SUV: Suppressing Undesired Video Content via Semantic Modulation Based on Text Embeddings Supplementary

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Overview

In this supplementary material, we provide more implementation details and results comparison. Specifically, Sec. A elaborates on the specific implementation details of the our proposed SUV method. Subsequently, Sec. B presents more quantitative comparisons with existing methods, demonstrating the superiority of our method in terms of alignment quality and efficiency. Then, Sec. C provides additional qualitative results with existing methods in qualitative aspects, demonstrating the advancement of our method in terms of visual quality, editing accuracy, and temporal consistency. Finally, more visualizations of the results of the ablation study and hyperparameter study are presented are presented in Sec. D.

A. More Implementation Details

Additional Setup Details. Our experiments are implemented with the Pytorch framework on a NVIDIA RTX A6000 GPU. To demonstrate our method more clearly, Algorithm 1 describes the specific framework of our method. Evaluation Metrics. The automatic metrics are based on pre-trained CLIP models. Specifically, Temporal Consistency evaluates the temporal consistency of the edited frames by calculating the cosine similarity between successive frame pairs. Frame Accuracy measures the editing accuracy for each frame, i.e., whether the CLIP similarity between the edited image and the target prompt is higher than that with the source image. Meanwhile, to further assess text-image alignment quality, we adopt *PickScore* [4], which quantifies how well a generated image semantically matches the input text prompt. The user study includes four metrics: Editing Accuracy, Aesthetics Quality, Tem-

Algorithm 1: Algorithm of SUV.

```
Input: Source video V_{src}, Source text prompt P_{src}
                   and Target text prompt \mathcal{P}_{edit}.
  1 C_{src} = Text Encoder (P_{src}),
  2 z_0 = Image Encoder (\mathcal{V}_{src});
  3 DDIM inversion for latents z_0:
  4 for t = 1, 2, ..., T do
           \epsilon_t \leftarrow \epsilon_{\theta}(z_{t-1}, t, \mathcal{P}_{src}),
z_t = \sqrt{\alpha_t} \frac{z_{t-1} - \sqrt{1 - \alpha_{t-1}} \epsilon_{t-1}}{\sqrt{\alpha_{t-1}}} + \sqrt{1 - \alpha_t} \epsilon_t.
  8 \hat{z_T} = z_T.
  9 Dividing \hat{z_t} into m video groups \{V_1, \dots, V_m\};
10 C = \text{Text Encoder } (\mathcal{P}_{edit}), \hat{C} = \text{ES-Operato } (C);
11 for t = T, ..., 1 do
             \mathcal{X}_{FF}, \hat{\mathcal{X}}_{FF} \leftarrow \text{Fusion similar features},
            \mathcal{X}_{FD}, \hat{\mathcal{X}}_{FD} \leftarrow \text{Decomposition similar features},
14
            A_t^{PE}, A_t^{NE} = \text{CA}(\mathcal{X}_{FD}, \mathcal{C}_t),
15
            \hat{A}_t^{PE}, \hat{A}_t^{NE} = \text{CA}(\hat{\mathcal{X}}_{FD}, \hat{\mathcal{C}}_t),
16
           \mathcal{L}_{pr} = \left\| A_t^{PE} - \hat{A}_t^{PE} \right\|^2,
17
            \mathcal{L}_{ns} = -\left\|A_t^{NE} - \overline{A}_t^{NE}\right\|^2,
            \hat{\mathcal{C}}_t = \operatorname{argmin}(\mathcal{L}_{pr} + \mathcal{L}_{ns}),
            \hat{z}_{t-1} = Denoising (\hat{z}_t, t, \hat{C}_t).
21 end
     Output: Edited Video V_{edit} = Image Decoder(\hat{z}_0).
```

poral Consistency, and Overall Impression, which are used to assess the editing accuracy, aesthetic quality, temporal consistency, and overall impression of the edited video, respectively. For a fair comparison, we invite 31 subjects to

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Method	Control A Video	ControlVideo	FateZero	FLATTEN	TokenFlow	Ours
PickScore	0.132	0.145	0.169	0.148	0.165	0.240

Table 1. Quantitative evaluation with baselines on PickScore. The color of each cell shows the best and the second best.

Method	Control A Video	ControlVideo	TokenFlow	Ours
Running Time / GPU Memory	8.3min / 13.17G	4.4min / 11.81G	6.9min / 11.24G	8.6min / 12.07G
Temporal Consistency / Frame Accuracy	0.9751 / 0.6329	0.9809 / 0.7278	0.9824 / 0.6361	0.9896 / 0.8681

Table 2. Comparison of efficiency and performance.



Figure 1. The visual comparison of our SUV and existing baselines. Compared to the other methods, our SUV can effectively suppress the undesired content of video while maintaining overall temporal consistency of the generated video.

score the videos with different methods.

Comparison Baselines. We compared our method with five state-of-the-art video editing methods. (1) Control A Video [1] integrates motion priors and content priors into video generation to improve video temporary consistency. (2) ControlVideo [7] integrates temporarily extended ControlNet into the T2I diffusion model and utilizes information such as depth and edge maps of the original video to control the editing results. (3) FateZero [5] achieves first zero-shot video editing through DDIM Inversion and attention blending techniques. (4) FLATTEN [2] leverages an existing optical flow detection model for more accurate optical flow-guided attention learning. (5) TokenFlow [3] introduces a linear combination of diffusion features to enhance the consistency of the video for reducing the inter-

frame flickering.

B. More Quantitative Comparisons

We report the PickScore on 15 text-video pairs in Table 1, where our method significantly outperforms existing state-of-the-art approaches. In addition, to further illustrate the efficiency of our method, we present the Running Time and GPU Memory of different methods in Table 2. It can be seen that our method strikes a balance between performance and efficiency.

C. More Visual Results

In order to more intuitively illustrate the effectiveness of our method, we conducted extensive experiments compar-



Figure 2. The visual comparison of our SUV and existing baselines. Compared to the other methods, our SUV can effectively suppress the undesired content of video while maintaining overall temporal consistency of the generated video.



Figure 3. The visual comparison of our SUV and existing baselines. Compared to the other methods, our SUV can effectively suppress the undesired content of video while maintaining overall temporal consistency of the generated video.

ing our method with other existing methods. As shown in Figure 1, Figure 2, Figure 3 and Figure 4, the results indicate that these methods struggle to accurately understand

negative text prompt (e.g. "without glasses and without an earring"), resulting in undesired information still appearing in the edited video. In contrast, our approach not only ac-



Figure 4. The visual comparison of our SUV and existing baselines. Compared to the other methods, our SUV can effectively suppress the undesired content of video while maintaining overall temporal consistency of the generated video.



Figure 5. The visual comparison of our SUV and image-based editing method InfEdit. Compared to the InfEdit, our SUV can effectively suppress the undesired content of video while maintaining overall temporal consistency of the generated video.



A rabbit sitting on the snow eating something rather than a monkey sitting on the grassland.

Figure 6. The visual results of our method. Our proposed SUV not only supports undesired content suppression, but also enables to realize general editing tasks such as editing grassland to snow.

curately achieves video content suppression, but also effectively maintains the temporal consistency of the video during the editing process.

Furthermore, to validate the capability of FFS in maintaining temporal consistency, we integrate it into the image-based editing method InfEdit [6] for comparison, and the re-

sults are illustrated in Figure 5. It can be seen that although InfEdit performs well in terms of temporal consistency, it fails to effectively suppress unwanted content, while our method yields superior results. Additionally, our method also supports general editing task, such as background from grassland to snow, as shown in Figure 6.

Number of m	m=2	m=4	m = 6
Temporal Consistency / Frame Accuracy	0.9689 / 0.8654	0.9748 / 0.8934	0.9735 / 0.8763

Table 3. Ablation studies on the number of video groups. The color of each cell shows the best and the second best.

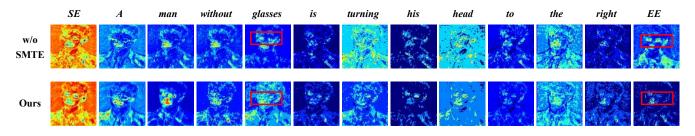


Figure 7. The impact of the semantic modulation based on text embeddings. It can be seen that after removing the module, the content of glass appears in both "glass" and "EE" of the text embeddings, and our SUV can effectively remove these undesired negative content.

D. More Ablation Results

We perform visual validation of semantic modulation based on text embeddings, and the results are shown in Figure 7. When removing the SMTE, we obtain each cross-attention maps corresponding to the text embeddings. It can be seen the content of glasses appear in both "glass" and "EE" of the text embeddings after removing the SMTE, it indicates the SUV can effectively remove these undesired content of video.

In addition, we also conduct ablation studies on the hyperparameter m, and the results are shown in Table 3. We adopt m=4 by default as it yields the best performance.

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