics. InternVL2 [83] describes each collision moment independently but lacks a description of the whole process and includes inaccuracies. LLaVA-OneVision [47] and Qwen2-VL [86] exhibit numerous errors when capturing object interactions. In contrast, our PVC not only accurately describes the process of each collision and the associated object movements but also identifies the causal relationships between multiple collisions.

Image Progressive Encoding



User: What is the content in this picture?

PVC (image repeat \times 1):

The image is an infographic related to Sustainable Development Goal 15, which focuses on Life on Land. It highlights the importance of forests in Indonesia and the challenges they face. Here is a detailed breakdown of the content:

Title and Header

- SDGs FACTSHEET
- INDONESIA

· LIFE ON LAND

Key Points

1. Forest Area

- There are 91 million hectares of forests in Indonesia, covering just over 10%of the total land area.

2. Archipelagic and State Forests

Indonesia is home to the third largest tropical forests, which are essential for the livelihood of 48.8 million Indonesians. These forests cover 14.9 million , or nearly 8% of Indonesia's total land area.

Tropical forests are home to important biodiversity, providing a highly effective natural terrestrial carbon storage system.

4. Mangrove Forests

Mangrove forests provide multiple ecosystem services, including fishery resources, coastal protection, and biodiversity support.

5. Land Use and Emissions

In 2005, 63% of emissions were the result of land use change and peatland degradation. Mangrove forests are also threatened.

6. Deforestation and Loss

The average annual net loss of forest is 685,000 hectares. Forests are lost through deforestation, biodiversity loss, and affecting the livelihoods of forest-dependent communities.

7. Future Goals

By 2030, Indonesia aims to restore 2 million hectares of degraded peatland ecosystems

Visual Elements

- · Icons: The infographic uses icons of trees, forests, and other related imagery to visually represent the information.
- Colors: Predominantly green, symbolizing nature and forests, with white and brown accents for text and details.

Conclusion

The infographic emphasizes the critical role of forests in Indonesia, the threats they face, and the country's efforts to address these issues through sustainable practices and restoration goals.

PVC (image repeat \times 4):

The image is an infographic related to Goal 15 of the Sustainable Development Goals (SDGs), which focuses on Life on Land. The infographic provides information about Indonesia's forests and peatlands, emphasizing the importance of forest conservation and restoration. Here is a detailed breakdown of the content:

Title and Goal

- SDGs FACTSHEET
- INDONESIA
- Goal 15: Life on Land
 - · Protect, restore, and promote the sustainable use of terrestrial ecosystems, sustainably manage forests, combat desertification, halt and reverse land degradation, and halt biodiversity loss

Key Points

1. Forest Area

- There are 91 million hectares of forests in Indonesia, covering just over half of the country's total land area.
- 2. Archipelagic and State by Area
- Indonesia is the largest archipelagic and 15th biggest state by area in the world. It has a significant impact on the world's climate conditions

3. Dependence on Forests

Indonesia is home to the third largest tropical forests. 48.8 million people in Indonesia directly depend on forest (or forest ecosystem services) for their livelihood.

· Peatlands cover an estimated 14.9 million hectares, or nearly 8%, of Indonesia's total land area. Tropical peatlands are home to important biodiversity and a highly effective natural terrestrial carbon storage system.

5. Mangrove Forests

Indonesia is home to more than 20% (2.2 million hectares) of the world's mangrove forests. Mangrove forest ecosystems nurture fishery and forest resources, mitigate coastal disasters, and climate change, provide multiple ecosystem services, and eco-tourism opportunities, and accommodate biodiversity.

6. Emissions and Degradation

- . In 2005, 63% of emissions were the result of land use change and peat fires
- The average annual net loss of forest between 2010 and 2015 was 685,000 hectares. Forests are lost through deforestation, endangering globally important biodiversity and affecting the livelihoods of forest-dependent communities.

7. Future Goals

By 2030, Indonesia aims to restore 2 million hectares of degraded peatland ecosystems

Visual Elements

- · The infographic includes icons of trees, forests, and peatlands
- It uses a green color scheme to emphasize the environmental focus.
- The United Nations Sustainable Development Goals logo is present at the bottom left.

The infographic highlights the critical role of forests and peatlands in Indonesia, emphasizing the need for sustainable forest management and restoration to combat deforestation, land degradation, and biodiversity loss. It underscores the interdependence of local communities on forest ecosystems and the global impact of Indonesia's forests on climate conditions.

Figure 4. PVC achieves image progressive encoding. The image is repeated once (left) and four times (right). Supplementary contents are marked in blue, incorrect contents in red, and corrected contents in green.

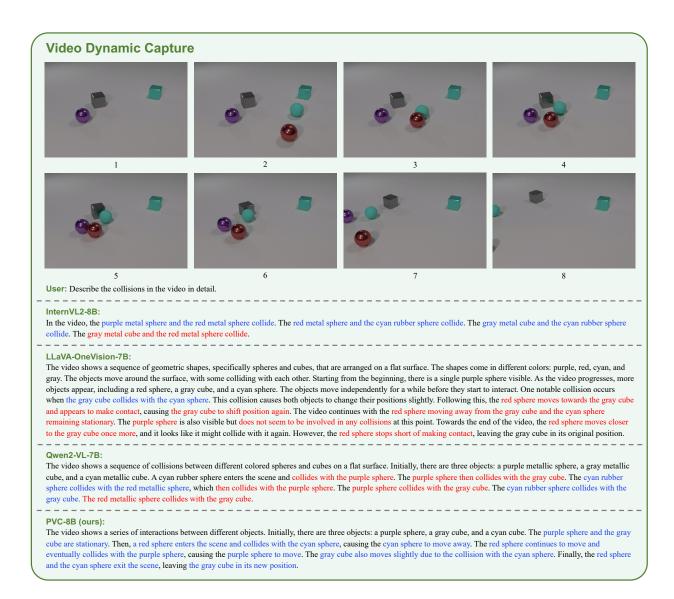


Figure 5. **PVC effectively captures spatiotemporal dynamics in videos.** Correct descriptions of the movements and interactions of the objects are marked in blue, while incorrect descriptions are marked in red. For visualization, we select the above 8 key frames from the video, while the entire video is fed into the models.

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