# LaSOT: A High-quality Benchmark for Large-scale Single Object Tracking —Supplementary Material—

NUS-PRO [4]		OTB-2	OTB-2015 [7]		TC-128 [5]		UAV123 [6]		17 [3]	NfS [2]		LaS	от
class	# entries	class	# entries	class	# entries	class	# entries	class	# entries	class	# entries	class	# entrie
person	193	person	36	person	45	person	48	person	19	ball	21	airplane	20
head	60	head	26	head	16	car	30	head	5	person	20	basketball	20
car	31	car	12	sphere	8	drone	10	fish	4	animal	10	bear	20
airnlane	20	tov	8	2D print	5	wakeboard	10	motorcycle	4	vehicle	9	bicycle	20
boat	20	2D print	4	biquala	5	host	0	ant	2	shuffahoard	é	bird	20
balicontar	20	2D print auboid	4	bicycle	5	building	5	drama	2	fnce	6	boat	20
nencopter	20	cubold	5	car	3	building	5	drone	3	Tace	0	boat	20
motorcycle	20	bird	2	ball	4	truck	5	ant	2	cup	4	DOOK	20
drone	1	motorcycle	1	toy	4	bicycle	3	ball	2	dollar	4	bottle	20
-	-	deer	1	hand	3	bird	3	bird	2	aircraft	4	bus	20
-	-	bottle	1	kite	3	-	-	toy	2	airboard	2	car	20
-	-	panda	1	logo	3	-	-	bag	1	fish	2	cat	20
-	-	board	1	cuboid	3	-	-	book	1	motorcycle	2	cattle	20
-	-	can	1	boat	2	-	-	butterfly	1	drone	2	chameleon	20
-	-	dog	1	cup	2	-	-	cable	1	bicycle	2	coin	20
-	-	transformer	1	fish	2	-	-	crab	1	bird	2	crab	20
		bicycle	1	ouitar	2			cat	1	hag	1	crocodile	20
_	_	-		bird	2		_	flamingo	1	vovo	1	cup	20
-	-	-	-		2	-	-	faintingo	1	yoyo	1	cup	20
-	-	-	-	microphone	2	-	-	misbee	1	-	-	deer	20
-	-	-	-	torso	2	-	-	glove	1	-	-	dog	20
-	-	-	-	motorcycle	2	-	-	hand	1	-	-	drone	20
-	-	-	-	airplane	2	-	-	helicopter	1	-	-	electricFan	20
-	-	-	-	board	1	-	-	leaf	1	-	-	elephant	20
-	-	-	-	bottle	1	-	-	rabbit	1	-	-	flag	20
-	-		-	can	1	-	-	sheen	1		-	fox	20
				deer	1			r				frog	20
				ring	1							gamaTargat	20
-	-	-	-	torus	1	-	-	-	-	-	-	gamerarget	20
-	-		-	torus	1		-	-	-	-	-	geeko	20
-	-	-	-	-	-	-	-	-	-	-	-	girane	20
-	-	-	-	-	-	-	-	-	-	-	-	goldfish	20
-	-	-	-	-	-	-	-	-	-	-	-	gorilla	20
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-	-	-	-	-	-	-	-	-	-	-	-	swing	20
-	-	-	-	-	-	-	-	-	-	-	-	tank	20
	-	-	-	-	-	-	-	-	-	-	-	tiger	20
	-	-	-	-	-	-		-	-	-	-	train	20
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Table 1. Details of 70 object categories in LaSOT and comparison with existing dense benchmark. Best viewed when zoomed-in.

#### 1. Details of 70 Object Categories in LaSOT and Comparison with Existing Dense Benchmarks

LaSOT consists of 70 object categories with each containing 20 videos, as shown in Tab. 1. Most of 70 classes are chosen form the 1,000 classes in ImageNet [1], with a few exceptions such as drone and gametarget, which are carefully selected by the experts for tracking. The selection of each category must be agreed upon by all the experts to ensure its usability for visual tracking. In addition, we also compare the object categories of different dense benchmarks. As shown in Tab. 1, the number of object categories in LaSOT is two times more than that of existing benchmarks (e.g., TC-128 [5] with 27 classes). Moreover, LaSOT eliminates the category bias of dataset for tracking while others do not.

### 2. Traing/Testing Split in Protocol II

In protocol II, we split LaSOT into *training* and *testing* sets. The *training* set contains of 1,120 videos (*i.e.*, 16 sequences for each category) with 2.83M frames in total. The rest 280 videos (i.e., 4 sequences for each category) with 690K frames are used for testing.



Table 2. Comparison between training and testing sets of LaSOT.

Figure 1. Comparison of sequence distribution in each attribute between training and testing sets. Best viewed in color.

Attribute

Tab. 2 reports the detailed comparison between the *training* and the *testing* sets of LaSOT. We observe that the *min frames*, mean frames, median frames and max frames are similar between these two subsets. In addition, as shown in Fig. 1, we can see that the ratios of sequences in all 14 attributes are similar. Both Tab. 2 and Fig. 1 evidence the consistency of our training/testing split.

## 3. Detailed Attribute-based Performance under Protocol I

Fig. 2 shows the performance of trackers on each attribute using precision under protocol I.



Figure 2. Performance of trackers on each attribute using precision under protocol I. Best viewed in color.



Fig. 3 shows the performance of trackers on each attribute using normalized precision under protocol I.

Figure 3. Performance of trackers on each attribute using precision under protocol I. Best viewed in color.





Figure 4. Performance of trackers on each attribute using success under protocol I. Best viewed in color.

## 4. Detailed Attribute-based Performance under Protocol II

Fig. 5 shows the performance of trackers on each attribute using precision under protocol II.



Figure 5. Performance of trackers on each attribute using precision under protocol II. Best viewed in color.



Fig. 6 shows the performance of trackers on each attribute using normalized precision under protocol II.

Figure 6. Performance of trackers on each attribute using precision under protocol II. Best viewed in color.

Fig. 7 shows the performance of trackers on each attribute using success under protocol II.



Figure 7. Performance of trackers on each attribute using success under protocol II. Best viewed in color.

#### References

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