Semantic Segmentation in Aerial Imagery Using Multi-level Contrastive Learning with Local Consistency

Supplementary Material

1 Pseudo-cloud Augmentation

One of the contribution of our paper is to propose the pseudo cloud noise method as an addition of data augmentation. The details of this algorithm has been showed in Algorithm 1. The random functions (denoted with random.int (rand.int) for random integer in range (x,y) or random float (rand.float) which returns a random float, if parameters are provided then argument 1 is the center of the distribution, argument 2 is the standard deviation, and argument 3 is the number of samples) were used from numpy.

Algorithm 1 Pseudo-cloud noise algorithm

```
cluster \leftarrow 10
cluster_{size} \leftarrow 250
cluster_{samples} \leftarrow 1000
max_x, max_y \leftarrow 256, 256
cent_x \leftarrow rand.int(0, max_x)
cent_{u} \leftarrow rand.int(0, max_{u})
scale_x \leftarrow rand.int(10, cluster_{size})
scale_{y} \leftarrow rand.int(10, cluster_{size})
while cluster \neq 0 do
    sample_x \leftarrow rand.float(cent_x, scale_x, cluster_{size})
     sample_{y} \leftarrow rand.float(cent_{y}, scale_{y}, cluster_{size})
    if sample_y or sample_x \ge 255 then
         sample_u or sample_x \leftarrow 255
    end if
    for i \leftarrow 1 in cluster<sub>samples</sub> do
         if N is odd then
             Pixel_{RBG} * rand.float(0.5, 1)
             if Pixel_{RBG} \ge 255 then
                  Pixel_{RBG} \leftarrow 255
             end if
         end if
    end for
     cluster \leftarrow cluster - 1
end while
```

2 Segmentation Results in 4.2

Here, we show more details, the semantic segmentation results, about the experiments for Comparison with State-of-the-Art. In following contents, we showed the raw image; ground truth; the supervised semantic segmentation results with DeepLab V3+; the best result among the contrastive learning methods for natural images, including MoCo V2, SimCLR, BYOL, SimSiam; the result of GLCNet; and the result of the proposed method mCL-LC.



Figure 1: Segmentation results in Potsdam dataset



Figure 2: Segmentation results in Vaihingen dataset



Figure 3: Segmentation results in Nice dataset



Figure 4: Segmentation results in Nantes Saint dataset