Aerial Image Dehazing with Attentive Deformable Transformers

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Supplementary Material

Overview

The supplementary material contains:

- Conceptual Differences between Proposed Method and Existing Methods
- Loss Functions
- More Discussion about Ablation Study
- More Qualitative Results

1 Conceptual Differences between Proposed Method and Existing Methods

The conceptual differences between the networks of the existing methods and the proposed method are provided in Table S 1. The proposed method incorporates all the essential blocks required for effective aerial image dehazing.

2 Loss Functions

We train the proposed network using L₁ loss (\mathbb{L}_1), edge loss (\mathbb{L}_{Edge}) and perceptual loss (\mathbb{L}_p). The detailed equations of these loss functions are:

2.1 L_1 Loss

 \mathbb{L}_1 loss aims at reduction of the per pixel difference between the output image (I_O) and ground truth (I_{GT}), which can be formulated as:

$$\mathbb{L}_{1} = \|I_{O} - I_{GT}\|_{1} \tag{1}$$

2.2 Edge Loss

Edge loss (\mathbb{L}_{Edge}) aims at improving the edge details by calculating the discrepancies between edges of the output image and ground truth image. It can be represented as:

$$\mathbb{L}_{Edge} = \left\| \psi\left(I_O\right) - \psi\left(I_{GT}\right) \right\|_1 \tag{2}$$

where, $\psi(\cdot)$ is Sobel operator.

2.3 Perceptual Loss

The perceptual loss (\mathbb{L}_P) aims at improving the perceptual quality of the output by calculating the differences between output and ground truth at various feature levels. The pretrained layers of VGG-16 [1] model are used as feature space for the loss calculation. The perceptual loss can be represented mathematically as:

$$\mathbb{L}_{P} = \left\| \Phi_{i \in (3,8,15)} \left(I_{O} \right) - \Phi_{i \in (3,8,15)} \left(I_{GT} \right) \right\|_{1}$$
(3)

where, $\Phi_i(\cdot)$ is i^{th} layer of VGG-16 model.

3 More Discussion about Ablation Study

The description regarding which blocks and loss functions are used in each network setting in ablation study is provided in Table S 2.

Method	Publication	Local Dependency	Global Dependency	Geometric Adaptability	Edge Boosting Skip Connections
SPA-GAN [7]	-	\checkmark	×	×	×
Huang et al. [9]	WACV-20	\checkmark	×	×	×
SkyGAN [10]	WACV-21	\checkmark	×	×	×
UFormer [8]	CVPR-22	\checkmark	\checkmark	×	×
Proposed Method	-	\checkmark	\checkmark	\checkmark	\checkmark

Table S 1: Conceptual comparison of the proposed method with existing state-of-the-art methods.

Setting	Attention Type	Offset Extraction Type	Skip Connection Type	Loss Functions
Network 1	Vanilla Attention [11]	Spatially Attentive	Edge Boosting Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 2	DW-MSA [8]	Spatially Attentive	Edge Boosting Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 3	Deformable MSA	Deformable [12]	Edge Boosting Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 4	Deformable MSA	Modulated Deformable [13]	Edge Boosting Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 5	Deformable MSA	Spatially Attentive	No Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 6	Deformable MSA	Spatially Attentive	Regular Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$
Network 7	Deformable MSA	Spatially Attentive	Edge Boosting Skip Connection	\mathbb{L}_1
Network 8	Deformable MSA	Spatially Attentive	Edge Boosting Skip Connection	\mathbb{L}_1 + \mathbb{L}_{Edge}
Proposed	Deformable MSA	Spatially Attentive	Edge Boosting Skip Connection	$\mathbb{L}_1 + \mathbb{L}_{Edge} + \mathbb{L}_P$

Table S 2: Details regarding modules and losses used in each network setting (DW-MSA: DepthWise convolution based Multi-head Self Attention).

4 More Qualitative Results

We provide more qualitative results on RICE dataset for aerial haze removal in Figure S 1. We compare the qualitative results with state-of-the-art methods GCANet [2], USID [3], MSBDN [4], TSDNet [5], RDNet [6], SPA-GAN [7] and UFormer [8]. As seen from the results, the proposed method is able to maintain more spatial content and color balance.



Input GCANet [2] USID [3] MSBDN [4] TSDNet [5] RDNet [6] SPA-GAN [7] UFormer [8] Ours Ground Truth

Figure S 1: Qualitative results comparison of the proposed method with existing state-of-the-art methods on RICE dataset for aerial haze removal.

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