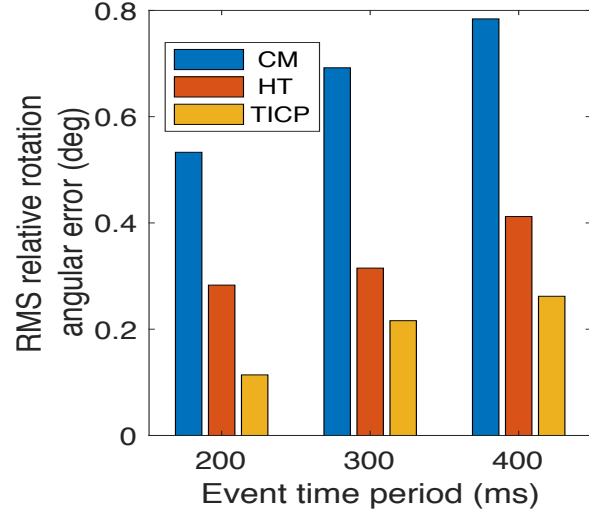
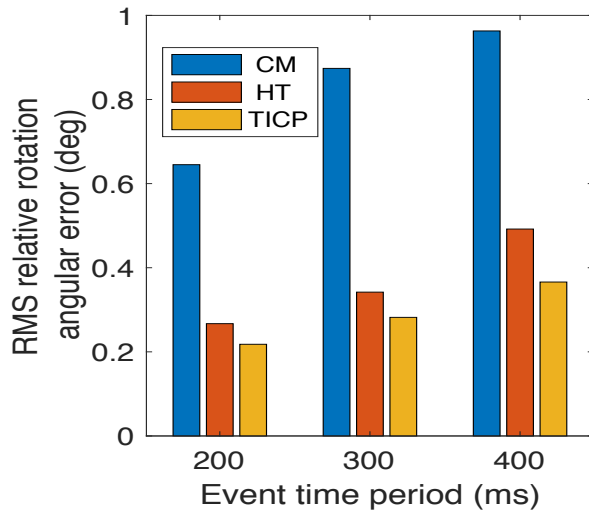


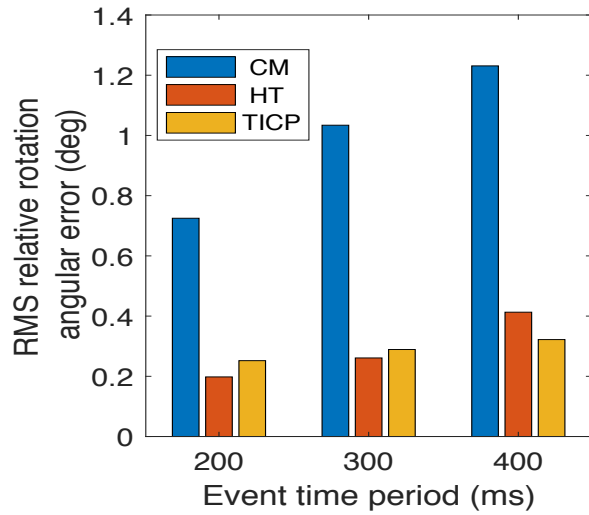
(a) Sequence 7



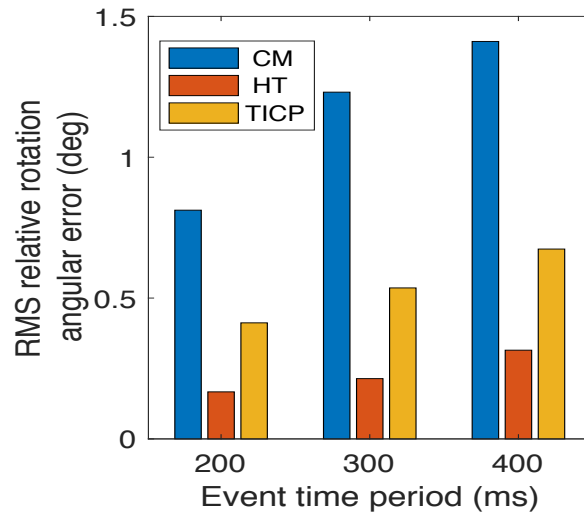
(b) Sequence 8



(c) Sequence 9

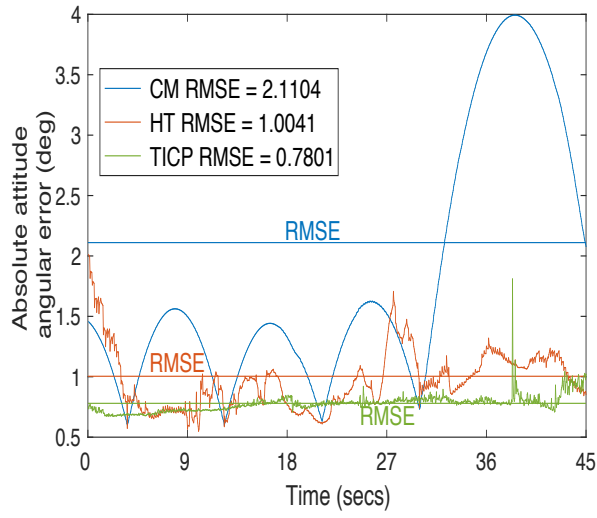


(d) Sequence 10

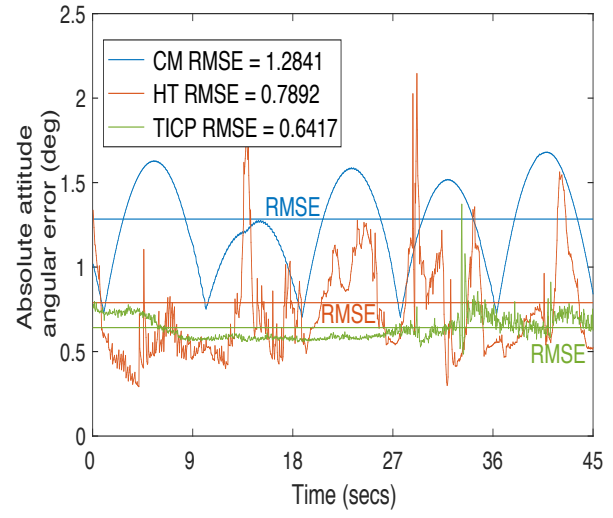


(e) Sequence 11

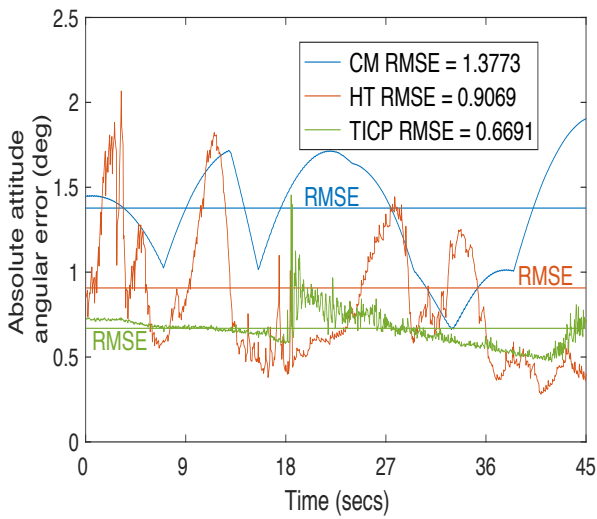
Figure 1. Comparison of relative rotation estimation accuracy using three methods (HT, TICP and CM) for five additional sequences



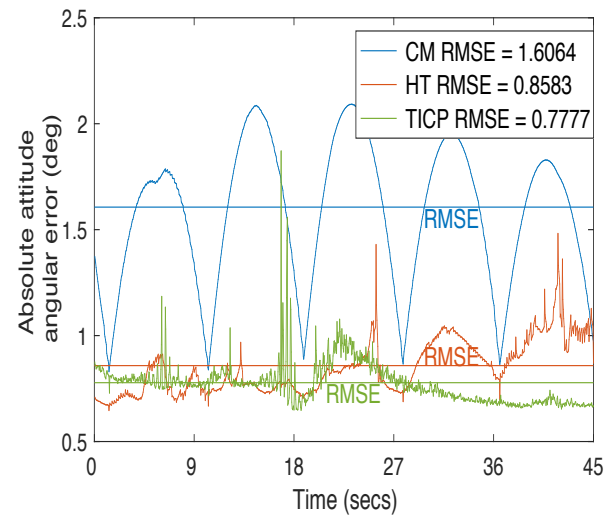
(a) Sequence 7



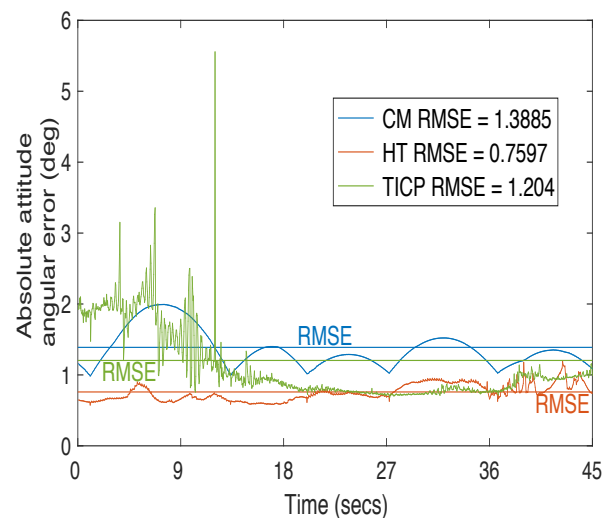
(b) Sequence 8



(c) Sequence 9



(d) Sequence 10



(e) Sequence 11

Figure 2. Comparison of absolute attitude estimation accuracy using three methods (HT, TICP and CM) for five additional sequences