

# VOCAL: Visual Odometry via ContrAstive Learning

## Supplementary Material

### 6. Resources

For additional resources and demo videos, please visit:  
<https://github.com/huang-chiyao/vocal>.

### 7. Feature Distribution

In this section, we present the detailed feature distribution for all six degrees of freedom across the test datasets (KITTI sequences 03–07 and 10).

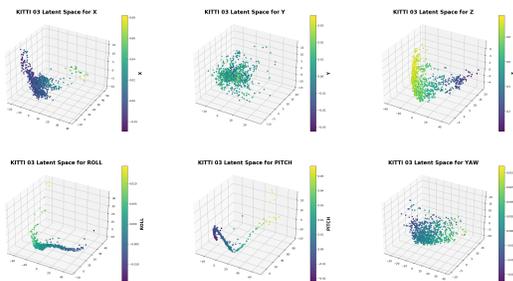


Figure 7. KITTI 03 Feature Distribution

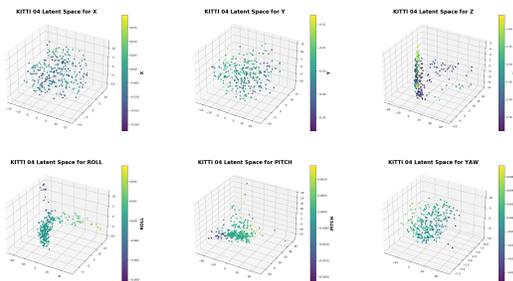


Figure 8. KITTI 04 Feature Distribution

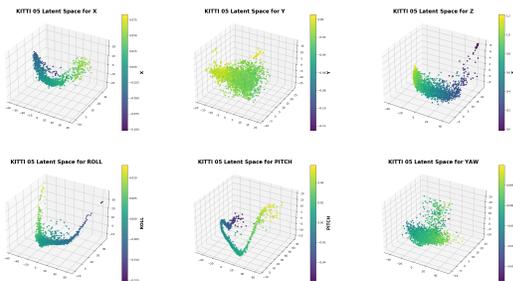


Figure 9. KITTI 05 Feature Distribution

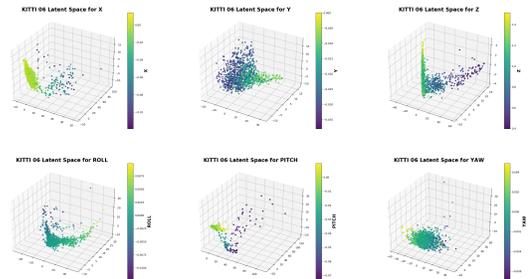


Figure 10. KITTI 06 Feature Distribution

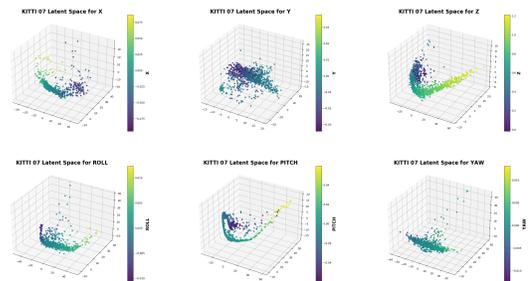


Figure 11. KITTI 07 Feature Distribution

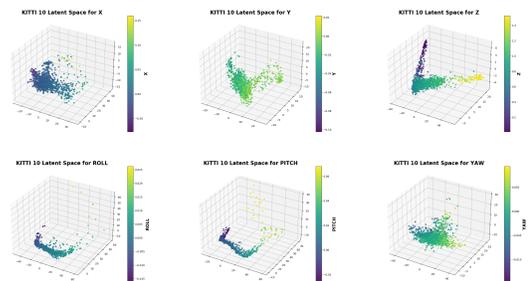


Figure 12. KITTI 10 Feature Distribution