Unfolding-Associative Encoder-Decoder Network with Progressive Alignment for Pansharpening

Supplementary Material

Overview

All source code will be made publicly available for further research.

In this supplementary material, we present more details about our study, including:

- Sec. 1 provides the mathematical model of UED-Net based on C-SALSA solver.
- Sec. 2 delves into the our configuration of UED-Net to reproduce the experimental results presented in this paper.
- Sec. 3 contains additional comparisons with state-of-theart (SOTA) methods.
- Sec. 4 discusses more extensive ablation studies, which include the effects of the number of stages (Sec. 4.1) and different cross-stage interactions (Sec. 4.2).

1. C-SALSA for UED-Net

1.1. Model Formulation

We design the architecture of UED-Net based on the C-SALSA solver, which effectively decouples mixed constraints to optimize the high-resolution multispectral (HRMS) image processing. To reiterate the description in the main paper, the recovery of **H** from **L** and **P** is modeled using the mathematical formula of the deep unfolding network in UED-Net as follows:

$$\mathbf{H} \in \underset{\mathbf{H}}{\operatorname{arg\,min}} ||F_{Ge}(\mathbf{H}) - \mathbf{L}|| + |F_{Se}(\mathbf{H}, \mathbf{L})| + ||F_{Ga}(\mathbf{H}) - \mathbf{P}|| + |F_{Sa}(\mathbf{H}, \mathbf{P})|,$$

$$(1)$$

where ||*|| term represents the global degradation-aware fidelity component constrained by the ℓ_2 -norm, reflecting the HRMS image's global perception of spatial and spectral modalities, while, the |*| term, constrained by the ℓ_1 -norm, is designed to capture sparse multi-scale prior information. Together, these terms jointly capture comprehensive degradation patterns perceived from the LRMS and PAN images, whose specific forms of these terms are defined in Eq. (13) and Eq. (14) of the main paper.

Next, we solve the constrained problem based on the C-SALSA algorithm. First, by introducing auxiliary variables V_{Ge} , V_{Se} , V_{Ga} , and V_{Sa} , we split the mixed regularization terms in Eq. (1). This reformulation leads to a new constrained optimization problem:

$$\mathbf{H} \in \underset{\mathbf{H}}{\operatorname{arg \, min}} ||\mathbf{V}_{Ge}|| + |\mathbf{V}_{Se}| + ||\mathbf{V}_{Ga}|| + |\mathbf{V}_{Sa}|,$$

$$\operatorname{s.t.} \mathbf{V}_{Ge} = F_{Ge}(\mathbf{H}) - \mathbf{L}, \mathbf{V}_{Se} = F_{Se}(\mathbf{H}, \mathbf{L}),$$

$$\mathbf{V}_{Ga} = F_{Ga}(\mathbf{H}) - \mathbf{P}, \mathbf{V}_{Se} = F_{Sa}(\mathbf{H}, \mathbf{P}).$$
(2)

Subsequently, we apply the Augmented Lagrangian (AL) method to incorporate penalty terms into the Eq. (2),

transforming it into the following equivalent iterative optimization problem:

$$(\mathbf{H}^{(k)}, \mathbf{V}_{Ge}^{(k)}, \mathbf{V}_{Ga}^{(k)}, \mathbf{V}_{Se}^{(k)}, \mathbf{V}_{Sa}^{(k)}) |\mathbf{V}_{Se}^{(k)}| + |\mathbf{V}_{Sa}^{(k)}| + ||\mathbf{V}_{Ge}^{(k)}|| + ||\mathbf{V}_{Ga}^{(k)}|| + ||\mathbf{V}_{Ga}^{(k)}|| + ||\mathbf{V}_{Ga}^{(k)}|| + ||\mathbf{F}_{Ga}(\mathbf{H}^{(k)}) - \mathbf{P} - \mathbf{V}_{Ga}^{(k)} - \mathbf{W}_{Ga}^{(k)}|| + ||\mathbf{F}_{Sa}(\mathbf{H}^{(k)}, \mathbf{P}) - \mathbf{V}_{Sa}^{(k)} - \mathbf{W}_{Sa}^{(k)}|| + ||\mathbf{F}_{Ge}(\mathbf{H}^{(k)}) - \mathbf{L} - \mathbf{V}_{Ge}^{(k)} - \mathbf{W}_{Ge}^{(k)}|| + ||\mathbf{F}_{Se}(\mathbf{H}^{(k)}, \mathbf{L}) - \mathbf{V}_{Se}^{(k)} - \mathbf{W}_{Se}^{(k)}||,$$

$$(3)$$

where $k \in \{0, 1, ..., N\}$ and N denotes the maximum number of iterations. $\mathbf{W}_{Ge}^{(k)}, \mathbf{W}_{Ga}^{(k)}, \mathbf{W}_{Se}^{(k)}, \text{and} \mathbf{W}_{Sa}^{(k)}$ are the Lagrange multipliers, which store the residuals between hierarchical iterative features and are updated in the k^{th} iteration through the following equation:

$$\mathbf{W}_{Ge}^{(k)} = \mathbf{W}_{Ge}^{(k-1)} + \mathbf{f}_{Ge}^{(k)} - \mathbf{V}_{Ge}^{(k-1)},$$

$$\mathbf{W}_{Ga}^{(k)} = \mathbf{W}_{Ga}^{(k-1)} + \mathbf{f}_{Ga}^{(k)} - \mathbf{V}_{Ga}^{(k-1)},$$

$$\mathbf{W}_{Se}^{(k)} = \mathbf{W}_{Se}^{(k-1)} + \mathbf{f}_{Se}^{(k)} - \mathbf{V}_{Se}^{(k-1)},$$

$$\mathbf{W}_{Sa}^{(k)} = \mathbf{W}_{Sa}^{(k-1)} + \mathbf{f}_{Ge}^{(k)} - \mathbf{V}_{Sa}^{(k-1)},$$

$$(4)$$

where $(\mathbf{f}_{Ge}^{(k)}, \mathbf{f}_{Se}^{(k)})/(\mathbf{f}_{Ga}^{(k)}, \mathbf{f}_{Sa}^{(k)})$ represent the feature representations of the spectral/spatial modalities of the global degradation-aware fidelity and sparse multi-scale prior at the k^{th} stage. Similarly, their specific formulations can be found in Eq. (13) and (14) of the main paper.

1.2. Model Solution

Direct solving Eq. (3) is challenging due to inseparable quadratic terms and non-smooth components. To address this, we decouple the mixed constraints, enabling us to minimize three sub-problems alternately, which include the fidelity terms $(\mathbf{V}_{Ge}^{(k)}, \mathbf{V}_{Ga}^{(k)})$, the sparse prior terms $(\mathbf{V}_{Se}^{(k)}, \mathbf{V}_{Sa}^{(k)})$, and their integration into $\mathbf{H}^{(k)}$.

Update of $(\mathbf{V}_{Se}^{(k)}, \mathbf{V}_{Sa}^{(k)})$: We separate the sparse multiscale prior terms from Eq. (3), formulating it as a Lasso problem expressed as follows:

$$\mathbf{V}_{Se}^{(k)} \in \underset{\mathbf{V}_{Se}}{\arg\min} \ |\mathbf{V}_{Se}| + ||\mathbf{V}_{Se} + \mathbf{f}_{Se}^{(k)} + \mathbf{W}_{Se}^{(k-1)}||,$$

$$\mathbf{V}_{Sa}^{(k)} \in \underset{\mathbf{V}_{Se}}{\arg\min} \ |\mathbf{V}_{Sa}| + ||\mathbf{V}_{Sa} + \mathbf{f}_{Sa}^{(k)} + \mathbf{W}_{Sa}^{(k-1)}||.$$
(5)

To solve this problem effectively and promote sparsity in multi-scale features, we employ the soft-thresholding shrinkage [3] method:

$$\mathbf{V}_{Se}^{(k)} = S_{\epsilon_e}(\mathbf{f}_{Se}^{(k)} + \mathbf{W}_{Se}^{(k-1)}),$$

$$\mathbf{V}_{Sa}^{(k)} = S_{\epsilon_a}(\mathbf{f}_{Sa}^{(k)} + \mathbf{W}_{Sa}^{(k-1)}),$$
(6)

where ϵ_e and ϵ_a are randomly initialized and stage-wise learnable parameters, which control the sparsity enforced

by shrinkage to reduce noise introduced by multi-scale sampling and enhance the representation of multi-scale details. For any ϵ , the $S_{\epsilon}(*)$ is defined as:

$$S_{\epsilon}(*) = \operatorname{sgn}(*) \cdot \max(|*| - \epsilon, 0). \tag{7}$$

Update of $(\mathbf{V}_{Ge}^{(k)}, \mathbf{V}_{Ga}^{(k)})$: Similarly, we decouple the global degradation-aware data fidelity terms from Eq. (3), which are formulated with ℓ_2 constraints, encourage smooth degradation representation:

$$\mathbf{V}_{Ge}^{(k)} \in \underset{\mathbf{V}_{Ge}}{\arg\min} \ ||\mathbf{V}_{Ge}|| + ||\mathbf{V}_{Ge} + \mathbf{f}_{Ge}^{(k)} + \mathbf{W}_{Ge}^{(k-1)}||,$$

$$\mathbf{V}_{Ga}^{(k)} \in \underset{\mathbf{V}_{Ga}}{\arg\min} \ ||\mathbf{V}_{Ga}|| + ||\mathbf{V}_{Ga} + \mathbf{f}_{Ga}^{(k)} + \mathbf{W}_{Ga}^{(k-1)}||,$$
(8)

The approximate solutions for $\mathbf{V}_{Ge}^{(k)}$ and $\mathbf{V}_{Ga}^{(k)}$ correspond to orthogonal projections onto an ℓ_2 ball of sufficiently small radius [1], expressed as:

$$\mathbf{V}_{Ge}^{(k)} = \mathbf{V}_{Ge}^{(k-1)} + \frac{\mathbf{f}_{Ge}^{(k)} + \mathbf{W}_{Ge}^{(k-1)}}{\|\mathbf{f}_{Ge}^{(k)} + \mathbf{W}_{Ge}^{(k-1)}\|},$$

$$\mathbf{V}_{Ga}^{(k)} = \mathbf{V}_{Ga}^{(k-1)} + \frac{\mathbf{f}_{Ga}^{(k)} + \mathbf{W}_{Ga}^{(k-1)}}{\|\mathbf{f}_{Ga}^{(k)} + \mathbf{W}_{Ga}^{(k-1)}\|}.$$
(9)

In the DUN context, we apply learnable normalization to enhance the generalization of this process:

$$\mathbf{V}_{Ge}^{(k)} = \mathbf{V}_{Ge}^{(k-1)} + GN_1(F_{Ge}(\mathbf{H}^{(k-1)}, \mathbf{L}) + \mathbf{W}_{Ge}^{(k-1)}),$$

$$\mathbf{V}_{Ga}^{(k)} = \mathbf{V}_{Ga}^{(k-1)} + GN_1(F_{Ga}(\mathbf{H}^{(k-1)}, \mathbf{L}) + \mathbf{W}_{Ga}^{(k-1)}),$$
(10)

where GN_1 represents the normalization with the number of groups being 1.

Updata of H^(k): We regard updated auxiliary variables as constants and decouple the data terms about H from Eq. (3), establishing $\mathbf{H}^{(k)}$:

$$\mathbf{H}^{(k)} \in \underset{\mathbf{H}}{\operatorname{arg \, min}} ||F_{Ga}(\mathbf{H}^{(k)}) - \mathbf{P} - \mathbf{V}_{Ga}^{(k)} - \mathbf{W}_{Ga}^{(k)}||$$

$$+ ||F_{Sa}(\mathbf{H}^{(k)}, \mathbf{P}) - \mathbf{V}_{Sa}^{(k)} - \mathbf{W}_{Sa}^{(k)}||$$

$$+ ||F_{Ge}(\mathbf{H}^{(k)}) - \mathbf{L} - \mathbf{V}_{Ge}^{(k)} - \mathbf{W}_{Ge}^{(k)}||$$

$$+ ||F_{Se}(\mathbf{H}^{(k)}, \mathbf{L}) - \mathbf{V}_{Se}^{(k)} - \mathbf{W}_{Se}^{(k)}||.$$
(11)

The Eqs. (5) to (10) in UED-Net is outlined as encoding the degraded pattern, while Eq. (11) can be solved using a gradient descent, which is summarized as the following decoding.

We first further combine the spatially and spectrally degradation-aware auxiliary variables to obtain the feature representations of the degradation pattern at this stage, $\mathbf{f}_{spe}^{(k)}$ and $\mathbf{f}_{spa}^{(k)}$, as described in Eq. (19) and (4) of the main paper.

Next, we employ PGAM to calibrate the spatial offsets of $\mathbf{f}_{spe}^{(k)}$ and $\mathbf{f}_{spa}^{(k)}$, regulating the spatial/spectral distributions at this stage to obtain the $\mathbf{f}_{mm}^{(k)}$, as detailed in Eq. (5)-(8) of the main paper.

Furthermore, we utilize the customized UAAM to capture cross-stage feature interactions, mitigating noise accumulation across stages to obtain the $\mathbf{f}_s^{(k)}$, as described in Eq. (9).

Finally, we adaptively perceive the iteration step size and the gradient descent feature representation $\nabla \mathbf{H}^{(k-1)}$ using Eq. (10)-(12) of the main paper, and reconstruct the HRMS at the k^{th} stage using the following general gradient descent formulation:

$$\mathbf{H}^{(k)} = \mathbf{H}^{(k-1)} + \nabla \mathbf{H}^{(k-1)}. \tag{12}$$

2. More Model Reproducible Details

Table 1. Training parameters and model configuration.

Configurations	Default Settings					
Base Learning Rate	5×10^{-4}					
Min Learning Rate	5×10^{-8}					
Optimizer	ADAM					
Weight Decay	0					
Optimizer Momentum	0.9,0.999					
Batch Size	4					
Training Epochs	<1000					
Learning Rate Schedule	Cosineannealing					
Number of Head (T)	4					
Number of Stages (N)	7					
Hidden Layer Dimensions (S)	16					
Convolution Initialization	Kaiming					
$\mu_w^{(s)}, s \in \{1, \dots, S\}$	$8 \cdot (\frac{k}{S-1})^{1.35} - 5$					
$\mu_u^{(s)}, s \in \{1, \dots, S\}$	$log(0.3) + \frac{((k+1)\%3-1)}{2}$					
$(\mathbf{V}_{ii}^{(0)}, \mathbf{W}_{ii}^{(0)}), ii \in \{Ge, Ga, Se, Sa\}$	Zero Matrix					
Other Learnable Parameters	torch.randn					
Implementation	PyTorch 2.5.1					
CPU	Intel i5-10600KF					
GPU	NVIDIA GeForce RTX 4090					

We use UED-Net with 7 reconstruction stages (N=7) and 16 hidden layers (S=16) as the default model, which is derived from the ablation study on the number of stages in Sec. 4. UED-Net upscales the LRMS using bicubic interpolation to initialize $\mathbf{H}^{(0)}$. Additionally, the learnable auxiliary parameters in the UAAM are initialized as described in the RWKV [10]. The auxiliary iterative variables in the SSEM are initialized as zero matrices. Other learnable parameters are initialized with random values from a normal distribution within the range [0,1]. We summarize the key training parameters and model configurations in Tab. 1 for a better understanding of our approach.

Based on this experimental configuration, the default UED-Net requires approximately 35 milliseconds for inference on a multispectral image with 4 bands and a spatial size of 128×128 .

The supplementary materials include source code and detailed experimental settings required to replicate the findings outlined in this paper. Additionally, the source code will be made publicly available to enhance accessibility and promote reproducibility.

Table 2. Comparison of UED-Net with other methods in simulated tests on reduced-resolution data, with the best result highlighted in bold red and the second best result highlighted in blue.

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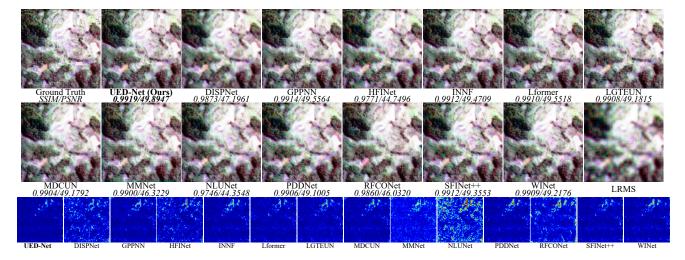


Figure 1. Visual comparison of UED-Net with other methods in simulated tests on GaoFen-2.

3. More Comparisons with SOTA Methods

In the main body of this paper, we compare the proposed UED-Net with various representative pansharpening methods, which are configured according to the best settings reported in their respective papers, including (SHIP-Net++ [20], CANNet [4], SFINet++ [19], HFINet [12], WINet [17], PDDNet [5], INNF [18], LFormer [6], and RF-CONet [11]), (MMNet [15], DISPNet [13], NLUNet [8], LGTEUN [8], MDCUN [16], and GPPNN [14]). In this subsection, we further highlight the significant advantages of UED-Net over these methods and provide a comparison with traditional methods (GSA [2], SFIM [9], Wavelet [7]). Additionally, we present a performance comparison of UED-Net under different representative configurations. In Tab. 2, we present the results of the further sim-

ulation tests, with the best, and second-best performances marked in red, and blue, respectively. The various configurations of UED-Net show significant performance improvements across three datasets. Specifically, on the GaoFen-2 dataset, UED-Net achieves a 0.2048 dB improvement in PSNR over the second-best algorithm, SFINet++; on the WorldView-II dataset, it outperforms the second-best algorithm, LGTEUN, by 0.0486 dB in PSNR; and on the WorldView-III dataset, UED-Net shows a 1.1849 dB improvement in PSNR compared to the second-best algorithm, DISPNet. These results indicate that our proposed method is not dataset-dependent and demonstrates reliable scalability generalization capability.

Furthermore, we present supplementary results on real test in Tab. 3, where our default UED-Net configuration

Table 3. Comparison of UED-Net with other methods in real tests on GaoFen-2 full-resolution data.

Metrics	Tradi	tional M	ethods	hods Pure DL-Based Methods											Deep Unfolding Methods				
Metrics	GSA	SFIM	Wavelet	SHIP++	SFINet++	HFINet	WINet	CANNet	LFormer	RFCONet	PDDNet	INNF	DISPNet	NLUNet	LGTEUN	MMNet	MDCUN	GPPNN	UED-Net
$D_{\lambda} \downarrow$	0.17344	0.16949	0.33271	0.07208	0.07836	0.09837	0.11871	0.07476	0.08352	0.25559	0.07984	0.07080	0.08068	0.07628	0.11336	0.07182	0.07649	0.09124	0.06801
$D_s \downarrow$	0.44336	0.30266	0.40957	0.09838	0.08855	0.08491	0.08273	0.09752	0.08593	0.13758	0.10634	0.10758	0.08224	0.10741	0.17165	0.17053	0.08860	0.09485	0.07011
$QNR\uparrow$	0.46010	0.57915	0.39399	0.84930	0.84003	0.82506	0.80838	0.83502	0.83773	0.64309	0.82231	0.82923	0.84371	0.82450	0.73445	0.76990	0.84168	0.82257	0.86665

Table 4. Ablation of the stage number.

Num of Stage	3	5	7 (Defult)	9	11	13
$\begin{array}{c} SSIM \!\!\uparrow \\ PSNR \!\!\uparrow \\ QNR \!\!\uparrow \end{array}$	0.9906	0.9907	0.9910	0.9910	0.9910	0.9910
	49.3232	49.3721	49.5648	49.5254	49.5032	49.5121
	0.7756	0.8083	0.8666	0.8645	0.8639	0.8652
FLOPs	1.0756	1.7927	2.5097	3.2268	3.9439	4.6609
Params	0.0721	0.1202	0.1682	0.2163	0.2643	0.3124

continues to exhibit superior performance, particularly in terms of QNR metrics and maintaining a balanced hardware load. Additionally, compared to DUN-based methods, our method incurs the lowest computational cost.

Finally, we include a visual comparison on the GaoFen-2 dataset for simulated tests, as shown in Fig. 1, highlighting both the reconstruction details and visualizations of the mean squared error (MSE). Notably, the comparisons further confirm that our method outperforms other algorithms across multiple scenarios, while offering a competitive performance-to-computation-cost ratio comparable to pure deep learning methods. This validates our hypothesis on the importance of effective cross-modal and cross-stage interactions at different abstraction levels in successful pansharpening.

4. More Ablation Studies

4.1. Number of Stages

We conduct an ablation study on the GaoFen-2 dataset to investigate how the performance of UED-Net varies with computational cost. As shown in Fig. 1 of main papet and Tab. 4, performance improves as we increase the number of stages. We observe that both performance and cost increase significantly with the number of stages. At 7 iterations, we achieve an impressive PSNR of 49.5648 dB in simulated tests and the highest QNR in real tests. After this point, the performance continues to improve slightly in simulated tests but shows some fluctuation. Additionally, we present the results for 9 and 11 stages in WorldView-II and WorldView-III tests, as shown in Tab. 2. Based on the performance-cost trade-off, we use 7 iterations stages as the default configuration for UED-Net.

4.2. Cross-stage feature interactions

Building on the ablation study of the UAAM presented in Sec. 4.2 of main paper, we further investigate the benefits of

Table 5. Ablation of cross-stage feature interactions.

			Simulat	ed Tests	I	Real Tes					
Method	(C	aoFen-2	2)	(Wo	rldView	-II)	(GaoFen-2)			Calculate Costs	
	ERGAS↓	SSIM↑	PSNR↑	ERGAS↓	SSIM↑	PSNR↑	$D_{\lambda} \downarrow$	$D_s \downarrow$	$QNR\uparrow$	FOLPs	Params
Net1	0.4616	0.9896	48.8597	0.8825	0.9718	42.2939	0.0680	0.0768	0.8604	1.5051	0.1065
Net2	0.4462	0.9901	49.1483	0.8623	0.9721	42.4275	0.9791	0.0100	0.8359	6.7954	0.4294
Net3	0.4443	0.9902	49.2000	0.8593	0.9723	42.4554	0.0797	0.1522	0.7802	3.6190	0.2364
Defult	0.4268	0.9910	49.5648	0.8349	0.9739	42.7251	0.0680	0.0701	0.8666	2.5097	0.1682

associative attention as a cross-stage interaction mechanism within our proposed UAAM by substituting it with various cross-stage interaction methods. Specifically, Net1 serves as a baseline network without any cross-stage interaction. For Net2, we implement the method proposed in MDCUN [16], which utilizes stacked intermediate variables. For Net3, we employ the LSTM-like stage interaction method outlined in MMNet [15]. As demonstrated in Tab. 5, our method outperforms Net1, Net2, and Net3 across all evaluation metrics, not only in the simulated tests of GaoFen-2 and WorldView-II but also in real tests, while maintaining superior computational efficiency.

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