# — Supplementary Material — Hierarchical 3D Scene Graphs Construction Outdoors

Jon Andri Nyffeler<sup>1</sup> Marc Pollefeys<sup>1,3</sup> Federico Tombari<sup>2</sup> Daniel Barath<sup>1,2,4</sup>
<sup>1</sup>ETH Zürich <sup>2</sup>Google <sup>3</sup>Microsoft Spatial AI Lab <sup>4</sup>HUN-REN SZTAKI

jon.nyffeler@gmail.com tombari@in.tum.de marc.pollefeys@inf.ethz.ch dbarath@ethz.ch

## A Appendix

### A.1 Example Sub-Scene Pair

Figure 1 shows an example pair of sub-scenes from the LIN dataset used for scene alignment. The overlapping region between the two sub-scenes is highlighted in orange, with each object assigned a slightly different shade. A few objects are labeled as illustrative examples. SGAligner [5] generates embeddings for each object and identifies the most similar pairs across the sub-scenes. Matched objects are connected with dotted lines for visualization.

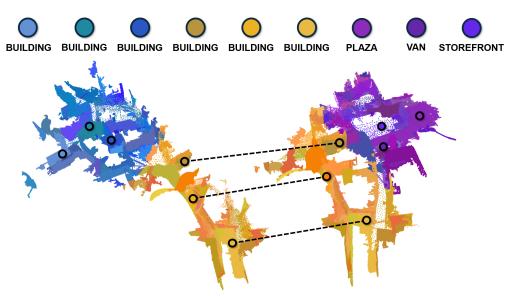


Figure 1. **Example of Object Matching for a Sub-Scene Pair.** The overlapping region is shown in orange, with distinct areas in blue and purple. Objects have slightly different tones, and selected examples are labeled with dotted lines indicating their matches.

#### A.2 LVLMs

A crucial step in 3D scene graph generation involves producing object labels, descriptions, and attributes. To achieve this, we select images of the target object, apply a red bounding box based on its SAM mask, and feed the result into a large vision-language model (LVLM) using a prompt designed to elicit detailed descriptions. In our experiments, we used GPT-4V [1] as the LVLM, although any other LVLM could be

employed. Table 1 shows an example of object description generation using several different LVLMs. Notably, GPT-4V, Gemini [3], and Claude [2] produce similarly detailed and accurate outputs. BLIP-2 [4], the only open-source model among them, also produces reasonable results, though its descriptions and attributes are generally less precise than those of the proprietary models.

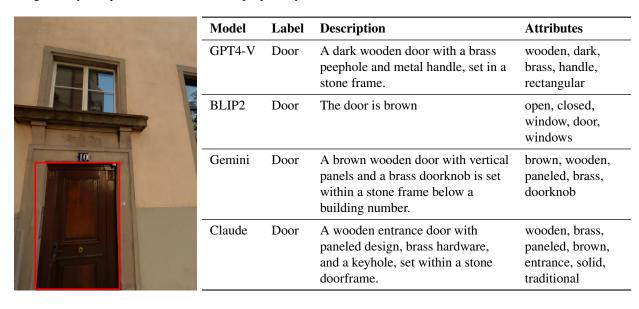


Table 1. Comparison of Different LVLMs in Object Description Generation. A door is used as the example object. On the left, the image shows the selected object with a red bounding box derived from its SAM mask. On the right, outputs from different LVLMs are shown for label, description, and attribute generation using the same prompt.

#### References

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