

DRAW: Defending Camera-shooted RAW against Image Manipulation

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Abstract

RAW files are the initial measurement of scene radiance widely used in most cameras, and the ubiquitously-used RGB images are converted from RAW data through Image Signal Processing (ISP) pipelines. Nowadays, digital images are risky of being nefariously manipulated. Inspired by the fact that innate immunity is the first line of body defense, we propose DRAW, a novel scheme of defending images against manipulation by protecting their sources, i.e., camera-shooted RAWs. Specifically, we design a lightweight Multi-frequency Partial Fusion Network (MPF-Net) friendly to devices with limited computing resources by frequency learning and partial feature fusion. It introduces invisible watermarks as protective signal into the RAW data. The protection capability can not only be transferred into the rendered RGB images regardless of the applied ISP pipeline, but also is resilient to post-processing operations such as blurring or compression. Once the image is manipulated, we can accurately identify the forged areas with a localization network. Extensive experiments on several famous RAW datasets, e.g., RAISE, FiveK and SIDD, indicate the effectiveness of our method. We hope that this technique can be used in future cameras as an option for image protection, which could effectively restrict image manipulation at the source.

1. Introduction

In the digital world, the credibility of the famous saying "seeing is believing" is largely at risk since nowadays people can easily manipulate critical content within an image and redistribute the fabricated version via the Internet. Owing to the fact that readers are more susceptible to well-crafted misleading material, fabricated images can be a means for some politicians to sway public opinion. In more severe cases, those fraudulent images can be used to bolster fake news or criminal investigation.

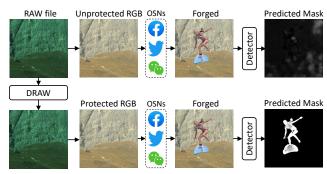


Figure 1. DRAW improves the performance of image manipulation localization against lossy image operations via imperceptible protective signal injection into RAW files.

Image manipulation detection [9, 32] and localization [10, 38] has become a critical area of research for decades, with the goal of distinguishing manipulated images from authentic ones and locating the manipulated areas. While early methods mainly check the integrity of the images from statistical aspects, e.g., the Photo-Response Non-Uniformity (PRNU) noise [9] and the fixed pattern noise (FPN) [23], the uprising of deep networks has greatly strengthened the capability to find traces left by a variety of manipulation [10, 40, 19]. However, the adversary is also continuously evolving both in strength and diversity. For example, recent deep-network-based image editing algorithms [36, 13] are reported to produce highly realistic images with almost no visible artifacts near the edges. Therefore, it remains a big issue whether the learned subtle forensics traces can always be present in the newly forged images. Also, though some works [38, 39] explicitly handle lossy online transmission scenarios, they still face limited performance against well-crafted forgeries, e.g., inpainting, or lossy image operations, e.g., Gaussian blurring.

Inspired by the fact that innate immunity is the first line of body defense and the best weapon to mitigate diseases, safeguarding images against manipulations is an alternative and promising way of deterring malicious attackers. Indeed, the ubiquitous 8-bit RGB images are not the pristine format for reflecting how we perceive the world. They are converted from RAW files via ISP pipelines. Therefore, we

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propose DRAW, a proactive image protection scheme that defends camera-shooted RAW data against malicious manipulation on the RGB domain. Specifically, we propose to introduce imperceptible protective signal into the RAW data, which can be transferred into the rendered RGB images, even though various types of ISP pipelines are applied. Once these images are manipulated, the localization networks can exactly localize the forged areas regardless of image post-processing operations such as blurring, compression or color jittering. Besides, a novel Multi-frequency Partial Fusion Network (MPF-Net) is proposed to implement RAW protection, which adopts frequency learning and cross-frequency partial feature fusion to significantly decrease the computational complexity. We illustrate the functionality of DRAW in Fig. 1, which promotes accurate manipulation localization without affecting the visual quality.

Extensive experiments on several famous RAW datasets, e.g., RAISE, FiveK and SIDD, prove the imperceptibility, robustness and generalizability of our method. Besides, to compare RAW-domain protection with previous works, we tempt to borrow the success of RGB-domain protection [4, 48] as the baseline method for proactive manipulation localization. The results show that DRAW hosts a noticeable performance gain and a nontrivial benefit of content-related adaptive embedding. In addition, MPF-Net provides superior performance compared to classical U-Net [33] architecture with only 20.9% of its memory cost and 0.95% of its parameters. The novel lightweight architecture makes it possible to be integrated into cameras in the future, thereby changing the current situation where digital images can be freely manipulated.

The contributions of this paper are three-folded, namely:

- DRAW is the first to propose RAW protection against image manipulation. The corresponding RGB images will carry imperceptible protective signal even though various types of imaging pipelines or lossy image operations are applied.
- With RAW protection, image manipulation localization networks can better resist lossy image operations such as JPEG compression, blurring and rescaling.
- A novel lightweight MPF-Net is proposed for integrating RAW protection into cameras in the future, thereby potentially changing the current situation where digital images can be freely manipulated.

2. Related Works

Passive Image Manipulation Localization. Many existing image forensics schemes are designed to detect special kinds of attacks, e.g., splicing detection [38, 34], copymoving detection [20, 26] and inpainting detection [51, 25]. In addition, some universal tampering detection

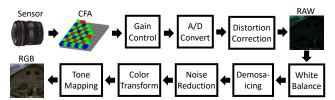


Figure 2. Typical camera imaging pipeline for RAW data acquisition and subsequent RGB image signal processing.

schemes [10, 40, 19] exploit universal noise artifacts left by manipulation. Mantra-Net [40] uses fully convolutional networks, Z-Pooling and long short-term memory cells for pixel-wise anomaly detection. MVSS-Net [10] jointly exploits the noise view and the boundary artifact using multi-view feature learning and multi-scale supervision. SPAN [19] models the relationship between image patches at multiple scales by constructing a pyramid of local self-attention blocks. RGB-N [49] additionally utilizes auto-generated data augmentation for training. RIML [38] includes adversarial training, where the lossy Online Social Network (OSN) transmission is simulated by modeling noise from different sources. However, these passive schemes are still limited in generalization to well-crafted manipulations or heavy lossy operations.

Watermarking for Image Protection. Many image protection schemes based on watermarking [29, 21, 14, 43] have been proposed. Asnani et al. [4] propose to embed templates into images for more accurate manipulation detection. Zhao et al. [48] embed watermarks as anti-Deepfake labels into the facial identity features. FakeTagger [37] embeds the identity information into the whole facial image, which can be recovered after illegal face swapping. Khachaturov et al. [22] and Yin et al [42] respectively propose to attack inpainting or Super-Resolution (SR) models by forcing them to work abnormally on the targeted images. However, these approaches do not tackle the issue of forgery localization, and many of them cannot combat lossy image operations. We alternatively introduce imperceptible protective signal into RAW data and transfer it into RGB images to aid robust manipulation localization.

Models for Limited Computing Resources. Classical network architectures for segmentation-based tasks, e.g., U-Net [33] or FPN [27], usually require non-affordable computing resources for many small devices. MobileNet [17] and ShuffleNet [30] are early works on addressing this issue respectively via Depth-wise Separable Convolution (DSConv) and channel split & shuffle. ENet [31] proposes an asymmetric encoder-decoder architecture with early downsampling. Despite the substantial efforts, these networks are either still computationally demanding or sacrifice performance for model size shrinkage. We propose MPF-Net that contains 20.9% of memory cost and 0.95% of parameters of U-Net yet provides surpassing performance.

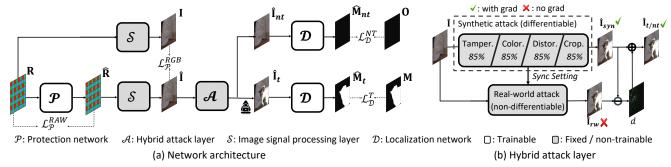


Figure 3. **Pipeline design of DRAW.** We design a lightweight protection network that embeds imperceptible protective signal in the RAW domain and transfers it into the rendered RGB images. On the recipient's side, the localization network identifies the forged areas.

3. Proposed Method

3.1. Approach

Fig. 3 depicts the pipeline design of DRAW. We denote the captured RAW data as R, and use a protection network \mathcal{P} to transform **R** into the protected RAW, i.e., $\hat{\mathbf{R}}$. The functionality of ${\mathcal P}$ is to adaptively embed a transferrable protective signal into R for robust and accurate image manipulation localization in the RGB domain. Considering the computational limitation of imaging equipment, we use a novel lightweight MPF-Net specified in Section 3.2 to implement \mathcal{P} . Next, we use the ISP layer \mathcal{S} to render $\hat{\mathbf{R}}$ into the protected RGB image I. Provided with a number of off-the-shelf deep-network-based ISP algorithms and nondifferentiable conventional ISP algorithms, during training, we include a popular conventional method, i.e., LibRaw [1] and two deep-learning methods, i.e., CycleISP [46] and InvISP [41], and leave other ISP algorithms [45, 2] for evaluation. To improve generalizability, interpolation is conducted on one network-rendered RGB $\hat{\mathbf{I}}_{net}$ and one conventionalalgorithm-generated RGB $\hat{\mathbf{I}}_{conv}$ to produce $\hat{\mathbf{I}}$, i.e., $\hat{\mathbf{I}} = \omega$. $\hat{\mathbf{I}}_{conv} + (1 - \omega) \cdot \hat{\mathbf{I}}_{net}$, where ω is uniformly within [0, 1].

Afterward, to simulate image redistribution of $\hat{\mathbf{I}}$, we include the hybrid attack layer A to perform manipulation and lossy operations on I. It comprises of modules for tampering, color adjustments, distortions (lossy operations) and cropping. To construct the binary tampering mask M, we apply the free-form mask generation [44] to arbitrarily select areas within I. In line with typical forgery detection works [10, 38], we consider inpainting, splicing and copy-moving as the most common three types of tampering, which often alter the underlying meaning of an image. In contrast, color adjustment and distortions are often considered benign yet can potentially erase traces for manipulation localization. During training, these modules can be conditionally performed according to the empirical activation possibilities (85%) and in any arbitrary ordering to encourage diversity, e.g., tampering then distorting, cropping then tampering, etc. We respectively denote the attacked images as $\hat{\mathbf{I}}_t$ if the tampering module is activated or $\hat{\mathbf{I}}_{nt}$ if otherwise. The latter is identified as authentic images, whose introduction is to explicitly minimize the false alarm rate of DRAW. Detailed implementations of these modules are specified in the supplement. Besides, to closer the gap between real and simulated lossy operations and color jittering operations, we add the difference between $\hat{\mathbf{I}}_{syn}$ and $\hat{\mathbf{I}}_{rw}$ on to $\hat{\mathbf{I}}_{syn}$, where $\hat{\mathbf{I}}_{syn}$ and $\hat{\mathbf{I}}_{rw}$ respectively denote synthetic and real-world processed image using the same setting. $x = \hat{\mathbf{I}}_{syn} + sg(\hat{\mathbf{I}}_{rw} - \hat{\mathbf{I}}_{syn}), x \in \{\hat{\mathbf{I}}_t, \hat{\mathbf{I}}_{nt}\}$, where sg stands for the stop-gradient operator [7].

On the recipient's side, we use the localization network \mathcal{D} to estimate the manipulated region given a doubted image that could be one of $\hat{\mathbf{I}}_t$ or $\hat{\mathbf{I}}_{nt}$. If it's an manipulated image $\hat{\mathbf{I}}_t$, the predicted mask $\hat{\mathbf{M}}_t$ should be close to the ground-truth M. Otherwise, it should be close to a zero matrix. DRAW is flexible on the selection of \mathcal{D} , where many off-the-shelf networks can be applied, e.g., DRAW-HRNet [35], DRAW-MVSS [10] or DRAW-RIML [38].

Objective Loss Functions. We need to include fidelity terms $\mathcal{L}_{\mathcal{P}}^{RAW}$ and $\mathcal{L}_{\mathcal{P}}^{RGB}$ to ensure imperceptible protection using the ℓ_1 distance.

$$\mathcal{L}_{\mathcal{P}}^{RAW} = \mathbb{E}_{\mathbf{R}} \left[\| \mathbf{R} - \mathcal{P} \left(\mathbf{R} \right) \|_{1} \right],$$

$$\mathcal{L}_{\mathcal{P}}^{RGB} = \mathbb{E}_{\mathbf{R}} \left[\| \mathcal{S} \left(\mathbf{R} \right) - \mathcal{S} \left(\mathcal{P} \left(\mathbf{R} \right) \right) \|_{1} \right].$$
(1)

Next, we include localization terms to minimize the Binary Cross Entropy (BCE) losses that respectively compare $\hat{\mathbf{M}}_t$ with \mathbf{M} , and $\hat{\mathbf{M}}_{nt}$ with a zero matrix.

$$L_{\mathcal{D}}^{T} = -\mathbb{E}_{\hat{\mathbf{I}}_{t}} \left[\mathbf{M} \log \left(\mathcal{D}(\hat{\mathbf{I}}_{t}) \right) + (1 - \mathbf{M}) \log \left(1 - \mathcal{D}(\hat{\mathbf{I}}_{t}) \right) \right],$$
$$L_{\mathcal{D}}^{NT} = -\mathbb{E}_{\hat{\mathbf{I}}_{mt}} \left[\log \left(1 - \mathcal{D}(\hat{\mathbf{I}}_{nt}) \right) \right].$$
(2)

The total loss for DRAW is shown in Eq. (3), where $\alpha, \beta, \gamma, \epsilon$ are empirically-set hyper-parameters.

$$\mathcal{L} = \alpha \cdot \mathcal{L}_{\mathcal{P}}^{RAW} + \beta \cdot \mathcal{L}_{\mathcal{P}}^{RGB} + \gamma \cdot \mathcal{L}_{\mathcal{D}}^{T} + \epsilon \cdot \mathcal{L}_{\mathcal{D}}^{NT},$$

$$\alpha = 10, \beta = 1, \gamma = 0.02, \epsilon = 0.01.$$
(3)

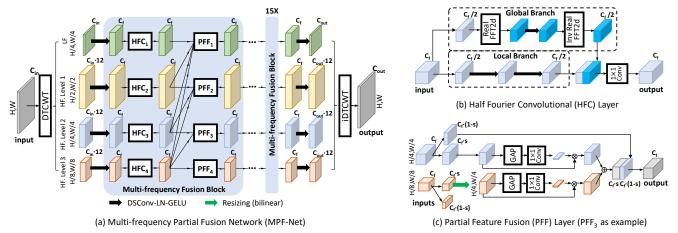


Figure 4. Network design of Multi-frequency Partial fusion Network (MPF-Net). It decomposes the input into multi-level subbands and during cross-frequency feature fusion, we preserve a proportion of features learned in the current layer. $C_{in} = C_{out} = 3$ and $C_f = 32$.

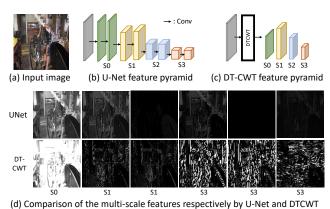


Figure 5. Illustration of feature mining respectively using DT-CWT transform and U-Net. DT-CWT requires fewer *Conv* layers yet the generated features show less redundancy or repetition.

3.2. Multi-frequency Partial Fusion Network

In order to combat sophisticated image manipulation within resource-limited environments such as cellphones and cameras, it is essential to deploy a lightweight architecture yet with rich feature extraction capabilities. Fig. 4 illustrates the network design, where we first use a threelevel DT-CWT transform to decompose the input into a low-frequency main component and three levels of higherfrequency subbands. Each level consists of six subbands in complex forms, representing different degrees of wavelet information. The real and imaginary parts of the subbands are then concatenated. In Fig. 5, we compare the feature pyramid of U-Net to that of DT-CWT. Vanilla convolutions can be less efficient due to the restriction of receptive field, feature redundancy, and repetition during training. In contrast, DT-CWT provides a strong prior for mitigating these issues, requiring only one layer of separable convolution and yielding richer patterns within representations.

Following the initial feature extraction, we apply a "DSConv-LN-GELU" layer to further refine the extracted features, which is in short for depth-wise separable convolution [17], Layer Normalization [5] and GELU activation [16]. Next, we cascade sixteen multi-frequency partial fusion blocks in each level as feature refinement and fusion. Each block contains a Half Fourier Convolution (HFC) layer and a Partial Feature Fusion (PFF) layer. Notably, these blocks do not alter either the resolution or channel number of the features. Then we project the features back into the main components and three levels of subbands using another "DSConv-LN-GELU" layer, which are then transformed back into the RGB domain via iDT-CWT.

Half Fourier Convolution Layer (HFC). We observe that features provided by DT-CWT provide a rich local pattern, whereas the global information representation is lacking. Considering that Fast Fourier Transform (FFT) is efficient in giving global information about the frequency components of an image [50, 24], we include both vanilla *Conv* layer and Fast Fourier Transform (FFT) in each HFC to enable simultaneous global and local feature mining. For the HFC layer at level *i*:

$$HFC_i: output = [GB(input_1), LB(input_2)],$$

 $input = [input_1, input_2],$ (4)

where we evenly split the input tensor by half, send them respectively into the Global Branch (GB) and Local Branch (LB) of the HFC layer, and concatenate the resultant features. GB contains FFT, *Conv* layer and inverse FFT. LB is composed of a cascade of two vanilla *Conv* layers.

Partial Feature Fusion Layer (PFF). On fusing different groups of features, two most commonly-accepted ways are "concatenate-and-reduce" [11, 35] or "attend-to-aggregate" [15, 47]. We propose a novel paradigm of "reserve-attend-and-assemble". Specifically, we split the

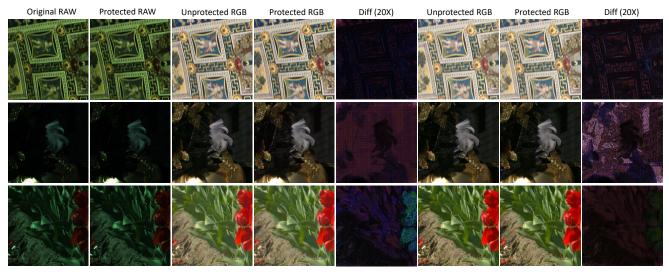


Figure 6. Examples of protected images under different ISPs. Dataset: RAISE. In each test, we apply two ISPs for rendering (upper: LibRAW / OpenISP, middle: InvISP / CycleISP, lower: OpenISP / InvISP). The RAW images are visualized through bilinear demosaicing.

Table 1. Quantitative analysis on the imperceptibility of RAW protection. $[\mathbf{R}, \hat{\mathbf{R}}]$: RAW file before and after protection. $[\mathbf{I}, \hat{\mathbf{I}}]$: RGB file rendered respectively from \mathbf{R} and $\hat{\mathbf{R}}$ using different ISP pipelines. Dataset: RAISE and Canon.

Process	512 >	< 512	256 >	< 256	1024×1024		
Process	PSNR	SSIM	PSNR	SSIM	PSNR	SSIM	
$[\mathbf{R},\hat{\mathbf{R}}]$	58.43	-	61.67	-	56.41	-	
$[\mathbf{I}, \hat{\mathbf{I}}]$ (InvISP)	45.13	0.977	46.20	0.985	45.60	0.983	
$[\mathbf{I}, \hat{\mathbf{I}}]$ (LibRaw)	41.25	0.960	41.97	0.967	41.07	0.957	
$[\mathbf{I},\hat{\mathbf{I}}]$ (Restormer)	45.75	0.980	46.24	0.984	45.03	0.977	
$[\mathbf{I}, \hat{\mathbf{I}}]$ (OpenISP)	40.52	0.960	41.95	0.966	40.34	0.955	

input features into two halves based on a predetermined ratio s (default 0.25), i.e., $input_i = [input_{i,1}, input_{i,2}]$ for PFF at level i. The first half of the multi-level features $(C_f \cdot s)$ are resized into the size of the current level, and then separately reweighed using channel attention (CA) [18]. Next, "assemble" is done by pixel-wisely aggregating all groups of reweighed features and concatenating them with the reserved second half $(C_f \cdot (1-s))$. Our paradigm can potentially mitigate the issue of over-attention on certain frequencies or covariance drift of the preserved representation, especially from shallow layers, caused by residual learning. Furthermore, we only pass higher-frequency subbands into lower levels, which also encourages each level to process unique combinations of frequencies which reduces redundancy. The operations in PFF at level i is as follows.

$$\textit{PFF}_i: \textit{output} = [\textit{input}_{i,2}, \sum_{j \leq i} \textit{CA}(\textit{Resize}(\textit{input}_{j,1}))] \quad (5)$$

where $\it CA$ is composed of a global average pooling layer and a 1×1 bottleneck convolution.

4. Experiments

4.1. Experimental Setups

We use RAISE [12] dataset (8156 image pairs) and Canon subset (2997 image pairs) from the FiveK [8] dataset as the training set. Meanwhile, RAISE, Canon subset and Nikon subset (1600 image pairs) from FiveK as well as SIDD dataset [3] are used to evaluate DRAW. We divide them into training sets and test sets at a ratio of 85: 15. We crop each RAW image into non-overlapping sub-images sized 512×512 . For quantitative analysis, manually manipulating all protected images requires unaffordable effort. Alternatively, inspired by [49, 38], we borrow the segmentation masks from MS-COCO [28] dataset, crop out the corresponding objects and iteratively add them onto the protected images I until the total manipulation rate exceeds 5%. For *copy-moving* and *inpainting*, we generate the attacked image under the same principle that was used during training. For qualitative analysis, we also manually manipulate over one hundred protected images and show some of the representative examples in the figures.

We train our benchmark model by jointly training \mathcal{P} with HRNet [35] as \mathcal{D} . We then fix \mathcal{P} and respectively training MVSS [10] and RIML [38] as \mathcal{D} on top of the protected RGB images. All models are trained with batch size 16 on four distributed NVIDIA RTX 3090 GPUs, and we train the networks for 10 epochs in roughly one day. For gradient descent, we use Adam optimizer with the default hyperparameters. The learning rate is 1×10^{-4} .

4.2. Performances

Image Quality Assessment. Fig. 6 and Table 1 respectively show the qualitative and quantitative results on the

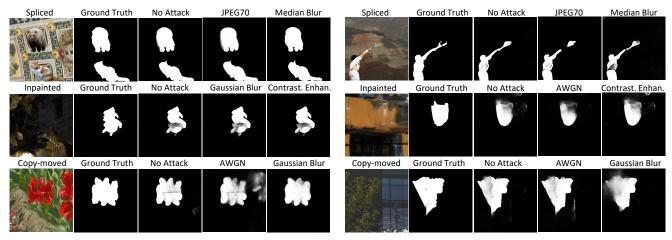


Figure 7. Exampled forgery localization results of DRAW-HRNet. Dataset: RAISE and Canon.

Table 2. **Average performance of different methods on forgery localization.** Dataset: RAISE. The best performances are highlighted in bold type. *: open-source pretrained models finetuned on original RAISE images with *copy-moving*, *splicing* and *inpainting*.

	Models	N	o Atta	ck	R	escalir	ıg	1	AWGN	1	J	PEG9	0	J	PEG7)		MBlur		_	GBlur	
	Wiodels	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU
	MVSS*	.908	.725	.597	.715	.609	.470	.954	.688	.547	.944	.627	.481	.915	.565	.415	.869	.695	.561	.181	.211	.138
s_u	RIML*	.941	.949	.908	.732	.795	.702	.900	.918	.863	.869	.892	.821	.777	.818	.721	.900	.918	.857	.096	.142	.094
ici	DRAW-MVSS	.867	.874	.793	.553	.636	.514	.886	.854	.764	.878	.856	.767	.820	.789	.680	.732	.770	.658	.320	.419	.301
spi	DRAW-RIML	.897	.926	.876	.877	.910	.856	.928	.946	.905	.913	.932	.884	.889	.909	.849	.917	.939	.893	.556	.639	.544
	DRAW-HRNet	.936	.947	.903	.922	.934	.884	.929	.934	.883	.933	.935	.885	.902	.861	.776	.927	.940	.891	.552	.638	.523
81	MVSS*	.833	.781	.703	.677	.636	.544	.861	.755	.668	.771	.627	.527	.653	.471	.366	.795	.731	.640	.339	.336	.258
vi	RIML*	.888	.889	.856	.774	.793	.737	.896	.895	.861	.829	.835	.788	.694	.719	.657	.850	.856	.811	.557	.572	.493
-m	DRAW-MVSS	.901	.893	.857	.839	.836	.780	.915	.890	.850	.862	.842	.793	.804	.767	.706	.871	.851	.803	.631	.657	.582
j.	DRAW-RIML	.915	.925	.910	.875	.895	.868	.906	.918	.899	.884	.899	.874	.845	.866	.829	.897	.910	.888	.774	.811	.768
9	DRAW-HRNet	.969	.970	.959	.960	.956	.937	.962	.957	.943	.955	.951	.932	.916	.884	.839	.958	.955	.939	.915	.920	.885
-	MVSS*	.259	.229	.172	.101	.062	.039	.404	.360	.263	.180	.090	.054	.212	.097	.058	.088	.050	.030	.085	.043	.026
ing	RIML*	.126	.140	.097	.035	.047	.030	.132	.155	.113	.014	.020	.013	.001	.001	.001	.037	.043	.026	.068	.077	.048
iini	DRAW-MVSS	.737	.752	.672	.657	.682	.588	.771	.756	.667	.617	.645	.546	.515	.536	.434	.567	.595	.497	.514	.561	.463
иbс	DRAW-RIML	.663	.716	.656	.457	.518	.452	.667	.718	.654	.348	.411	.342	.091	.121	.089	.366	.423	.360	.284	.338	.281
.7	DRAW-HRNet	.776	.791	.735	.754	.760	.685	.788	.771	.697	.719	.714	.625	.468	.454	.346	.732	.735	.647	.686	.704	.618

imperceptibility of the protection. Besides, we test the overall image quality of protected images using untrained ISP network, namely, Restormer [45], and another conventional ISP, namely, OpenISP [2]. Restormer is originally proposed for image restoration, but we find that the transformer-based architecture also shows excellent performance on RGB image rendering. OpenISP is another popular open-source ISP pipeline apart from LibRaw, and we customize the pipeline by applying the most essential modules. We can observe little artifact from the protected version of RAW data and RGB. From the augmented difference, DRAW imperceptibly introduce content-related local patterns, which function like digital *locks* onto the pixels and forgery localization is conducted by observing the integrity of these *locks*.

Robustness and Accuracy of Manipulation Localization.

We conduct comprehensive experiments on RAISE and Canon datasets under different lossy operations. The qualitative and quantitative comparisons in terms of the Recall, F1 and IoU in the pixel domain are reported in Fig. 7, Fig. 8, Table 2 and Table 4. In Table 3, we further conduct color

adjustment attacks and hybrid attacks on the protected images and let the networks detect the forged areas. We find that for DRAW-HRNet, although the images are manipulated by diverse lossy operations, we succeed in localizing the tampered areas. If there are no lossy operations, the F1 scores are in most cases above 0.8. Fig. 7 further provides exampled image manipulation localization results of DRAW-HRNet under different lossy operations.

Next, for fair comparison with previous arts, we finetune MVSS and RIML on RAISE and Canon dataset using the mechanisms proposed in the corresponding papers yet additionally considering *splicing*, *copy-moving* and *inpainting*. When heavy image lossy operations are present, MVSS fails to detect the tampered content. While RIML exhibits better robustness due to OSN transmission simulation, its performances under blurring or inpainting attacks are still restricted. However, training these detectors based on the protected images significantly improves their robustness. Besides, while MVSS and RIML are found limited in the generalizability to novel, untrained types of inpainting

Table 3. Average performance against color adjustment attacks and hybrid attacks on RAISE dataset. The detector can successfully locate the forged areas in most cases.

Attack	s	plicin	g	cop	y-mov	ing	inpainting			
Attack	Rec.	F1	IoU	Rec.	F1	IoU	Rec.	F1	IoU	
Hue Adjust.	.938	.949	.905	.973	.974	.962	.779	.794	.736	
Contra. Enhan.	.935	.945	.900	.971	.969	.958	.773	.783	.726	
Satur. Adjust.	.937	.948	.904	.969	.968	.958	.784	.795	.738	
Bright. Adjust.	.936	.947	.903	.960	.960	.948	.771	.782	.725	
JPEG70+Hue.	.900	.855	.769	.906	.872	.824	.489	.508	.396	
GBlur+Contra.	.553	.637	.520	.895	.902	.866	.755	.774	.692	
MBlur+Satur.	.927	.939	.890	.960	.956	.938	.821	.832	.754	
AWGN+Bright.	.930	.935	.885	.952	.944	.925	.842	.842	.778	

Table 4. Average performance of different methods on forgery localization. Dataset: CANON

iocalization. Dataset: CANON.									
	Models	No A	ttack	Rescaling		JPEG70		GB	lur
	Wiodels	F1	IoU	F1	IoU	F1	IoU	F1	IoU
	MVSS*	.610	.465	.530	.390	.503	.354	.210	.135
g_{μ}	RIML*	.925	.872	.716	.609	.783	.675	.136	.094
splicing	DRAW-MVSS	.841	.738	.875	.789	.842	.739	.829	.731
spi	DRAW-RIML	.887	.818	.925	.870	.855	.769	.906	.843
	DRAW-HRNet	.926	.869	.939	.889	.921	.861	.939	.891
- 82	MVSS*	.727	.628	.624	.526	.455	.341	.371	.283
copy-moving	RIML*	.892	.852	.789	.733	.702	.619	.569	.494
·mc	DRAW-MVSS	.912	.879	.868	.828	.832	.785	.826	.776
py.	DRAW-RIML	.969	.957	.962	.947	.911	.882	.952	.933
00	DRAW-HRNet	.968	.956	.960	.945	.922	.895	.952	.934
	MVSS*	.215	.150	.100	.064	.136	.083	.073	.045
ing	RIML*	.102	.070	.033	.021	.003	.001	.012	.007
inpainting	DRAW-MVSS	.829	.753	.676	.574	.115	.076	.513	.407
	DRAW-RIML	.949	.918	.889	.836	.406	.326	.849	.784
į	DRAW-HRNet	.934	.894	.867	.811	.360	.284	.761	.691

Table 5. Generalizability to untrained ISP pipelines or datasets. \mathcal{P} and \mathcal{D} are trained on RAISE.

JPEG70 MBlur GBlur Test Item Forgery NoAtk Rescaling Spli. 929 910 .837 933 620 OpenISP .941 Copy. .919 .843 .941 .880 Inpa. .850 .820 .451 .765 .756 ISPSpli. .946 .936 .863 .941 .648 Restormer .961 .947 .948 .904 Copy. .871 .906 .487 Inpa. .833 .789 .759 Spli. .936 925 .845 .931 596 Canon .957 .930 .859 .946 .881 Copy. Dataset .805 .732 .486 .710 .706 Inpa. 928 909 832 911 574 Spli. SIDD Copy. .967 .965 .891 .954 .880 Inpa. .686 .628 .400.574 .554

forgeries such as ZITS and LAMA, DRAW can also help improve their accuracy and robustness against such types, therefore ensuring generalizability even without frequently updating the trained parameters.

Generalizability. We conduct additional experiments where \mathcal{P} trained on RAISE dataset is applied on different RAW datasets, i.e., Canon and SIDD, and untrained ISP pipelines, i.e., OpenISP and Restormer. Table 5 shows that raw protection can generalize to untrained cameras and ISP pipelines while preserving promising detection capacity. For instance, given the new ISPs, the F1 scores under JPEG70 attack for *copy-moving* and *splicing* detection are

Table 6. Comparison of computational cost among lightweight image-to-image-translation or segmentation networks.

	SegNet [6]	ShuffleNet [30]	U-Net [33]	ENet [31]	MPF-Net
Params	29.5M	0.94M	26.35M	0.36M	0.25M
FLOPS	0.56T	22.9G	0.22T	2.34G	7.39G
Mem.	465MB	390MB	767MB	46MB	160MB

Table 7. Comparison with baseline methods on RAISE. We verify the importance of RAW protection by comparing the results with those of pure robust training using \mathcal{A} and direct RGB protection. \mathcal{P}^- : using \mathcal{P} for RGB protection. \mathcal{D} : MVSS*

\mathcal{P}^-	\mathcal{A}	\mathcal{D}	F1	aling IoU	T1					lur
				100	F1	IoU	F1	IoU	F1	IoU
		\checkmark	.609	.470	.565	.415	.695	.561	.211	.138
	\checkmark	✓	.668	.534	.725	.590	.762	.635	.303	.207
\checkmark	\checkmark	✓	.358	.253	.438	.317	.487	.361	.149	.097
	\checkmark	✓	.636	.514	.789	.680	.770	.658	.419	.301
		√	.636	.544	.471	.366	.731	.640	.336	.258
	\checkmark	✓	.859	.816	.648	.582	.782	.728	.528	.456
\checkmark	\checkmark	✓	.490	.412	.467	.382	.626	.548	.268	.208
	\checkmark	✓	.836	.780	.767	.706	.851	.803	.657	.582
		√	.062	.039	.097	.058	.050	.030	.043	.026
	\checkmark	✓	.605	.494	.231	.159	.398	.297	.342	.249
\checkmark	\checkmark	✓	.387	.291	.480	.371	.381	.288	.374	.279
	\checkmark	✓	.682	.588	.536	.434	.595	.497	.561	.463
	√ √ √ · √			✓ ✓ .668 ✓ ✓ ✓ .636 ✓ ✓ .636 ✓ ✓ .859 ✓ ✓ .490 ✓ ✓ .836 ✓ ✓ .605 ✓ ✓ .387	√ √ √ 668 .534 √ √ √ .636 .514 √ √ .859 .816 √ √ √ .490 .412 √ √ √ .836 .780 √ √ .605 .494 √ √ √ .387 .291	√ √ .668 .534 .725 √ √ √ .358 .253 .438 √ √ .636 .514 .789 √ √ .859 .816 .648 √ √ √ .490 .412 .467 √ √ .836 .780 .767 √ √ .605 .494 .231 √ √ .387 .291 .480	√ √ .668 .534 .725 .590 √ √ √ .358 .253 .438 .317 √ √ .636 .514 .789 .680 √ √ .859 .816 .648 .582 √ √ √ .490 .412 .467 .382 √ √ √ .836 .780 .767 .706 √ √ .602 .039 .097 .058 √ √ .605 .494 .231 .159 √ √ .387 .291 .480 .371	√ √ .668 .534 .725 .590 .762 √ √ √ .358 .253 .438 .317 .487 √ √ .636 .514 .789 .680 .770 √ √ .859 .816 .648 .582 .782 √ √ √ .490 .412 .467 .382 .626 √ √ .836 .780 .767 .706 .851 √ √ .605 .494 .231 .159 .398 √ √ √ .387 .291 .480 .371 .381	√ √ .668 .534 .725 .590 .762 .635 √ √ √ .358 .253 .438 .317 .487 .361 √ √ .636 .514 .789 .680 .770 .658 √ √ .859 .816 .648 .582 .782 .728 √ √ √ .490 .412 .467 .382 .626 .548 √ √ .836 .780 .767 .706 .851 .803 √ √ .602 .039 .097 .058 .050 .030 √ √ .605 .494 .231 .159 .398 .297 √ √ √ .387 .291 .480 .371 .381 .288	√ √ .668 .534 .725 .590 .762 .635 .303 √ √ √ .358 .253 .438 .317 .487 .361 .149 √ √ .636 .514 .789 .680 .770 .658 .419 √ √ .859 .816 .648 .582 .782 .728 .528 √ √ .490 .412 .467 .382 .626 .548 .268 √ √ .836 .780 .767 .706 .851 .803 .657 √ √ .605 .494 .231 .159 .398 .297 .342 √ √ √ .387 .291 .480 .371 .381 .288 .374

above 0.7, representing successful manipulation localization. Therefore, our method is shown to adapt to untrained ISP pipelines.

Computational Complexity. We compare the computational requirements of MPF-Net in Table 6 with SegNet [6], ShuffleNet [30], U-Net [33] and ENet [31], which are famous lightweight models for image segmentation. MPF-Net requires lower computing resources, e.g, only 20.9% in memory cost and 0.95% in parameters compared to the classical U-Net.

4.3. Baseline Comparisons

Previous techniques in proactive image forgery detection, e.g., tag retrieval [37] or template matching [4], are not suitable for image manipulation localization. Therefore, we alternatively build two baseline methods that respectively apply pure robust training using our proposed attack layer and apply RGB-domain protection. In the tests, MVSS is employed as localization network. The quantitative comparison results are reported in Table 7. Further details regarding the experimental settings for the two baseline methods are included in the supplement.

RAW Protection vs Pure Robust Training. Our proposed robust training mechanism reflected in the attack layer is different from that proposed in RIML. Specifically, we render the unprotected RAW files \mathbf{R} using \mathcal{S} , which are then attacked by \mathcal{A} . We see that the introduction of robust training can help boost the performance of MVSS. However, the overall performance is still worse than further applying RAW protection to aid localization. In severe degrading cases such as blurring, the performance gap between RAW

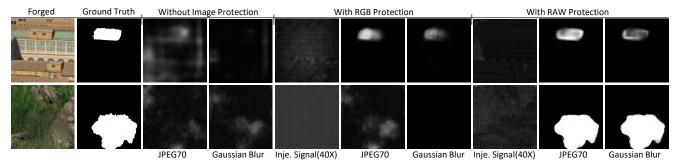


Figure 8. Baseline analysis on performance between passive localization without image protection, with RGB protection and with RAW protection. Dataset: RAISE. \mathcal{D} : MVSS* (upper), RIML* (lower). Type: copy-moving (upper), inpainting (lower).

protection and robust training without protection regarding F1 score is more than ten percent.

RAW protection vs RGB protection. For fair comparison, we regulate that the overall PSNR on RGB images before and after RGB protection should be above 40 dB, in line with the criterion in Table 1. We conduct qualitative experiment in Fig 8 to evaluate the effectiveness of image protection. According to the experimental results, RGB protection cannot aid robust manipulation localization if the magnitude of RGB modification is restricted. We also grayscale the augmented injected signal for better visualization and found that signal injected by RAW protection is more adaptive in magnitude to the image contents. One possible reason is that the densely-predicting task requires hiding more information than binary image forgery classification task, making it struggle to maintain high fidelity of the original image. In comparison, RAW protection can adaptively introduce protection with the help of content-related procedures, e.g., demosaicing and noise reduction, within the subsequent ISP algorithms that suppress unwanted artifacts and biases. Theoretically, RAW data modification enjoys a much larger search space that allows transformations from the original image into another image with high density upon sampling.

4.4. Ablation Studies

Table 8 and Fig. 9 respectively show the quantitative and qualitative results of ablation studies. In each test, we regulate that the averaged PSNR between $\hat{\mathbf{I}}$ and $\hat{\mathbf{I}}$, with ISP pipelines evenly applied, should be within the range of 41-43 dB, to ensure imperceptible image protection.

Substituting the architecture of \mathcal{P} **.** We first test if using U-Net with a similar amount of parameters or ENet [31] as \mathcal{P} can achieve similar performance on splicing detection. First, though ENet contains similar amount of parameters compared to MPF-Net, the performance of image manipulation localization using ENet as \mathcal{P} is not satisfactory. Second, though U-Net with DSConv provides much better result, because the channel numbers within each layer are restricted within 48 to save computational complexity, the

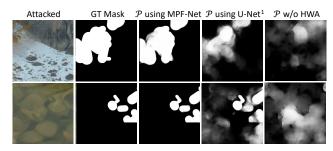


Figure 9. **Examples of ablation studies of DRAW.** We observe that either replacing MPF-Net with U-Net using *DSConv* or removing HFC module results in decreased performance. Upper: inpainting + JPEG80. Lower: copy-moving + median-blur.

Table 8. Ablation study on DRAW on Nikon using splicing attack. ¹: replacing *Conv* layers with *DSConv*.

Test	F1						
Test	NoAtk	JPEG70	Mblur				
\mathcal{P} using U-Net ¹	.877	.769	.535				
\mathcal{P} using ENet	.324	.137	.092				
MPF-Net w/o HFC	.844	.710	.602				
MPF-Net w/o DT-CWT	.852	.751	.626				
MPF-Net w/o PFF	.827	.712	.667				
w/o diff from real attack	.842	.566	.502				
using only one ISP Surrogate	.648	.455	.267				
w/o Image Distortion Module	.929	.245	.116				
w/o Color Ajustment Module	.814	.759	.641				
Full implementation of DRAW	.929	.838	.696				

performance is still worse than our benchmark.

Impact of components in MPF-Net. The most noticeable difference between MPFNet with previous U-shaped networks is that feature disentanglement can be better ensured even with fewer parameters. To verify this, we respectively replace the HFC layer and PFF layer with typical alternatives, i.e., vanilla convolution and channel-wise concatenation. The performances are nearly 5-10 points weaker compared to the MPF-Net setup. First, DT-CWT is a shift-invariant wavelet transform that comes with limited redundancy. Second, partial feature fusion and partial connection are more flexible. The design explicitly keeps some of the features extracted from the current level and directly feeds

them into the subsequent block. Therefore, for different levels, the input features will be different, which encourages feature disentanglement.

Impact of pipeline design. We also test the setting of not using the image distortion module or color adjustment module in the pipeline during training. The result is as expected that the scheme will therefore lack generalizability in overall robustness due to the fact that there are not enough random processes that can simulate the real-world situation. Besides, not introducing the difference between the real-world and simulated attacks or using only one ISP surrogate model will also impair the overall performance.

5. Conclusions

We present DRAW which introduces invisible water-marks as protective signal into the RAW data. The protection can not only be transferred into the rendered RGB images regardless of the applied ISP pipeline, but also is resilient to post-processing operations such as blurring or compression. Once the image is manipulated, we can accurately identify the forged areas with a localization network. Extensive experiments on typical RAW datasets prove the effectiveness of DRAW. We also verify that our novel MPF-Net provides superior performance compared to previous lightweight models for our task.

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