Feature Augmentation based Test-Time Adaptation Supplementary Material

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Due to the limited space of the main paper, we provide more experimental results and implementation details in the supplementary material.

Accuracy of pseudo-labels. Fig. A shows the accuracy of pseudo-labels as the model adapts. The pseudo-label accuracy is high compared to the output accuracy and improves over time.

Further experimental results. We present the full results of Tab. 4, Tab. 5, and Tab. 7 in the main paper, as shown in Tab. A, Tab. B, and Tab. C, respectively.



Figure A. Pseudo-label accuracy (%) on ImageNet-C. We use DeYO+FATA with ResNet50-GN for this experiment. Exponential moving average (p = 0.99) is applied.

Implementation details. We provide the full data of the hyperparameters in Tab. D.

Method	$Ar{\rightarrow}Cl$	Ar→Pr	$Ar \rightarrow Re$	$Cl{\rightarrow}Ar$	$Cl {\rightarrow} Pr$	Cl→Re	$Pr \rightarrow Ar$	Pr→Cl	$Pr \rightarrow Re$	$Re{\rightarrow}Ar$	$Re{\rightarrow}Cl$	$Re{\rightarrow}Pr$	Average	Δ Perf.
No Adapt	41.31	64.74	74.75	51.71	60.94	63.58	51.3	37.21	73.63	64.94	40.25	75.85	58.35	
MEMO [8]	42.18	65.65	75.03	49.94	60.26	62.82	50.31	37.25	72.44	64.81	40.37	76.73	58.15	
TENT [6]	41.4	64.74	74.75	51.71	60.89	63.64	51.3	37.16	73.65	65.02	40.21	75.87	58.36	
CoTTA [7]	41.28	64.79	71.86	51.71	60.91	63.6	51.3	37.21	72.11	64.94	40.3	70.87	57.57	
EATA [3]	41.99	64.83	74.87	51.71	60.96	63.64	51.42	37.82	73.67	65.1	41.03	75.94	58.58	
EATA+FATA	42.2	65.74	74.39	53.61	61.66	65.34	53.61	39.11	74.27	67.08	43.09	76.41	59.71	+1.13
SAR [4]	41.37	64.77	74.78	51.67	60.91	63.64	51.34	37.14	73.63	65.02	40.25	75.87	58.37	
SAR+FATA	42.02	64.63	74.73	53.32	61.59	64.82	51.63	38.72	73.88	65.51	42.47	76.82	59.18	+0.81
DeYO [2]	41.63	64.7	74.71	51.96	61.07	63.87	51.34	37.71	73.74	65.1	40.62	76.3	58.56	
DeYO+FATA	41.74	64.97	74.73	51.96	61.34	63.99	51.55	37.73	73.74	64.94	40.82	76.19	58.64	+0.08

Table A. Image classification results on Office-Home [5]. ResNet50 with GN is used for this experiment. We use the accuracy (%) as the metric. Δ Perf. is the performance gap between the original method and another version where our method is incorporated.

	Noise			Blur					Weather				Digital			
Method	Gauss.	Shot	Impul.	Defoc.	Glass	Motion	Zoom	Snow	Frost	Fog	Brit.	Contr.	Elastic	Pixel	JPEG	Avg.
No Adapt	17.98	19.84	17.88	19.75	11.35	21.42	24.92	40.43	47.30	33.59	69.28	36.27	18.61	28.40	52.28	30.62
DeYO [2]	39.46	41.90	41.03	22.27	24.11	38.48	37.87	50.51	49.59	1.43	73.17	49.95	41.54	55.96	57.82	41.67
DeYO+FATA (Layer 0)	35.58	38.56	36.51	20.32	17.61	41.07	40.53	48.89	48.40	54.22	71.25	49.74	8.08	55.29	56.76	41.52
DeYO+FATA (Layer 1)	39.84	42.11	40.47	21.84	23.68	39.93	41.17	55.03	50.82	1.09	72.86	51.13	39.57	57.26	57.97	42.32
DeYO+FATA (Layer 2)	39.72	42.77	41.03	21.44	23.04	39.74	42.76	54.51	52.04	0.84	73.57	51.67	45.92	57.89	58.16	43.01
DeYO+FATA (Layer 3)	39.71	42.49	41.37	22.29	24.46	38.90	38.31	51.23	50.02	56.31	73.19	50.03	42.10	55.99	57.79	45.61

Table B. Ablation study on the position of feature augmentation. ResNet50 with GN is used for this experiment.

D VO	1	Noise			Blur					Weather				Digital			
Dero	Augmentation loss	Gauss.	Shot	Impul.	Defoc.	Glass	Motion	Zoom	Snow	Frost	Fog	Brit.	Contr.	Elastic	Pixel	JPEG	Avg.
-	-	17.98	19.84	17.88	19.75	11.35	21.42	24.92	40.43	47.30	<u>33.59</u>	69.28	36.27	18.61	28.40	52.28	30.62
-	FATA loss (Ours)	37.92	39.99	38.70	25.96	22.21	36.06	37.77	51.99	51.33	2.85	73.11	48.83	13.10	53.78	56.73	39.35
\checkmark	-	<u>39.46</u>	<u>41.90</u>	41.03	22.27	24.11	38.48	37.87	50.51	49.59	1.43	73.17	49.95	41.54	55.96	57.82	41.67
\checkmark	Simple Aug.	38.19	41.31	39.31	21.64	23.43	36.96	34.93	48.72	46.50	1.14	72.90	49.19	37.43	55.39	57.39	40.30
\checkmark	MSE loss	0.22	0.46	0.57	0.88	0.89	0.57	2.15	2.00	7.49	8.18	61.78	6.37	0.83	2.19	3.52	6.54
\checkmark	FATA Loss (Ours)	39.71	42.49	41.37	<u>22.29</u>	24.46	38.90	38.31	<u>51.23</u>	<u>50.02</u>	56.31	73.19	50.03	42.10	55.99	<u>57.79</u>	45.61

Table C. Ablation study on the augmentation loss. ResNet50 with GN is used for this experiment.

Parameter	Meaning	Value
i	Layer to inject the feature augmentation	3 (ResNet50), 11 (ViT-B)
E_0	Entropy threshold for sample filtering	$0.5 \ln C$
E_{ω}	Normalization factor for sample weighting	$0.4 \ln C$
σ_n	Standard deviation for the noise	1.0
λ_{EMA}	Smoothing factor for exponential moving average	0.95
B	Default batch size	64
η	Learning rate	0.0005 (ResNet50, $B = 64$)
		0.001 (ViT-B, $B = 64$)
		0.00025 (ResNet50, $B = 1$)
		0.000016 (ViT-B, $B = 1$)

Table D. Hyperparameters for the experiment.

Rationale for replacing variance with standard deviation in Eq. (3). Eq. (3) is derived from Normalization Perturbation (NP) [1], which is formulated as follows:

$$\mathbf{z}' = \alpha \sigma_c \cdot \frac{\mathbf{z} - \mu_c}{\sigma_c} + \beta \mu_c = \alpha \mathbf{z} + (\beta - \alpha) \mu_c, \qquad (A)$$

where $\alpha, \beta \in \mathbb{R}^{B \times C}$ are the random noises sampled from $N(\mathbf{I}, \sigma_n \mathbf{I}), \mu_c, \sigma_c$ are the channel-wise feature mean and standard deviation, respectively. As formulated by Eq. (3), NP+ introduces the term $\delta = \operatorname{Var}(\mu_c)/\operatorname{max}(\operatorname{Var}(\mu_c))$ to control the magnitude of the noises α and β . We replace variance with standard deviation because the noises are related to standard deviation σ_c , not variance, as shown in Eq. (A).

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