

# MOERL: When Mixture-of-Experts Meet Reinforcement Learning for Adverse Weather Image Restoration

## Supplementary Material

### Overview

In this document, we first provide more details of the Transformer layer. Then we conduct an additional ablation study to evaluate the effectiveness of the proposed MOE layer. Finally, we provide more visual comparisons to demonstrate our method’s qualitative performance.

### 1. More details of Transformer layer

The MOE block combines a MOE layer and multiple Transformer units [8]. Each Transformer unit consists of a multi-dconv head transposed attention (MDTA) mechanism and a gated-dconv feed-forward network (GDFN). MDTA performs self-attention along the channel dimension, reducing computational complexity while preserving feature effectiveness. Given input features  $\mathbf{X} \in \mathbb{R}^{C \times H \times W}$ , layer normalization is applied, followed by  $1 \times 1$  and  $3 \times 3$  depth-wise convolutions to generate the Query ( $\mathbf{Q}$ ), Key ( $\mathbf{K}$ ), and Value ( $\mathbf{V}$ ). These tensors compute a channel-wise attention matrix to enhance feature interaction. This process can be expressed as

$$\text{Att}(\hat{\mathbf{Q}}, \hat{\mathbf{K}}, \hat{\mathbf{V}}) = \text{softmax} \left( \frac{\hat{\mathbf{Q}}\hat{\mathbf{K}}^\top}{\alpha} \right) \hat{\mathbf{V}}, \quad (1)$$

$$\hat{\mathbf{X}} = W_{1 \times 1} \text{Att}(\hat{\mathbf{Q}}, \hat{\mathbf{K}}, \hat{\mathbf{V}}) + \mathbf{X},$$

where  $\hat{\mathbf{X}}$  denotes the output features. GDFN adopts a gating mechanism to propagate useful information selectively. Specifically, given input  $\mathbf{X}$ , convolutions and element-wise operations controlled by a GELU activation function  $\phi(\cdot)$  refine the feature representation. The process of GDFN is shown as

$$\text{Gate} = \phi(W_{3 \times 3}^1 W_{1 \times 1}^1 (LN(\mathbf{X}))) \odot (W_{3 \times 3}^2 W_{1 \times 1}^2 (LN(\mathbf{X}))),$$

$$\hat{\mathbf{X}} = W_{1 \times 1} \text{Gate}(\mathbf{X}) + \mathbf{X}, \quad (2)$$

where  $LN$  is the normalization,  $\hat{\mathbf{X}} \in \mathbb{R}^{C \times H \times W}$  represents the output features,  $\text{Gate}(\cdot)$  refers to the gated mechanism.  $W_{1 \times 1}(\cdot)$  and  $W_{3 \times 3}(\cdot)$  denote  $1 \times 1$  convolution and  $3 \times 3$  depth-wise convolution.  $\odot$  is the element-wise multiplication operation. Together, MDTA and GDFN enable efficient feature extraction and transformation, ensuring robust restoration performance in adverse weather conditions.

### 2. Additional Ablation Study

Table 1 presents the results of an ablation study on the number of spatial and channel experts in the MOE layer, high-

Table 1. Ablation study settings. The MACs of each model is measured on  $256 \times 256$  image.

Models	Spatial experts	Channel experts	PSNR/SSIM	Params.	FLOPs
Variant1	4	4	32.65/0.9427	12.62M	68.58G
Variant2	6	6	32.76/0.9428	12.78M	69.57G
Variant3	8	8	32.78/0.9430	12.94M	70.58G
Ours	2	4	32.70/0.9428	12.50M	68.35G

lighting the trade-off between performance and computational efficiency. **Variant1**, with 4 spatial and 4 channel experts, achieves a PSNR of 32.65 and an SSIM of 0.9427, using 12.62M parameters and 68.58G FLOPs. Increasing the experts to 6 each in **Variant2** improves performance slightly to a PSNR of 32.76 and an SSIM of 0.9428, with a moderate increase in complexity (12.78M parameters and 69.57G FLOPs). **Variant3**, with 8 experts of each type, achieves the best performance (32.78 PSNR, 0.9430 SSIM) but incurs the highest computational cost (12.94M parameters and 70.58G FLOPs). Our chosen configuration, with 2 spatial experts and 4 channel experts, strikes the best balance, achieving a PSNR of 32.70 and an SSIM of 0.9428 while maintaining the lowest parameter count (12.50M) and computational demand (68.35G). These results confirm that our design achieves competitive performance with optimized efficiency.

### 3. More Visual Results

This section presents additional visual comparisons in different datasets, including Snow100K-S [3], Snow100K-L [3], Outdoor-Rain [2], RainDrop [5], and real-world images from Snow100K [3]. Specifically, the comparison methods are TransWeather [7], Chen *et al.* [1], WGWS-Net [9], WeatherDiff<sub>64</sub> [4], and Histoformer [6].

**Visual Results on Snow100K-S:** Figures 1, 2.

**Visual Results on Snow100K-L:** Figures 3, 4.

**Visual Results on Outdoor-Rain:** Figures 5 6.

**Results on RainDrop:** Figures 7, 8.

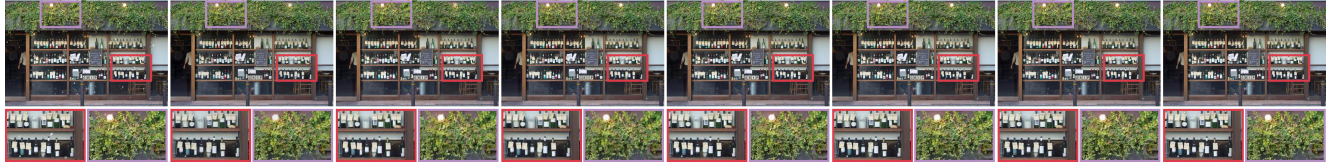
**Visual Results on real-world images:** Figures 9, 10.

## References

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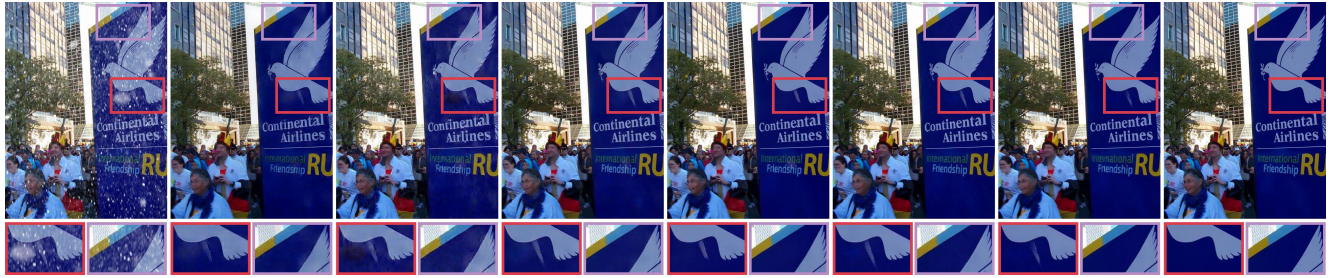
Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 1. Visual comparison on Snow100K-S dataset [3].



Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 2. Visual comparison on Snow100K-S dataset [3].



Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 3. Visual comparison on Snow100K-L dataset [3].



Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 4. Visual comparison on Snow100K-L dataset [3].



Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 5. Visual comparison on Outdoor-Rain dataset [2].



Input TransWeather Chen *et al.* WGWSNet WeatherDiff Histoformer Ours GT  
Figure 6. Visual comparison on Outdoor-Rain dataset [2].

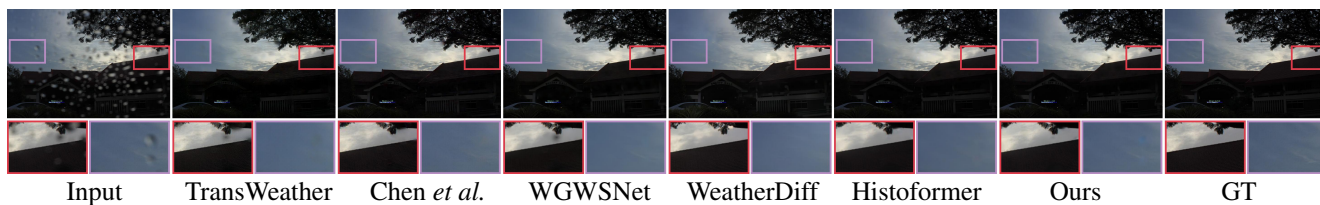


Figure 7. Visual comparison on RainDrop dataset [5].

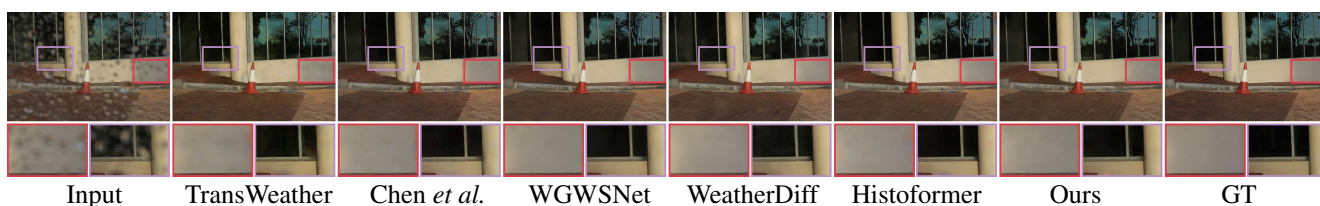


Figure 8. Visual comparison on RainDrop dataset [5].

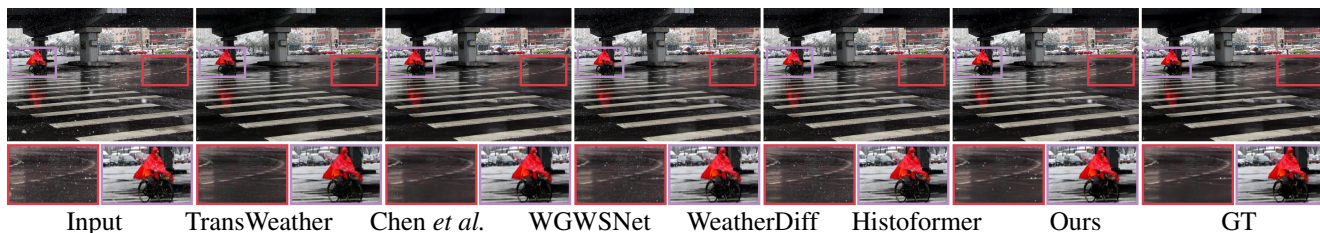


Figure 9. Visual comparison on real-world images from Snow100K dataset [3].

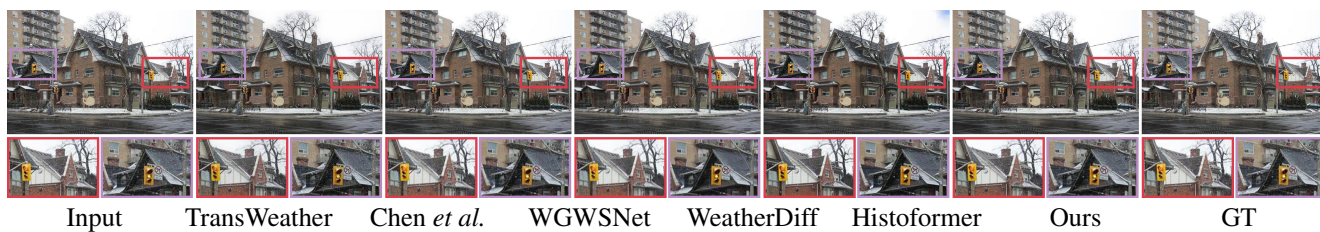


Figure 10. Visual comparison on real-world images from Snow100K dataset [3].