A Simple yet Mighty Hartley Diffusion Versatilist for Generalizable Dense Vision Tasks

Supplementary Material

7. More Visual Prediction Results

Fig. 8, Fig. 9 and Fig. 10 provides more visual prediction results between the proposed `HarDiff` and some state-of-the-art methods, on various unseen target domains. The proposed `HarDiff` shows a more robust prediction on each of the three dense vision tasks.
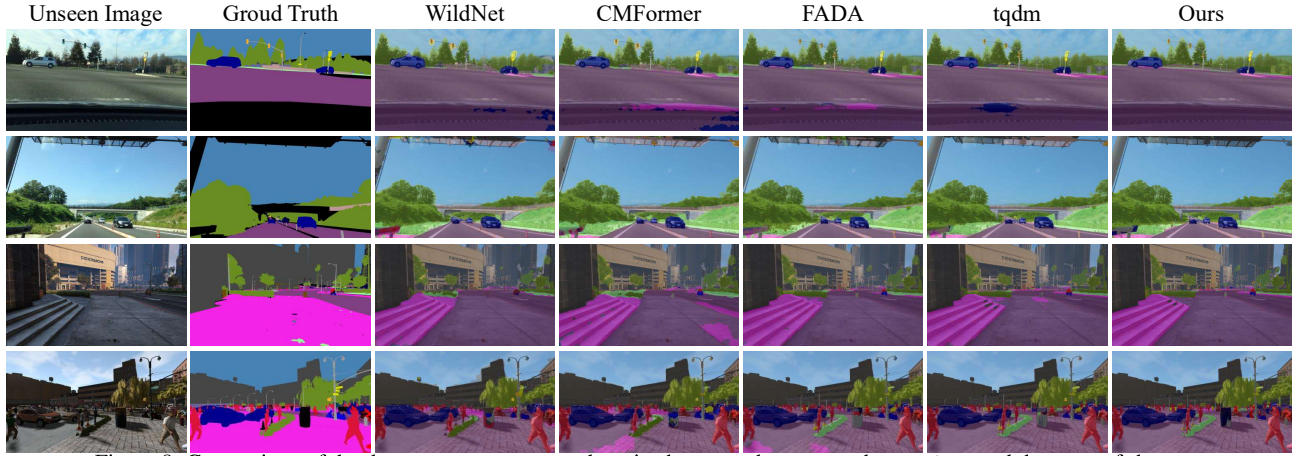
Figure 8. Comparison of the dense on unseen target domains between the proposed `HarDiff` and the state-of-the-art.
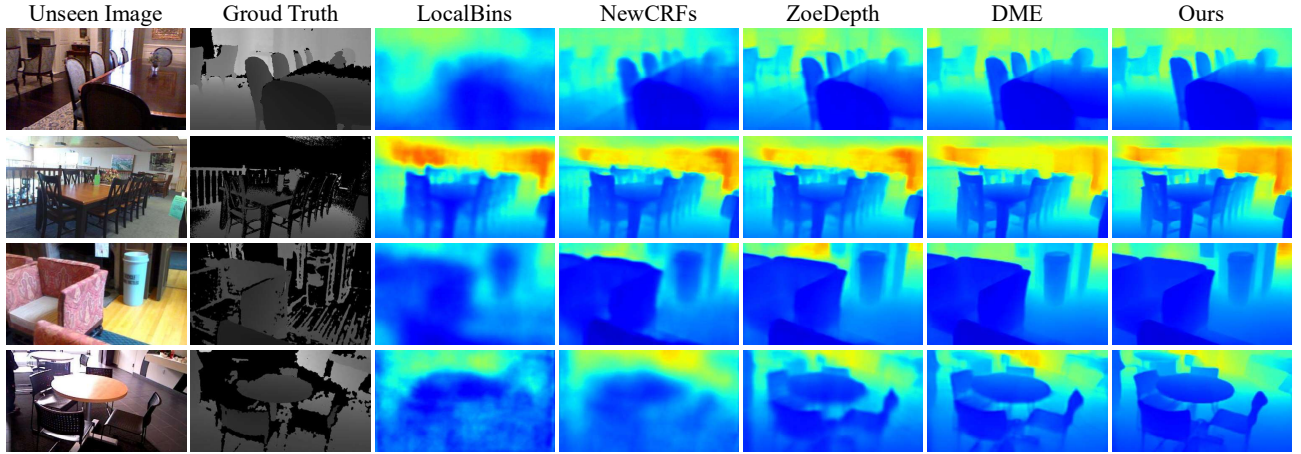

Figure 9. Comparison of the depth estimation map on unseen target domains between the proposed `HarDiff` and the state-of-the-art methods.
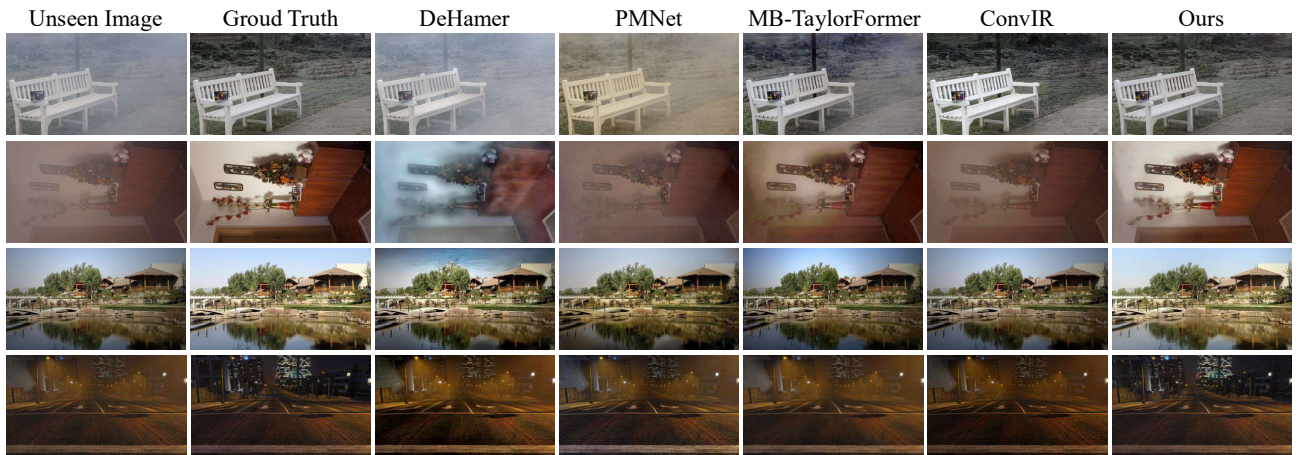

Figure 10. Comparison of the haze removal map on unseen target domains between the proposed `HarDiff` and the state-of-the-art methods.