# Supplementary Material: Multi-Granularity Reference-Aided Attentive Feature Aggregation for Video-based Person Re-identification

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# **1. More Experimental Details**

#### 1.1. Details of the Datasets

**MARS** [9] is a large-scale benchmark dataset for videobased person reID. It is captured by six cameras deployed in a university and contains 17503 tracklets corresponding to 1261 identities in total, of which 625 identities are used for training while the other 636 identities are used for testing. Besides, the additional 3248 tracklets are taken as distractors. The average number of frames per tracklet is 59. The bounding boxes for the target person are detected by Deformable Part Model (DPM, [2]) and tracked by the GMCP tracker [8].

**iLIDS-VID** [7] contains 600 video tracklets of 300 identities captured by 2 cameras. The length of sequences ranges from 23 to 192 frames with an average number of 73 frames. The bounding boxes are manually annotated.

**PRID2011** [4] consists of 400 video tracklets of 200 identities from 2 cameras. The sequence length varies from 5 to 675. As in the previous works [9, 10, 5], we select video sequences with more than 21 frames for training and testing, leading to 178 identities. The bounding boxes are manually annotated.

## **1.2. Details of the Evaluation Metrics**

The Cumulative Matching Characteristic (CMC) and the mean average precision (mAP) are used for evaluation. We use CMC to represent the number of true matching samples within the first k ranking results, which indicates the accuracy of person retrieval. Following the common practices, we report Rank-1, Rank-5, Rank-10, and Rank-20 accuracy, and also use mAP to evaluate the model performance in MARS. We obtain the average precision (AP) for each query and calculate the mean value of AP across all queries to obtain the mAP accuracy.

# **1.3. Implementation Details**

For all the reported models, the backbone network is pretrained on ImageNet [1] and both identification (cross entropy) loss with label smoothing [6] and triplet loss with Table 1: Performance (%) of using single granularity reference-aided attentive feature aggregation (SG-RAFA) at different granularities. "SG" denotes "Single-Granularity" and "MG" denotes "Multi-Granularity". N denotes the number of granularities. G-1st denotes the finest granularity with the spatial resolution of  $16 \times 8$  for  $F_{all}$  and  $F_R$ , while G-4th denoting the coarsest granularity with the spatial resolution of  $2 \times 1$  for  $F_{all}$  and  $F_R$ .

Models	MARS					
	mAP	R-1	R-5	R-10	R-20	
Baseline	82.1	85.9	95.1	96.5	97.3	
SG-RAFA (G-1st)	84.9	88.4	96.6	97.6	98.5	
SG-RAFA (G-2nd)	84.6	87.5	96.5	97.2	98.0	
SG-RAFA (G-3rd)	84.2	87.4	95.8	97.1	97.9	
SG-RAFA (G-4th)	83.2	86.7	95.3	96.7	97.7	
MG-RAFA (N=4)	85.9	88.8	97.0	97.7	98.5	

hard mining [3] are used. We use Adam optimizer with a weight decay of  $5 \times 10^{-4}$ . We warm up the models for 20 epochs with a linear growth learning rate from  $8 \times 10^{-6}$  to  $8 \times 10^{-4}$ . Then, the learning rate is decayed by a factor of 0.5 for every 40 epochs. We observe that the models converge after a training of 320 epochs and we use them for testing. All our models are implemented with PyTorch and trained on two P40 GPUs.

# 2. More Ablation Studies

#### 2.1. Performance of Different Granularities

In the paper, we have demonstrated the effectiveness of using multiple granularities and compared the corresponding performance with that using a single granularity in Section 4.3.1. For the single granularity setting in our paper, we use the finest granularity, *i.e.*, *G*-1st. Here, we study the performance of using other granularity alone, *e.g.*, *G*-2nd, *G*-3rd, *G*-4th, respectively, and show the results in Table 1. Here, *G*-1st denotes the finest granularity with the spatial resolution of  $16 \times 8$  for  $F_{all}$  and  $F_R$ , while *G*-4th denoting the coarsest granularity with the spatial resolution of  $2 \times 1$ 

Table 2: The ablation study of different pooling strategies to obtain coarse granularity features. "Max-Pooling" denotes max pooling strategy while "Avg-Pooling" denoting average pooling strategy.

Models	MARS					
	mAP	R-1	R-5	R-10	R-20	
Baseline	82.1	85.9	95.1	96.5	97.3	
Max-Pooling	84.1	87.3	95.9	97.4	98.0	
Avg-Pooling (Ours)	85.9	88.8	97.0	97.7	98.5	

for  $F_{all}$  and  $F_R$ . Note that S (which denotes the number of splits(groups) along the channel dimension for masking attention on each split respectively) is set as four for these schemes.

From Table 1, we observe that: (1) our proposed MG-RAFA (N=4) is superior to all the single-granularity schemes, which indicates that the exploration of different level semantics at different granularities are complementary and the joint exploration is effective. (2) All the SG-RAFA schemes of different granularities outperform the scheme *Baseline* consistently, which demonstrates the effectiveness of our proposed reference-aided attentive feature aggregation solution.

# 2.2. Study on Pooling Strategies

To obtain the features at coarse granularity, we perform average pooling on spatial feature positions (as described in Section 3.3 in our paper). We study the influence of different pooling strategies, including max pooling operation (denoted by "Max-Pooling"), and average pooling operation (denoted by "Avg-Pooling"). The results are shown in Table 2. We observe that average pooling strategy outperforms max pooling by 1.8% in mAP and 1.5% in Rank-1 respectively. Intuitively, average pooling can keep more information than max pooling and is robust to noise.

#### **2.3.** Multi-Granularity Design for *F*<sub>all</sub> and *F*<sub>R</sub>

In our proposed scheme MG-RAFA, for each coarse granularity, both the spatial temporal feature nodes  $F_{all}$  and reference nodes  $F_R$  are spatially average pooled to have a lower resolution. This ensures that the relation modeling and attention learning are at the same semantics level for each granularity. We validate the effectiveness of modeling at the same semantics levels in Table 3. Here, SG- $F_{all}$ denotes the scheme that we only generate multi-granularity features for the S-RFNs (*i.e.*  $F_R$ ) while using the original granularity features for the spatial temporal features  $F_{all}$ . We compare SG- $F_{all}$  to our final scheme MG-RAFA which generates multi-granularity features for  $F_{all}$  (denoted by MG- $F_{all}$ ). We observe that MG- $F_{all}$  outperforms SG- $F_{all}$  by 2.6% in mAP and 2.4% in Rank-1, demonstrating the effectiveness of our matched multi-granularity design.

Table 3: The comparison of using single-granularity framelevel features (denoted by "SG- $F_{all}$ ") and using multigranularity frame-level features (denoted by "MG- $F_{all}$ ") in the feature aggregation with multi-granularity S-RFNs.

	MARS					
Models	mAP	R-1	R-5	R-10	R-20	
Baseline	82.1	85.9	95.1	96.5	97.3	
SG-Fall	83.3	86.4	95.1	96.4	97.2	
$MG\text{-}F_{all}  (MG\text{-}RAFA)$	85.9	88.8	97.0	97.7	98.5	

# 3. More Visualization

In this section, we visualize the attention masks learned by our proposed multi-granularity reference-aided attentive feature aggregation (MG-RAFA) scheme across different frames and granularities on four video sequences in Table 1. Note that in our paper, we only partially show the visualization results due to space limitation.

From Figure 1, we have several observations. (1) The learned attention tends to focus on different semantic regions from different frames, which gets rid of a lot of repetitions (redundancy). (2) The learned attention is able to select the better represented areas (e.g., at the 2nd granularity (G-2nd) of the right-bottom example, the shoe region in the 8th frame is clearly visible and thus has high response) and exclude the interferences (e.g., at all granularities of the left-top example, the left regions are not attenteded because there are occlusions). (3) It seems our model captures different semantics at different granularities, which tends to capture more details at finer granularities and larger body parts at coarser granularities. At the coarsest granularity, i.e. G-4th, it seems the attention plays a role of selecting some frames to exclude redundancy. We believe our referenceaided attention modeling is an effective method to capture and learn discriminative spatial and temporal representation.

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Figure 1: Visualization for the learned attention masks of our proposed MG-RAFA across different frames (columns) and granularities (rows). *G-1st* to *G-4th* denote the *1st* to the *4th* granularities, and the corresponding spatial resolutions of the attention masks for each frame are  $16 \times 8$ ,  $8 \times 4$ ,  $4 \times 2$ ,  $2 \times 1$ , respectively. For different granularities, we rescale the attention masks of different spatial resolutions to the same resolution for visualization.

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