

A. Proofs

The BLP relaxation [17] introduces a probability distribution μ_i over $\{0, 1\}$ for each $i \in [d]$ and a probability distribution μ_t over $\text{dom } f_t$ for each $t \in T$. It can be written as follows:

$$\begin{aligned} \min_{\mu \geq 0} \quad & \sum_{t \in T} \sum_{z \in \text{dom } f_t} \mu_t(z) f_t(z) \\ \text{s.t.} \quad & \mu_i(0) + \mu_i(1) = 1 \quad \forall i \in [d] \\ & \sum_{z \in \text{dom } f_t} \mu_t(z) = 1 \quad \forall t \in T \\ & \sum_{z \in \text{dom } f_t: z_i = a} \mu_t(z) = \mu_i(a) \quad \forall t \in T, i \in A_t, a \in \{0, 1\} \end{aligned} \quad (19)$$

Let us show that the optimal values of (19) and (3) coincide.

Proof of equivalence of (19) and (3). Define an extension $\hat{f}_t : \mathbb{R}^{A_t} \rightarrow \mathbb{R} \cup \{+\infty\}$ of function $f_t : \{0, 1\}^{A_t} \rightarrow \mathbb{R} \cup \{+\infty\}$ as follows: for a vector $x \in \mathbb{R}^{A_t}$ set

$$\begin{aligned} \hat{f}_t(x) = \min_{\mu \geq 0} \quad & \sum_{z \in \text{dom } f_t} \mu_t(z) f_t(z) \\ \text{s.t.} \quad & \sum_{z \in \text{dom } f_t} \mu_t(z) = 1 \\ & \sum_{z \in \text{dom } f_t} \mu_t(z) \cdot z = x \end{aligned} \quad (20)$$

Note, if $x \notin [0, 1]^{A_t}$ then (20) does not have a feasible solution, and so $\hat{f}_t(x) = +\infty$. Observe that the constraints in the last line of (19) for $a = 0$ are redundant - they follow from the remaining constraints. Also observe that constraints $\sum_{z \in \text{dom } f_t: z_i = 1} \mu_t(z) = \mu_i(1)$ for $i \in A_t$ can be written as $\sum_{z \in \text{dom } f_t} \mu_t(z) \cdot z = x$ if we denote $x_i = \mu_i(1)$ for $i \in A_t$. Therefore, problem (19) can be equivalently rewritten as follows:

$$\min_{x \in \mathbb{R}^d} \sum_{t \in T} \hat{f}_t(x_{A_t}) \quad (21)$$

It can be seen that the last problem is equivalent to (3). Indeed, we just need to observe that for each $t \in T$ and $x \in \mathbb{R}^{A_t}$ we have

$$\begin{aligned} \min_{\substack{y \in \text{conv}(\mathcal{Y}_t) \\ y_* = x}} y_o &= \min_{\substack{\alpha \geq 0, \sum_{z \in \text{dom } f_t} \alpha(z) = 1 \\ y = \sum_{z \in \text{dom } f_t} \alpha(z) \cdot [z \ f(z)] \\ y_* = x}} y_o \\ &= \min_{\substack{\alpha \geq 0, \sum_{z \in \text{dom } f_t} \alpha(z) = 1 \\ \sum_{z \in \text{dom } f_t} \alpha(z) \cdot z = x}} \sum_{z \in \text{dom } f_t} \alpha(z) f(z) = \hat{f}_t(x) \end{aligned} \quad \square$$

Proof of Proposition 1. Write $f(y) := \sum_{t \in T} y_o^t$, then problem (3) can be written as

$$\min_{\substack{(y, x) \in \mathbb{Y} \times \mathbb{R}^d \\ y_*^t = x_{A_t} \quad \forall t \in T}} f(y) \quad (22)$$

The Lagrangian w.r.t. the equality constraints is given by

$$\begin{aligned} L(y, x, \lambda) &= f(y) + \sum_{t \in T} \langle y_*^t - x_{A_t}, \lambda^t \rangle \\ &= \sum_{t \in T} \langle y^t, [\lambda^t \ 1] \rangle - \sum_{t \in T} \langle x_{A_t}, \lambda^t \rangle \end{aligned}$$

Therefore, the dual function for $\lambda \in \bigotimes_{t \in T} \mathbb{R}^{A_t}$ is

$$\begin{aligned} h(\lambda) &= \min_{(y, x) \in \mathbb{Y} \times \mathbb{R}^d} L(y, x, \lambda) \\ &= \begin{cases} \sum_{t \in T} \min_{y^t \in \mathbb{Y}_t} \langle y^t, [\lambda^t \ 1] \rangle & \text{if } \lambda \in \Lambda \\ -\infty & \text{otherwise} \end{cases} \end{aligned}$$

The problem can thus be formulated as $\max_{\lambda} h(\lambda)$, or equivalently as $\max_{\lambda \in \Lambda} h(\lambda)$. This coincides with formulation given in Proposition 1.

Since constraint $y \in \mathbb{Y}$ can be expressed as a linear program, the duality between (3) and (5) can be viewed as a special case of linear programming (LP) duality (where the value of function $h(\lambda)$ is also written as a resulting of some LP). For LPs it is known that strong duality holds assuming that either the primal or the dual problems have a feasible solution. This holds in our case, since vector $\lambda = \mathbf{0} \in \Lambda$ is feasible. We can conclude that we have a strong duality between (3) and (5). \square

Proof of Proposition 2. First, we derive the dual of $h_{\mu, c}$:

$$\begin{aligned} \max_{\lambda \in \Lambda} h_{\mu, c}(\lambda) &= \max_{\lambda \in \Lambda} \sum_{t \in T} \min_{y^t \in \mathbb{Y}_t} \langle y^t, [\lambda^t \ 1] \rangle - \frac{1}{2c} \|\lambda^t - \mu^t\|^2 \\ &= \min_{y \in \mathbb{Y}} \max_{\lambda \in \Lambda} \underbrace{\sum_{t \in T} \langle y^t, [\lambda^t \ 1] \rangle - \frac{1}{2c} \|\lambda^t - \mu^t\|^2}_{=: f_{\mu, c}(y)} \end{aligned}$$

The function $f_{\mu, c}(y)$ has a closed form expression, since it is a quadratic function subject to linear equalities. Write $\nu_i = \frac{1}{|T_i|} \sum_{t \in T_i} (c \cdot y_i^t + \mu_i^t)$ for $i \in [d]$. The arg max in the expression defining $f_{\mu, c}(y)$ are

$$\lambda^t = (c \cdot y_*^t + \mu^t) - \nu_{A_t} \quad (23)$$

The function value is

$$\begin{aligned} f_{\mu, c}(x) &= \sum_{t \in T} \langle y^t, [\lambda_*^t \ 1] \rangle - \frac{1}{2c} \|\lambda_*^t - \mu^t\|^2 \\ &= \sum_{t \in T} \left(\langle y_*^t, c \cdot y_*^t + \mu^t - \nu_{A_t} \rangle + y_o^t - \frac{1}{2c} \|c y_*^t + \mu^t - \nu_{A_t} - \mu^t\|^2 \right) \\ &= \sum_{t \in T} \left(c \|y_*^t\|^2 + \langle y_*^t, \mu^t - \nu_{A_t} \rangle + y_o^t - \frac{1}{2c} \|c y_*^t - \nu_{A_t}\|^2 \right) \\ &= \sum_{t \in T} \left(c \|y_*^t\|^2 + \langle y_*^t, \mu^t - \nu_{A_t} \rangle + y_o^t - \frac{1}{2c} \{ \|c y_*^t\|^2 - 2c \langle y_*^t, \nu_{A_t} \rangle + \|\nu_{A_t}\|^2 \} \right) \\ &= \sum_{t \in T} \left(\frac{c}{2} \|y_*^t\|^2 + \langle y_*^t, \mu^t \rangle + y_o^t - \frac{1}{2c} \|\nu_{A_t}\|^2 \right). \end{aligned}$$

The gradient is $\nabla_t f_{\mu,c}(y) = [c \cdot y^t + \mu^t - \nu_{A_t} \mathbf{1}] = [\lambda^t \mathbf{1}]$. \square

Proof of Proposition 3. Let $\overline{\mathbb{Y} \times \mathbb{R}^d}$ be the set of vectors $(y, x) \in \mathbb{Y} \times \mathbb{R}^d$ satisfying the equality constraints $y_\star^t = x_{A_t}$ for all t . By construction, for any $\lambda \in \Lambda$ we have

$$f(y) = L(y, x, \lambda) \quad \forall (y, x) \in \overline{\mathbb{Y} \times \mathbb{R}^d} \quad (24a)$$

$$L(y, x, \lambda) \geq h(\lambda) \quad \forall (y, x) \in \overline{\mathbb{Y} \times \mathbb{R}^d} \quad (24b)$$

$$L(y, x, \lambda) = \sum_{t \in T} \langle y^t, [\lambda^t \mathbf{1}] \rangle \quad (24c)$$

Eq. (24c) gives that $A_{y,\lambda} = L(y, x, \lambda) - h(\lambda)$ for any $(y, \lambda) \in \overline{\mathbb{Y} \times \Lambda}$ and $x \in \mathbb{R}^d$, and so from (24b) we get that $A_{y,\lambda} \geq 0$. Clearly, we have $B_y \geq 0$. The following two facts imply part (b) of Proposition 3:

- Consider vector $y \in \mathbb{Y}$. Then $B_y = 0$ if and only if $(y, x) \in \overline{\mathbb{Y} \times \mathbb{R}^d}$ for some x . (This can be seen from the definition of B_y in Section 2.3).
- Consider vectors $(y, x) \in \overline{\mathbb{Y} \times \mathbb{R}^d}$ and $\lambda \in \Lambda$. They are an optimal primal-dual pair if and only if $f(y) = h(\lambda)$, which in turn holds if and only if $A_{y,\lambda} = 0$ (since $A_{y,\lambda} = L(y, x, \lambda) - h(\lambda) = f(y) - h(\lambda)$).

It remains to show inequality (11). Denote $\delta = \lambda^* - \lambda$, then $\sum_{t \in T_i} \delta_i^t = 0$ for any $i \in [d]$. Denoting $y_i^- = \min_{t \in T_i} y_i^t$ and $y_i^+ = \max_{t \in T_i} y_i^t$, we get

$$\begin{aligned} \sum_{t \in T_i} y_i^t \cdot \delta_i^t &= \sum_{t \in T_i} [y_i^t - y_i^-] \cdot \delta_i^t \\ &\leq \sum_{t \in T_i} [y_i^+ - y_i^-] \cdot |\delta_i^t| \\ &\leq [y_i^+ - y_i^-] \cdot \|\delta\|_{1,\infty} \end{aligned}$$

Summing these inequalities over $i \in [d]$ gives

$$\sum_{t \in T} \langle y_\star^t, \delta^t \rangle \leq B_y \cdot \|\delta\|_{1,\infty}$$

Recalling that $A_{\lambda^*,y} \geq 0$, we obtain the desired claim:

$$\begin{aligned} h(\lambda^*) &\leq \sum_{t \in T} \langle y^t, [(\lambda^*)^t \mathbf{1}] \rangle \\ &= \sum_{t \in T} \langle y^t, [\lambda^t \mathbf{1}] \rangle + \sum_{t \in T} \langle y_\star^t, \delta^t \rangle \\ &\leq \sum_{t \in T} \langle y^t, [\lambda^t \mathbf{1}] \rangle + B_y \cdot \|\delta\|_{1,\infty} \end{aligned}$$

\square

Lemma 1 (step size in Algorithm 1). *The optimal step size γ in Algorithm 1 is*

$$\gamma = \frac{\langle \nabla_t f_{\mu,c}(y), y^t - z^t \rangle}{c \|y_\star^t - z_\star^t\|^2} = \frac{\langle [c \cdot y_\star^t + \mu^t - \nu_{A_t} \mathbf{1}], y^t - z^t \rangle}{c \|y_\star^t - z_\star^t\|^2} \quad (25)$$

and clip γ to $[0, 1]$.

Proof. Recall that $y(\gamma)$ in algorithm 1 is defined as $y(\gamma)^s = \begin{cases} y^s, & s \neq t \\ (1 - \gamma)y^t + \gamma z^t, & s = t \end{cases}$. The derivative $f_{\mu,c}(y(\gamma))' = \langle \nabla f_{\mu,c}(y(\gamma)), y(\gamma)' \rangle$ is hence zero except in the t -th place. Thus,

$$\begin{aligned} &f_{\mu,c}(x(\gamma))' \\ &= \langle \nabla_t f_{\mu,c}(y), -y^t + z^t \rangle \\ &= \langle [c \cdot y_\star^t(\gamma) + \mu^t - \nu_{A_t} \mathbf{1}], -y^t + z^t \rangle \\ &= \langle [c \cdot y_\star^t + \mu^t - \nu_{A_t} \mathbf{1}], -y^t + z^t \rangle \\ &\quad + \gamma \langle c \cdot (-y_\star^t + z_\star^t), -y_\star^t + z_\star^t \rangle \end{aligned} \quad (26)$$

Setting the above derivative zero yields

$$\gamma = \frac{\langle [c \cdot y_\star^t + \mu^t - \nu_{A_t} \mathbf{1}], y^t - z^t \rangle}{c \|y_\star^t - z_\star^t\|^2}.$$

Recalling that we require $\gamma \in [0, 1]$, we get the desired formula. \square

B. Detailed experimental evaluation

In Table 2 we give the final lower bound obtained by each tested algorithm for every instance of every dataset we evaluated on. The averaged numbers are given in Table 1.

Table 2: Lower bound of each instance. † means method not applicable. **Bold** numbers indicate highest lower bound among competing methods.

Instance	FWMAP	CB	SA	MP
<u>MRF</u>				
protein folding				
1CKK	-12840.23	-12857.29	-12945.39	-12924.97
1CM1	-12486.15	-12499.21	-12591.23	-12488.10
1SY9	-9193.38	-9196.14	-9293.58	-9194.77
2BBN	-12396.51	-12461.89	-12585.85	-12417.20
2BCX	-14043.57	-14144.89	-14231.86	-14112.73
2BE6	-13311.78	-13381.35	-13410.24	-13438.23
2F3Y	-14572.71	-14619.70	-14672.71	-14641.60
2FOT	-12049.52	-12112.31	-12154.66	-12103.75
2HQW	-13514.79	-13573.99	-13610.14	-13539.69
2O60	-13557.32	-13664.00	-13718.71	-13565.42
3BXL	-14125.86	-14165.97	-14266.01	-14136.79
<u>Discrete tomography</u>				
2 projections				
0.10_0.10_2	97.99	97.94	96.46	†
0.20_0.20_2	226.81	226.66	222.05	†
0.30_0.30_2	205.65	205.25	194.49	†
0.40_0.40_2	271.23	270.99	253.94	†
0.50_0.48_87	340.13	339.98	315.41	†
0.60_0.58_28	313.19	312.80	288.73	†
0.70_0.67_47	287.11	286.83	246.04	†
0.80_0.76_72	338.97	338.78	290.73	†
0.90_0.85_63	313.98	313.77	246.63	†
4 projections				
0.10_0.10_2	102.00	101.55	99.50	†
0.20_0.20_2	250.61	250.02	245.30	†
0.30_0.30_2	247.86	246.44	233.65	†
0.40_0.40_2	365.05	364.00	346.89	†
0.50_0.48_87	439.60	435.50	412.32	†
0.60_0.58_28	400.91	400.05	368.05	†
0.70_0.67_47	393.88	392.57	371.80	†
0.80_0.76_72	443.87	440.91	413.42	†
0.90_0.85_63	397.14	395.93	358.60	†
6 projections				
0.10_0.10_2	102.00	102.00	101.82	†
0.20_0.20_2	256.00	255.85	254.74	†
0.30_0.30_2	295.85	292.28	272.74	†
0.40_0.40_2	461.27	456.70	433.89	†
0.50_0.48_87	533.95	526.86	494.29	†
0.60_0.58_28	514.05	507.34	474.61	†
0.70_0.67_47	577.38	566.15	530.47	†
0.80_0.76_72	542.96	534.01	488.62	†
0.90_0.85_63	535.78	518.67	468.60	†
sheep logan 64x64				
Logan_64_2	582.52	541.62	392.47	†
Logan_64_4	871.58	831.63	702.32	†

Table 2: Lower bound of each instance. † means method not applicable. **Bold** numbers indicate highest lower bound among competing methods.

Instance	FWMAP	CB	SA	MP
Logan_64_6	1237.44	1170.36	1011.00	†
sheep logan 256x256				
Logan_256_2	3709.46	3505.46	2599.41	†
Logan_256_4	4888.25	4739.40	976.29	†
Logan_256_6	5142.48	4832.85	-2463.81	†
Graph matching				
6d scene flow				
board	-2262.66	-2262.66	-2262.89	-2262.66
books	-4179.79	-4186.16	-4191.30	-4204.14
hammer	-2125.87	-2127.66	-2130.58	-2146.81
party	-3648.03	-3648.71	-3649.41	-3657.12
table	-3340.59	-3341.12	-3343.81	-3363.98
walking	-1627.30	-1627.34	-1627.58	-1627.79