Auto-encoder	Pre-trained	sd-vae-ft-mse	
	In channels	3	
	Latent channels	4	
	Block channels	[128, 256, 512, 512]	
	Down-sample ratio	8	
	Layers per block	2	
	Norm groups	32	
	Pre-trained	×	
	In channels	8	
	Out channels	4	
	Block channels	[128, 256, 512, 512]	
U-Net	Attention channels	[128, 256, 512, 512]	
	Layers per block	2	
	Head nums	8	
	Filter nums	64	
	Norm groups	32	
Source image encoder	Pre-trained	×	
	In channels	4	
	Block channels	[128 256 512 512]	
	Lavers per block	1	
	Norm groups	32	
	Time embedding	32 ¥	
	Time embedding	~	
	0 1 1 1	0 1 11	
	β schedule	Scaled linear	
Noise scheduler	β schedule β start	Scaled linear 0.00085	
Noise scheduler	β schedule β start β end	Scaled linear 0.00085 0.012	
Noise scheduler	$\beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline RandomCrop \\ \hline$	Scaled linear 0.00085 0.012 X	
Noise scheduler Data augmentation	$ \begin{array}{l} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \end{array} \\ \hline \\ \textbf{RandomCrop} \\ \hline \\ \textbf{RandomFlip} \end{array} $	Scaled linear 0.00085 0.012 ✗ ✓	
Noise scheduler Data augmentation	$ \begin{array}{c} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \end{array} \\ \hline RandomCrop \\ RandomFlip \\ \hline Iterations \end{array} $	Scaled linear 0.00085 0.012 × ✓ 600k	
Noise scheduler Data augmentation	$ \begin{array}{c} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \end{array} \\ \hline RandomCrop \\ RandomFlip \\ \hline Iterations \\ Batch size \end{array} $	Scaled linear 0.00085 0.012 × × 600k 32	
Noise scheduler Data augmentation		Scaled linear 0.00085 0.012 × × 600k 32 5e-5	
Noise scheduler Data augmentation		Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation	$\begin{array}{l} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline \\ RandomCrop \\ RandomFlip \\ \hline \\ Iterations \\ Batch size \\ Initial LR \\ Warm-up scheme \\ Warm-up iterations \\ \hline \end{array}$	Scaled linear 0.00085 0.012 X V 600k 32 5e-5 Linear 1k	
Noise scheduler Data augmentation Training setting	β schedule β start β end RandomCrop RandomFlip Iterations Batch size Initial LR Warm-up scheme Warm-up iterations Warm-up starting	Scaled linear 0.00085 0.012 ✗ ✓ 600k 32 5e-5 Linear 1k 0	
Noise scheduler Data augmentation Training setting	$\begin{array}{c} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline \\ RandomCrop \\ RandomFlip \\ \hline \\ Iterations \\ Batch size \\ Initial LR \\ Warm-up scheme \\ Warm-up scheme \\ Warm-up starting \\ Optimizer \\ \end{array}$	Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation Training setting	β schedule β start β end RandomCrop RandomFlip Iterations Batch size Initial LR Warm-up scheme Warm-up starting Optimizer Weight decay	Scaled linear 0.00085 0.012 X V 600k 32 5e-5 Linear 1k 0 Adam (0.9, 0.999) 0.01	
Noise scheduler Data augmentation Training setting	$\begin{array}{c} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline \\ $	Scaled linear 0.00085 0.012 x x x x x x x x	
Noise scheduler Data augmentation Training setting	$\begin{array}{c} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline \\ $	Scaled linear 0.00085 0.012 x x x x x x x x	
Noise scheduler Data augmentation Training setting	$\begin{array}{c} \beta \mbox{ schedule} \\ \beta \mbox{ start} \\ \beta \mbox{ end} \\ \hline \end{array} \\ \hline RandomCrop \\ RandomFlip \\ \hline \\ RandomFlip \\ \hline \\ Iterations \\ Batch size \\ Initial LR \\ Warm-up scheme \\ Warm-up scheme \\ Warm-up starting \\ Optimizer \\ Weight decay \\ Gradient clip \\ Precision \\ CFG probability \\ \hline \end{array}$	Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation Training setting	β schedule β start β end RandomCrop RandomFlip Iterations Batch size Initial LR Warm-up scheme Warm-up starting Optimizer Weight decay Gradient clip Precision CFG probability Scheduler	Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation Training setting Sampling setting	$\begin{array}{l} \beta \text{ schedule} \\ \beta \text{ start} \\ \beta \text{ end} \\ \hline \\ RandomCrop \\ RandomFlip \\ \hline \\ Iterations \\ Batch size \\ Initial LR \\ Warm-up scheme \\ Warm-up scheme \\ Warm-up starting \\ Optimizer \\ Weight decay \\ Gradient clip \\ Precision \\ CFG probability \\ \hline \\ Scheduler \\ CFG scale \\ \hline \end{array}$	Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation Training setting Sampling setting	$\begin{array}{l} \beta \mbox{ schedule} \\ \beta \mbox{ start} \\ \beta \mbox{ end} \\ \hline \beta \mbox{ start} \\ \beta \mbox{ end} \\ \hline RandomCrop \\ RandomFlip \\ \hline \\ RandomFlip \\ \hline \\ Iterations \\ Batch size \\ Initial LR \\ Warm-up scheme \\ Warm-up scheme \\ Warm-up scheme \\ Warm-up iterations \\ Warm-up starting \\ Optimizer \\ Weight decay \\ Gradient clip \\ Precision \\ CFG probability \\ \hline \\ Scheduler \\ CFG scale \\ Steps \\ \hline \end{array}$	Scaled linear 0.00085 0.012	
Noise scheduler Data augmentation Training setting Sampling setting	$\begin{array}{l} \beta \mbox{ schedule} \\ \beta \mbox{ start} \\ \beta \mbox{ end} \\ \hline \beta \mbox{ end} \\ \hline RandomCrop \\ RandomFlip \\ \hline \\ RandomFlip \\ \hline \\ Iterations \\ Batch \mbox{ size} \\ Initial \ LR \\ Warm-up \ scheme \\ Warm-up \ scheme \\ Warm-up \ scheme \\ Warm-up \ starting \\ Optimizer \\ Weight \ decay \\ Gradient \ clip \\ Precision \\ CFG \ probability \\ \hline \\ Scheduler \\ CFG \ scale \\ Steps \\ \hline \\ GPU \\ \hline \end{array}$	Scaled linear 0.00085 0.012 X V 6 00k 32 5e-5 Linear 1k 0 Adam (0.9, 0.999) 0.01 0.1 fp16 10% PNDM [3] 5 50 2 × V100 (32 GB)	

Table 1. Details for training and sampling PoCoLD.

A. Implementation details

We list all hyper-parameters used for training and sampling our PoCoLD in Tab. 1, including model architecture details, training recipe, and sampling setting.

B. Additional experiment results

Impact of CFG values. While tuning CFG is indeed useful, it alone is insufficient to achieve SOTA performance along with vanilla cross attention, as reflected in Tab. 2. We empirically found that PIDM's CFG strategy is not suited for our case and exploited our well-tuned CFG strategy

Attention	CFG Type	CFG Values	$\mathbf{FID}\downarrow$	SSIM \uparrow	LPIPS \downarrow
Vanilla	Disentangled	$\omega_p, \omega_s = 2$	19.0473	0.5327	0.3620
Vanilla	Dual CFG [1]	$\omega_p, \omega_s = 2$	11.9200	0.6601	0.2440
Vanilla	Dual CFG [1]	$\omega_p, \omega_s = 5$	8.2903	0.7095	0.1783
Ours	Dual CFG [1]	$\omega_p, \omega_s = 5$	8.0667	0.7310	0.1642

Table 2. Quantitative results of tuning different CFG values.



Figure 1. Qualitative comparison between our PoCoLD and the variant which replaces DensePose with pose skeleton.

(Dual CFG [2] with $\omega_p, \omega_s = 5$) as the default setting for all experiments. The proposed attention is designed for efficiently leveraging DensePose, resulting in further performance improvements on the basis of already using the best CFG, and achieving SOTA results.

Impact of DensePose. We try to replace DensePose by using the body skeleton in the latent space (channel-wise) while keeping all training recipes intact. This variant gives 14.7362/0.6315/0.2550 in FID/SSIM/LPIPS, *vs.* 8.0667/0.7310/0.1642 by the original variant. Along with the qualitative results shown in Fig. 1, this verifies again that: (1) DensePose offers more comprehensive structural information, which is helpful to mitigate ambiguity; and (2) DensePose facilitates spatial alignment with the target image under proper regularization (*e.g.*, the proposed pose constraints).

High-resolution visualization results. We provide some high-resolution visualization results in Fig. 2 to better understand the performance of our PoCoLD in a qualitative way. We mainly compare our PoCoLD with prior diffusion-based art, *i.e.*, PIDM [1]. In each row, the sequence of images is as follows, from left to right: source image, target pose, ground truth, generation by PIDM, and our result. Our PoCoLD exhibits enhanced preservation of both texture and shape. Moreover, it demonstrates greater stability in generating results in certain infrequent scenarios, *e.g.*, enlarged person/garment in the source image.





Figure 2. High-resolution qualitative result (from left to right: source image, target pose, ground truth, PIDM, and our PoCoLD).

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