

Referring to Any Person

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Figure 1. We introduce referring to any person, a task that requires detecting all individuals in an image which match a given natural language description, and a new model RexSeek designed for this task with strong perception and understanding capabilities that effectively captures attributes, spatial relations, interactions, reasoning, celebrity recognition, etc.

Abstract

Humans are undoubtedly the most important participants in computer vision, and the ability to detect any individual given a natural language description, a task we define as referring to any person, holds substantial practical value. However, we find that existing models generally fail to achieve real-world usability, and current benchmarks are limited by their focus on one-to-one referring, which hin-

ders progress in this area. In this work, we revisit this task from three critical perspectives: task definition, dataset design, and model architecture. We first identify five aspects of referable entities and three distinctive characteristics of this task. Next, we introduce HumanRef, a novel dataset designed to tackle these challenges and better reflect real-world applications. From a model design perspective, we integrate a multimodal large language model with an object detection framework, constructing a robust referring model named RexSeek. Experimental results reveal that state-of-the-art models, which perform well on commonly used benchmarks like RefCOCO+/g, struggle with HumanRef due to their inability to detect multiple individuals. In con-

This work was done when Qing Jiang and Lin Wu were interns at IDEA.

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trast, *RexSeek* not only excels in human referring but also generalizes effectively to common object referring, making it broadly applicable across various perception tasks. Code is available at <https://github.com/IDEA-Research/RexSeek>.

1. Introduction

Humans are central to computer vision [4, 10–12, 16, 21, 27, 28, 30, 45, 46, 63, 65, 84, 85], and the ability to identify and detect specific individuals based on natural language descriptions, a task we define as referring to any person, is crucial for numerous applications, including human-robot interaction, industrial automation, healthcare, etc.

However, we argue that progress in this area has been hindered by unclear task definitions and a lack of high-quality data. Our findings show that despite achieving state-of-the-art performance on referring benchmarks RefCOCO+/g [50, 75], most models remain impractical for real-world applications, as illustrated in Figure 2. To address this challenge, we revisit this task from three perspectives: task definition, dataset construction, and model design.

We begin by formally defining the task of referring to any person: *given a natural language description and an input image, the model needs to detect all individuals in the image who match the description*. To comprehensively capture the scope of this task, we identify five key aspects that define how humans can be referred to: **i) Attributes:** Encompassing intrinsic characteristics such as gender, age, action, clothing, etc. **ii) Position:** Describing spatial relationships both among individuals and between individuals and their surroundings. **iii) Interaction:** Accounting for human-to-human, human-to-object, and human-to-environment interactions. **iv) Reasoning:** Involving multi-step inference that considers multiple objects to resolve complex expressions. **v) Celebrity Recognition:** Identifying specific individuals, whether by their real names or characters names.

Next, we identify three crucial characteristics that define this task: **i) Multi-Instance Referring:** A referring expression can correspond to multiple individuals. While mainstream referring datasets RefCOCO+/g [50, 75] typically assume that each expression refers to a single object, this does not align with real-world scenarios. We find through experiments that most models experience significant performance degradation when tasked with identifying more than one individual. **ii) Multi-Instance Discrimination:** The image should contain multiple individuals in addition to the target person. This setting ensures that the model fully comprehends the referring expression to identify the correct individual rather than simply detecting all people in the image. **iii) Rejection of Non-existence:** If the referred person is not present in the image, the model should refuse to generate a result rather than produce a hallucinated output.

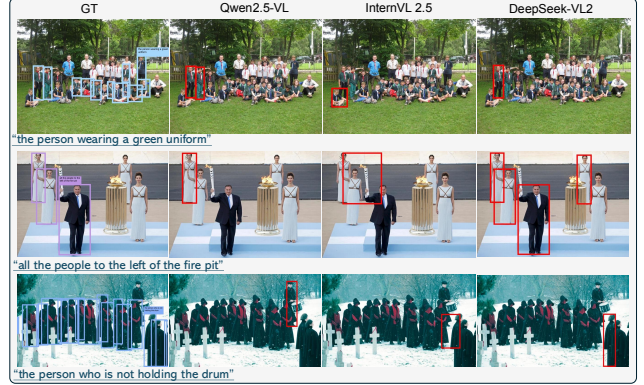


Figure 2. Visualization results of Qwen2.5-VL [3], InternVL-2.5 [14], and DeepSeek-VL2 [70] on the human referring task. Despite achieving strong results on referring benchmarks RefCOCO+/g [50, 75], state-of-the-art models struggle when tasked with identifying multiple individuals as they output an insufficient number of bounding boxes.

Based on the task definition, we manually constructed a novel dataset for human referring, named HumanRef. Unlike the traditional ReferItGame [29] annotation approach, where one annotator describes an object and another finds it based on the description, we adopt a different annotation methodology. Our process begins with annotators listing the key properties of individuals in an image according to the predefined referable entities. Next, for each person, they determine whether these properties apply and result in a property dictionary. Finally, a large language model [71] composes these properties into referring expressions. HumanRef comprises 103,028 referring statements, with each expression referring to an average of 2.2 instances. We also split a benchmark from HumanRef with 6,000 referring expressions spanning six subsets, ensuring comprehensive coverage across all referable properties.

From the model design perspective, we argue that a robust referring model should possess two key characteristics: **i) Robust Perception Ability:** The model should be capable of detecting all individuals in an image. **ii) Strong Language Comprehension:** The model should effectively interpret complex language descriptions of people. To address these requirements, we introduce *RexSeek*, a detection-oriented multimodal large language model specifically designed for this task. Inspired by ChatRex [25], we formulate referring as a retrieval-based task. *RexSeek* integrates a person detector [60] as its box input, ensuring strong perception capabilities while incorporating Qwen2.5 [71] as the LLM to enhance language comprehension. We adopt a multi-stage training approach that progressively refines both detection and comprehension skills, equipping *RexSeek* with strong referring capabilities.

Experimental results indicate that most state-of-the-art models [3, 9, 14, 25, 49, 60, 70, 74] exhibit performance

degradation on the HumanRef benchmark, despite achieving strong results on RefCOCO+/g. The primary limitation is that these models typically detect only a single instance, as they are trained on datasets that assume one-to-one referring. In contrast, RexSeek, trained on HumanRef, exhibits strong referring capabilities. Additionally, benefiting from the multi-stage training approach, RexSeek also emerges with the ability to refer to generalized objects, extending its applicability beyond human-centric tasks. To summarize, our contributions are threefold:

- We introduce referring to any person with a clear definition by identifying five aspects of referable entities and three key characteristics that distinguish this task.
- We introduce HumanRef, a novel referring dataset, and establish a challenging benchmark to drive progress in human-centric referring expression research.
- We propose RexSeek, a detection-oriented multimodal large language model trained through a multi-stage process, demonstrating strong referring capabilities for both humans and general objects.

2. Related Work

Referring Expression Comprehension Task. Referring Expression Comprehension (REC) [29, 36, 48, 50, 56, 72, 75, 76, 76, 81] involves interpreting a natural language expression to localize specific objects within an image. Unlike open-vocabulary object detection [15, 26, 34, 42, 52, 60, 61, 69, 73, 78] or phrase grounding [18, 23, 31, 54, 68], which identify objects based on brief category names or short phrases, REC requires understanding complex, free-form descriptions. This task necessitates not only recognizing object attributes and relationships but also comprehending spatial configurations and interactions, making it inherently more challenging. In this work, we systematically analyze the referable entities and the critical characteristics that define this task.

REC Datasets and Benchmarks. The first large-scale Referring Expression Comprehension (REC) dataset, ReferItGame [29], was created through a two-player game in which one annotator describes an object, and another selects it. This was later followed by more sophisticated datasets [7, 13, 17, 19, 54, 55], such as RefCOCO [75], RefCOCO+ [75], and RefCOCOg [50], which leverage MSCOCO [37] images to provide more complex referring expressions. Beyond these general datasets, others address specific challenges. CLEVR-Ref+ [40] focuses on geometric object referring. RefCrowd [57] targets person detection in crowded scenes. Ref-L4 [8] handles longer and more detailed descriptions. GRES [77] introduces multi-target referring expression segmentation. However, existing datasets typically assume a one-to-one correspondence between a referring expression and a single instance, which fails to reflect real-world scenarios. To address this gap, we

domain	sub-domains	examples
attribute	gender, age, race, profession, posture, appearance, clothing and accessories, action	<i>male, female, white man, the police officer, person with a shocked expression, person wearing a mask, person standing</i>
position	inner position (human to human), outer position (human to environment)	<i>the second person from left to right, person at the right, person closest to the microphone, person sitting in the chair</i>
interaction	inner interaction (human with human), outer interaction (human with environment)	<i>two people holding hands, people locked in each other's gaze, the person holding a gun, person holding the certificate in hand</i>
reasoning	inner position reasoning, outer position reasoning, attribute reasoning	<i>all the people to the right of the person closest to the glass, person wearing a lab coat but not putting their hand on the board</i>
celebrity recognition	actor, character, athlete, entrepreneur, scientist, politician, singer	<i>Brad Pitt, Bruce Wayne, Cristiano Ronaldo, Rihanna, Elon Musk, Albert Einstein, Donald Trump</i>
rejection	attribute, position, interaction, reasoning	<i>a man in red hat, three women in a circle</i>

Table 1. The primary annotation domains and their corresponding sub-domains within HumanRef.

refine the referring task and introduce HumanRef, a dataset specifically designed to support multi-instance referring and advance research in this domain.

MLLM-based REC Methods Multimodal Large Language Models (MLLMs) [1–3, 14, 20, 32, 33, 35, 44, 47, 53, 64, 66, 70, 82] have demonstrated strong capabilities in both text and image comprehension, motivating efforts to integrate referring expression understanding into these models. A common approach involves outputting bounding box coordinates as tokens [3, 9, 14, 51, 67, 70, 74, 79, 80, 83]. Alternatively, methods like Groma [49] and ChatRex [25] frame detection as a retrieval task, where a proposal model generates bounding boxes, and the LLM selects the index of the relevant box based on the referring expression. While these MLLM-based methods achieve high performance on RefCOCO+/g, our experiments reveal that they remain inadequate for practical applications due to low recall rate on multi-instance referrals.

3. HumanRef Dataset

In this section, we present the design philosophy, data acquisition process, annotation pipeline, and dataset statistics of the proposed HumanRef dataset.

3.1. Data Design Philosophy

We define five key aspects that determine how humans can be referred to using natural language, including attribute, position, interaction, reasoning, and celebrity recognition. These categories are further elaborated with definitions and examples in Table 1. A key distinction between HumanRef and existing referring datasets is its focus on multi-instance referring rather than one-to-one object referring. Our dataset ensures that a single referring expression can correspond to multiple individuals, providing a more realistic and practical reflection of real-world scenarios.

3.2. Data Acquisition

The HumanRef dataset is designed to capture human presence across diverse contexts, including natural environments, industrial settings, healthcare, sports, films, animations, etc. To ensure dataset diversity, we sourced images

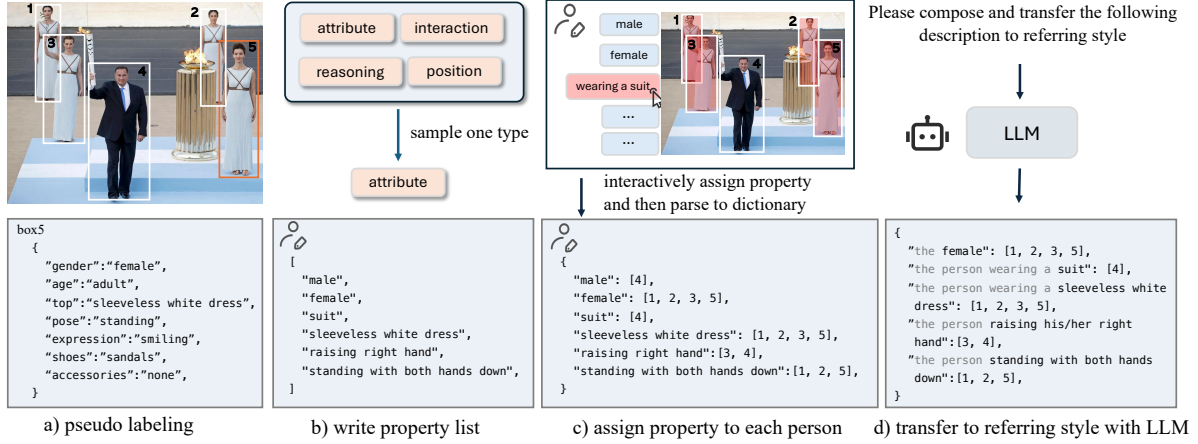


Figure 3. Overview of the manual annotation pipeline of the HumanRef dataset.

containing humans from the web image dataset [5]. To filter candidate images, we first retained those with a resolution larger than 1000×1000 pixels to ensure high-quality content. Next, we use an open-set object detector DINO-X [60] to detect human instances. To align with the multi-instance discrimination requirement, we retain only images containing at least four individuals.

To assist the annotator in writing properties, we prompt the QwenVL-2.5 [3] model to create a structured property dictionary for each person in the image, capturing details such as gender, clothing, actions, etc. Ultimately, this phase produced image, person box, and person description triples used for further annotation.

3.3. Manual Annotation

For attribute, position, interaction, and reasoning subsets, we adopt manual annotation. This annotation process consists of three main steps: property listing, property assignment, and referring style rewriting. Given an image, along with the corresponding person boxes and pre-labeled property dictionary, the annotation system will randomly select one annotation type from attribute, location, interaction, and reasoning to assign to the annotator. The following annotation process is then carried out:

Property Listing: The annotator examines all individuals in the image, considering both their visual appearance, action, position, interaction, and the pre-labeled property dictionary. Based on these observations, the annotator compiles a list of properties. To enhance dataset richness, annotators are encouraged to label attributes shared by multiple individuals while avoiding those common to all. Additionally, we monitor the word frequency of labeled referring expressions and restrict the use of high-frequency words to improve data diversity.

Property Assignment: Once the properties are listed, annotators systematically assign them to the correspond-

ing individuals. This interactive process involves selecting a property value and clicking on the associated bounding boxes to link it to the correct person. The final output is a structured dictionary, where keys represent property names and values contain lists of bounding box indices corresponding to the individuals possessing each property.

Referring Style Rewriting: In the final step, we prompt Qwen2.5-14B [71] to reformulate the structured attribute dictionary into short, natural language referring expressions. The final annotated data also undergoes a thorough review process to ensure its quality.

3.4. Automatic Annotation

For celebrity recognition and rejection referring, we employ two efficient and effective automatic annotation pipelines.

Celebrity Recognition: We first categorize celebrities into seven distinct fields: actors, film characters, athletes, singers, entrepreneurs, scientists, and politicians. For each field, we identify the most well-known individuals, compiling a final list of 636 names, which we then used as prompts to retrieve images via the Bing Search API. The collected images include both individual and group photos, necessitating a method to accurately associate each celebrity name with the correct person in the image. To achieve this, we first use the DINO-X [60] model to detect all human faces and persons, linking each detected face to its corresponding person box based on overlap measurements. If an image contains only one person, we assume this individual is the target celebrity. For images featuring multiple individuals, we use a Python face recognition library, leveraging a single-person image as a recognition template to match and identify the same person in such images.

Rejection Referring: The objective of this sub-dataset is to ensure that when a referring description targets a per-

<https://www.microsoft.com/en-us/bing/apis>
<https://github.com/ageitgey/facerecognition>

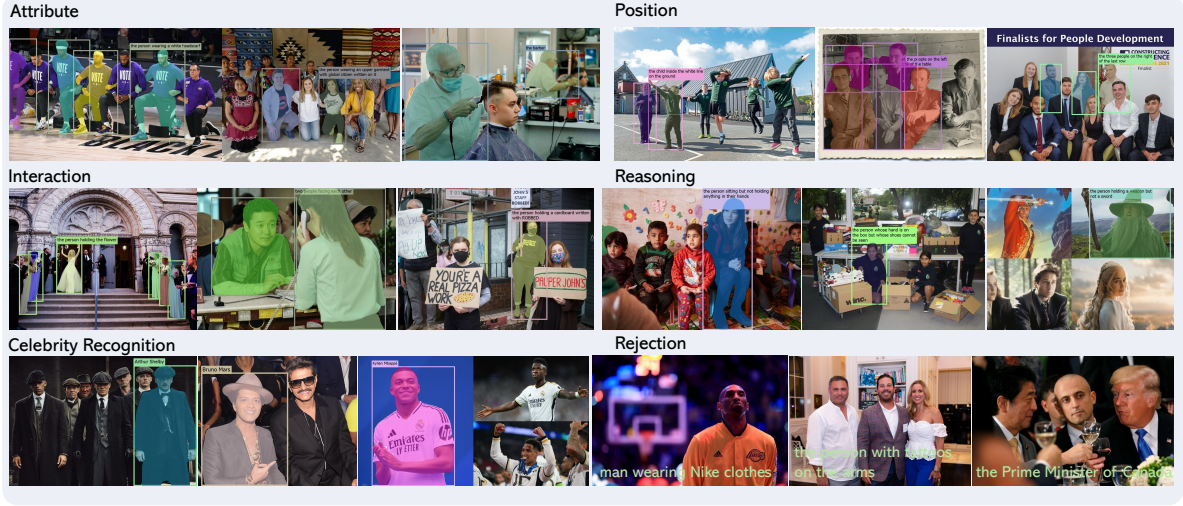


Figure 4. Visualization of the six subsets in the HumanRef Benchmark.

son who does not exist in the input image, the model rejects the referring request instead of hallucinating and outputting an incorrect bounding box. To construct this dataset, we first extract referring expressions from the attribute, position, interaction, and reasoning subsets. We then prompt Qwen2.5 [71] to modify these descriptions, transforming them into similar but semantically altered versions. For instance, a description such as “the person wearing a blue hat” may be changed to “the person wearing a red hat”. To validate the generated descriptions, we prompt Molmo [20] to detect the modified referring expression. If no matching object is found in the output, the data is retained.

3.5. HumanRef Benchmark

To construct the HumanRef Benchmark, we sample 1,000 referring expressions from each of the four manually annotated subsets. Additionally, for the celebrity and rejection subsets, we conduct a separate manual annotation process to create 1,000 new referring expressions for each category, ensuring high-quality and challenging evaluation data. To further support advancements in referring expression segmentation, we utilize SAM2 [59] to generate masks for each ground truth bounding box. Figure 4 presents example cases from the HumanRef Benchmark, illustrating the diversity and complexity of the dataset.

3.6. Statistics

We first present the basic statistics of the HumanRef dataset and its subsets in Table 2, and then illustrate the characteristics of multi-instance referring and multi-instance discrimination in HumanRef in Figure 5. Additionally, Table 3 compares the HumanRef Benchmark with widely used referring benchmarks, including RefCOCO, RefCOCO+, and RefCOCOg. A key distinction of HumanRef is its higher

HumanRef Train						
type	attribute	position	interaction	reasoning	celebrity	rejection
images	8,614	7,577	1,632	4,474	4,990	7,519
referrings	52,513	22,496	2,911	6,808	4,990	13,310
avg. boxes/ref	2.9	1.9	3.1	3.0	1.0	0

HumanRef Benchmark						
type	attribute	position	interaction	reasoning	celebrity	rejection
images	838	972	940	982	1,000	1,000
referrings	1,000	1,000	1,000	1,000	1,000	1,000
avg. boxes/ref	2.8	2.1	2.1	2.7	1.1	0

Table 2. Main statistics of the HumanRef dataset, including the number of images, the number of referring expressions, the average word count per referring expression, and the average number of instances associated with each referring expression.

Datasets	images	refs	vocabs	avg. size	avg. person/image	avg. words/ref	avg. boxes/ref
RefCOCO [75]	1,519	10,771	1,874	593x484	5.72	3.43	1
RefCOCO+ [75]	1,519	10,908	2,288	592x484	5.72	3.34	1
RefCOCOg [50]	1,521	5,253	2,479	585x480	2.73	9.07	1
HumanRef	5,732	6,000	2,714	1432x1074	8.60	6.69	2.2

Table 3. Comparison of the HumanRef Benchmark with RefCOCO+/g. For a fair comparison, we present only the statistics related to human referring in RefCOCO+/g.

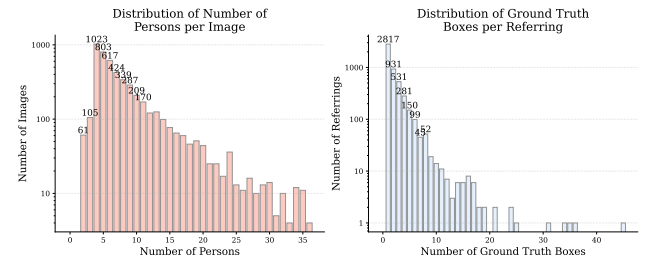


Figure 5. Distribution of the number of individuals per image and the number of individuals referenced by each referring expression.

image resolution and larger number of individuals per image, requiring models to precisely identify all correct individuals among multiple people. Unlike traditional benchmarks, where each referring expression corresponds to a

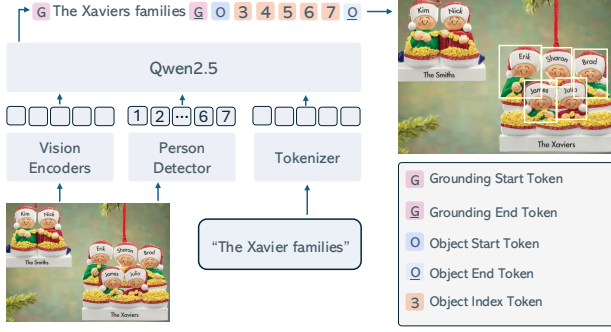


Figure 6. Overview of the RexSeek model. RexSeek is a retrieval-based model built upon ChatRex [25]. By integrating a person detection model, RexSeek transforms the referring task from predicting box coordinates to retrieving the index of input boxes.

single person, HumanRef supports multi-instance referring, offering a more realistic and challenging evaluation setting for referring expression comprehension.

4. RexSeek Model

4.1. Model Design Philosophy

From a model design perspective, we argue that a robust referring model should have two essential capabilities: **i) robust perception ability**, where the model can reliably detect all individuals in an image, and **ii) strong language comprehension**, where the model can accurately interpret complex natural language descriptions of people.

For the first capability, modern object detection models [26, 41, 60, 61] are highly effective at identifying people within images. However, these models often lack the necessary language comprehension abilities to process intricate and nuanced referring expressions. On the other hand, while MLLMs are proficient in understanding natural language, they often struggle with fine-grained object detection tasks. Inspired by ChatRex [25], we propose a hybrid framework, RexSeek, which integrates the strengths of both object detection models and LLMs. RexSeek combines a high-performance detection model with a multimodal LLM to achieve both accurate detection and effective language understanding.

4.2. Architecture

Following ChatRex, we formulate the referring task as a retrieval-based process [25, 49]. As illustrated in Figure 6, RexSeek consists of three main components: vision encoders, a person detector, and a large language model. Given an input image, we first pass it through a dual vision encoder module used in ChatRex. This module consists of a CLIP [58] to extract low-resolution image features \mathcal{F}_{low} and a ConvNeXt [43] to extract high-resolution image features $\mathcal{F}_{\text{high}}$. We adjust the input resolutions for both vision en-

coders to ensure they generate the same number of tokens at the last scale. The final vision tokens \mathcal{F} is obtained by concatenating these features at the channel dimension:

$$\mathcal{F} = \text{Concat}(\mathcal{F}_{\text{low}}, \mathcal{F}_{\text{high}})$$

Next, we prompt DINO-X [60] to get the bounding boxes of persons $\{B_i\}_{i=1}^K$ in the image. For each bounding box, we extract its RoI features \mathcal{C}_i and add their positional embeddings to generate object tokens \mathcal{O}_i , which capture both the content and spatial context of each detected person:

$$\mathcal{O}_i = \mathcal{C}_i + \text{PE}(B_i)$$

Specifically, the RoI feature is extracted from the high-resolution vision features using a multi-scale RoI Align operation [24]. The positional embedding is computed by encoding the bounding box coordinates (x, y, w, h) using a sinusoidal encoding function and concatenating the encoded values along the channel dimension.

Finally, the vision tokens \mathcal{F} , object tokens \mathcal{O} , and text tokens \mathcal{T} are projected using different MLPs and then fed into the LLM. By default, we use Qwen2.5 [71] as the LLM. The LLM decodes the input to produce the corresponding box indices \mathcal{I} :

$$\mathcal{I} = \text{LLM}(\mathcal{F}, \mathcal{O}, \mathcal{T})$$

The output \mathcal{I} consists of object indices that correspond to the bounding boxes of the target persons corresponding to the referring. This sequence is structured as follows:

`<g>referring</g><o><objm>...<objn></o>`

Here, `<objm>` and `<objn>` refer to specific object index tokens that correspond to the detected persons. The special tokens `<g>`, `</g>`, `<o>`, and `</o>` are used to format the output, linking the referring expression with the relevant object indices.

4.3. Four Stage Training

Similar to other VLMs, we adopt a pretraining followed by supervised fine-tuning approach [39]. Our training process consists of four stages. In the first stage, we align the visual and textual modalities using image-captioning data. In the second stage, we focus on perception training with detection-oriented data, enabling the model to retrieve relevant objects from input bounding boxes. In the third stage, we incorporate multimodal data to enhance the model’s general understanding abilities. Finally, in the fourth stage, we fine-tune the model using the HumanRef dataset, resulting in the final RexSeek model. The data, task, and trainable modules for each stage are shown in Table 5.

5. Experiments

In this section, we first introduce the evaluation metrics used in our study and assess the performance of multimodal models on HumanRef. We perform a comprehensive analysis to

Method	Attribute			Position			Interaction			Reasoning			Celebrity			Average			Rejection Score
	R	P	DF1	R	P	DF1	R	P	DF1	R	P	DF1	R	P	DF1	R	P	DF1	
Baseline†	100.0	37.2	24.2	100.0	28.5	15.9	100.0	32.5	19.4	100.0	42.6	30.3	100.0	14.4	4.9	100.0	31.0	18.9	0.0
DINOx [60]	59.5	28.8	20.9	78.8	28.1	17.6	67.3	28.5	18.9	76.2	32.1	22.2	94.1	48.0	37.0	75.2	33.1	23.3	36.0
InternVL-2.5-8B [14]	23.5	39.0	27.1	23.0	28.0	24.3	27.8	40.1	31.3	17.5	22.8	18.9	57.4	59.3	58.0	29.8	37.8	31.9	54.9
Ferret-7B [74]	27.9	44.4	30.4	30.2	36.2	29.8	30.8	41.8	31.2	19.7	33.7	22.8	63.2	60.0	57.5	34.4	43.2	34.3	2.0
Groma-7B [49]	67.5	47.8	38.6	63.2	43.1	37.2	66.6	48.1	40.6	59.1	41.4	34.8	73.2	63.3	59.1	65.9	48.7	42.1	0.0
ChatRex-7B [25]	44.3	78.0	51.8	48.0	66.7	52.5	49.6	74.8	56.5	36.6	65.1	42.8	73.7	76.5	74.2	50.4	72.2	55.6	0.0
Qwen2.5-VL-7B [3]	49.1	71.3	54.4	50.2	61.7	52.8	48.2	66.3	53.2	34.6	61.2	40.3	80.3	81.9	80.1	52.5	68.5	56.2	7.1
DeepSeek-VL2-small [70]	52.3	78.0	57.7	56.4	66.1	58.1	55.4	75.7	60.7	46.6	61.7	50.1	85.9	74.3	70.7	59.3	71.2	59.5	3.1
Molmo-7B-D* [20]	82.7	86.4	76.3	78.0	80.6	72.4	69.9	77.7	66.1	72.1	80.4	65.5	85.9	87.5	82.9	77.7	82.5	72.6	68.6
RexSeek-7B	87.2	86.8	81.5	86.1	86.3	83.8	84.8	84.6	80.7	87.8	84.7	81.5	83.4	86.5	84.2	85.9	85.8	82.3	54.1

Table 4. Benchmarking multimodal models on HumanRef Benchmark. R, P, and DF1 represent Recall, Precision, and DensityF1, respectively. † A simple baseline that uses the bounding boxes of all persons in the image as results, simulating a person detection model that does not follow the referring description. * Molmo-7B-D predicts point coordinates as output and use point-in-mask evaluation criteria.

Stage	Trainable Modules	Task	# Samples	Datasets
Stage1	MLPs	Image Captioning	976K	ALLAVA-4V-Caption [6]
Stage2	MLPs + LLM + Vision Encoders	Grounding & Region Understanding	2.07M	COCO [37], LVIS [22], O365 [62], Rexverse-2M [25]
Stage3	MLPs + LLM + Vision Encoders	General Knowledge & Grounding & Region Understanding	2.15M	LLAVA-665K [38] Rexverse-2M [25]
Stage4	MLPs + LLM + Vision Encoders	Referring	103K	HumanRef

Table 5. Data, task, and trainable modules for each stage.

explore the challenges faced by existing models in handling the referring task. Additionally, we perform ablation experiments on RexSeek for model design choices.

5.1. Metrics

We evaluate the referring task using Precision, Recall, and DensityF1 Score. Given a referring expression, the model predicts one or more bounding boxes, and a prediction is considered correct if its IoU with any ground truth box exceeds a predefined threshold. Following the evaluation protocol in COCO [37], we report the average performance across IoU thresholds from 0.5 to 0.95 in increments of 0.05. For models that only output points, such as Molmo [20], a prediction is considered correct if the predicted point falls within the mask of the corresponding instance. However, this evaluation is less strict than the IoU-based metric, as point-in-mask criteria impose looser spatial constraints, making direct comparisons less fair. For the rejection subset, we calculate the number of referring expressions that the model does not predict any boxes and divide it by the number of total expressions.

To penalize models that indiscriminately detect all persons in an image to achieve a high F1 score through high recall, we introduce the DensityF1 Score, which modifies the standard F1 Score with a density-aware penalty:

$$\text{DensityF1} = \frac{1}{N} \sum_{i=1}^N 2 \times \frac{\text{Precision}_i \times \text{Recall}_i}{\text{Precision}_i + \text{Recall}_i} \times D_i \quad (1)$$

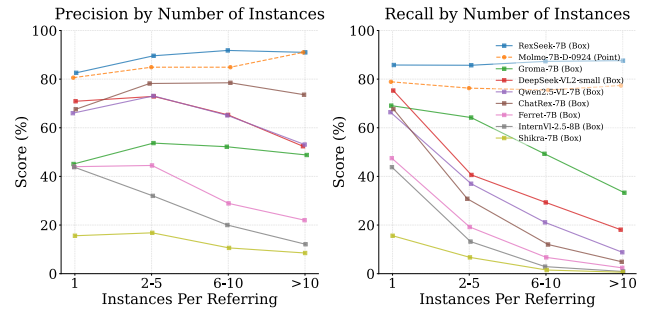


Figure 7. Visualizing the trend of recall and precision variations across different models as the number of instances corresponding to each referring expression increases.

where D_i is the density penalty factor, defined as:

$$D_i = \min(1.0, \frac{\text{GT Count}_i}{\text{Predicted Count}_i}) \quad (2)$$

Here, GT Count is the total number of persons in an image, and Predicted Count is the number of predicted boxes for a given referring expression. This penalty discourages over-detection by reducing the score when the predicted box count significantly exceeds the ground truth count.

5.2. Benchmarking on HumanRef

In Table 4, we evaluate the performance of various multimodal models on the HumanRef benchmark. While these models perform well on the widely used RefCOCO, RefCOCO+, and RefCOCOg benchmarks, their performance significantly degrades on HumanRef. Our analysis reveals two common issues among these models:

Low Recall for Multi Instance: We observe a common issue among most models: when a referring expression corresponds to multiple instances, recall drops significantly, as shown in Figure 7. This suggests that when multiple objects need to be detected, most models tend to predict only a few bounding boxes, limiting their applicability in real-world scenarios. A key factor contributing to this behavior is the nature of the training data. Most multimodal models are trained on RefCOCO, RefCOCO+, and RefCOCOg,

Model	With Rejection Data	Rejection Score
RexSeek-7B	No	0
RexSeek-7B	Yes	541

Table 6. Rejection score comparison under different model scales with and without rejection data during training.

Loading Stage	HumanRef Average		
	R	P	DF1
stage1	73.9	73.5	68.2
stage2	77.0	77.3	72.2
stage3	77.9	78.0	73.0

Table 7. Ablation experiments on multi-stage training by loading models from different training stages and fine-tuning them on the HumanRef dataset. We Qwen2.5-3B as the base LLM.

Method	RefCOCOg	
	val	test
Shikra-7B [9]	82.3	82.2
InternVL2-8B [14]	82.7	82.7
Grounding DINO-L [42]	86.1	87.0
Qwen2.5-VL-7B [3]	87.2	87.2
MM1.5-7B [82]	-	87.1
ChatRex-7B [25]	88.8	88.6
RexSeek-7B	84.0	84.4

Table 8. Zero-shot evaluation of RexSeek on RefCOCOg. We use the open-set detector DINO-X to detect the subject object in the image and use the detected bounding box as input to RexSeek.

where referring expressions rarely correspond to multiple instances. As a result, these models become biased toward single-instance predictions. In contrast, RexSeek has been trained on datasets that explicitly include multi-instance referring expressions, demonstrate a significantly improved ability to handle these real-world cases.

Hallucination Issue: On the rejection subset, we observe that most models perform poorly with low rejection score. This indicates that regardless of whether the referred object is actually present in the image, these models tend to predict a bounding box, exhibiting a severe hallucination issue. In real-world referring applications, such as referring in video streams, it is crucial for models to accurately determine whether the specified object exists in the image. Additionally, we find that the rejection capability can be significantly improved by incorporating appropriate training data. As shown in Table 6, when trained without the rejection data in HumanRef, RexSeek also demonstrates strong hallucination tendencies. This highlights the critical role of dataset design in the referring task, as inadequate dataset construction can lead to overconfident predictions.

5.3. Ablations on RexSeek

Ablation of Multi-stage Training: We analyzed the impact of the four-stage training approach used in RexSeek. As shown in Table 7, we conducted supervised fine-tuning on the HumanRef dataset after each training stage. The re-



Figure 8. RexSeek can refer to arbitrary objects beyond person.

sults demonstrate that the model achieves its best performance after undergoing SFT with general multimodal data (LLaVA-665K [38]). We attribute this improvement to the model acquiring richer general knowledge from multimodal data, which enhances its ability to accurately refer to persons in complex scenarios.

Generalization to Any Object Referring: Although RexSeek is trained exclusively on human-related referring data, we find that it also demonstrates the ability to refer to arbitrary objects. We first evaluate the performance of RexSeek on RefCOCOg. Given a referring expressions, we apply DINO-X to detect the main object in the image, using the detected bounding box as input to RexSeek. As shown in Table 8, RexSeek achieves competitive performance on RefCOCO+/g, despite not being explicitly trained on general object referring. Additionally, Figure 8 presents visualizations illustrating that RexSeek can also detect multiple instances even for non-human objects. We attribute this generalization ability to our multi-stage training approach, where perception and multimodal understanding training develop object comprehension, and fine-tuning on HumanRef effectively extends it to arbitrary objects.

6. Conclusion

In this work, we identify the fundamental limitations of existing referring datasets and models, demonstrating that they fail to meet real-world application demands, particularly in multi-instance referring. To address this, we introduce HumanRef, a large-scale benchmark reflecting real-world complexity, and propose RexSeek, a retrieval-based detection MLLM integrating person detection with a language model. Our multi-stage training approach equips RexSeek with strong generalization capabilities, allowing it to excel in human-centric referring while extending effectively to arbitrary object referring. Extensive evaluations highlight the struggles of state-of-the-art models with multi-instance detection and hallucination, underscoring the importance of dataset design and training strategies for more reliable and generalizable referring expression models.

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