Supplementary Materials: Hyperbolic Audio-visual Zero-shot Learning

Jie Hong^{1,2}, Zeeshan Hayder², Junlin Han^{1,2}, Pengfei Fang³, Mehrtash Harandi⁴, Lars Petersson²

¹Australian National University, ²Data61-CSIRO, ³Southeast University, ⁴Monash University

jie.hong@anu.edu.au, zeeshan.hayder@data61.csiro.au, junlinhcv@gmail.com,

fangpengfei@seu.edu.cn, mehrtash.harandi@monash.edu, lars.petersson@data61.csiro.au

1. Methodology

Prior to the Hyperbolic Alignment Module, we introduce two toy models, *Hyper-embedding* and *Hyper-net*, as shown in Figure 1 (a) and (b), in addition to our Hyperbolic Alignment Module.

1.1. Hyper-embedding.

Hyper-embedding, illustrated in Figure 1 (a), projects all features onto a hyperbolic tangent space before computing the loss \mathcal{L}_{avca} . The hyperbolic tangent space $T_z \mathbb{H}_c^n$ is a Euclidean space, so the loss \mathcal{L}_{avca} can be directly applied.

1.2. Hyper-net.

Hyper-net replaces all Euclidean MLP with Hyperbolic MLP, enabling the entire network to be learned under the Poincaré ball space \mathbb{H}_c^n (See Figure 1 (b)). We investigate the potential of applying hyperbolic geometry in audio-visual zero-shot learning by designing and testing two toy models.

2. Experiment

2.1. Ablation Study

Align similarity matrix *vs.* features. We align the similarity matrices between audio and visual features. This can be understood as preserving the latent structure between the two modalities, as captured by the respective similarities. Consequently, it is not necessary for one modality to precisely replicate the representation space of the other modality, as this would impose a strong constraint on the feature space. We conduct an ablation study on UCF-GZSL^{cls} where we align the features directly. The results are shown in Tab. 1.

2.2. Result Analysis

Results. The experimental results of Hyper-embedding and Hyper-net are presented in Table 2 and 3, respectively.

	Similari	ty alignment	Feature alignment				
Method	$\mathrm{HM}\uparrow$	$\operatorname{ZSL}\uparrow$	$\mathrm{HM}\uparrow$	$\operatorname{ZSL}\uparrow$			
Hyper-alignment	42.52	39.80	29.11	29.74			
Hyper-single	44.99	39.86	31.01	30.19			
Hyper-multiple	48.30	52.11	37.19	39.23			

Table 1. Ablation study: align similarity matrix vs. features. Different alignments are tested on dataset UCF-GZSL^{cls}.

AVCA [2] serves as the baseline. The two toy models that incorporate hyperbolic geometry outperform the baseline in certain cases. For example, on VGGSound-GZSL^{cls}, Hyper-embedding achieves 8.74%/7.19% in HM/ZSL, which is higher than the 8.31%/6.91% of AVCA. On UCF-GZSL, Hyper-net surpasses AVCA in ZSL by 1.84%. These results suggest hyperbolic geometry may be a promising approach in audio-visual zero-shot learning. In addition to the visualized examples presented in the paper, more visualizations are provided in Figure 2.

References

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 2

^{*}Corresponding author

(a) Hyper-embedding Hyperbolic Logarithmic

(b) Hyper-net



Figure 1. The framework of two toy designs: (a) Hyper-embedding and (b) Hyper-net.

	VGGSound-GZSL			UCF-GZSL				ActivityNet-GZSL				
Method	$S\uparrow$	$\mathrm{U}\uparrow$	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$	$S\uparrow$	$\mathrm{U}\uparrow$	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$	$S\uparrow$	U↑	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$
CJME [3]	8.69	4.78	6.17	5.16	26.04	8.21	12.48	8.29	5.55	4.75	5.12	5.84
AVGZSLNet [1]	18.05	3.48	5.83	5.28	52.52	10.90	18.05	13.65	8.93	5.04	6.44	5.40
AVCA [2]	14.90	4.00	6.31	6.00	51.53	18.43	27.15	20.01	24.86	8.02	12.13	9.13
Hyper-embedding	17.49	5.19	8.00	5.68	64.47	16.36	26.10	19.29	31.33	7.21	11.72	9.90
Hyper-net	8.34	4.46	5.81	5.80	54.56	17.19	26.14	21.85	16.17	8.87	11.46	9.90
Hyper-multiple	15.02	6.75	9.32	7.97	63.08	19.10	29.32	22.24	23.38	8.67	12.65	9.50

Table 2. Experimental results of audio-visual zero-shot learning on three datasets (main feature). AVCA [2] is adopted as the baseline for the proposed toy designs, Hyper-embedding and Hyper-net. The best results in HM and ZSL are in **bold**.

	VGGSound-GZSL ^{cls}			UCF-GZSL ^{cls}				ActivityNet-GZSL ^{cls}				
Method	$S\uparrow$	$\mathrm{U}\uparrow$	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$	$S\uparrow$	$\mathrm{U}\uparrow$	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$	$S\uparrow$	$\mathrm{U}\uparrow$	${\rm HM}\uparrow$	$\operatorname{ZSL}\uparrow$
CJME [3]	10.86	2.22	3.68	3.72	33.89	24.82	28.65	29.01	10.75	5.55	7.32	6.29
AVGZSLNet [1]	15.02	3.19	5.26	4.81	74.79	24.15	36.51	31.51	13.70	5.96	8.30	6.39
AVCA [2]	12.63	6.19	8.31	6.91	63.15	30.72	41.34	37.72	16.77	7.04	9.92	7.58
Hyper-embedding	15.88	6.03	8.74	7.19	72.47	29.06	41.48	36.10	31.10	7.45	12.02	8.37
Hyper-net	7.56	3.16	4.45	4.91	33.77	37.24	35.42	37.88	21.15	7.60	11.18	8.32
Hyper-multiple	15.62	6.00	8.67	7.31	74.26	35.79	48.30	52.11	36.98	9.60	15.25	10.39

Table 3. Experimental results of audio-visual zero-shot learning on three datasets (cls feature). AVCA [2] is adopted as the baseline for the proposed toy designs, Hyper-embedding and Hyper-net. The best results in HM and ZSL are in **bold**.



Figure 2. Visualization examples on UCF-GZSL^{*cls*}. We give t-SNE visualizations of θ_v from two unseen classes: "PlayingFlute" and "ShavingBeard".